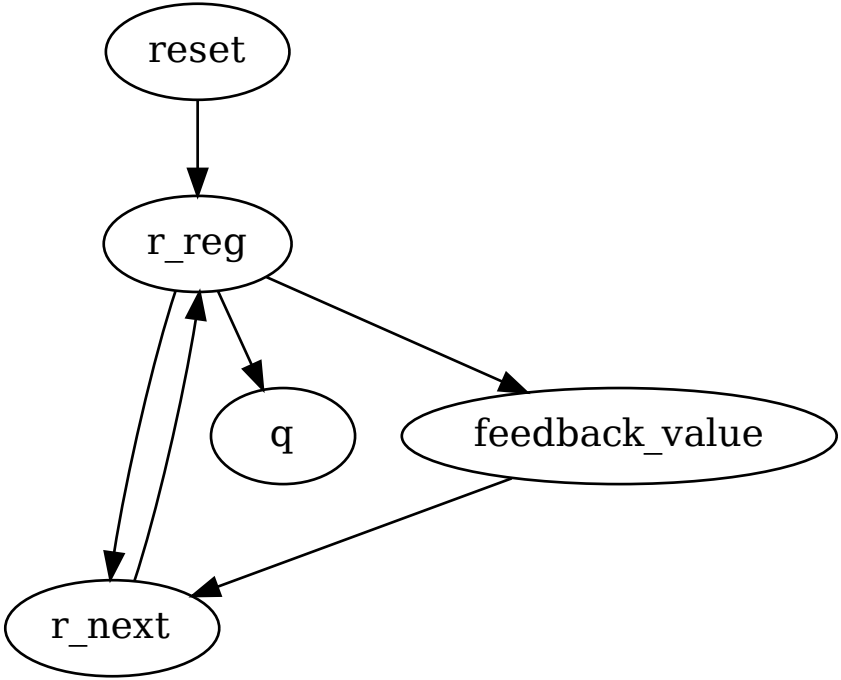
reset
r_reg
q
feedback_value
r_next