GPS filter

Point S.6

```
┌ ─ ─ ─ ─ ─ ─ ─ ┐
   Apply filters          →    Iterate through          →    Location and Speed filter
└ ─ ─ ─ ─ ─ ─ ─ ┘              list of sensors                Compare the solved values
                                                              (for instance speed)
                                                              with know values and
                                                              accepted deviaton
```

Apply filters → Iterate through list of sensors → Location and Speed filter: Compare the solved values (for instance speed) with know values and accepted deviaton

Return ← Raise (potential) alarms ←