

The z Transform

EPD 30.114 ADVANCED FEEDBACK & CONTROL

Role of the z Transform

- Recall that the **Laplace Transform** was a crucial mathematical tool in the analysis and synthesis of continuous-time control systems which are described using **linear time-invariant (LTI) differential equations**
- The **z Transform** plays a similar role in the analysis and synthesis of discrete-time control systems which are described using **linear time-invariant (LTI) difference equations**
- With the z transform method, the solutions to the LTI difference equations become algebraic in nature (now in z rather than s)
- For the rest of the class, we will only consider discrete-time systems (sampling only, no amplitude quantization) that have periodic sampling
- Representation of Discrete-Time signals:
 - Let T be the sampling period, a sequence of discrete value sampled from $x(t)$:

$$x(kT) = x(0) \ , \ x(T), \ x(2T), \ x(3T), \ \dots$$

Explicit expression with T

$$x(k) = x(0) \ , \ x(1), \ x(2), \ x(3), \ \dots$$

Implicit expression with T

Definition of the z Transform

- Consider a time function $x(t)$ for $t > 0$, the sampled values of $x(t)$, if the sampling period was T is expressed by:

$$x(kT) = x(0), x(T), x(2T), \dots \quad x(k) = x(0), x(1), x(2), \dots$$

- The z transform of $x(t)$ is denoted by $X(z)$ and described by:

$$\mathcal{Z}[x(t)] = X(z) = \sum_{k=0}^{\infty} x(kT)z^{-k} = \sum_{k=0}^{\infty} x(k)z^{-k}$$

Blast from the past!

$$\mathcal{L}[f(t)] = F(s) = \int_0^{\infty} f(t)e^{-st} dt$$

Where: z is a complex variable

\mathcal{Z} is the z Transform Operator

$X(z)$ is the z Transform of $x(t)$

- Because the z transform can be expressed as a series, the z^{-k} indicates the position in time at which the amplitude $x(kT)$ occurs
- z Transform is also linear! $\mathcal{Z}[a_1x_1(t) + a_2x_2(t)] = a_1X_1(z) + a_2X_2(z)$

Geometric Series

- Before we continue, we need to refresh a fairly important theorem in mathematics!
- To motivate, let's tell a joke!

An infinite number of mathematicians walk into a bar...

The first one orders a beer.

The second one orders half a beer.

The third one orders a fourth of a beer.

The bartender stops them, pours two beers and says, "You're all a bunch of idiots."

- The punchline? $1 + \frac{1}{2} + \frac{1}{4} + \frac{1}{8} + \dots = 2$

- It is derived from the Geometric Power Series where:

$$1 + x + x^2 + x^3 + \dots = \frac{1}{1-x}$$

Series converges if $|x| < 1$

$$1 + 2x + 3x^2 + \dots = \frac{1}{(1-x)^2}$$

- Remember this series, we will use it again shortly!

zT of Elementary Functions

■ The Unit-Step Function: (Unit-Step Sequence)

$$x(t) = \begin{cases} 1(t) & t \geq 0 \\ 0 & t < 0 \end{cases}$$

$$x(kT) = x(k) = 1 \quad k = 0, 1, 2, 3, \dots$$

$$X(z) = \sum_{k=0}^{\infty} 1z^{-k} = 1 + z^{-1} + z^{-2} + z^{-3} + \dots$$

$$= \frac{1}{1 - z^{-1}}$$

$$= \frac{z}{z - 1}$$

Laplace Transform

$$X(s) = \frac{1}{s}$$

■ The Unit-Ramp Function:

$$x(t) = \begin{cases} t & t \geq 0 \\ 0 & t < 0 \end{cases}$$

$$x(kT) = kT \quad k = 0, 1, 2, 3, \dots$$

$$x(k) = k$$

$$X(z) = \sum_{k=0}^{\infty} kTz^{-k} = T(z^{-1} + 2z^{-2} + 3z^{-3} + \dots)$$

$$= Tz^{-1}(1 + 2z^{-1} + 3z^{-2} + \dots)$$

$$= \frac{Tz^{-1}}{(1 - z^{-1})^2}$$

$$= \frac{Tz}{(z - 1)^2}$$

$$X(s) = \frac{1}{s^2}$$

zT of Elementary Functions

■ The Exponential Function:

$$x(t) = \begin{cases} e^{-at} & t \geq 0 \\ 0 & t < 0 \end{cases} \quad X(z) = \sum_{k=0}^{\infty} e^{-akT} z^{-k} = 1 + e^{-aT} z^{-1} + e^{-2aT} z^{-2} + e^{-3aT} z^{-3} + \dots$$

$$x(kT) = e^{-akT} \quad k = 0, 1, 2, 3, \dots$$

$$X(z) = \frac{1}{1 - e^{-aT} z^{-1}} = \frac{z}{z - e^{-aT}}$$

$$X(s) = \frac{1}{s + a}$$

■ The Sinusoidal Function:

$$x(t) = \begin{cases} \sin \omega t & t \geq 0 \\ 0 & t < 0 \end{cases} \quad X(z) = \mathcal{Z} \left[\frac{1}{2j} (e^{j\omega t} - e^{-j\omega t}) \right]$$

$$\sin \omega t = \frac{1}{2j} (e^{j\omega t} - e^{-j\omega t})$$

$$X(z) = \frac{1}{2j} \left(\frac{1}{1 - e^{j\omega T} z^{-1}} - \frac{1}{1 - e^{-j\omega T} z^{-1}} \right)$$

$$= \frac{z^{-1} \sin \omega T}{1 - 2z^{-1} \cos \omega T + z^{-2}} = \frac{z \sin \omega T}{z^2 - 2z \cos \omega T + 1}$$

$$X(s) = \frac{\omega}{s^2 + \omega^2}$$

zT of Elementary Functions

■ The Polynomial Function:

$$x(k) = \begin{cases} a^k & k = 0, 1, 2, 3, \dots \\ 0 & k < 0 \end{cases}$$
$$X(z) = \sum_{k=0}^{\infty} a^k z^{-k} = 1 + az^{-1} + a^2 z^{-2} + a^3 z^{-3} + \dots$$
$$= \frac{1}{1 - az^{-1}}$$
$$= \frac{z}{z - a}$$

No Laplace Equivalent!

■ The Unit-Impulse Sequence:

$$x(k) = \begin{cases} 1 & k = 0 \\ 0 & k \neq 0 \end{cases}$$
$$X(z) = 1$$

Similar to Unit-Impulse Function

$$X(s) = 1$$

Properties of zT

- Similar to the Laplace Transform, there are several properties for zT
 - Unlike LT, there is no more differentiation and integration properties as they no longer exist in discrete signals

- Linearity:
$$\mathcal{Z}[a_1 x_1(t) + a_2 x_2(t)] = a_1 X_1(z) + a_2 X_2(z)$$

- Multiplicative (Scaling):
$$\mathcal{Z}[a^k x(k)] = X(a^{-1}z)$$

- Time Shift:
$$\mathcal{Z}[x(t - nT)] = z^{-n} X(z)$$

$$\mathcal{Z}[x(t + nT)] = z^n \left[X(z) - \sum_{k=0}^{n-1} x(kT) z^{-k} \right]$$

zT Pairs

	$X(s)$	$x(t)$	$x(kT)$ or $x(k)$	$X(z)$
1.	—	—	Kronecker delta $\delta_0(k)$ 1 $k = 0$ 0 $k \neq 0$	1
2.	—	—	$\delta_0(n-k)$ 1 $n = k$ 0 $n \neq k$	z^{-k}
3.	$\frac{1}{s}$	$1(t)$	$1(k)$	$\frac{1}{1-z^{-1}}$
4.	$\frac{1}{s+a}$	e^{-at}	e^{-akT}	$\frac{1}{1-e^{-aT}z^{-1}}$
5.	$\frac{1}{s^2}$	t	kT	$\frac{Tz^{-1}}{(1-z^{-1})^2}$
6.	$\frac{2}{s^3}$	t^2	$(kT)^2$	$\frac{T^2 z^{-1}(1+z^{-1})}{(1-z^{-1})^3}$
7.	$\frac{6}{s^4}$	t^3	$(kT)^3$	$\frac{T^3 z^{-1}(1+4z^{-1}+z^{-2})}{(1-z^{-1})^4}$
8.	$\frac{a}{s(s+a)}$	$1 - e^{-at}$	$1 - e^{-akT}$	$\frac{(1-e^{-aT})z^{-1}}{(1-z^{-1})(1-e^{-aT}z^{-1})}$
9.	$\frac{b-a}{(s+a)(s+b)}$	$e^{-at} - e^{-bt}$	$e^{-akT} - e^{-bkT}$	$\frac{(e^{-aT} - e^{-bT})z^{-1}}{(1-e^{-aT}z^{-1})(1-e^{-bT}z^{-1})}$
10.	$\frac{1}{(s+a)^2}$	te^{-at}	kTe^{-akT}	$\frac{Te^{-aT}z^{-1}}{(1-e^{-aT}z^{-1})^2}$
11.	$\frac{s}{(s+a)^2}$	$(1-at)e^{-at}$	$(1-akT)e^{-akT}$	$\frac{1-(1+aT)e^{-aT}z^{-1}}{(1-e^{-aT}z^{-1})^2}$

zT Pairs

12.	$\frac{2}{(s+a)^3}$	$t^2 e^{-at}$	$(kT)^2 e^{-akT}$	$\frac{T^2 e^{-aT} (1 + e^{-aT} z^{-1}) z^{-1}}{(1 - e^{-aT} z^{-1})^3}$
13.	$\frac{a^2}{s^2 (s+a)}$	$at - 1 + e^{-at}$	$akT - 1 + e^{-akT}$	$\frac{[(aT - 1 + e^{-aT}) + (1 - e^{-aT} - aT e^{-aT}) z^{-1}] z^{-1}}{(1 - z^{-1})^2 (1 - e^{-aT} z^{-1})}$
14.	$\frac{\omega}{s^2 + \omega^2}$	$\sin \omega t$	$\sin \omega kT$	$\frac{z^{-1} \sin \omega T}{1 - 2z^{-1} \cos \omega T + z^{-2}}$
15.	$\frac{s}{s^2 + \omega^2}$	$\cos \omega t$	$\cos \omega kT$	$\frac{1 - z^{-1} \cos \omega T}{1 - 2z^{-1} \cos \omega T + z^{-2}}$
16.	$\frac{\omega}{(s+a)^2 + \omega^2}$	$e^{-at} \sin \omega t$	$e^{-akT} \sin \omega kT$	$\frac{e^{-aT} z^{-1} \sin \omega T}{1 - 2e^{-aT} z^{-1} \cos \omega T + e^{-2aT} z^{-2}}$
17.	$\frac{s+a}{(s+a)^2 + \omega^2}$	$e^{-at} \cos \omega t$	$e^{-akT} \cos \omega kT$	$\frac{1 - e^{-aT} z^{-1} \cos \omega T}{1 - 2e^{-aT} z^{-1} \cos \omega T + e^{-2aT} z^{-2}}$
18.	—	—	a^k	$\frac{1}{1 - az^{-1}}$
19.	—	—	a^{k-1} $k = 1, 2, 3, \dots$	$\frac{z^{-1}}{1 - az^{-1}}$
20.	—	—	ka^{k-1}	$\frac{z^{-1}}{(1 - az^{-1})^2}$
21.	—	—	$k^2 a^{k-1}$	$\frac{z^{-1} (1 + az^{-1})}{(1 - az^{-1})^3}$
22.	—	—	$k^3 a^{k-1}$	$\frac{z^{-1} (1 + 4az^{-1} + a^2 z^{-2})}{(1 - az^{-1})^4}$

Exercise:

- Find the z-Transform of: $x(t) = 1(t - T)$
 $x(t) = 1(t - 4T)$

$$\mathcal{Z}[1(t - T)] = z^{-1} \mathcal{Z}[1(t)] = z^{-1} \frac{1}{1 - z^{-1}} = \frac{z^{-1}}{1 - z^{-1}}$$

$$\mathcal{Z}[1(t - 4T)] = z^{-4} \mathcal{Z}[1(t)] = z^{-4} \frac{1}{1 - z^{-1}} = \frac{z^{-4}}{1 - z^{-1}}$$

Exercise

- Consider a function $y(k)$ which is defined as a sum of functions $x(h)$ such that

$$y(k) = \sum_{h=0}^k x(h)$$

Find the z transform of $y(k)$

$$y(k) = x(0) + x(1) + \cdots + x(k-1) + x(k)$$

$$y(k-1) = x(0) + x(1) + \cdots + x(k-1)$$

Subtracting:

$$y(k) - y(k-1) = x(k)$$

Taking zT:

$$\mathcal{Z}[y(k) - y(k-1)] = \mathcal{Z}[x(k)]$$

$$Y(z) - z^{-1}Y(z) = X(z)$$

$$Y(z) = \frac{1}{1 - z^{-1}} X(z)$$

Initial & Final Value Theorem (IVT, FVT)

- **IVT:** If $x(t)$ has the z transform $X(z)$ and if the limit exists, $\lim_{z \rightarrow \infty} X(z)$

Then the initial value $x(0)$ of $x(t)$ or $x(k)$ is given by:

$$x(0) = \lim_{z \rightarrow \infty} X(z)$$

- Why? Easy!

$$X(z) = \sum_{k=0}^{\infty} x(k)z^{-k} = x(0) + x(1)z^{-1} + x(2)z^{-2} + \dots$$

- **FVT:** Suppose that $x(k)$, where $x(k)=0$ for $k<0$, has the z transform $X(z)$ and that all the poles of $X(z)$ lie **inside the unit circle**, with exception of the pole at $z=1$. The final value of $x(k)$ as k approaches infinity is:

$$\lim_{k \rightarrow \infty} x(k) = \lim_{z \rightarrow 1} \left[(1 - z^{-1}) X(z) \right]$$

- Why?

$$\mathcal{Z}[x(k)] = X(z) = \sum_{k=0}^{\infty} x(k)z^{-k}$$

$$\mathcal{Z}[x(k-1)] = z^{-1}X(z) = \sum_{k=0}^{\infty} x(k-1)z^{-k}$$

$$\sum_{k=0}^{\infty} x(k)z^{-k} - \sum_{k=0}^{\infty} x(k-1)z^{-k} = X(z) - z^{-1}X(z)$$

$$\lim_{z \rightarrow 1} \left[\sum_{k=0}^{\infty} x(k)z^{-k} - \sum_{k=0}^{\infty} x(k-1)z^{-k} \right] = \lim_{z \rightarrow 1} \left[(1 - z^{-1}) X(z) \right]$$

$$\lim_{k \rightarrow \infty} x(k) = \lim_{z \rightarrow 1} \left[(1 - z^{-1}) X(z) \right]$$

Exercise

$$\lim_{k \rightarrow \infty} x(k) = \lim_{z \rightarrow 1} \left[(1 - z^{-1}) X(z) \right]$$

- Determine the final value of $x(t)$ (or $x(k)$) of $X(z) = \frac{1}{1 - z^{-1}} - \frac{1}{1 - e^{-aT} z^{-1}}$ $a > 0$

$$\begin{aligned} x(\infty) &= \lim_{z \rightarrow 1} \left[(1 - z^{-1}) \left[\frac{1}{1 - z^{-1}} - \frac{1}{1 - e^{-aT} z^{-1}} \right] \right] \\ &= \lim_{z \rightarrow 1} \left[1 - \frac{1 - z^{-1}}{1 - e^{-aT} z^{-1}} \right] = 1 \end{aligned}$$

For the given $X(z)$, it was actually the z Transform of:

$$x(t) = 1 - e^{-at}$$

zT Properties

	$x(t)$ or $x(k)$	$\mathcal{Z}\{x(t)\}$ or $\mathcal{Z}\{x(k)\}$
1.	$ax(t)$	$aX(z)$
2.	$ax_1(t) + bx_2(t)$	$aX_1(z) + bX_2(z)$
3.	$x(t+T)$ or $x(k+1)$	$zX(z) - zx(0)$
4.	$x(t+2T)$	$z^2X(z) - z^2x(0) - zx(T)$
5.	$x(k+2)$	$z^2X(z) - z^2x(0) - zx(1)$
6.	$x(t+kT)$	$z^kX(z) - z^kx(0) - z^{k-1}x(T) - \dots - zx(kT-T)$
7.	$x(t-kT)$	$z^{-k}X(z)$
8.	$x(n+k)$	$z^kX(z) - z^kx(0) - z^{k-1}x(1) - \dots - zx(k-1)$
9.	$x(n-k)$	$z^{-k}X(z)$
10.	$tx(t)$	$-Tz \frac{d}{dz} X(z)$
11.	$kx(k)$	$-z \frac{d}{dz} X(z)$
12.	$e^{-at}x(t)$	$X(ze^{aT})$

zT Properties

13.	$e^{-ak}x(k)$	$X(ze^a)$
14.	$a^kx(k)$	$X\left(\frac{z}{a}\right)$
15.	$ka^kx(k)$	$-z\frac{d}{dz}X\left(\frac{z}{a}\right)$
16.	$x(0)$	$\lim_{z \rightarrow \infty} X(z)$ if the limit exists
17.	$x(\infty)$	$\lim_{z \rightarrow 1} [(1-z^{-1})X(z)]$ if $(1-z^{-1})X(z)$ is analytic on and outside the unit circle
18.	$\nabla x(k) = x(k) - x(k-1)$	$(1-z^{-1})X(z)$
19.	$\Delta x(k) = x(k+1) - x(k)$	$(z-1)X(z) - zx(0)$
20.	$\sum_{k=0}^n x(k)$	$\frac{1}{1-z^{-1}}X(z)$
21.	$\frac{\partial}{\partial a}x(t, a)$	$\frac{\partial}{\partial a}X(z, a)$
22.	$k^m x(k)$	$\left(-z\frac{d}{dz}\right)^m X(z)$
23.	$\sum_{k=0}^n x(kT)y(nT-kT)$	$X(z)Y(z)$
24.	$\sum_{k=0}^{\infty} x(k)$	$X(1)$