

# Radio Telescope & Antenna Tracker Project

---

## Project Vision

---

Incremental build of an antenna-tracked radio telescope system, starting with automated weather satellite reception and a weather prediction AI for Warsaw, then expanding into radio astronomy and citizen science contributions.

---

## PHASE 1: Automated Weather Satellite Station + Weather AI

---

### 1A: Meteor-M LRPT Reception (No Tracker Needed) — ~\$60-100

The easiest and fastest entry point. Meteor-M N2-3/N2-4 are Russian polar-orbiting weather satellites transmitting at 137 MHz. Multiple passes over Warsaw daily. No tracking needed (omnidirectional antenna). Will be available into the 2040s.

**Important context:** All NOAA POES satellites (15, 18, 19) were decommissioned in mid-2025. Meteor-M is now the primary 137 MHz weather satellite. From Warsaw, GOES satellites are NOT visible (geostationary over Americas).

## Hardware

Item	Cost	Notes
RTL-SDR Blog V4	~\$35	Main receiver
QFH antenna (DIY)	~\$10-15	Copper pipe + PVC, circularly polarized
SAW filter + LNA (137 MHz)	~\$15-25	Optional but recommended for Warsaw RFI
Raspberry Pi 4/5	~\$50-80	Or use existing PC
SMA cables, adapters	~\$10	

## Software Stack

- **SatDump** (satdump.org) — all-in-one: satellite tracking, SDR control, decoding, image generation. Has built-in automation (auto-track, auto-record, auto-decode). Replaces the old chain of 6+ programs
- Runs on Raspberry Pi 5 or any Linux box
- Outputs: visible light images, infrared images, false-color composites, map overlays

## What you get

- 1 km/px resolution images of Europe (JPEG compressed but good)
- 3 spectral channels (visible, near-IR, thermal IR)
- Multiple passes/day, automated capture 24/7
- Cloud patterns, storm systems, snow cover over Warsaw region

## 1B: HRPT Reception with Antenna Tracker — ~\$300-500 additional

The big upgrade: high-resolution, uncompressed multi-channel imagery. This requires building the antenna tracker (your main engineering project).

## Receivable satellites from Warsaw with HRPT (1.7 GHz, L-band)

Satellite	Operator	Status	Data
Meteor-M N2-3	Roscosmos	Active	6 channels, 1 km, uncompressed
Meteor-M N2-4	Roscosmos	Active	6 channels, 1 km, uncompressed
Metop-B	EUMETSAT	Until ~2027	6 channels AVHRR, 1 km
Metop-C	EUMETSAT	Until ~2030	6 channels AVHRR, 1 km
AWS (Arctic Weather Sat)	ESA	Active	Microwave radiometer

## Hardware — Antenna Tracker (custom build)

Item	Cost	Notes
2x NEMA23 stepper motors	\$30-60	Torque for dish + wind
2x TMC2209 stepper drivers	\$10-20	Silent, reliable
ESP32 dev board	\$8-12	Rotator controller
GT2 timing belt + pulleys (80T+20T)	\$15-20	4:1 first stage reduction
Worm gear set (or 3D printed)	\$15-30	Second stage, 10:1-15:1
6200/6201 bearings (4-6x)	\$10-20	AZ and EL axes
2040 aluminum extrusion	\$20-40	Frame structure
3D printed parts (PETG)	\$20-25	Gear housings, mounts, adapters
Slip ring (12-wire)	\$10-15	Cable management through AZ axis
Steel plate/tube (base)	workshop	Welded base for rooftop mount
Weatherproof enclosure	\$15-25	For electronics
AS5600 magnetic encoders (2x)	\$5-10	Position feedback

## Hardware — RF Chain

Item	Cost	Notes
80-100cm offset satellite dish	\$0-50	Used, from classifieds (OLX.pl)
L-band helicone feed (3D printed)	\$5-10	Popular open-source design
Nooelec SAWbird+ GOES LNA	~\$35	0.5 dB NF, filtered for 1.7 GHz
Airspy Mini (upgrade from RTL-SDR)	~\$100	12-bit, 6 MHz BW, much better for HRPT

## Tracker Software (your code)

```
Rotator Controller (ESP32, C/C++):
├─ Stepper motor control (AccelStepper library)
├─ AS5600 encoder feedback (I2C)
├─ EasyComm2 protocol over serial/WiFi
├─ Web interface for manual control
├─ Homing routine (limit switches or encoder)
└─ Wind stow mode (auto-park in high wind)

Host Software (Python, Raspberry Pi):
├─ SatDump integration (autotrack + decode)
├─ Satellite pass prediction (pyorbital/skyfield)
├─ Rotator command interface (rotctld/Hamlib)
├─ Image post-processing pipeline
├─ Database for captured images + metadata
└─ API for weather AI module
```

## What you get

- 1 km/px UNCOMPRESSED images, 6 spectral channels
- Thermal IR for cloud-top temperatures
- Near-IR for vegetation, water vapor
- Multiple satellites per day = more frequent coverage of Warsaw
- Raw data for serious weather analysis

## 1C: Geostationary Satellite Reception (Fixed Dish) — ~\$50-150 additional

Add continuous weather monitoring from Elektro-L (Russian geostationary satellite being repositioned to cover Europe in late 2025/2026).

## Setup

- Small fixed dish (60-80cm) pointed at Elektro-L N°3 (14.5°W from Warsaw = ~30° elevation, ~245° azimuth)
- Same L-band LNA + SDR as HRPT setup (can share or add second RTL-SDR)
- SatDump decodes LRIT/HRIT
- Full-disk images every 30 minutes, continuously

Alternative: **EUMETCast via DVB-S2** — standard satellite TV setup pointed at Hotbird 13°E, provides Meteosat data. Requires EUMETSAT registration (free for non-commercial/educational use).

## 1D: Weather Prediction AI — Software Project

This is the software centerpiece: an AI system that learns weather patterns from your satellite imagery and predicts weather for Warsaw.

**Architecture**

## Weather AI System

### DATA COLLECTION

- └ Satellite images (your captures)
  - └ Meteor-M LRPT (137 MHz, automated)
  - └ Meteor-M/Metop HRPT (1.7 GHz, tracked)
    - └ Elektro-L HRIT (geostationary, continuous)
- └ Ground truth weather data
  - └ IMGW API (Polish Met Institute)
  - └ OpenWeatherMap API (current + historical)
    - └ Your own weather station (optional, future)
- └ Timestamp + geolocation metadata

### DATA PIPELINE

- └ Image preprocessing
  - └ Georeferencing (map projection)
  - └ Crop to Warsaw region (~200km radius)
  - └ Normalize channels
  - └ Cloud classification (IR thresholding)
    - └ RFI artifact removal
- └ Feature extraction
  - └ Cloud coverage %
  - └ Cloud motion vectors (consecutive images)
  - └ Cloud-top temperature distribution
  - └ Visible albedo patterns
    - └ Temporal sequences (last N images)
- └ Storage (PostgreSQL + image files)

### AI MODELS

- └ Nowcasting (0-6 hours)
  - └ ConvLSTM / U-Net for cloud motion prediction
  - └ Input: sequence of satellite images
    - └ Output: predicted cloud/rain patterns
- └ Short-term forecast (6-24 hours)
  - └ Transformer-based sequence model
  - └ Input: satellite images + weather features
    - └ Output: temperature, precipitation, cloud cover
- └ Evaluation
  - └ Compare vs actual weather (IMGW data)
  - └ Compare vs official forecast (IMGW/ECMWF)
  - └ Track accuracy metrics over time
    - └ Skill score relative to persistence forecast

### DASHBOARD (Web)

- └ Live satellite image viewer
- └ AI prediction display with confidence
- └ Comparison: AI vs actual vs official forecast
- └ Historical accuracy charts
- └ Alerts for severe weather detection

## Tech Stack

- **Python** — main language (PyTorch/TensorFlow, SatDump integration, data pipeline)
- **PostgreSQL + TimescaleDB** — time-series weather data + image metadata
- **FastAPI** — backend API
- **React or Svelte** — dashboard frontend
- **PyTorch** — model training (ConvLSTM, U-Net, or transformer)
- **Docker** — containerized deployment on Raspberry Pi 5 or mini PC

## Open-Source Models to Build On

- **NPM** ([github.com/seominseok0429/Data-driven-Precipitation-Nowcasting-Using-Satellite-Imagery](https://github.com/seominseok0429/Data-driven-Precipitation-Nowcasting-Using-Satellite-Imagery)) — directly uses satellite imagery, 2 km resolution
- **OpenClimatefix skillful\_nowcasting** — DeepMind DGMR reimplementation
- **ConvLSTM** implementations for sequence prediction
- **Awesome-LWMs** ([github.com/jaychempan/Awesome-LWMs](https://github.com/jaychempan/Awesome-LWMs)) — curated list of weather AI models

## Training Data Strategy

1. **Bootstrap**: Start collecting satellite images + corresponding IMGW weather data from day 1
2. **Pre-train**: Use publicly available satellite datasets (SEVIR, EarthNet2021) for initial model training
3. **Fine-tune**: Once you have weeks/months of Warsaw-specific data, fine-tune on your own captures
4. **Iterate**: Continuously retrain as more data accumulates

## Warsaw-Specific Weather Data Sources

- **IMGW (Instytut Meteorologii i Gospodarki Wodnej)** — Polish meteorological data API
  - **OpenWeatherMap** — free tier: current weather, 5-day forecast, historical data
  - **Open-Meteo** — free, open-source weather API, historical + forecast data
  - **ECMWF** — European Centre for Medium-Range Weather Forecasts (open data)
-



## **PHASE 2: Radio Astronomy (Future, ~\$100-300 additional)**

---

After the weather station is operational, add radio astronomy capability to the same tracked dish:

- Swap/add a 1420 MHz feed horn + SAWbird+ H1 LNA
- Hydrogen line detection and Milky Way mapping
- Join SARA, contribute data
- Same tracker, same SDR infrastructure

## **PHASE 3: Large Dish + Advanced Targets (Future, ~\$500-1500)**

---

- Upgrade to 2-3m dish (used TVRO)
  - Upgrade SDR to SDRplay RSPdx (14-bit)
  - Pulsar detection attempts
  - Join SatNOGS network, Wow@Home
  - Multi-band capability
-

# Project Repository Structure

---

```
space-station/
├── firmware/                                # ESP32 rotator controller
│   ├── src/
│   │   ├── main.cpp
│   │   ├── stepper_control.cpp
│   │   ├── easycomm.cpp                    # EasyComm2 protocol
│   │   ├── encoder.cpp                     # AS5600 position feedback
│   │   └── web_server.cpp                  # Status + manual control
│   └── platformio.ini
├── tracker/                                # Host-side tracking software
│   ├── scheduler.py                        # Satellite pass scheduler
│   ├── rotator.py                          # Rotator communication
│   ├── satdump_integration.py              # SatDump automation hooks
│   └── config.yaml
├── weather-ai/                             # Weather prediction AI
│   ├── data/
│   │   ├── collectors/                    # IMGW, OpenWeatherMap scrapers
│   │   ├── pipeline.py                    # Image preprocessing
│   │   └── dataset.py                     # PyTorch dataset class
│   ├── models/
│   │   ├── nowcast.py                     # ConvLSTM nowcasting model
│   │   ├── forecast.py                    # Transformer forecast model
│   │   └── evaluate.py                     # Accuracy metrics
│   ├── api/
│   │   └── main.py                         # FastAPI backend
│   └── train.py
├── dashboard/                              # Web frontend
│   ├── src/
│   └── package.json
├── hardware/                               # CAD files, wiring diagrams
│   ├── rotator/                           # 3D print STL files
│   ├── antenna/                           # QFH, feed horn designs
│   └── enclosure/
├── docs/
│   ├── build-guide.md
│   └── calibration.md
├── docker-compose.yml
└── README.md
```

# Implementation Order

---

## Sprint 1: Get Images Flowing

1. Order RTL-SDR V4, build QFH antenna
2. Install SatDump on Raspberry Pi / PC
3. Receive first Meteor-M LRPT image
4. Set up automated capture (SatDump autotrack)
5. Build image storage database
6. Start collecting IMGW/Open-Meteo weather data for Warsaw

## Sprint 2: Build the Tracker

1. Design rotator in CAD (Fusion 360 / FreeCAD)
2. 3D print gear housings and structural parts
3. Weld steel base frame
4. Assemble mechanical system
5. Write ESP32 firmware (stepper control + EasyComm2)
6. Integrate with SatDump for automated HRPT tracking

## Sprint 3: HRPT Reception

1. Acquire/build dish (80-100cm) + L-band feed
2. Install LNA + cabling
3. First tracked HRPT capture
4. Set up multi-satellite automated schedule

## Sprint 4: Weather AI v1

1. Build data pipeline (satellite images → preprocessed dataset)
2. Implement baseline model (ConvLSTM for cloud motion)
3. Train on accumulated data + public datasets
4. Build dashboard with live images + predictions
5. Start tracking prediction accuracy vs actual weather

## Sprint 5: Iterate & Expand

1. Improve AI model based on accuracy data
  2. Add Elektro-L geostationary reception
  3. Add radio astronomy capability (1420 MHz feed)
  4. Join SARA / SatNOGS communities
- 

## Verification

---

### Phase 1A (LRPT)

- First Meteor-M image captured within first evening
- SatDump autotrack captures 4+ passes per day unattended
- Images show recognizable cloud patterns over Europe

### Phase 1B (HRPT + Tracker)

- Rotator responds correctly to EasyComm2 commands
- Gpredict satellite tracking test: rotator follows predicted pass
- HRPT image quality visibly superior to LRPT (sharper, more channels)
- Tracker survives wind test (weights attached to simulate dish wind load)

### Phase 1D (Weather AI)

- Dashboard shows latest satellite images + weather data
  - Nowcast model produces cloud predictions for next 1-3 hours
  - Track "skill score" vs persistence baseline (just predicting "same as now")
  - After 1+ month of data: compare AI accuracy vs IMGW official forecast
- 

## Sources

---

- [SatDump](#) — all-in-one satellite decoding software
- [Beyond POES: Amateur Satellite Reception](#) — post-NOAA landscape

- [Meteor-M Reception Guide](#) — Jacopo's comprehensive guide
- [HRPT Beginners Guide](#)
- [SatDump Automation](#)
- [Tysonpower DIY Rotator](#)
- [SatNOGS Rotator v3](#)
- [NPM Precipitation Nowcasting](#)
- [DGMR Reimplementation](#)
- [Awesome Large Weather Models](#)
- [SARA](#) — Society of Amateur Radio Astronomers
- [SatNOGS](#) — satellite ground station network
- [Radio JOVE](#)