

**Problem 1.**

Find the position vector of the foot of the perpendicular from the point with position vector  $\mathbf{c}$  to the line with equation  $\mathbf{r} = \mathbf{a} + \lambda\mathbf{b}$ ,  $\lambda \in \mathbb{R}$ . Leave your answers in terms of  $\mathbf{a}$ ,  $\mathbf{b}$  and  $\mathbf{c}$ .

**Solution**

Let the foot of the perpendicular be  $F$ . We have that  $\overrightarrow{OF} = \mathbf{a} + \lambda\mathbf{b}$  for some real  $\lambda$ , and  $\overrightarrow{CF} \cdot \mathbf{b} = 0$ .

$$\begin{aligned}\overrightarrow{CF} \cdot \mathbf{b} &= 0 \\ \Rightarrow (\overrightarrow{OF} - \overrightarrow{OC}) \cdot \mathbf{b} &= 0 \\ \Rightarrow (\mathbf{a} + \lambda\mathbf{b} - \mathbf{c}) \cdot \mathbf{b} &= 0 \\ \Rightarrow \lambda\mathbf{b} \cdot \mathbf{b} + (\mathbf{a} - \mathbf{c}) \cdot \mathbf{b} &= 0 \\ \Rightarrow \lambda|\mathbf{b}|^2 &= (\mathbf{c} - \mathbf{a}) \cdot \mathbf{b} \\ \Rightarrow \lambda &= \frac{(\mathbf{c} - \mathbf{a}) \cdot \mathbf{b}}{|\mathbf{b}|^2} \\ \Rightarrow \overrightarrow{OF} &= \mathbf{a} + \frac{(\mathbf{c} - \mathbf{a}) \cdot \mathbf{b}}{|\mathbf{b}|^2} \mathbf{b}\end{aligned}$$

$$\boxed{\overrightarrow{OF} = \mathbf{a} + \frac{(\mathbf{c} - \mathbf{a}) \cdot \mathbf{b}}{|\mathbf{b}|^2} \mathbf{b}}$$

**Problem 2.**

The point  $O$  is the origin, and points  $A, B, C$  have position vectors given by  $\overrightarrow{OA} = 6\mathbf{i}$ ,  $\overrightarrow{OB} = 3\mathbf{j}$ ,  $\overrightarrow{OC} = 4\mathbf{k}$ . The point  $P$  is on line  $AB$  between  $A$  and  $B$ , and is such that  $AP = 2PB$ . The point  $Q$  has position vector given by  $\overrightarrow{OQ} = q\mathbf{i}$ , where  $q$  is a scalar.

- Express, in terms of  $\mathbf{i}, \mathbf{j}, \mathbf{k}$ , the vector  $\overrightarrow{CP}$ .
- Show that the line  $BQ$  has equation  $\mathbf{r} = 3\mathbf{j} + t(q\mathbf{i} - 3\mathbf{j})$ , where  $t$  is a parameter. Give an equation of the line  $CP$  in a similar form.
- Find the value of  $q$  for which the lines  $CP$  and  $BQ$  are perpendicular.
- Find the sine of the acute angle between the lines  $CP$  and  $BQ$  in terms of  $q$ .

**Solution**

We have that  $\overrightarrow{OA} = \begin{pmatrix} 6 \\ 0 \\ 0 \end{pmatrix}$ ,  $\overrightarrow{OB} = \begin{pmatrix} 0 \\ 3 \\ 0 \end{pmatrix}$  and  $\overrightarrow{OC} = \begin{pmatrix} 0 \\ 0 \\ 4 \end{pmatrix}$ .

**Part (a)**

By the Ratio Theorem,

$$\begin{aligned} \overrightarrow{OP} &= \frac{2\overrightarrow{OB} + \overrightarrow{OA}}{1+2} \\ &= \frac{1}{3} \left( 2 \begin{pmatrix} 0 \\ 3 \\ 0 \end{pmatrix} + \begin{pmatrix} 6 \\ 0 \\ 0 \end{pmatrix} \right) \\ &= \begin{pmatrix} 2 \\ 2 \\ 0 \end{pmatrix} \\ \Rightarrow \overrightarrow{CP} &= \overrightarrow{OP} - \overrightarrow{OC} \\ &= \begin{pmatrix} 2 \\ 2 \\ 0 \end{pmatrix} - \begin{pmatrix} 0 \\ 0 \\ 4 \end{pmatrix} \\ &= \begin{pmatrix} 2 \\ 2 \\ -4 \end{pmatrix} \end{aligned}$$

$$\boxed{\overrightarrow{CP} = 2\mathbf{i} + 2\mathbf{j} - 4\mathbf{k}}$$

**Part (b)**

Note that  $\overrightarrow{BQ} = \overrightarrow{OQ} - \overrightarrow{OB} = \begin{pmatrix} q \\ 0 \\ 0 \end{pmatrix} - \begin{pmatrix} 0 \\ 3 \\ 0 \end{pmatrix} = \begin{pmatrix} q \\ -3 \\ 0 \end{pmatrix}$ . Thus,  $BQ$  is given by

$$\mathbf{r} = \begin{pmatrix} 0 \\ 3 \\ 0 \end{pmatrix} + t \begin{pmatrix} q \\ -3 \\ 0 \end{pmatrix}, t \in \mathbb{R}$$

$$\implies \mathbf{r} = 3\mathbf{j} + t(q\mathbf{i} - 3\mathbf{j}), t \in \mathbb{R}$$

Note that  $\overrightarrow{CP} = \begin{pmatrix} 2 \\ 2 \\ -4 \end{pmatrix} = 2 \begin{pmatrix} 1 \\ 1 \\ -2 \end{pmatrix}$ . Hence,  $CP$  is given by

$$\mathbf{r} = \begin{pmatrix} 0 \\ 0 \\ 4 \end{pmatrix} + u \begin{pmatrix} 1 \\ 1 \\ -2 \end{pmatrix}, u \in \mathbb{R}$$

$$\boxed{CP : \mathbf{r} = 4\mathbf{k} + u(\mathbf{i} + \mathbf{j} - 2\mathbf{k}), u \in \mathbb{R}}$$

### Part (c)

Since  $CP$  is perpendicular to  $BQ$ , we have  $\overrightarrow{CP} \cdot \overrightarrow{BQ} = 0$ .

$$\begin{aligned} \overrightarrow{CP} \cdot \overrightarrow{BQ} &= 0 \\ \implies 2 \begin{pmatrix} 1 \\ 1 \\ -2 \end{pmatrix} \cdot \begin{pmatrix} q \\ -3 \\ 0 \end{pmatrix} &= 0 \\ \implies q - 3 + 0 &= 0 \\ \implies q &= 3 \end{aligned}$$

$$\boxed{q = 3}$$

### Part (d)

Let  $\theta$  be the acute angle between  $CP$  and  $BQ$ .

$$\begin{aligned} \left| \begin{pmatrix} 1 \\ 1 \\ -2 \end{pmatrix} \times \begin{pmatrix} q \\ -3 \\ 0 \end{pmatrix} \right| &= \left| \begin{pmatrix} 1 \\ 1 \\ -2 \end{pmatrix} \right| \left| \begin{pmatrix} q \\ -3 \\ 0 \end{pmatrix} \right| \sin \theta \\ \implies \left| \begin{pmatrix} -6 \\ 2q \\ 3-q \end{pmatrix} \right| &= \left| \begin{pmatrix} 1 \\ 1 \\ -2 \end{pmatrix} \right| \left| \begin{pmatrix} q \\ -3 \\ 0 \end{pmatrix} \right| \sin \theta \\ \implies \sqrt{(-6)^2 + (2q)^2 + (3-q)^2} &= \sqrt{1^2 + 1^2 + (-2)^2} \cdot \sqrt{q^2 + (-3)^2 + 0^2} \cdot \sin \theta \\ \implies \sqrt{36 + 4q^2 + 9 - 6q + q^2} &= \sqrt{6} \cdot \sqrt{q^2 + 9} \cdot \sin \theta \\ \implies \sqrt{5q^2 - 6q + 45} &= \sqrt{6(q^2 + 9)} \sin \theta \\ \implies \sqrt{5q^2 - 6q + 45} &= \sqrt{6q^2 + 54} \sin \theta \\ \implies \sin \theta &= \frac{\sqrt{5q^2 - 6q + 45}}{\sqrt{6q^2 + 54}} \end{aligned}$$

$$= \sqrt{\frac{5q^2 - 6q + 45}{6q^2 + 54}}$$

$$\sin \theta = \sqrt{\frac{5q^2 - 6q + 45}{6q^2 + 54}}$$

**Problem 3.**

Line  $l_1$  passes through the point  $A$  with position vector  $3\mathbf{i} - 2\mathbf{k}$  and is parallel to  $-2\mathbf{i} + 4\mathbf{j} - \mathbf{j}$ .  
Line  $l_2$  has Cartesian equation given by  $\frac{x-1}{2} = y = z + 3$ .

- Show that the two lines intersect and find the coordinates of their point of intersection.
- Find the acute angle between the two lines  $l_1$  and  $l_2$ . Hence, or otherwise, find the shortest distance from point  $A$  to line  $l_2$ .
- Find the position vector of the foot  $N$  of the perpendicular from  $A$  to the line  $l_2$ . The point  $B$  lies on the line  $AN$  produced and is such that  $N$  is the mid-point of  $AB$ . Find the position vector of  $B$ .

**Solution**

We have that

$$l_1 : \mathbf{r} = \begin{pmatrix} 3 \\ 0 \\ -2 \end{pmatrix} + \lambda \begin{pmatrix} -2 \\ 4 \\ -1 \end{pmatrix}, \lambda \in \mathbb{R}$$

and

$$l_2 : \mathbf{r} = \begin{pmatrix} 1 \\ 0 \\ -3 \end{pmatrix} + \mu \begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix}, \mu \in \mathbb{R}$$

**Part (a)**

Consider  $l_1 = l_2$ .

$$\begin{aligned} l_1 &= l_2 \\ \Rightarrow \begin{pmatrix} 3 \\ 0 \\ -2 \end{pmatrix} + \lambda \begin{pmatrix} -2 \\ 4 \\ -1 \end{pmatrix} &= \begin{pmatrix} 1 \\ 0 \\ -3 \end{pmatrix} + \mu \begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix} \\ \Rightarrow \mu \begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix} - \lambda \begin{pmatrix} -2 \\ 4 \\ -1 \end{pmatrix} &= \begin{pmatrix} 2 \\ 0 \\ 1 \end{pmatrix} \end{aligned}$$

This gives the following system:

$$\begin{cases} 2\mu + 2\lambda = 2 \\ \mu - 4\lambda = 0 \\ \mu + \lambda = 1 \end{cases}$$

which has the unique solution  $\mu = \frac{4}{5}$  and  $\lambda = \frac{1}{5}$ . Thus, the intersection point  $P$  has

position vector  $\begin{pmatrix} 3 \\ 0 \\ -2 \end{pmatrix} + \frac{1}{5} \begin{pmatrix} -2 \\ 4 \\ -1 \end{pmatrix} = \frac{1}{5} \begin{pmatrix} 13 \\ 4 \\ -11 \end{pmatrix}$  and thus has coordinates  $\left(\frac{13}{5}, \frac{4}{5}, -\frac{11}{5}\right)$ .

$$\boxed{\left(\frac{13}{5}, \frac{4}{5}, -\frac{11}{5}\right)}$$

**Part (b)**

Let  $\theta$  be the acute angle between  $l_1$  and  $l_2$ .

$$\begin{aligned}
 \cos \theta &= \frac{\left| \begin{pmatrix} -2 \\ 4 \\ -1 \end{pmatrix} \cdot \begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix} \right|}{\left| \begin{pmatrix} -2 \\ 4 \\ -1 \end{pmatrix} \right| \left| \begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix} \right|} \\
 &= \frac{|-4 + 4 - 1|}{\sqrt{21} \cdot \sqrt{6}} \\
 &= \frac{1}{\sqrt{126}} \\
 \Rightarrow \quad \theta &= \arccos \frac{1}{\sqrt{126}} \\
 &= 84.9^\circ \text{ (1 d.p.)} \\
 \boxed{\theta = 84.9^\circ}
 \end{aligned}$$

Note that

$$\begin{aligned}
 AP &= \sqrt{\left(\frac{17}{5} - 3\right)^2 + \left(-\frac{4}{5} - 0\right)^2 + \left(-\frac{9}{5} - (-2)\right)^2} \\
 &= \sqrt{\frac{21}{25}} \\
 &= \frac{\sqrt{21}}{5}
 \end{aligned}$$

Since  $\sin \theta = \frac{AN}{AP}$ , we have that  $AN = AP \sin \theta$ .

$$\begin{aligned}
 AN &= \frac{\sqrt{21}}{5} \sin \arccos \frac{1}{\sqrt{126}} \\
 &= \frac{\sqrt{21}}{5} \cdot \frac{\sqrt{(\sqrt{126})^2 - 1}}{\sqrt{126}} \\
 &= \frac{\sqrt{21}}{5} \cdot \frac{\sqrt{125}}{\sqrt{126}} \\
 &= \frac{\sqrt{21}}{5} \cdot \frac{5\sqrt{5}}{\sqrt{6} \cdot \sqrt{21}} \\
 &= \frac{\sqrt{5}}{\sqrt{6}} \\
 &= \sqrt{\frac{5}{6}}
 \end{aligned}$$

The shortest distance between  $A$  and  $l_2$  is  $\sqrt{\frac{5}{6}}$  units.

**Part (c)**

Since  $N$  is on  $l_2$ , we have that  $\overrightarrow{ON} = \begin{pmatrix} 1 \\ 0 \\ 03 \end{pmatrix} + \mu \begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix}$  for some real  $\mu$ .

$$\begin{aligned}
 & \overrightarrow{AN} \cdot \begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix} = 0 \\
 \Rightarrow & (\overrightarrow{ON} - \overrightarrow{OA}) \cdot \begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix} = 0 \\
 \Rightarrow & \left( \begin{pmatrix} 1 \\ 0 \\ -3 \end{pmatrix} + \mu \begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix} - \begin{pmatrix} 3 \\ 0 \\ -2 \end{pmatrix} \right) \cdot \begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix} = 0 \\
 \Rightarrow & \begin{pmatrix} -2 + 2\mu \\ \mu \\ -1 + \mu \end{pmatrix} \cdot \begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix} = 0 \\
 \Rightarrow & 2(-2 + 2\mu) + \mu + (-1 + \mu) = 0 \\
 \Rightarrow & \mu = \frac{5}{6} \\
 \Rightarrow & \overrightarrow{ON} = \begin{pmatrix} 1 \\ 0 \\ -3 \end{pmatrix} + \frac{5}{6} \begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix} \\
 & = \frac{1}{6} \begin{pmatrix} 16 \\ 5 \\ -13 \end{pmatrix}
 \end{aligned}$$

$$\boxed{\overrightarrow{ON} = \frac{1}{6} \begin{pmatrix} 16 \\ 5 \\ -13 \end{pmatrix}}$$

By the Ratio Theorem,

$$\begin{aligned}
 \overrightarrow{ON} &= \frac{\overrightarrow{OA} + \overrightarrow{OB}}{2} \\
 \Rightarrow \overrightarrow{OB} &= 2\overrightarrow{ON} - \overrightarrow{OA} \\
 &= \frac{2}{6} \begin{pmatrix} 16 \\ 5 \\ -13 \end{pmatrix} - \begin{pmatrix} 3 \\ 0 \\ -2 \end{pmatrix} \\
 &= \frac{1}{3} \begin{pmatrix} 7 \\ 5 \\ -7 \end{pmatrix}
 \end{aligned}$$

$$\boxed{\overrightarrow{OB} = \frac{1}{3} \begin{pmatrix} 7 \\ 5 \\ -7 \end{pmatrix}}$$