# Aseem Saxena

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# Experience

### Research Assistant

# National University of Singapore

Sep '17-Jul '18

Adaptive Computing Lab, Prof David Hsu

- · Implementation of a feature rich visualization tool based on Python Tkinter to visualize and debug QMDPNet, a deep learning algorithm for solving POMDPs.
- · Robot infrastructure setup for executing actions output by QMDPnet reliably and safely. Implementation of a robust position controller on the Fetch robot.
- · Imitation Learning for autonomous driving in an unstructured environment.

# **Active Participant**

# Stanford Scholar Initiative

Dec '16-Current

· Led and actively participated in the creation of research talks on influential research papers viz. Deep Residual Learning, FRAUDAR, Rovables, Real-Time 3D Reconstruction and 6-DoF Tracking with an Event Camera and Bayesian Active Learning for Posterior Estimation.

### Research Assistant

# Robotics Research Center, International Institute of Information Technology Hyderabad, India

Apr '17-Jul '17

Mahindra Driverless Car Challenge

· Worked on developing a robust system for traffic sign detection, recognition and tracking.

# Computer Vision Engineer Ducere Technologies Pvt Ltd Hyderabad, India

Jul '16-Apr '17

- · Worked on developing a low cost LiDAR system using a Teraranger One ToF sensor on a pan tilt unit for 3D scanning.
- · Experimented with various depth perception techniques such as structured light, stereo, ToF for implementing obstacle detection for a visually challenged person.

### Research Assistant

# Robotics Research Center, International Institute of Information Technology Hyderabad, India

Jun '15-Jul '16

- · Research into an End-to-end learning based approach for visual servoing in diverse scenes.
- · Implementation of 'Guess from Far Recognise when Near', a system for object search in unknown environments via frontier based navigation, far object recognition using 2D image segmentation and near object recognition using a bag of words model trained on 3D point clouds.
- · Deep Learning for Table Interest Point Detection Research to find interest points or corner points of tables in a scene using cues from semantic segmentation and vanishing lines. Availability of semantic information such as interest points can help mobile robots navigate in a better way.
- · Automating GrabCut for Multilabel Image Segmentation Implementing multi label Image Segmentation without user guidance by learning a Gaussian mixture model for each label and performing alpha expansion algorithm using MRF2.2 Library.

Research Intern Strand Life Sciences Pvt. Ltd. Bangalore, India · Applied Decision Trees and Support Vector Machines and other classification algorithms for classifying mutations as cancerous.

### **Publications**

Exploring Convolutional Networks for End-to-End Visual Servoing Aseem Saxena, Harit Pandya, Gourav Kumar, K. Madhava Krishna IEEE ICRA, 2017 (Accepted)

#### Education

# B.E(Hons) in Electrical and Electronics Engineering

Aug '11-May '16

Birla Institute of Technology and Science Pilani

Pilani, India

CGPA: 7.34/10.00

# M.Sc(Hons) in Biological Sciences

Aug '11-May '16

Birla Institute of Technology and Science Pilani

Pilani, India CGPA: 7.34/10.00

# Scholarships and Certificates

Kishore Vaigyanik Protsahan Yojana Fellowship

Department of Science and Technology, Government of India. 2011 - 2016

All India Rank 1 in National Cyber Olympiad

2010

### Skills

Deep Learning Caffe, Tensorflow, Pytorch OpenCV, Point Cloud Library Computer Vision

Robotics Platforms Robot Operating System(ROS), Gazebo, OpenRAVE

Programming Languages Python, C/C++, JAVA, MATLAB

Audio and Video Editing Cubase, Kdenlive

### **Academic Projects**

Object avoidance on Firebird V and E-puck Robots

Problems in current best protein model assessment measures

Application of Genetic Algorithms to Robot Locomotion

### Extra-Cirrucular Activities

Member of INSPIRE robotics lab at BITS Pilani.

Guitarist, Bassist, Vocalist and Keyboardist at Music Club BITS Pilani.

Avid Marathon runner

Keen Swimmer