view frames Result Recorded at time: 1757224574.8701248 map Broadcaster: default authority Average rate: 1.98 Buffer length: 1.01 Most recent transform: 1757224573.115366 Oldest transform: 1757224572.105194 odom Broadcaster: default authority Average rate: 30.191 Buffer length: 4.67 Most recent transform: 1757224574.783249 Oldest transform: 1757224570.113015 base_footprint Broadcaster: default authority Average rate: $10\overline{0}00.0$ Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 base link Broadcaster: default authority Average rate: 18.217 Average rate: 18.217 Average rate: $10\overline{0}00.0$ Average rate: 10000.0 Average rate: 10000.0 Buffer length: 0.0 Buffer length: 5.05 Buffer length: 5.05 Buffer length: 0.0 Most recent transform: 1757224574.773349 Most recent transform: 1757224574.773349 Most recent transform: 0.0 Oldest transform: 1757224569.723119 Oldest transform: 1757224569.723119 Oldest transform: 0.0 rearwhl_r link rear_poolnoodle link drivewhl_l_link front_poolnoodle link drivewhl r link hesai lidar rearwhl l link base_scan camera bottom screw frame Broadcaster: default authority Average rate: $10\overline{0}00.0$ Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 camera link Broadcaster: default authority Average rate: $10\overline{0}00.0$ Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 camera_depth_frame camera_gyro_frame camera_infra1_frame camera_infra2_frame camera_accel_frame camera_color_frame Broadcaster: default authority Average rate: $10\overline{0}00.0$ Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 camera_accel_optical frame camera_color_optical frame camera_depth_optical_frame camera_infra1_optical_frame camera_infra2_optical_frame camera gyro optical frame