

Quantum-Inspired Observational–Expected Distribution Algorithm

This document presents a description of a quantum-inspired algorithm for managing and predicting outcomes with separate “observed” and “expected” amplitude distributions. The method is designed to capture and adapt to loose or cyclical patterns in a (near-)random process, especially one separated into two categories (**pb** and **mb**) that occur on different days of the week.

1 Overview

- **Major Sets**

- **pb**: Occurs on Monday, Wednesday, and Saturday.
 - * State space Ω_{pb} consists of combinations (5 from 1–69, 1 from 1–26).
- **mb**: Occurs on Tuesday and Friday.
 - * State space Ω_{mb} consists of combinations (5 from 1–70, 1 from 1–25).

- **Amplitude Distributions**

Each major set has two separate amplitude distributions:

1. **Observed Distribution** $\alpha^{(\text{obs})}$ – tracks empirical data in near-real time.
2. **Expected Distribution** $\alpha^{(\text{exp})}$ – represents a stable forecast or model of future outcomes.

2 State Spaces

2.1 Define Ω_{pb}

$$\Omega_{pb} = \{s \mid s \text{ is a 6-value outcome for pb}\}, \quad |\Omega_{pb}| = \binom{69}{5} \times 26.$$

2.2 Define Ω_{mb}

$$\Omega_{mb} = \{s \mid s \text{ is a 6-value outcome for mb}\}, \quad |\Omega_{mb}| = \binom{70}{5} \times 25.$$

2.3 Initialize Distributions

For each set Ω_{pb} and Ω_{mb} , initialize two vectors of amplitudes:

$$\alpha_s^{(\text{obs})} \quad \text{and} \quad \alpha_s^{(\text{exp})},$$

where $s \in \Omega_{pb}$ or $s \in \Omega_{mb}$. Each vector is normalized so that

$$\sum_{s \in \Omega_{pb}} |\alpha_s^{(\text{obs})}|^2 = 1, \quad \sum_{s \in \Omega_{pb}} |\alpha_s^{(\text{exp})}|^2 = 1,$$

and similarly for Ω_{mb} .

3 Observational Updates

3.1 Observed Distribution Update

Purpose Reflects the direct frequency of outcomes in the data, potentially with a smoothing or decay factor to emphasize recent observations.

Example Rule When a new outcome s_{obs} in Ω_{pb} or Ω_{mb} is recorded, update the corresponding observed distribution as follows:

1. Apply an exponential decay to all amplitudes:

$$\alpha_s^{(\text{obs})} \leftarrow \gamma \cdot \alpha_s^{(\text{obs})},$$

for each $s \in \Omega$, where $\gamma \in [0, 1)$ is a decay parameter.

2. Boost the observed amplitude for the actually drawn state:

$$\alpha_{s_{\text{obs}}}^{(\text{obs})} \leftarrow \alpha_{s_{\text{obs}}}^{(\text{obs})} + (1 - \gamma).$$

3. Normalize to ensure:

$$\sum_{s \in \Omega} |\alpha_s^{(\text{obs})}|^2 = 1.$$

3.2 Expected Distribution Update

Purpose Maintains a stable prediction model that does not overreact to individual observations.

Example Rule After updating the observed distribution, adjust the expected distribution with a small learning rate η :

$$\alpha_s^{(\text{exp})} \leftarrow \alpha_s^{(\text{exp})} + \eta \left(\alpha_s^{(\text{obs})} - \alpha_s^{(\text{exp})} \right).$$

Then normalize:

$$\sum_{s \in \Omega} |\alpha_s^{(\text{exp})}|^2 = 1.$$

4 Daily Procedure

The following procedure outlines how the algorithm is executed each day of the week, respecting the schedules for pb and mb:

Algorithm QuantumInspiredObservationalExpectedModel:

1. For each day D in the repeating weekly cycle:

(a) If D is one of $\{Monday, Wednesday, Saturday\}$:

- i. Obtain the real-world outcome s_{obs} in Ω_{pb} .
- ii. Update Observed Distribution $\alpha^{(\text{obs}, \text{pb})}$:
 - Apply exponential decay: $\alpha_s^{(\text{obs}, \text{pb})} \leftarrow \gamma \cdot \alpha_s^{(\text{obs}, \text{pb})}$.
 - Increment $\alpha_{s_{\text{obs}}}^{(\text{obs}, \text{pb})}$ by $(1 - \gamma)$.
 - Normalize $\alpha^{(\text{obs}, \text{pb})}$.
- iii. Update Expected Distribution $\alpha^{(\text{exp}, \text{pb})}$:
 - For each $s \in \Omega_{pb}$:

$$\alpha_s^{(\text{exp}, \text{pb})} \leftarrow \alpha_s^{(\text{exp}, \text{pb})} + \eta \left(\alpha_s^{(\text{obs}, \text{pb})} - \alpha_s^{(\text{exp}, \text{pb})} \right).$$

- Normalize $\alpha^{(\text{exp}, \text{pb})}$.

(b) Else if D is one of $\{Tuesday, Friday\}$:

- i. Obtain the real-world outcome s_{obs} in Ω_{mb} .
- ii. Update Observed Distribution $\alpha^{(\text{obs}, \text{mb})}$:
 - Apply exponential decay: $\alpha_s^{(\text{obs}, \text{mb})} \leftarrow \gamma \cdot \alpha_s^{(\text{obs}, \text{mb})}$.
 - Increment $\alpha_{s_{\text{obs}}}^{(\text{obs}, \text{mb})}$ by $(1 - \gamma)$.
 - Normalize $\alpha^{(\text{obs}, \text{mb})}$.
- iii. Update Expected Distribution $\alpha^{(\text{exp}, \text{mb})}$:
 - For each $s \in \Omega_{mb}$:

$$\alpha_s^{(\text{exp}, \text{mb})} \leftarrow \alpha_s^{(\text{exp}, \text{mb})} + \eta \left(\alpha_s^{(\text{obs}, \text{mb})} - \alpha_s^{(\text{exp}, \text{mb})} \right).$$

- Normalize $\alpha^{(\text{exp}, \text{mb})}$.

2. End For

5 Optional Quantum Interference Extension

In a strictly real-valued approach, amplitudes α_s are non-negative. A quantum-inspired algorithm can allow **complex amplitudes** with phases, enabling interference effects:

1. **Complex Representation:**

$$\alpha_s = r_s e^{i\theta_s},$$

where $r_s \geq 0$ and $\theta_s \in [0, 2\pi)$.

2. **Phase Updates:** Observed outcomes or suspected cyclical patterns can trigger phase shifts. For instance:

$$\theta_s \leftarrow \theta_s + \Delta\theta \quad (\text{constructive shift if } s \text{ aligns with observation}),$$

or

$$\theta_s \leftarrow \theta_s - \Delta\theta \quad (\text{destructive shift if } s \text{ conflicts with observation}).$$

Magnitudes are also updated to reflect empirical frequency. This method can highlight or suppress overlapping patterns via interference.

3. **Normalization:**

$$\sum_s |\alpha_s|^2 = 1$$

remains a strict requirement after each update step.

6 Use Cases and Benefits

- **Adaptive Forecasting:** The expected distribution adjusts gently over time, guided by the observed distribution, which tracks new data more directly.
- **Noise vs. Pattern Detection:** Persistent increases in observed amplitude for certain outcomes indicate recurring patterns, while sporadic occurrences fade due to exponential decay.
- **Quantum-Inspired Explorations:** Introducing phases allows the system to represent and potentially amplify loose or cyclic patterns that might not be captured well by purely real-valued probability models.

7 Conclusion

The described *Quantum-Inspired Observational–Expected Distribution Algorithm* maintains two amplitude distributions for each major set (**pb** or **mb**), reflecting both empirical outcomes and stable predictive expectations. The daily update cycle ensures alignment with real-world data while avoiding overfitting to single observations. Extensions with complex phases permit interference, a core quantum phenomenon that can further expose or harness subtle recurring structures in near-random processes.