

Tutorial sheet 3

1. Show that $\mathcal{O}(x^a) + \mathcal{O}(x^b) = \mathcal{O}(x^{\min(a,b)})$
 Hint: Around 0 we have $x^a = \mathcal{O}(x^b)$ for all $b \leq a$.

Write a MATLAB program for each of the following.

2. Using Gauss elimination, solve the system $Ax = b$, where A and b are given as

(a) $A = \begin{bmatrix} 1 & 2 & 3 \\ 3 & 1 & 2 \\ 2 & 3 & 1 \end{bmatrix}, b = \begin{bmatrix} 0 \\ 3 \\ 2 \end{bmatrix}$

(b) $A = \begin{bmatrix} 4 & 3 & 2 & 1 \\ 3 & 4 & 3 & 2 \\ 2 & 3 & 4 & 3 \\ 1 & 2 & 3 & 4 \end{bmatrix}, b = \begin{bmatrix} 1 \\ 1 \\ -1 \\ -1 \end{bmatrix}$

(c) $A = \begin{bmatrix} 0 & 1 \\ 2 & 3 \end{bmatrix}, b = \begin{bmatrix} 2 \\ 8 \end{bmatrix}$

(d) $A = \begin{bmatrix} 0.001 & 1 \\ 2 & 3 \end{bmatrix}, b = \begin{bmatrix} 2 \\ 8 \end{bmatrix}$

What do you observe in (c), (d)?

3. Consider the following system of equations:

$$0.729x + 0.81y + 0.9z = 0.6867$$

$$x + y + z = 0.8338$$

$$1.331x + 1.21y + 1.1z = 1$$

Solve using Gauss elimination method:

- (a) Without pivoting
 (b) With partial pivoting

Compare your result with the exact solution: $x = 0.2245, y = 0.2814, z = 0.3279$.

4. Using Gauss - Jordan, solve the system $Ax = b$, where A and b are given as in 1.

Algorithm for Gauss Elimination method for solving $Ax = b$

Step 1: Enter the coefficient matrix A and the vector b .

Step 2: Form the augmented matrix $C = [A \mid b]$.

Step 3: Check for existence of solution by checking rank of matrix A and augmented

matrix C . If a unique solution exists, go to step 4 otherwise Gauss elimination is not possible.

Without pivoting

Step 4a: Elimination: Apply row operations on the augmented matrix C so as to reduce the matrix A into an upper triangular matrix.

Let row and col be the number of rows and columns in A . if $C(i,i) \neq 0$

for $i = 1, 2, \dots, \text{col}-1$

for $j = i+1, i+2, \dots, \text{row}$

$\lambda = C(j,i)/C(i,i)$

$R_j \rightarrow R_j - \lambda R_i$

end

end

else Stop, Gauss Elimination is not applicable.

end

Step 5a: Use **back substitution** to obtain the final solution.

$x_n = \frac{C(n,n+1)}{C(n,n)}$

% Here row = col = n(say)

for $k = n-1, n-2, \dots, 1$

Define sum = 0

for $j = k+1, k+2, \dots, n$

sum = sum + $C(k,j) * x_j$

end

$x_k = \frac{1}{C(k,k)}(C(k,n+1) - \text{sum})$

end

With pivoting

Aim: To get the maximum element of the column i as the pivot element when working on column i

Step 4b: Partial pivoting and elimination:

for $i = 1, 2, \dots, \text{col}-1$

for $j = i+1, i+2, \dots, \text{row}$

if $|C(j,i)| \geq |C(i,i)|$

$R_j \leftrightarrow R_i$

end

if $C(i,i) \neq 0$

$\lambda = C(j,i)/C(i,i)$

$R_j \rightarrow R_j - \lambda R_i$

else Stop, Gauss elimination not applicable.

end

end

end

Step 5b: Back substitution Same as step 5a.

MATLAB commands needed

a) To add λ times row i to row j

$A(i,:) = A(j,:) + \lambda A(i,:)$

b) To interchange row i and row j

$$A([i, j], :) = A([j, i], :)$$

c) To interchange column i and column j

$$A(:, [i, j]) = A(:, [j, i])$$

or a three line code can be written

d) $\max(\text{abs}(A))$, where A is a $n \times n$ matrix.

e) return
