Stocastic

Ashan Jayamal

2024-08-02

# Contents

1	Premilaries					
	1.1	Brownian Motion	5			
	1.2	Definition of Brownian Motion	5			
	1.3	Simple Properties of Brownian Motion	6			
	1.4	Wiener Integral	6			
2	Introduction					
	2.1	Events and Probability	7			
	2.2	Random Variables	12			
	2.3	Conditional Probability and Independence	20			
3	Rar	ndom Walk to Brownier Motion.	<b>25</b>			
4	Cor	nditional Expectation	29			
	4.1	Conditioning on an Event	29			
	4.2	Conditioning on a Discrete Random Variable	32			
5	Les		37			
	5.1	Integrals	37			
	5.2	Random Walks	37			

4 CONTENTS

## Chapter 1

## **Premilaries**

**Definition 1.1.** Consider a set X. An  $\sigma$ -algebra  $\mathcal{F}$  of subsets of X is a collection  $\mathcal{F}$  of subsets of X satisfying the following conditions:

- $\emptyset \in \mathcal{F}$
- If  $B \in \mathcal{F}$ , then its complement  $B^c$  is also in F
- If  $B_1, B_2, \dots$  is a countable collection of sets in  $\mathcal{F}$ , then their union  $\bigcup_{n=1}^{\infty} B_n$  is also in  $\mathcal{F}$ .

#### 1.1 Brownian Motion

Let  $(\Omega, F, P)$  be a probability space. A stochastic process is a measurable function  $X(t, \omega)$  defined on the product space  $[0, \infty) \times \Omega$ . In particular:

- For each  $t, X(t, \cdot)$  is a random variable.
- For each  $\omega$ ,  $X(\cdot, \omega)$  is a measurable function (called a sample path).

For convenience, the random variable  $X(t,\cdot)$  will be written as X(t) or  $X_t$ . Thus, a stochastic process  $X(t,\omega)$  can also be expressed as  $X(t)(\omega)$  or simply as X(t) or  $X_t$ .

#### 1.2 Definition of Brownian Motion

**Definition 1.2.** A stochastic process  $B(t, \omega)$  is called a Brownian motion if it satisfies the following conditions:

1. 
$$P(\{\omega : B(0, \omega) = 0\}) = 1$$
.

2. For any  $0 \le s < t$ , the random variable B(t) - B(s) is normally distributed with mean 0 and variance t - s, i.e., for any a < b,

$$P(a \leq B(t) - B(s) \leq b) = \frac{1}{\sqrt{2\pi(t-s)}} \int_a^b e^{-x^2/2(t-s)} \, dx.$$

3.  $B(t,\omega)$  has independent increments, i.e., for any  $0 \le t_1 < t_2 < \ldots < t_n$ , the random variables

$$B(t_1), B(t_2) - B(t_1), \dots, B(t_n) - B(t_{n-1})$$

are independent.

4. Almost all sample paths of  $B(t,\omega)$  are continuous functions, i.e.,

$$P(\{\omega:B(\cdot,\omega)\text{ is continuous}\})=1$$

.

#### 1.3 Simple Properties of Brownian Motion

 $\mathrm{Let}B(t)$  be a fixed Brownian motion. We give below some simple properties that follow directly from the definition of Brownian motion.

**Proposition 1.1.** For any t > 0, B(t) is normally distributed with mean 0 and variance t. For any  $s, t \ge 0$ , we have  $\mathbb{E}[B(s)B(t)] = \min\{s, t\}$ .

Remark. Regarding Definition @ref(def:Brownian\_Motaion), it can be proved that condition (2) and  $E[B(s)B(t)] = min\{s, t\}$  imply condition (3).

*Proof.* By condition (1), we have B(t) = B(t) - B(0) and so the first assertion follows from condition (2). With out loss of generality, assume that s < t.

$$\mathbb{E}[B(s)B(t)] = \mathbb{E}[B(s)(B(t)-B(s)) + B(s)^2] = 0 + s = s$$

which is equal to  $\min\{s, t\}$ .

**Proposition 1.2** (Translation Invariance). For a fixed  $t_0 \ge 0$ , the stochastic process  $B(t) = B(t+t_0) - B(t_0)$  is also a Brownian motion.

**Proposition 1.3** (Scaling invariance). For any real number  $\lambda > 0$ , the stochastic process  $B(t) = \frac{B(\lambda t)}{\sqrt{\lambda}}$  is also a Brownian motion.

## 1.4 Wiener Integral

## Chapter 2

## Introduction

## 2.1 Events and Probability

**Definition 2.1.** Let  $\Omega$  be a non-empty set. A  $\sigma$ -field  $\mathcal{F}$  on  $\Omega$  is a family of subsets of  $\Omega$  such that:

- The empty set  $\emptyset$  belongs to  $\mathcal{F}$ ;
- If A belongs to  $\mathcal{F}$ , then so does the complement  $\Omega \setminus A$ ;
- If  $A_1,A_2,\dots$  is a sequence of sets in  $\mathcal{F}$ , then their union  $A_1\cup A_2\cup \dots$  also belongs to  $\mathcal{F}$ .

#### Example 2.1. a

**Definition 2.2.** Let  $\mathcal{F}$  be a  $\sigma$ -field on  $\Omega$ . A probability measure P is a function  $P: \mathcal{F} \to [0,1]$  such that

- 1.  $P(\Omega) = 1$ ;
- 2. if  $A_1,A_2,...$  are pairwise disjoint sets (that is,  $A_i\cap A_j=\emptyset$  for  $i\neq j)$  belonging to  $\mathcal F,$  then

$$P\left(\bigcup_{i=1}^{\infty}A_{i}\right)=\sum_{i=1}^{\infty}P(A_{i});$$

- The triple  $(\Omega, \mathcal{F}, P)$  is called a probability space.
- The sets belonging to  $\mathcal{F}$  are called events.
- An event A is said to occur almost surely (a.s.) whenever P(A) = 1.

Example 2.2. Let consider,

•  $\Omega = [0,1]$  with the

- $\sigma$ -field = $\mathcal{F} = \mathcal{B}([0,1])$  of Borel sets  $B \subseteq [0,1]$ , and
- Lebesgue measure P = Leb on [0, 1].

Then  $(\Omega, \mathcal{F}, P)$  is a probability space.

Recall that Leb is the unique measure defined on Borel sets such that

$$Leb[a, b] = b - a$$

for any interval [a, b]. (In fact, Leb can be extended to a larger  $\sigma$ -field, but we shall need Borel sets only.)

**Exercise 2.1.** Show that if  $A_1, A_2, ...$  is an expanding sequence of events, that is

$$A_1 \subseteq A_2 \subseteq A_3 \subseteq \cdots$$

then

$$P\left(\bigcup_{n=1}^{\infty}A_{n}\right)=\lim_{n\to\infty}P(A_{n}).$$

Similarly, if  $A_1, A_2, ...$  is a contracting sequence of events, that is,

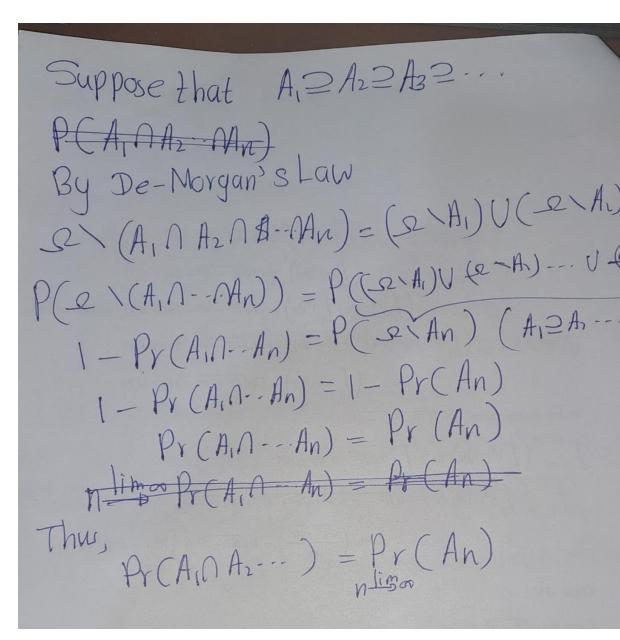
$$A_1 \supseteq A_2 \supseteq A_3 \supseteq \cdots$$

then

$$P\left(\bigcap_{n=1}^{\infty} A_n\right) = \lim_{n \to \infty} P(A_n).$$

**Hint:** Write  $A_1 \cup A_2 \cup \cdots$  as the union of a sequence of disjoint events: start with  $A_1$ , then add a disjoint set to obtain  $A_1 \cup A_2$ , then add a disjoint set again to obtain  $A_1 \cup A_2 \cup A_3$ , and so on. Now that you have a sequence of disjoint sets, you can use the definition of a probability measure. To deal with the product  $A_1 \cap A_2 \cap \cdots$ , write it as a union of some events with the aid of De Morgan's law.

Scippose that A., Az -- & is an expanding sequence of events. i.e.  $A_1 \subseteq A_2 \subseteq \cdots$ Now observe  $A_1 \cup A_2 \cup A_3 \cup \cdots = A_1 \cup (A_2 \setminus A_1) \cup (A_3 \setminus A_2) \cup \cdots = (*)$ Note that A, (Az A), (A3 Az). are pairwise disjoint. (Because this expanding sequince) Let Sn:= P(A1) + P(A2)A1) + -- + P(An) An-1) = Pr (A1 U(A2 \ A1) U (A3 \ A2) U (And) =Pr(A,UAzU-- An) =Pr(An) n-lim os Sn = nlim Pr(An) called Pr(A)+Pr(A)A)+···= nling or Pr(An) -P(AUA2U---) = P(A,U(A),A)U(A3),A)U...) = Enling Pr(An) (By ()

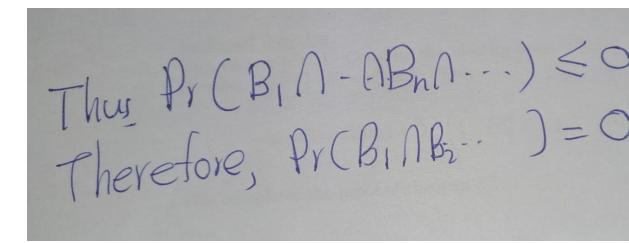


**Lemma 2.1** (Borei-Cantelli). Let  $A_1, A_2, ...$  be a sequence of events such that  $P(A_1) + P(A_2) + ... < \infty$  and let  $B_n = A_n \cup A_{n+1} \cup ...$  Then  $P(B_1 \cap B_2 \cap ...) = 0$ .

Exercise 2.2. Prove the Borel-Cantelli lemma above.

**Hint**:  $B_1, B_2, ...$  is a contracting sequence of events.

Let A., Az... be a sequice of events such that P(A)+P(Az)+--- 200 and let Bn:= An VAnti V... Observe that Bi= Bi=Bi. Using the previous result from exericine Pr(B1 AB2 A...) = n limal(Bn) = nlim & P(AnV An+1V-...) ∠ n limas P (An) + P(An+1)+--(sub addtive property) Given that EP(Ai) is con vergent. The P(A) + ENH Most ringht hand side part in equation (\*) is ofter called tail of series. If an isegt then tail of acg We know that tail of got series tend to Thus right hand side of equation



#### 2.2 Random Variables

**Definition 2.3.** If  $\mathcal{F}$  is a  $\sigma$ -field on  $\Omega$ , then a function  $X : \Omega \to \mathbb{R}$  is said to be  $\mathcal{F}$ -measurable if

$$\{\omega\in\Omega:X(\omega)\in B\}=X^{-1}(\omega)$$

for every Borel set  $B \in \mathcal{B}(\mathbb{R})$ .

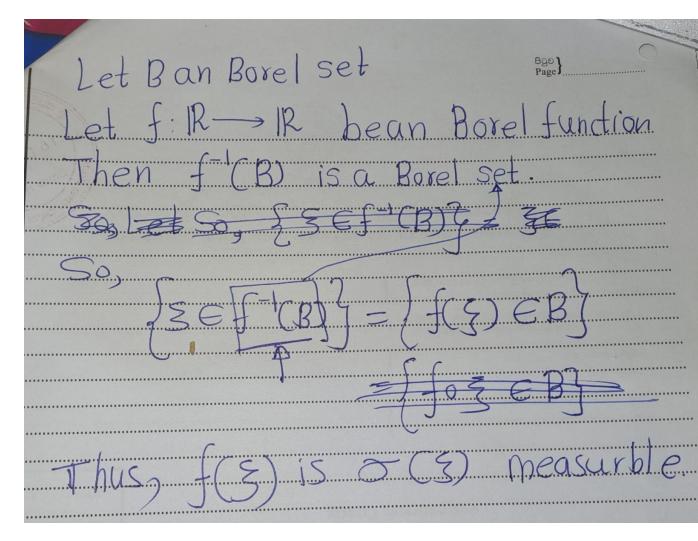
If  $(\Omega, \mathcal{F}, P)$  is a probability space, then such a function X is called a **random** variable.

**Definition 2.4.** The  $\sigma$ -field  $\sigma(X)$  generated by a random variable  $X:\Omega\to\mathbb{R}$  consists of all sets of the form  $\{\omega\in\Omega:X(\Omega)\in B\}$ , where B is a Borel set in  $\mathbb{R}$ .

**Definition 2.5.** The  $\sigma$ -field  $\sigma(\{X_i:i\in I\})$  generated by a family  $\{X_i:i\in I\}$  of random variables is defined to be the smallest  $\sigma$ -field containing all events of the form  $\{X_i\in B\}$ , where B is a Borel set in  $\mathbb R$  and  $i\in I$ .

**Exercise 2.3.** We call  $f : \mathbb{R} \to \mathbb{R}$  a **Borel function** if the inverse image  $f^{-1}(B)$  of any Borel set B in  $\mathbb{R}$  is a Borel set. Show that if f is a Borel function and X is a random variable, then the composition f(X) is  $\sigma(X)$ -measurable.

*Hint*: Consider the event  $\{f(X) \in B\}$ , where B is an arbitrary Borel set. Can this event be written as  $\{X \in A\}$  for some Borel set A?



**Lemma 2.2** (Doob-Dynkin). Let X be a random variable. Then each  $\sigma(X)$ -measurable random variable  $\eta$  can be written as

$$\eta = f(X)$$

for some Borel function  $f: \mathbb{R} \to \mathbb{R}$ .

Proof. Omiited  $\Box$ 

**Definition 2.6.** Every random variable  $X:\Omega\to\mathbb{R}$  gives rise to a probability measure

$$P_X(B) = P\{X \in B\}$$

on  $\mathbb{R}$  defined on the  $\sigma$ -field of Borel sets  $B \in \mathcal{B}(\mathbb{R})$ . We call  $P_X$  the distribution of X. The function  $F_X : \mathbb{R} \to [0,1]$  defined by

$$F_X(x) = P\{X \le x\}$$

is called the cumulative distribution function (CDF) of X.

**Exercise 2.4.** Show that the distribution function F is non-decreasing, right-continuous, and

$$\lim_{x \to -\infty} F_{\xi}(x) = 0, \quad \lim_{x \to +\infty} F_{\Xi}(x) = 1.$$

**Hint:** For example, to verify right-continuity show that  $F_{\xi}(x_n) \to F_{\xi}(x)$  for any decreasing sequence  $x_n$  such that  $x_n \to x$ . You may find the results of Exercises useful.

Non-decreasing

Let  $x,y \in \mathbb{R}$  such that x < y. Thus,  $\{3 \le x\} \subseteq \{3 \le y\}$  —  $\mathbb{C}$ - Recall from the measure therey.

Let (x, y, y) be an measure  $x \in \mathbb{C}$ If  $A, B \in \mathcal{P}$  and  $A \subseteq \mathcal{B}$  then  $A \in \mathcal{B}$ Thus,  $P(S \le x) \le P(S \le y)$   $F_S(x) \le F_S(y)$ .

Right Continuity

Let  $\{x_n\}_{n\in\mathbb{N}}$  be an electrosting sequence and  $x_n \to x$  as  $n\lim_{x\to\infty} \infty$ Since,  $\{x_n\}_n$  is decreasing sequence,  $x_1 > x_2 > \cdots$ Now observe that,  $\{x_n\}_n = \{x_n\}_n =$ 

Therefore F is right continuous.

First observe that

{\$<-1}={\$<-2}= {\$<-3}=...

Fruither \$= {\$<-1} \( \) {\$<-2} \( \) {\$<-3}...

$$\chi \lim_{n\to\infty} -\infty F_{s}(\chi) = n \lim_{n\to\infty} \infty F_{s}(\eta)$$

on 
$$\frac{\ln 50}{5} = (n)$$

First observe that
 $\{5 < 1\} \subseteq \{5 < -2\} \subseteq ---$ 
and  $\{5 < 1\} \cup \{5 < 2\} \cup --- = 0$ 
 $\frac{\ln 50}{5} = \frac{\ln 50}{5} = \frac{1}{5} = 0$ 
 $= \frac{1}{5} = \frac{1}{5} = 0$ 
 $= \frac{1}{5} = 0$ 
 $= \frac{1}{5} = 0$ 
 $= \frac{1}{5} = 0$ 

**Definition 2.7.** If there is a Borel function  $f: \mathbb{R} \to \mathbb{R}$  such that for any Borel set  $B \subset \mathbb{R}$ 

$$P\{\xi\in B\}=\int_B f_\xi(x)\,dx,$$

then  $\xi$  is said to be a random variable with absolutely continuous distribution and  $f_{\xi}$  is called the **density of**  $\xi$ . If there is a (finite or infinite) sequence of

pairwise distinct real numbers  $x_1, x_2, \dots$  such that for any Borel set  $B \subset \mathbb{R}$ 

$$P\{\xi\in B\}=\sum_{x_i\in B}P\{\xi=x_i\},$$

then  $\xi$  is said to have a discrete distribution with values  $x_1,x_2,\dots$  and mass  $P\{\xi=x_i\}$  at  $x_i.$ 

**Exercise 2.5.** Suppose that  $\xi$  has a continuous distribution with density f. Show that f is continuous at x.

**Hint:** Express F(x) as an integral of f.

Suppose that 
$$S$$
 has a continous distribution with density  $f_{\xi}$ .

$$F_{\xi}(\chi) = P(S < \chi) = \int_{S}^{\chi} f_{\xi}(y) \, dy.$$
Using the fundamental theorm of calcuss.

$$F_{\xi}(\chi) = f_{\xi}(\chi)$$

Show that if  $\xi$  has discrete distribution with values  $x_1, x_2, ...$ , then  $F_{\xi}$  is constant on each interval (s, t] not containing any of the x\_i's and has jumps of size P  $\{=x_i\}$  at each x\_i · Hint The increment Fe (t) - Fe (s) is equal to the total mass of the Xi's that belong to the interval [s, t).

Suppose that 
$$S$$
 has a continous distribution with density  $f_{\xi}$ .

$$F_{\xi}(\chi) = P(S < \chi) = \int_{S}^{\chi} f_{\xi}(y) dy.$$
Using the fundamental theorm of calcuss.

$$F(\chi) = f_{\xi}(\chi)$$

**Definition 2.8.** The **joint distribution** of several random variables  $\xi_1,\ldots,\xi_n$  is a probability measure  $P_{\xi_1,\ldots,\xi_n}$  on  $\mathbb{R}^n$  such that

$$P_{\xi_1,\dots,\xi_n}(B) = P\left\{\xi_1,\dots,\xi_n \in B\right\}$$

for any Borel set B in  $\mathbb{R}^n$ . If there is a Borel function  $f_{\xi_1,\dots,\xi_n}:\mathbb{R}^n\to\mathbb{R}$  such that

$$P\{(\xi_1,\ldots,\xi_n)\in B\}=\int_B f_{\xi_1,\ldots,\xi_n}(x_1,\ldots,x_n)\,dx_1\cdots dx_n$$

for any Borel set B in  $\mathbb{R}^n$ , then  $f_{\xi_1,\dots,\xi_n}$  is called the **joint density** of  $\xi_1,\dots,\xi_n$ .

**Definition 2.9.** A random variable  $\xi:\Omega\to\mathbb{R}$  is said to be **integrable** if

$$\int_{\Omega} |\xi|\,dP < \infty.$$

The integral

$$\mathbb{E}(\xi) = \int_{\Omega} \xi \, dP$$

exists and is called the expectation of  $\xi$ . The family of integrable random variables  $\xi:\Omega\to\mathbb{R}$  will be denoted by  $L^1$  or, in case of possible ambiguity, by  $L^1(\Omega,\mathcal{F},P)$ .

**Example 2.3.** The indicator function  $\mathbf{1}_A$  of a set A is equal to 1 on A and 0 on the complement  $\Omega \setminus A$  of A. i.e.:

$$1_A(a) := \begin{cases} 1 & \text{if } a \in A \\ 0 & \text{if } a \notin A \end{cases}$$

For any event A,

$$\mathbb{E}[1_A] = \int_{\Omega} 1_A dP = P(A)$$

we say that  $\eta:\Omega\to\mathbb{R}$  is a step function if

$$\eta = \sum_{i=1}^{n} \eta_i \mathbf{1}_{A_i},$$

where  $\eta_1, \dots, \eta_n$  are real numbers and  $A_1, \dots, A_n$  are pairwise disjoint events. Then,

$$\mathbb{E}[\eta] = \int_{\Omega} \eta dP = \sum_{i=1}^n \eta_i \int_{\Omega} 1_{A_i} dP = \sum_{i=1}^n \eta_i P(A_i)$$

**Exercise 2.6.** Show that for any Borel function  $h : \mathbb{R} \to \mathbb{R}$  such that h(X) is integrable,

$$\mathbb{E}(h(X)) = \int h(x) \, dP_X(x).$$

**Hint:** First verify the equality for step functions  $h: \mathbb{R} \to \mathbb{R}$ , then for nonnegative ones by approximating them by step functions, and finally for arbitrary Borel functions by splitting them into positive and negative parts

More to go ...

## 2.3 Conditional Probability and Independence

**Definition 2.10.** For any events  $A, B \in \mathcal{F}$  such that  $P(B) \neq 0$ , the conditional probability of A given B is defined by

$$P(A \mid B) = \frac{P(A \cap B)}{P(B)}$$

**Exercise 2.7.** Prove the **total probability formula** for any event  $A \in \mathcal{F}$  and any sequence of pairwise disjoint events  $B_1, B_2, ... \in \mathcal{F}$  such that  $B_1 \cup B_2 \cup \cdots = \emptyset$  and  $P(B_n) \neq 0$  for any n.

**Hint**:  $A = (A \cap B_1) \cup (A \cap B_2) \cup \cdots$ 

Let  $A \in \mathcal{F}$ . Let  $\{B_n\}_{n \in \mathbb{N}}$  be a sequence of pairswise disjoint events. With  $B_n \in \mathcal{F}$   $\forall n = 1, 2, ...$  such that  $B_1 \cup B_2 \cup ... = \mathcal{A}$  and  $P(B_n) \neq 0$ .

By de- of conditionally probability  $P(A \cap B_n) = P(A \cap B_n) \cdot P(B_n) \quad \forall n = 1,2,...$ 

Note that  $A = (A \cap B_1) \cup (A \cap B_2) \cup \cdots$   $P(A) = P((A \cap B_1) \cup (A \cap B_2) \cup (A \cap B_3) \cdots)$   $= P(A \cap B_1) + P(A \cap B_2) + P(A \cap B_3) + \cdots$ (cauntable add tive)  $= P(A \mid B_1) \cdot P(B_1) + P(A \mid B_2) \cdot P(B_3) + \cdots$ 

**Definition 2.11.** Two events  $A, B \in \mathcal{F}$  are called **independent** if

$$P(A \cap B) = P(A)P(B).$$

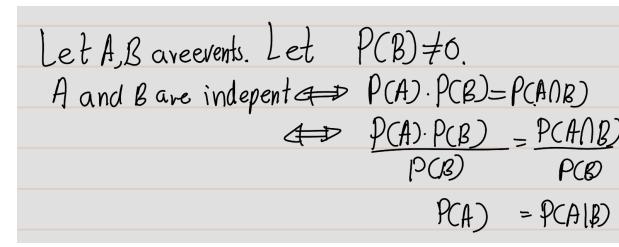
In general, we say that n events  $A_1, \ldots, A_n \in \mathcal{F}$  are **independent** if for any indices  $1 \le i_1 < i_2 < \cdots < i_k \le n$ ,

$$P(A_{i_1} \cap A_{i_2} \cap \dots \cap A_{i_k}) = P(A_{i_1})P(A_{i_2}) \dots P(A_{i_k}).$$

**Exercise 2.8.** Let  $P(B) \neq 0$ . Show that A and B are independent events if and only if

$$P(A \mid B) = P(A)$$
.

**Hint:** If  $P(B) \neq 0$ , then you can divide by it.



**Definition 2.12.** Two random variables  $\xi$  and  $\eta$  are called independent if for any Borel sets  $A, B \in \mathcal{B}(\mathbb{R})$ , the two events

$$\{\xi \in A\}$$
 and  $\{\eta \in B\}$ 

are independent.

We say that n random variables  $\xi_1,\ldots,\xi_n$  are independent if for any Borel sets  $B_1,\ldots,B_n\in\mathcal{B}(\mathbb{R})$ , the events

$$\{\xi_1 \in B_1\}, \{\xi_2 \in B_2\}, \dots, \{\xi_n \in B_n\}$$

are independent.

In general, a (finite or infinite) family of random variables is said to be independent if any finite number of random variables from this family are independent.

**Proposition 2.1.** If two integrable random variables  $\xi, \eta : \Omega \to \mathbb{R}$  are independent, then they are uncorrelated, i.e.,

$$E(\xi \eta) = E(\xi)E(\eta),$$

provided that the product  $\xi \eta$  is also integrable.

If  $\xi_1, \dots, \xi_n : \Omega \to \mathbb{R}$  are independent integrable random variables, then

$$E(\xi_1 \xi_2 \cdots \xi_n) = E(\xi_1) E(\xi_2) \cdots E(\xi_n),$$

provided that the product  $\xi_1 \xi_2 \cdots \xi_n$  is also integrable.

**Definition 2.13.** Two  $\sigma$ -fields  $\mathcal G$  and  $\mathcal H$  contained in  $\mathcal F$  are called independent if any two events

$$A \in \mathcal{G}$$
 and  $B \in \mathcal{H}$ 

are independent.

Similarly, any finite number of  $\sigma$ -fields  $\mathcal{G}_1, \dots, \mathcal{G}_n$  contained in  $\mathcal{F}$  are independent if any n events

$$A_1 \in \mathcal{G}_1, \dots, A_n \in \mathcal{G}_n$$

are independent.

In general, a (finite or infinite) family of  $\sigma$ -fields is said to be independent if any finite number of them are independent.

**Exercise 2.9.** Show that two random variables  $\xi$  and  $\eta$  are independent if and only if the  $\sigma$ -fields  $\sigma(\xi)$  and  $\sigma(\eta)$  generated by them are independent.

**Hint:** The events in  $\sigma(\xi)$  and  $\sigma(\eta)$  are of the form  $\{\xi \in A\}$  and  $\{\eta \in B\}$ , where A and B are Borel sets.

Let 
$$S$$
,  $N$  be an random varible. Let  $A$ ,  $B$  are Borel set in  $N$ . Further  $CS$ ) and  $CN$  have events are in the form  $\{E \in A\}$  and  $\{N \in B\}$ 

$$C(S) \text{ and } C(N) \Longrightarrow \{E \in A\} \text{ and } \{N \in B\}$$

$$\text{are independent} \qquad \text{are independent} \qquad \text{by } \text{def}_{D}^{n} \text{ (.14 in the book)}$$

$$S \text{ and } N \text{ care independent} \qquad \text{(by } \text{def}_{D}^{n} \text{ (.13 in )}$$

$$\text{book}$$

Sometimes it is convenient to talk of independence for a combination of random variables and  $\sigma$ -fields.

**Definition 2.14.** We say that a random variable  $\xi$  is independent of a  $\sigma$ -field  $\mathcal{G}$  if the  $\sigma$ -fields

$$\sigma(\xi)$$
 and  $\mathcal{G}$ 

are independent. This can be extended to any (finite or infinite) family consisting of random variables or  $\sigma$ -fields or a combination of them both. Namely,

such a family is called independent if for any finite number of random variables  $\xi_1,\ldots,\xi_m$  and  $\sigma$ -fields  $\mathcal{G}_1,\ldots,\mathcal{G}_n$  from this family, the  $\sigma$ -fields

$$\sigma(\xi_1),...,\sigma(\xi_m),\mathcal{G}_1,..,\mathcal{G}_n$$

are independent.

## Chapter 3

# Random Walk to Brownier Motion.

Slandered approach model stochastic dynamic in discrete time.

Let  $\eta_i$  be an random variable on a comman probability space. We often  $\Omega, \mathcal{F}, P$  assume that i.i.d. This case  $\eta_i$  is called white noise, otherwise coloured noise. Now we have definite dynamics. It will be given as discreate time dynamical systems recursively by some non linear function. We define,

$$X_{n+1} = X_n + \phi_{n+1}(X_n, \eta_{n+1}) \quad n = 0, 1, 2, \dots \tag{3.1}$$

where  $\phi_n: \mathbb{R}^d \times \mathbb{R}^d \to \mathbb{R}^d$  are measurable. Further, if  $X_0$  and  $\eta_0$  are all independent then  $X_n$  is called **Markov Chain**.

Now let  $\eta_i$  be i.i.d and defined a random walk

$$S_n := \sum_{i=1}^n \eta_i \tag{3.2}$$

$$S_{(n+1)} := S_n + \eta_{(n+1)} \tag{3.3}$$

We can rewrite (3.1) as

$$X_{n+1} - X_n = \phi_{n+1}(X_n, S_{n+1} - S_n)$$
  $n = 0, 1, ...$ 

This equation is called Stochastic difference equations.

AIM: Develop a continuous time analogous.

Question What to use an continuous time replacement of the random walks?

**Definition 3.1.** Let I be index set  $(I = \mathbb{N} \text{ or } I = \mathbb{R}^+)$ . A collection of random varibels  $(X_t)_{i \in I}$  on  $(\Omega, \mathcal{F}, P)$  is called staocastic process.

We need I to be a just totally ordered set for convention of time. If it is not an totally ordered set it is not a stochastic process but a random field.

Now we need a notation of a filtration.

**Definition 3.2.** Le  $\mathcal{F}_t$  be non-decreasing sequence of sub sigma algebra of  $\mathcal{F}$  (i.e.  $\mathcal{F}_s \subseteq \mathcal{F}_t$  for all  $s \geq t, s, t \in I$ ), then  $(\mathcal{F}_t)_{t \in I}$  is called a filtration.

Last we need the notation adaptness.

**Definition 3.3.** A stocticstic process  $X_t$  is called adapted to filteration  $(\mathcal{F}_t)_t$  if  $X_t \in \mathcal{F}_t$ . i.e.  $X_t$  is measurable

**Theorem 3.1** (Central Limit Theorem). Let  $Y_{n_i}:\Omega\to\mathbb{R}^d$  (be collection of random varibles),  $1\leq i\leq n<\infty$  be identical distributed and square intergable random variable on  $(\Omega,\mathcal{F},P)$  such that  $Y_{n_1},Y_{n_2},...,Y_{n_n}$  are independent for all  $n\in\mathbb{N}$ . Then

$$\left(\frac{1}{\sqrt{n}}\sum_{i=1}^n Y_{n_i} - \mathbb{E}[Y_i]\right) \xrightarrow{\mathcal{D}} N(0,C) \ as \ n \to \infty$$

, where N(0,C) is multivarible normal distribution with covarice matrix

$$Y_{k,l} = Cov[Y_{n_i}^{(k)} - Y_{n_i}^{(l)}]$$

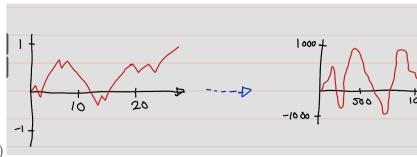
 $and \xrightarrow{\mathcal{D}} means$  "distribution is convergent" to "'

Proof. Omitted 
$$\Box$$

We consider the random walk

$$S_n = \sum_{i=1}^n \eta_i$$

with  $\eta_i \in L^2(\Omega, \mathcal{F}, P)$  and normalized. (i.e.  $\mathbb{E}[\eta_i] = 0, Var[\eta_i] = 1$ )



Plotting (Linear Interpolation)

This gives an idea about the existence of a scaling limit. Now a question might be rising.

Question: What is right rescaling?

That is we try to define a rescaled random walk  $S^m_t$ (Here superscipt m is for mesh size),  $(t=0,\frac{1}{m},\frac{2}{m},cdots)$  with step-size  $\frac{1}{m}$ 

$$S_{\frac{k}{m}}^{(m)}=c_mS_k$$

Here  $herec_m$  is rescaling constant. It is difficulit to correct  $c_m$ , because unless it decay so fast at the end you convert to zero or blow up whole thing and goes to infinity.

For  $t = \frac{k}{m}$  we have

$$Var[S_t^{(m)}] = c_m^2$$

## Chapter 4

## Conditional Expectation

#### 4.1 Conditioning on an Event

The first and simplest case to consider is that of the conditional expectation  $\mathbf{E}(\xi|B)$  of a random variable  $\xi$  given an event B.

**Definition 4.1.** For any integrable random variable  $\xi$  and any event  $B \in \mathcal{F}$  such that  $P(B) \neq 0$ , the conditional expectation of  $\xi$  given B is defined by

$$E(\xi\mid B) = \frac{1}{P(B)} \int_{B} \xi\, dP.$$

**Example 4.1.** Three coins, 10p, 20p, and 50p are tossed. The values of those coins that land heads up are added to work out the total amount  $\xi$ . What is the expected total amount  $\xi$  given that two coins have landed heads up?

Let B be the event two coins landed two I.e. B:= { HHT, HTH, THHY (H-head T-Need to calculate [ (31B). Furthur 3 (HHT) = 10+20=30 {(HTH) = 10+50 = 60 § (THH) = 20+58=70 Then by above defb

$$E(3|B) = \frac{1}{P(x)} \int_{B} \int dP.$$

$$= \frac{1}{(3/8)} \left( \frac{30}{8} + \frac{60}{8} + \frac{70}{8} \right)$$
$$= \frac{160}{3} /$$

31

**Exercise 4.1.** Show that  $E(\xi \mid D) = E(\xi)$ .

**Hint**: The definition of  $E(\xi)$  involves an integral and so does the definition of  $E(\xi \mid D)$ . How are these integrals related?

$$E(3|\Omega) = \frac{1}{P(\Omega)} (3dP) = E(3)$$
Note that  $P(\Omega) = 1$  and  $\int_{a} 3dP = E(3) (def^{n} 1.9)$ 

Exercise 4.2. Show that if

$$\mathbf{1}_A(\omega) = \begin{cases} 1 & \text{for } \omega \in A \\ 0 & \text{for } \omega \not\in A \end{cases}$$

(the indicator function of A), then

$$E(\mathbf{1}_A \mid B) = P(A \mid B),$$

where

$$P(A \mid B) = \frac{P(A \cap B)}{P(B)}$$

is the conditional probability of A given B.

**Hint**: Write  $\int_B \mathbf{1}_A dP$  as  $P(A \cap B)$ .

$$t(|A|B) = \int_{P(B)} \int_{B} |A| dP$$

$$= \int_{P(B)} \int_{A \cap B} |A| dP$$

# 4.2 Conditioning on a Discrete Random Variable

The next step towards the general definition of conditional expectation involves conditioning by a discrete random variable  $\eta$  with possible values  $y_1, y_2, ...$  such that  $P\{\eta=y_n\}\neq 0$  for each n. Finding out the value of  $\eta$  amounts to finding out which of the events  $\{\eta=y_n\}$  has occurred or not. Conditioning by  $\eta$  should therefore be the same as conditioning by the events  $\{\eta=y_n\}$ . Because we do not know in advance which of these events will occur, we need to consider all possibilities, involving a sequence of conditional expectations

$$E(\xi \mid \{\eta = y_1\}), E(\xi \mid \{\eta = y_2\}), \dots$$

A convenient way of doing this is to construct a new discrete random variable constant and equal to  $E(\xi \mid \{\eta = y_n\})$  on each of the sets  $\{\eta = y_n\}$ . This leads us to the next definition.

**Definition 4.2.** Let  $\xi$  be an integrable random variable and let  $\eta$  be a discrete random variable as above. Then the conditional expectation of  $\xi$  given  $\eta$  is

defined to be a random variable  $E(\xi \mid \eta)$  such that

$$E(\xi \mid \eta)(\omega) = E(\xi \mid \{\eta = y_n\})$$
 if  $\eta(\omega) = y_n$ 

for any  $n = 1, 2, \dots$ 

**Example 4.2.** Three coins, 10p, 20p, and 50p are tossed as in Example 4.1. What is the conditional expectation  $E(\xi \mid \eta)$  of the total amount  $\xi$  shown by the three coins given the total amount  $\eta$  shown by the 10p and 20p coins only?

First observe that n is discreate random varible.  All the possible values for n is 0,10,20 and 30.								
	n	10p >= 0 >= 1	20p   0 - 1 - 1 -	→ 0 → 10 → 20 → 30				
All possible events. <u>50p</u> 20p 10p n E								
50p	209	10p	n	٤				
He	He	H	30	රිර				
Н	H	T	20	70				
H	The	H	10	60				
Н	T	T	٥	50				
TIM	H	H	30	30				
T	H	T	20	20				
T	T	Н	10	10				
T	T	Т	0	O				

$$E(3|\{\eta=0\}) = \frac{1}{P(\{\eta=0\})} \int_{\{\eta=0\}}^{16} \frac{d\varphi}{\eta^{-2}} d\varphi$$

$$= \frac{1}{(2/8)} \left[0 + \frac{50}{8}\right] = 25$$

$$E(3|\{\eta=10\}) = \frac{1}{P(\{\eta=10\})} \int_{\{\eta=10\}}^{3} \frac{d\varphi}{\eta^{-2}} d\varphi$$

$$= \frac{1}{(2/8)} \left[\frac{60}{8} + \frac{10}{8}\right] = 35$$

$$E(3|\{\eta=20\}) = \frac{1}{P(\{\eta=20\})} \int_{\{\eta=20\}}^{3} \frac{d\varphi}{\eta^{-2}} d\varphi$$

$$= \frac{1}{(2/8)} \left(\frac{70}{8} + \frac{20}{8}\right) = 45$$

$$E(3|\{\eta=20\}) = \frac{1}{P(\{\eta=30\})} \int_{\{\eta=30\}}^{3} \frac{d\varphi}{\eta^{-2}} d\varphi$$

$$= \frac{1}{(2/8)} \left[\frac{30}{8} + \frac{30}{8}\right] = 55$$

Therefore,
$$\begin{aligned}
&\text{Therefore,} \\
&\text{E(S|n)(w):=} \\
&\text{So if } n(w) = 0 \\
&\text{45 if } n(w) = 20 \\
&\text{55 if } n(w) = 30.
\end{aligned}$$

## Chapter 5

## Les

### 5.1 Integrals

First we review the definitions of the Riemann integral in calculus and the Riemann–Stieltjes integral in advanced calculus.

#### 5.1.1 Riemann Integral

Let f be an bounded function defined on a finite closed interval [a, b]. Then f is called *Riemann integrable* if the following limit exists.

$$x (5.1)$$

#### 5.2 Random Walks

Consider a random walk starting at 0 with jumps h and -h equally likely at times  $\delta, 2\delta, ...$ , where  $h, \delta > 0$ . More precisely, let  $\{X_n\}_{n=1}^\infty$  be a sequence of independent and identically distributed random variables with

$$P(X_j=h)=P(X_j=-h)=\frac{1}{2}$$

Let  $Y_{\delta,h}(0) = 0$ 

$$Y_{\delta,h}(n\delta) = X_1 + X_2 + \ldots + X_n$$

For t > 0 define  $Y_{\delta,h}(t)$  by linearization: (i.e. For  $n\delta < t < (n+1)\delta$ , define

$$Y_{\delta,h}(t) = \frac{(n+1)\delta - t}{\delta} Y_{\delta,h}(n\delta) + \frac{t - n\delta}{\delta} Y_{\delta,h}((n+1)\delta).$$