Ashar Alam

EDUCATION

STANFORD UNIVERSITY

MS IN MECHANICAL ENGINEERING March 2020 | Stanford, CA

KAIST

BS IN MECHANICAL ENGINEERING August 2018 | Daejeon, South Korea College of Engineering Magna Cum Laude

GIIS QUEENSTOWN

Grad. May 2014 Queenstown, Singapore

COURSEWORK

GRADUATE

- Smart Product Design (ME218)
- Principles of Robotic Autonomy
- Computer Organizations and Systems
- Vehicle Dynamics and Controls
- Introduction to Robotics Introduction to Control Design Techniques
- Introduction to Linear Dynamical Systems* • Decision Making Under Uncertainty* • Robot Perception and Decision Making*

*(Courses to be done in Fall' 2019)

UNDERGRADUATE

 Modelling and Control of Engineering Systems
Mechatronics
Applied Electronics

SKILLS

PROGRAMMING

- C C++ Python HTML/CSS
- ROS MATLAB/Simulink Docker
- Assembly Unix Tools and Scripting
- CARLA Unreal Engine Blender

ELECTRICAL

- CAD Altium Designer
- Equipment Oscilloscope, Saleae Logic Analyzer, DMM, Function Generator, Soldering

MECHANICAL

- CAD SOLIDWORKS, AutoCAD
- CAE ANSYS, OpenFOAM
- Manufacturing/Prototyping -Conventional Workshop machines, Laser cutting, FDM/SLA 3D Printing, Clean Room, Photolithography

PROFESSIONAL AND TECHNICAL EXPERIENCE

LUCID MOTORS | AUTONOMOUS DRIVING SOFTWARE INTERN Jun 2019 - Sep 2019 | Newark, CA

- Tested control algorithms on multiple driving simulation platforms using C++ and Python for validating controller design for ADAS and AD scenarios
- Developed middleware interface between simulation softwares and controller architecture
- Customized simulation software environment for validating and testing vehicle dynamics and autonomous driving control algorithms
- Implemented controller architectures for Autonomous Driving on Highways

SMART PRODUCT DESIGN | Mechatronics - ME218

Sep 2018 - Jun 2019 | Stanford university | Prof. Ed Carryer

- Built intelligent electro-mechanical systems and embedded hardware and software with experience in:
 - Efficient event-driven software design using state machines
 - Use of SPI, I2C and UART for inter-process communication
 - Circuit design for range detectors, photodiodes/photoresistors, accelerometers, motor drivers, voltage regulators, DC, Stepper Servo motors
 - Use of equipment such as oscilloscopes, logic analyzers, DMMs etc.
- Built an arcade game, an autonomous ball collecting robot and a remote controlled hovercraft (using XBee for RC communication) with event-driven code in C on a TI (ARM 32-bit) microcontroller and assembly code on a PIC

AUTONOMOUS DRIVING - SIMULATION & EXPERIMENT | ME227

Apr 2019 - Jun 2019 | Stanford university | Prof. Chris Gerdes

- Generated a velocity and acceleration profile, and calculated lateral forces based on vehicle modelling to traverse an oval path in a given time
- Designed and calculated gains for a Lookahead controller and LQR controller with feedback to adhere to generated profiles
- Simulated controller performances in MATLAB and implemented the aforementioned controllers on a Golf GTI which drove itself autonomously around its designated oval path in a parking lot

AUTONOMOUS DRIVING WITH A TURTLEBOT | AA274

Jan 2019 - Mar 2019 | Stanford university | Prof. marco Pavone

- Developed a ROS package for a TurtleBot3 Burger to autonomously explore a mock environment where it needed to "pick up and deliver" food items
- Used a costmap overlay and a modified Djikstra algorithm over a map generated by EKF-SLAM package to find the closest unexplored part of the map
- Implemented algorithms in Python to develop the autonomy stack including modules for perception, localization, motion planning and controls

RESEARCH

FLOW CONTROL LAB | UNDERGRADUATE RESEARCHER

Jun 2017 - Dec 2017 | Daejeon, South Korea

- Worked with Dr. Ghulam Destgeer and Prof Hyung Jin Sung to characterize
 Microchannel Anechoic Corner, a region within a microfluidic channel in which
 Surface Acoustic Waves fail to excite microparticles^[1]
- [1] G. Destgeer, A. Alam, H. Ahmed, J. Park, J. H. Jung, K. Park, and H. J. Sung. Characterization of microchannel anechoic corners formed by surface acoustic waves. *Applied Physics Letters, Volume* 112, *Issue* 8, February 2018.