

Machine Learning End Term Exam

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Question 2

To derive the solution to the modified linear regression leads to the generalized form of ridge regression.

Solution:-

Given the attribute $x_i = \hat{x}_i + \epsilon_i$, where the \hat{x}_i are the true measurements and ϵ_i is the zero mean vector with covariance matrix $\sigma^2 I$
Modified loss function

$$W^* = \underset{W}{\operatorname{argmin}} E_{\epsilon} \sum_{i=1}^n (y_i - W^T (\hat{x}_i + \epsilon_i))^2$$

Where W is the transformation vector.

$$W^* = \underset{W}{\operatorname{argmin}} E_{\epsilon} \|Y - (X + \epsilon)W\|_2^2 \quad (1)$$

Where

$$Y = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{bmatrix}$$

$$X = \begin{bmatrix} \hat{x}_1^T \\ \hat{x}_2^T \\ \vdots \\ \hat{x}_n^T \end{bmatrix}$$

$$\epsilon = \begin{bmatrix} \epsilon_1^T \\ \epsilon_2^T \\ \vdots \\ \epsilon_n^T \end{bmatrix}$$

Expanding right hand side of equation 1.

$$\begin{aligned} E_\epsilon \|Y - (X + \epsilon)W\|_2^2 &= E_\epsilon \left[(Y - (X + \epsilon)W)^T (Y - (X + \epsilon)W) \right] \\ &= E_\epsilon \left[Y^T Y + W^T (X + \epsilon)^T (X + \epsilon) W - 2W^T (X + \epsilon)^T Y \right] \end{aligned} \quad (2)$$

To minimize the equation we will differentiate eq 2 wrt W.

$$\frac{\partial E_\epsilon \left[Y^T Y + W^T (X + \epsilon)^T (X + \epsilon) W - 2W^T (X + \epsilon)^T Y \right]}{\partial W} = 0$$

We know that $\frac{\partial E(f(x))}{\partial} = E \frac{\partial f(x)}{\partial x}$.

$$E_\epsilon \left[\frac{\partial Y^T Y}{\partial W} + \frac{\partial W^T (X + \epsilon)^T (X + \epsilon) W}{\partial W} - 2 \frac{\partial W^T (X + \epsilon)^T Y}{\partial W} \right] = 0$$

$$E_\epsilon [2(X + \epsilon)^T (X + \epsilon) W - 2(X + \epsilon)^T Y] = 0$$

$$2E_\epsilon [(X + \epsilon)^T (X + \epsilon) W] - 2E_\epsilon [(X + \epsilon)^T Y] = 0$$

$$E_\epsilon [(X^T X + \epsilon^T \epsilon + 2\epsilon^T X) W] = E_\epsilon [(X + \epsilon)^T Y]$$

$$E_\epsilon (X^T X W) + E_\epsilon (\epsilon^T \epsilon W) + 2E_\epsilon (\epsilon^T X W) = E_\epsilon (X^T Y) + E_\epsilon (\epsilon^T Y)$$

We know that $E(AB) = E(A)E(B)$ if A and B are independent variables and $E_f(h(x)) = \int_{-\infty}^{\infty} h(x)f(x)dx$.

$$\sum_{i=1}^n X^T X W P(\epsilon_i) + E_\epsilon (\epsilon \epsilon^T) E_\epsilon (W) + 2E_\epsilon (X) E_\epsilon (\epsilon) = \sum_{i=1}^n X^T Y P(\epsilon_i) + E_\epsilon (Y) E_\epsilon (\epsilon)$$

We know that the noise is a zero mean Gaussian noise therefore $E(\epsilon) = 0$

$$(X^T X + \sigma^2 I) W = X^T Y$$

$$W = (X^T X + \sigma^2 I)^{-1} X^T Y$$

therefore the solution of the minimization is

$$W^* = (X^T X + \sigma^2 I)^{-1} X^T Y$$

This solution is same as the solution for Ridge regression

$$W^* = (X^T X + \lambda I)^{-1} X^T Y$$

Question 5

Let $\vec{x}_1, \vec{x}_2, \dots, \vec{x}_n$ be the feature vectors of n data points in the original feature space. Let ϕ be the feature transformation function. Then, $\phi(\vec{x}_1), \phi(\vec{x}_2), \dots, \phi(\vec{x}_n)$ are the feature vectors in the transformed feature space.

Let K be the kernel function such that:

$$K(i, j) = \phi(x_i)^T \phi(x_j)$$

The center of mass, $\vec{\mu}$, in the feature space can be defined as the average of the vectors in the transformed feature space.

$$\vec{\mu} = \frac{1}{n} \sum_{i=1}^n \phi(\vec{x}_i)$$

Consider:

$$\begin{aligned} \|\mu\|^2 &= \mu^T \mu \\ &= \mu^T \frac{1}{n} \sum_{i=1}^n \phi(\vec{x}_i) \\ &= \frac{1}{n} \sum_{j=1}^n \phi(\vec{x}_j)^T \frac{1}{n} \sum_{i=1}^n \phi(\vec{x}_i) \\ &= \frac{1}{n^2} \sum_{i,j} \phi(\vec{x}_j)^T \phi(\vec{x}_i) \\ &= \frac{1}{n^2} \sum_{i,j} K(i, j) \end{aligned}$$

Average of the squared Euclidean distances from μ to each $\phi(x)$

The squared euclidean distance of a single feature vector in the transformed space from the center of mass $\vec{\mu}$ can be expressed as follows:

$$\begin{aligned} \|\phi(\vec{x}_i) - \vec{\mu}\|^2 &= (\phi(\vec{x}_i) - \vec{\mu})^T (\phi(\vec{x}_i) - \vec{\mu}) \\ &= \phi(\vec{x}_i)^T \phi(\vec{x}_i) - 2\phi(\vec{x}_i)^T \vec{\mu} + \|\vec{\mu}\|^2 \\ &= K(i, i) - \frac{2}{n} \phi(\vec{x}_i)^T \sum_{j=1}^n \phi(\vec{x}_j) + \|\vec{\mu}\|^2 \\ &= K(i, i) - \frac{2}{n} \sum_{j=1}^n \phi(\vec{x}_i)^T \phi(\vec{x}_j) + \|\vec{\mu}\|^2 \\ &= K(i, i) - \frac{2}{n} \sum_{j=1}^n K(i, j) + \frac{1}{n^2} \sum_{r,s} K(r, s) \end{aligned}$$

The average of the euclidean distances of all the points from the center of mass can be written as:

$$\begin{aligned}
\frac{1}{n} \sum_{i=1}^n \|\phi(\vec{x}_i) - \vec{\mu}\|^2 &= \frac{1}{n} \left(\sum_{i=1}^n \left(K(i, i) - \frac{2}{n} \sum_{j=1}^n K(i, j) + \frac{1}{n^2} \sum_{r,s} K(r, s) \right) \right) \\
&= \frac{1}{n} \left(\sum_{i=1}^n K(i, i) - \frac{2}{n} \sum_{i,j} K(i, j) + \frac{n}{n^2} \sum_{r,s} K(r, s) \right) \\
&= \frac{1}{n} \left(\sum_{i=1}^n K(i, i) - \frac{1}{n} \sum_{i,j} K(i, j) \right)
\end{aligned}$$

Thus, the average of euclidean distances from the center of mass $\vec{\mu}$ to each $\phi(x)$ can be expressed in terms of the kernel function K .