

Classical Black Holes

10. Viscous Torques

Edward Larrañaga

Outline for Part 1

- 1. Viscous Torques
 - 1.1 Differential Rotation
 - 1.2 Radial Structure Evolution
 - 1.3 The α -Prescription for Viscosity

2. Novikov-Thorne Thin Disk

Viscous Torques

Accretion Disk

• If the only interaction between fluid elements is gravity, the angular momentum is conserved.

Accretion Disk

- If the only interaction between fluid elements is gravity, the angular momentum is conserved.
- In the description of the accretion disk it is needed a force responsible for the redistribution of angular momentum.

Keplerian Velocity

$$\Omega = \Omega(r)$$

Keplerian Velocity

$$\Omega = \Omega(r)$$

Neighboring material at different radii moves with different velocity

Keplerian Velocity

$$\Omega = \Omega(r)$$

- Neighboring material at different radii moves with different velocity
- The disk is not a solid body. It moves with differential rotation.

Keplerian Velocity

$$\Omega = \Omega(r)$$

- Neighboring material at different radii moves with different velocity
- The disk is not a solid body. It moves with differential rotation.
- The thermal motion of the fluid molecules and the turbulent motion of the fluid produce viscous stresses.

 In our simple description we will consider only momentum transport in the radial direction, produced by the process known as shear viscosity.

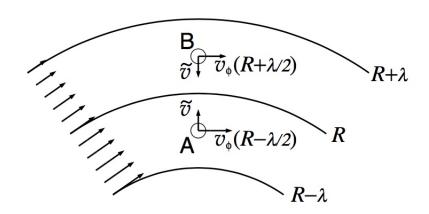
- In our simple description we will consider only momentum transport in the radial direction, produced by the process known as shear viscosity.
- It appears when there are internal distortions (usually local stresses that are proportional to the local rate of strain)

- In our simple description we will consider only momentum transport in the radial direction, produced by the process known as shear viscosity.
- It appears when there are internal distortions (usually local stresses that are proportional to the local rate of strain)
- Although the following is the simplest description, it can be used to describe other mechanisms of angular momentum transport such as magnetic loops that couple fluid elements at macroscopic distances across the disk.

• λ: Typical scale in the accretion disk

- λ: Typical scale in the accretion disk
- \tilde{v} : typical speed in the accretion disk

- λ: Typical scale in the accretion disk
- \tilde{v} : typical speed in the accretion disk
- As a first model, consider a uniform gas moving only in the tangential direction woth velocity $v_{\phi}(r)$.



The only non-vanishing component of the stress tensor is the ϕ -component of the force per unit surface of the r =constant surface,

$$\sigma_{r\phi} = -\eta \left. \frac{\partial \mathsf{v}_{\phi}}{\partial r} \right|_{R}$$

The only non-vanishing component of the stress tensor is the ϕ -component of the force per unit surface of the r =constant surface,

$$\sigma_{r\phi} = -\eta \left. \frac{\partial \mathsf{V}_{\phi}}{\partial r} \right|_{R}$$

 η : dynamical viscosity

$$v_{\phi}(r) = \Omega(r)r$$

 $\frac{\partial v_{\phi}}{\partial r}$: velocity gradient

$$\sigma_{r\phi} = -\eta R \left. \frac{\partial \Omega}{\partial r} \right|_{R}$$

 ϕ -component of the force per unit surface of the r =constant surface.

$$\sigma_{r\phi} = -\eta R \left. \frac{\partial \Omega}{\partial r} \right|_{R}$$

 ϕ -component of the force per unit surface of the r =constant surface. The dynamical viscosity is usually written in terms of the kinematical viscosity, ν , as $\eta = \rho \nu$

$$\sigma_{r\phi} = -\rho \nu R \left. \frac{\partial \Omega}{\partial r} \right|_{R}$$

 ϕ -component of the force per unit surface of the r =constant surface.

$$\sigma_{r\phi} = -\rho \nu R \left. \frac{\partial \Omega}{\partial r} \right|_{R}$$

 ϕ -component of the force per unit surface of the r =constant surface.

The net torque $(\vec{R} \times \vec{F})$ is calculated by multiplying $\sigma_{r\phi}$ by the area of the r = R =constant surface, $2\pi RH$.

$$\sigma_{r\phi} = -\rho \nu R \left. \frac{\partial \Omega}{\partial r} \right|_{R}$$

 ϕ -component of the force per unit surface of the r =constant surface.

The net torque $(\vec{R} \times \vec{F})$ is calculated by multiplying $\sigma_{r\phi}$ by the area of the r = R =constant surface, $2\pi RH$.

H: Height of the disk

Net torque on the outer ring due to the inner one .

Net torque on the outer ring due to the inner one .

Torque =
$$R \times 2\pi RH \times \sigma_{r\phi}$$

Net torque on the outer ring due to the inner one.

Torque
$$= R \times 2\pi RH \times \sigma_{r\phi}$$

Torque =
$$-2\pi R^3 H \rho v \left. \frac{\partial \Omega}{\partial r} \right|_{R}$$

Using the surface mass density,

Using the surface mass density,

$$\Sigma = \int_0^H \rho(r) dz = \rho H$$

Using the surface mass density,

$$\Sigma = \int_0^H \rho(r) dz = \rho H$$

Torque
$$= -2\pi R^3 \Sigma \nu \left. \frac{\partial \Omega}{\partial r} \right|_{R}$$

$$G(r) = 2\pi r^3 \Sigma \nu \frac{\partial \Omega}{\partial r}$$

• If
$$\frac{\partial \Omega}{\partial r} = 0$$

$$G(r) = 2\pi r^3 \Sigma \nu \frac{\partial \Omega}{\partial r}$$

- If $\frac{\partial \Omega}{\partial r} = 0$
 - → Rigid body rotation

$$G(r) = 2\pi r^3 \Sigma \nu \frac{\partial \Omega}{\partial r}$$

- If $\frac{\partial \Omega}{\partial r} = 0$
 - → Rigid body rotation
 - → No torque

$$G(r) = 2\pi r^3 \Sigma \nu \frac{\partial \Omega}{\partial r}$$

- If $\frac{\partial \Omega}{\partial r} = 0$
 - → Rigid body rotation
 - → No torque
- If $\Omega(r)$ decreases outwards, $\frac{\partial \Omega}{\partial r} < 0$,

$$G(r) = 2\pi r^3 \Sigma \nu \frac{\partial \Omega}{\partial r}$$

- If $\frac{\partial \Omega}{\partial r} = 0$
 - → Rigid body rotation
 - → No torque
- If $\Omega(r)$ decreases outwards, $\frac{\partial \Omega}{\partial r} < 0$,

$$\rightarrow G(r) < 0$$

We define the torque on the inner ring by the outer one at the coordinate *r* as the function,

$$G(r) = 2\pi r^3 \Sigma \nu \frac{\partial \Omega}{\partial r}$$

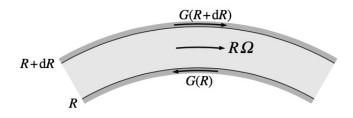
- If $\frac{\partial \Omega}{\partial r} = 0$
 - → Rigid body rotation
 - → No torque
- If $\Omega(r)$ decreases outwards, $\frac{\partial \Omega}{\partial r} < 0$,
 - $\rightarrow G(r) < 0$
 - → angular momentum goes from inner circles to outer circles.

We define the torque on the inner ring by the outer one at the coordinate *r* as the function,

$$G(r) = 2\pi r^3 \Sigma \nu \frac{\partial \Omega}{\partial r}$$

- If $\frac{\partial \Omega}{\partial r} = 0$
 - → Rigid body rotation
 - → No torque
- If $\Omega(r)$ decreases outwards, $\frac{\partial \Omega}{\partial r} < 0$,
 - $\rightarrow G(r) < 0$
 - → angular momentum goes from inner circles to outer circles.
 - → The gas slowly spirals in!

Differential viscous torque



The net torque on the ring between r and r + dr is

$$G(r+dr)-G(r)=\frac{\partial G}{\partial r}dr$$

The net torque on the ring between r and r + dr is

$$G(r+dr)-G(r)=\frac{\partial G}{\partial r}dr$$

The work done by this torque is

The net torque on the ring between r and r + dr is

$$G(r+dr)-G(r)=\frac{\partial G}{\partial r}dr$$

The work done by this torque is

$$dW = \frac{\partial G}{\partial r} dr d\phi$$

The net torque on the ring between r and r + dr is

$$G(r+dr)-G(r)=\frac{\partial G}{\partial r}dr$$

The work done by this torque is

$$dW = \frac{\partial G}{\partial r} dr d\phi$$

and the associated power is

$$P = \frac{\partial G}{\partial r} \Omega dr = \left[\frac{\partial}{\partial r} (G(r)\Omega(r)) - G(r) \frac{\partial \Omega}{\partial r} \right] dr$$

$$P = \left[\frac{\partial}{\partial r} \left(G(r) \Omega(r) \right) - G(r) \frac{\partial \Omega}{\partial r} \right] dr$$

 $\frac{\partial}{\partial r}(G(r)\Omega(r)) dr$: Rate of *convection* of the rotational energy through the gas by the torques.

$$P = \left[\frac{\partial}{\partial r} \left(G(r) \Omega(r) \right) - G(r) \frac{\partial \Omega}{\partial r} \right] dr$$

 $\frac{\partial}{\partial r}$ ($G(r)\Omega(r)$) dr: Rate of *convection* of the rotational energy through the gas by the torques.

Integration over the whole disk depends only on boundary conditions,

$$P = \left[\frac{\partial}{\partial r} \left(G(r) \Omega(r) \right) - G(r) \frac{\partial \Omega}{\partial r} \right] dr$$

 $\frac{\partial}{\partial r}(G(r)\Omega(r)) dr$: Rate of *convection* of the rotational energy through the gas by the torques.

Integration over the whole disk depends only on boundary conditions,

$$\int_{r_{in}}^{r_{out}} \frac{\partial}{\partial r} (G(r)\Omega(r)) dr = \Omega(r)G(r)|_{r_{in}}^{r_{out}}$$

$$P = \left[\frac{\partial}{\partial r} \left(G(r) \Omega(r) \right) - G(r) \frac{\partial \Omega}{\partial r} \right] dr$$

 $-G(r)\frac{\partial\Omega}{\partial r}dr$: Local rate of loss of mechanical energy, which is transformed into heat.

$$P = \left[\frac{\partial}{\partial r} \left(G(r) \Omega(r) \right) - G(r) \frac{\partial \Omega}{\partial r} \right] dr$$

 $-G(r)\frac{\partial\Omega}{\partial r}dr$: Local rate of loss of mechanical energy, which is transformed into heat.

This is the viscous dissipation rate per ring of width dr.

$$P = \left[\frac{\partial}{\partial r} \left(G(r) \Omega(r) \right) - G(r) \frac{\partial \Omega}{\partial r} \right] dr$$

 $-G(r)\frac{\partial\Omega}{\partial r}dr$: Local rate of loss of mechanical energy, which is transformed into heat.

This is the viscous dissipation rate per ring of width dr.

$$D(r) = G(r) \frac{\partial \Omega}{\partial r} dr$$

Each ring of width dr has two sides, with area $\sim 2\pi r dr$.

Each ring of width dr has two sides, with area $\sim 2\pi r dr$. We define the dissipation rate per unit plane surface as

$$D(r) = \frac{G(r)\frac{\partial \Omega}{\partial r}dr}{2(2\pi r dr)}$$

Each ring of width dr has two sides, with area $\sim 2\pi r dr$. We define the dissipation rate per unit plane surface as

$$D(r) = \frac{G(r)\frac{\partial \Omega}{\partial r}dr}{2(2\pi r dr)}$$

$$D(r) = \frac{1}{2} \nu \Sigma \left(r \frac{\partial \Omega}{\partial r} \right)^2$$

$$D(r) = \frac{1}{2} \nu \Sigma \left(r \frac{\partial \Omega}{\partial r} \right)^2$$

$$D(r) = \frac{1}{2} \nu \Sigma \left(r \frac{\partial \Omega}{\partial r} \right)^2$$

 $D(r) \ge 0$ always \rightarrow it always dissipate.

$$D(r) = \frac{1}{2} \nu \Sigma \left(r \frac{\partial \Omega}{\partial r} \right)^2$$

 $D(r) \ge 0$ always \to it always dissipate. The zero corresponds to the rigid body, $\left(\frac{\partial \Omega}{\partial r} = 0\right)$

$$D(r) = \frac{1}{2} \nu \Sigma \left(r \frac{\partial \Omega}{\partial r} \right)^2$$

$$D(r) = \frac{1}{2} \nu \Sigma \left(r \frac{\partial \Omega}{\partial r} \right)^2$$

Using the Keplerian angular velocity,

$$\Omega = \Omega_k(r) = \sqrt{\frac{\mathsf{GM}}{r^3}}$$

$$D(r) = \frac{1}{2} \nu \Sigma \left(r \frac{\partial \Omega}{\partial r} \right)^2$$

Using the Keplerian angular velocity,

$$\Omega = \Omega_k(r) = \sqrt{\frac{GM}{r^3}}$$

$$D(r) = \frac{9}{8} \nu \Sigma \frac{GM}{r^3}$$

In order to describe the radial structure of disk and its evolution we will use cylindrical coordinates (r, ϕ, z) .

In order to describe the radial structure of disk and its evolution we will use cylindrical coordinates (r, ϕ, z) .

Angular velocity:

$$\Omega = \Omega_k(r) = \sqrt{\frac{\mathsf{GM}}{r^3}}$$

In order to describe the radial structure of disk and its evolution we will use cylindrical coordinates (r, ϕ, z) .

Angular velocity:

$$\Omega = \Omega_k(r) = \sqrt{\frac{GM}{r^3}}$$

Tangential velocity:

$$v_{\phi}=r\Omega_k(r)$$

In order to describe the radial structure of disk and its evolution we will use cylindrical coordinates (r, ϕ, z) .

Angular velocity:

$$\Omega = \Omega_k(r) = \sqrt{\frac{GM}{r^3}}$$

Tangential velocity:

$$v_{\phi} = r\Omega_k(r)$$

Small radial drift velocity: $v_r = v_r(t, r) < 0$ (negative for accretion)

In order to describe the radial structure of disk and its evolution we will use cylindrical coordinates (r, ϕ, z) .

Angular velocity:

$$\Omega = \Omega_k(r) = \sqrt{\frac{GM}{r^3}}$$

Tangential velocity:

$$v_{\phi} = r\Omega_k(r)$$

Small radial *drift* velocity: $v_r = v_r(t, r) < 0$ (negative for accretion) Surface mass density: $\Sigma = \Sigma(t, r)$

Consider m.

Consider m.

Mass: $2\pi r dr \Sigma$

Consider m.

Mass: $2\pi r dr \Sigma$

Total angular momentum: $(2\pi r dr \Sigma)r^2\Omega$

Consider m.

Mass: $2\pi r dr \Sigma$

Total angular momentum: $(2\pi r dr \Sigma)r^2\Omega$

Rate of change of mass:

$$\frac{\partial}{\partial t} (2\pi r dr \Sigma) \cong -2\pi dr \frac{\partial}{\partial r} (r \Sigma v_r)$$

Consider m.

Mass: $2\pi r dr \Sigma$

Total angular momentum: $(2\pi r dr \Sigma)r^2\Omega$

Rate of change of mass:

$$\frac{\partial}{\partial t} (2\pi r dr \Sigma) \cong -2\pi dr \frac{\partial}{\partial r} (r \Sigma v_r)$$

In the limit $dr \rightarrow 0$ this gives the mass conservation equation

$$r\frac{\partial \Sigma}{\partial t} + \frac{\partial}{\partial r}(r\Sigma v_r) = 0$$

Rate of change of the total angular momentum:

$$\frac{\partial}{\partial t} \left(2\pi r dr \Sigma r^2 \Omega \right) \cong -2\pi dr \frac{\partial}{\partial r} \left(r \Sigma v_r r^2 \Omega \right) + \frac{\partial G}{\partial r} dr$$

Rate of change of the total angular momentum:

$$\frac{\partial}{\partial t} \left(2\pi r dr \Sigma r^2 \Omega \right) \cong -2\pi dr \frac{\partial}{\partial r} \left(r \Sigma v_r r^2 \Omega \right) + \frac{\partial G}{\partial r} dr$$

In the limit $dr \rightarrow 0$ this gives the momentum conservation equation

$$r\frac{\partial}{\partial t}\left(\Sigma r^2\Omega\right) + \frac{\partial}{\partial r}\left(r\Sigma v_r r^2\Omega\right) = \frac{1}{2\pi}\frac{\partial G}{\partial r}$$

Equations determining the radial structure of the accretion disk:

$$r\frac{\partial \Sigma}{\partial t} + \frac{\partial}{\partial r}(r\Sigma v_r) = 0$$

$$r\frac{\partial}{\partial t}(\Sigma r^2 \Omega) + \frac{\partial}{\partial r}(r\Sigma v_r r^2 \Omega) = \frac{1}{2\pi}\frac{\partial G}{\partial r}$$

$$G(r, t) = 2\pi r \nu \Sigma r^2 \frac{\partial \Omega}{\partial r}$$

Equation for the kinematical viscosity ν

Combining the equations determining the radial structure of the accretion disk and assuming that $\frac{\partial\Omega}{\partial t}=0$, we obtain

$$r\Sigma v_r \frac{\partial}{\partial r} \left(r^2 \Omega \right) = \frac{1}{2\pi} \frac{\partial G}{\partial r}$$

Combining the equations determining the radial structure of the accretion disk and assuming that $\frac{\partial \Omega}{\partial t} = 0$, we obtain

$$r\Sigma v_r \frac{\partial}{\partial r} \left(r^2 \Omega \right) = \frac{1}{2\pi} \frac{\partial G}{\partial r}$$

Eliminating the velocity, v_r , we have

$$r\frac{\partial \Sigma}{\partial t} = -\frac{\partial}{\partial r} \left[\frac{1}{2\pi \frac{\partial (r^2 \Omega)}{\partial r}} \frac{\partial G}{\partial r} \right]$$

Using the Keplerian angular velocity we obtain the equation for the time evolution of the surface mass density

Using the Keplerian angular velocity we obtain the equation for the time evolution of the surface mass density

$$\frac{\partial \Sigma}{\partial t} = \frac{3}{r} \frac{\partial}{\partial r} \left[r^{1/2} \frac{\partial}{\partial r} \left(\nu \Sigma r^{1/2} \right) \right]$$

Using the Keplerian angular velocity we obtain the equation for the time evolution of the surface mass density

$$\frac{\partial \Sigma}{\partial t} = \frac{3}{r} \frac{\partial}{\partial r} \left[r^{1/2} \frac{\partial}{\partial r} \left(\nu \Sigma r^{1/2} \right) \right]$$

This is a nonlinear diffusion equation for Σ and one needs to know the function ν to solve it.

Using the Keplerian angular velocity we obtain the equation for the time evolution of the surface mass density

$$\frac{\partial \Sigma}{\partial t} = \frac{3}{r} \frac{\partial}{\partial r} \left[r^{1/2} \frac{\partial}{\partial r} \left(\nu \Sigma r^{1/2} \right) \right]$$

This is a nonlinear diffusion equation for Σ and one needs to know the function ν to solve it.

The radial velocity becomes

$$v_r = -\frac{3}{\Sigma r^{1/2}} \frac{\partial}{\partial r} \left[\nu \Sigma r^{1/2} \right]$$

Consider the particular case in which ν =constant.

Consider the particular case in which ν =constant.

$$\frac{\partial}{\partial t} \left(\Sigma r^{1/2} \right) = \frac{3\nu}{r} \left(r^{1/2} \frac{\partial}{\partial r} \right)^2 \left(\Sigma r^{1/2} \right)$$

Change $s = 2r^{1/2}$

Change
$$s = 2r^{1/2}$$

$$\frac{\partial}{\partial t} \left(\Sigma r^{1/2} \right) = \frac{12\nu}{s^2} \frac{\partial^2}{\partial s^2} \left(\Sigma r^{1/2} \right)$$

Change $s = 2r^{1/2}$

$$\frac{\partial}{\partial t} \left(\Sigma r^{1/2} \right) = \frac{12\nu}{s^2} \frac{\partial^2}{\partial s^2} \left(\Sigma r^{1/2} \right)$$

Now consider $\Sigma r^{1/2} = T(t)S(s)$,

Change $s = 2r^{1/2}$

$$\frac{\partial}{\partial t} \left(\Sigma r^{1/2} \right) = \frac{12\nu}{s^2} \frac{\partial^2}{\partial s^2} \left(\Sigma r^{1/2} \right)$$

Now consider $\Sigma r^{1/2} = T(t)S(s)$,

$$\frac{1}{T}\frac{dT}{dt} = \frac{12\nu}{s^{"}}\frac{d^2S}{ds^2} = -\lambda^2 = \text{constant}$$

Change $s = 2r^{1/2}$

$$\frac{\partial}{\partial t} \left(\Sigma r^{1/2} \right) = \frac{12\nu}{s^2} \frac{\partial^2}{\partial s^2} \left(\Sigma r^{1/2} \right)$$

Now consider $\Sigma r^{1/2} = T(t)S(s)$,

$$\frac{1}{T}\frac{dT}{dt} = \frac{12\nu}{s''}\frac{d^2S}{ds^2} = -\lambda^2 = \text{constant}$$

- T: Exponential function
- S: Bessel function

The solution of this equation considering the initial distribution

$$\Sigma(r, t=0) = \frac{m}{2\pi r_0} \delta(r - r_0)$$

The solution of this equation considering the initial distribution

$$\Sigma(r, t = 0) = \frac{m}{2\pi r_0} \delta(r - r_0)$$

is the function

$$\Sigma(x,\tau) = \frac{m}{\pi r_0^2} \tau^{-1} x^{-1/4} \exp\left[-\frac{1+x^2}{\tau}\right] I_{1/4} \left(\frac{2x}{\tau}\right)$$

The solution of this equation considering the initial distribution

$$\Sigma(r, t = 0) = \frac{m}{2\pi r_0} \delta(r - r_0)$$

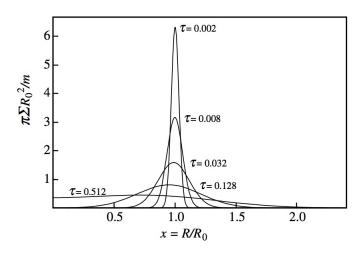
is the function

$$\Sigma(x,\tau) = \frac{m}{\pi r_0^2} \tau^{-1} x^{-1/4} \exp\left[-\frac{1+x^2}{\tau}\right] I_{1/4} \left(\frac{2x}{\tau}\right)$$

 $I_{1/4}(z)$: Modified Bessel function

$$x = \frac{r}{r_0}$$
$$\tau = \frac{12\nu t}{r_0^2}$$

Formation of the Accretion Disk



• The effect of this simple model viscosity is to spread the original ring distribution into a disk.

- The effect of this simple model viscosity is to spread the original ring distribution into a disk.
- The time scale of the spreading is (note the argument in the exponential function $(1 + x^2)\tau^{-1} \sim x^2\tau^{-1} \sim 1$)

$$t_{\text{visc}} \sim \frac{r^2}{\nu}$$

• From the expression for the radial velocity one obtains

$$v_r \sim \frac{v_r}{r}$$

From the expression for the radial velocity one obtains

$$v_r \sim \frac{v}{r}$$

The time scale of the spreading can be written as

$$t_{visc} \sim \frac{r}{v_r}$$

This is called the viscous or radial drift timescale.

The kinematical viscosity is modeled as

$$\nu \sim \lambda \tilde{\nu}$$

The kinematical viscosity is modeled as

$$\nu \sim \lambda \tilde{\nu}$$

Molecular transport:

 λ : mean free path

 \tilde{v} : thermal speed

The kinematical viscosity is modeled as

$$\nu \sim \lambda \tilde{\nu}$$

Molecular transport:

λ: mean free path

v: thermal speed

Turbulent motion:

 λ : spatial scale (or characteristic wavelength) of the turbulence

 \tilde{v} : typical velocity of the eddies

In order to characterize viscosity, we introduce the Reynolds number,

$$Re = \frac{\mathrm{inertia}}{\mathrm{viscosity}} \sim \frac{\Omega^2 r}{\lambda \tilde{v} v_\phi/r^2}$$

In order to characterize viscosity, we introduce the Reynolds number,

$$Re = \frac{\mathrm{inertia}}{\mathrm{viscosity}} \sim \frac{\Omega^2 r}{\lambda \tilde{v} v_{\phi}/r^2}$$

$$Re \sim \frac{v_{\phi}/r}{\lambda \tilde{v} v_{\phi}/r^2}$$

In order to characterize viscosity, we introduce the Reynolds number,

$$Re = \frac{\mathrm{inertia}}{\mathrm{viscosity}} \sim \frac{\Omega^2 r}{\lambda \tilde{v} v_{\phi}/r^2}$$

$$Re \sim \frac{v_{\phi}/r}{\lambda \tilde{v} v_{\phi}/r^2}$$

$$Re \sim \frac{r v_p h i}{\lambda \tilde{v}}$$

In order to characterize viscosity, we introduce the Reynolds number,

$$Re = \frac{\mathrm{inertia}}{\mathrm{viscosity}} \sim \frac{\Omega^2 r}{\lambda \tilde{v} v_{\phi}/r^2}$$

$$Re \sim \frac{v_{\phi}/r}{\lambda \tilde{v} v_{\phi}/r^2}$$

$$Re \sim \frac{r v_p h i}{\lambda \tilde{v}}$$

If $Re \ll 1$: Viscous force dominates the flow.

In order to characterize viscosity, we introduce the Reynolds number,

$$Re = \frac{\mathrm{inertia}}{\mathrm{viscosity}} \sim \frac{\Omega^2 r}{\lambda \tilde{v} v_{\phi}/r^2}$$

$$Re \sim \frac{v_{\phi}/r}{\lambda \tilde{v} v_{\phi}/r^2}$$

$$Re \sim \frac{r v_p h i}{\lambda \tilde{v}}$$

If $Re \ll 1$: Viscous force dominates the flow.

If $Re \gg 1$: Viscosity is unimportant.

For molecular viscosity:

For molecular viscosity:

$$Re_{mol} \sim 0.2N \left(\frac{M}{M_{\odot}}\right)^{1/2} R_{10}^{1/2} T_4^{-5/2}$$

For molecular viscosity:

$$Re_{mol} \sim 0.2N \left(\frac{M}{M_{\odot}}\right)^{1/2} R_{10}^{1/2} T_4^{-5/2}$$

N: Gas density in cm⁻³. $[N > 10^{15} \text{ cm}^{-3}]$

 T_4 : Temperature of the gas in 10⁴ K units. [$T_4 \sim 1$]

 R_{10} : Distance from the primary in units of 10^{10} cm. [$R_{10} \sim 1$]

$$\left[\frac{M}{M_{\odot}} \sim 10^2\right]$$

For molecular viscosity:

$$Re_{mol} \sim 0.2N \left(\frac{M}{M_{\odot}}\right)^{1/2} R_{10}^{1/2} T_4^{-5/2}$$

N: Gas density in ${\rm cm}^{-3}$. $\left[N > 10^{15}~{\rm cm}^{-3}\right]$

 T_4 : Temperature of the gas in 10⁴ K units. [$T_4 \sim 1$]

 R_{10} : Distance from the primary in units of 10^{10} cm. [$R_{10} \sim 1$]

$$\left[\frac{M}{M_{\odot}} \sim 10^2\right]$$

$$Re_{mol} > 10^{15}$$

For molecular viscosity:

$$Re_{mol} \sim 0.2N \left(\frac{M}{M_{\odot}}\right)^{1/2} R_{10}^{1/2} T_4^{-5/2}$$

N: Gas density in ${\rm cm}^{-3}$. $\left[N > 10^{15}~{\rm cm}^{-3}\right]$

 T_4 : Temperature of the gas in 10⁴ K units. [$T_4 \sim 1$]

 R_{10} : Distance from the primary in units of 10^{10} cm. [$R_{10} \sim 1$]

$$\left[\frac{M}{M_{\odot}} \sim 10^2\right]$$

$$Re_{mol} > 10^{15}$$

Molecular viscosity is too weak for the needed dissipation and angular momentum transport.

Turbulence in accretion disk is the best method to explain the angular momentum transport.

With turbulence the fluid velocity begins to exhibit large and chaotic variations!

Turbulence in accretion disk is the best method to explain the angular momentum transport.

With turbulence the fluid velocity begins to exhibit large and chaotic variations!

But, how to model turbulence viscosity?

$$\nu \sim \tilde{v}_T \lambda_T$$

$$\nu \sim \tilde{v}_T \lambda_T$$

We can estimate some limit values for \tilde{v}_T and λ_T .

$$\nu \sim \tilde{v}_T \lambda_T$$

We can estimate some limit values for \tilde{v}_T and λ_T .

The largest eddies can not exceed the disk thickness,

$$\lambda_T \lesssim H$$

$$\nu \sim \tilde{v}_T \lambda_T$$

We can estimate some limit values for \tilde{v}_T and λ_T .

The largest eddies can not exceed the disk thickness,

$$\lambda_T \lesssim H$$

The velocity is unlikely to be supersonic,

$$\tilde{\mathsf{v}}_\mathsf{T} \lesssim \mathsf{c}_\mathsf{s}$$

Shakura y Sunyaev propose the α -prescription, modelling the turbulence viscosity as

Shakura y Sunyaev propose the α -prescription, modelling the turbulence viscosity as

$$\nu = \alpha c_s H$$

Shakura y Sunyaev propose the α -prescription, modelling the turbulence viscosity as

$$\nu = \alpha c_s H$$

 α is a constant or a function that includes all our ignorance about viscosity.

Outline for Part 2

- 1. Viscous Torques
 - 1.1 Differential Rotation
 - 1.2 Radial Structure Evolution
 - 1.3 The α -Prescription for Viscosity

• Geometrically thin and optically thick accretion disk.

- Geometrically thin and optically thick accretion disk.
- Has four parameters: BH mass, BH spin, mass accretion rate and viscosity parameter.

• The spacetime is stationary, axisymmetric, asymptotically flat, and reflection- symmetric with respect to the equatorial plane.

- The spacetime is stationary, axisymmetric, asymptotically flat, and reflection- symmetric with respect to the equatorial plane.
- The accretion disk is non-self-gravitating; that is, the impact of the disk's mass on the background metric is ignored.

- The spacetime is stationary, axisymmetric, asymptotically flat,
 and reflection- symmetric with respect to the equatorial plane.
- The accretion disk is non-self-gravitating; that is, the impact of the disk's mass on the background metric is ignored.
- The accretion disk is in the equatorial plane; that is, the disk is perpendicular to the black hole spin.

- The spacetime is stationary, axisymmetric, asymptotically flat, and reflection-symmetric with respect to the equatorial plane.
- The accretion disk is non-self-gravitating; that is, the impact of the disk's mass on the background metric is ignored.
- The accretion disk is in the equatorial plane; that is, the disk is perpendicular to the black hole spin.
- The inner edge of the disk is at the ISCO radius.

- The spacetime is stationary, axisymmetric, asymptotically flat, and reflection- symmetric with respect to the equatorial plane.
- The accretion disk is non-self-gravitating; that is, the impact of the disk's mass on the background metric is ignored.
- The accretion disk is in the equatorial plane; that is, the disk is perpendicular to the black hole spin.
- The inner edge of the disk is at the ISCO radius.
- The accretion disk is geometrically thin, namely the disk opening angle is $h/r \ll 1$, where H(r) is the semi-thickness of the disk at the radial coordinate r.

 We suppose to average over time scales Δt that are short enough to assume that the spacetime is stationary (for instance, the mass accreted by the central object does not appreciable change the background metric) and large enough to neglect possible inhomogeneities in the accretion fluid.

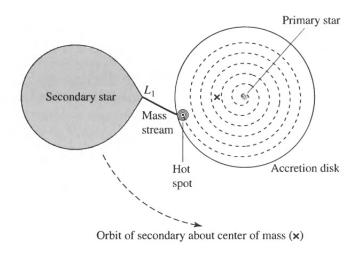
- We suppose to average over time scales Δt that are short enough to assume that the spacetime is stationary (for instance, the mass accreted by the central object does not appreciable change the background metric) and large enough to neglect possible inhomogeneities in the accretion fluid.
- The particles of the gas follow nearly-geodesic circular orbits in the equatorial plane.

- We suppose to average over time scales Δt that are short enough to assume that the spacetime is stationary (for instance, the mass accreted by the central object does not appreciable change the background metric) and large enough to neglect possible inhomogeneities in the accretion fluid.
- The particles of the gas follow nearly-geodesic circular orbits in the equatorial plane.
- Radial heat transport is ignored, and energy and angular momentum are radiated from the disk surface.

- We suppose to average over time scales Δt that are short enough to assume that the spacetime is stationary (for instance, the mass accreted by the central object does not appreciable change the background metric) and large enough to neglect possible inhomogeneities in the accretion fluid.
- The particles of the gas follow nearly-geodesic circular orbits in the equatorial plane.
- Radial heat transport is ignored, and energy and angular momentum are radiated from the disk surface.
- Magnetic fields are ignored.

• Energy and angular momentum from the disk's surface are only carried away by photons with wavelength $\lambda \ll M$.

- Energy and angular momentum from the disk's surface are only carried away by photons with wavelength $\lambda \ll M$.
- The effect of energy and angular momentum transport by photons emitted from the disk and returning to the disk due to strong light bending in the vicinity of the black hole (returning radiation) is neglected.





$$v_{\parallel} \lesssim c_{\rm s}$$

 $c_{\rm s}$: speed of sound in the envelope of the star.

$$|v_{\parallel}| \lesssim c_{\rm s}$$

 c_s : speed of sound in the envelope of the star. For normal stellar envelope temperatures, (< 10⁵ K);

$$v_{\parallel} \lesssim c_s$$

 c_s : speed of sound in the envelope of the star. For normal stellar envelope temperatures, (< 10 $^5~{\rm K}$); $c_s\lesssim$ 10 ${\rm km/s}$

$$\mathbf{v}_{\perp} \sim b\omega = \frac{2\pi b}{\tau}$$

$$v_{\perp} \sim b\omega = \frac{2\pi b}{\tau}$$

Using

$$b \approx a [0.500 - 0.227 \log_1 0(q)]$$

$$a = 3.5 \times 10^{10} \left(\frac{M}{M_{\odot}}\right)^{1/3} (1+q)^{1/3} \tau_{hr}^{2/3} \text{ [cm]}$$

$$v_{\perp} \sim b\omega = \frac{2\pi b}{\tau}$$

Using

$$b \approx a [0.500 - 0.227 \log_1 0(q)]$$

$$a = 3.5 \times 10^{10} \left(\frac{M}{M_{\odot}}\right)^{1/3} (1+q)^{1/3} \tau_{hr}^{2/3} [\text{cm}]$$

we get

$$v_{\perp} \gtrsim 305.6 \left(\frac{M}{M_{\odot}}\right)^{1/3} (1+q)^{1/3} \tau_{hr}^{-1/3} \text{ [km/s]}$$

$$\begin{split} v_{\parallel} \lesssim c_s \lesssim 10~\mathrm{km/s} \\ v_{\perp} \gtrsim 305.6 \left(\frac{M}{M_{\odot}}\right)^{1/3} (1+q)^{1/3} \, \tau_{hr}^{-1/3} \; [\mathrm{km/s}] \end{split}$$

$$egin{align*} v_{\parallel} \lesssim c_{s} \lesssim 10 \; \mathrm{km/s} \ & v_{\perp} \gtrsim 305.6 \left(rac{M}{M_{\odot}}
ight)^{1/3} (1+q)^{1/3} \, au_{hr}^{-1/3} \; [\mathrm{km/s}] \ & v_{\perp} \gtrsim 104.2 \left(rac{M}{M_{\odot}}
ight)^{1/3} (1+q)^{1/3} \, au_{days}^{-1/3} \; [\mathrm{km/s}] \ & v_{\perp} \gg v_{\parallel} \ \end{split}$$

A particle (or parcel of gas) is released form rest at the point L₁,
 i.e. pressure effects are neglected.

- A particle (or parcel of gas) is released form rest at the point L₁,
 i.e. pressure effects are neglected.
- Because of the motion of the star, this particle is moving with velocity v_⊥ as seen from the BH.

- A particle (or parcel of gas) is released form rest at the point L₁,
 i.e. pressure effects are neglected.
- Because of the motion of the star, this particle is moving with velocity v_⊥ as seen from the BH.
- The particle will describe an elliptical trajectory around the BH but the presence of the star will make this ellipse to precess slowly.

• In the stream of accreting particles, their orbits will intersect, resulting in dissipation of energy via collisions.

- In the stream of accreting particles, their orbits will intersect, resulting in dissipation of energy via collisions.
- However, angular momentum will be conserved in this collisions.

- In the stream of accreting particles, their orbits will intersect, resulting in dissipation of energy via collisions.
- However, angular momentum will be conserved in this collisions.
- Hence, particles will go into the trajectories with minimum energy for a given angular momentum,

- In the stream of accreting particles, their orbits will intersect, resulting in dissipation of energy via collisions.
- However, angular momentum will be conserved in this collisions.
- Hence, particles will go into the trajectories with minimum energy for a given angular momentum, i.e. circular orbits!

- In the stream of accreting particles, their orbits will intersect, resulting in dissipation of energy via collisions.
- However, angular momentum will be conserved in this collisions.
- Hence, particles will go into the trajectories with minimum energy for a given angular momentum, i.e. circular orbits!
- This process is called *circularization*.

- In the stream of accreting particles, their orbits will intersect, resulting in dissipation of energy via collisions.
- However, angular momentum will be conserved in this collisions.
- Hence, particles will go into the trajectories with minimum energy for a given angular momentum, i.e. circular orbits!
- This process is called *circularization*.
- The radius of the resulting circular orbit is called circularization radius, r_{circ}.

 Ω_k : Keplerian angular velocity in the circular orbit

 Ω_k : Keplerian angular velocity in the circular orbit

 v_{ϕ} : Tangential velocity in the circular orbit

 Ω_k : Keplerian angular velocity in the circular orbit v_{ϕ} : Tangential velocity in the circular orbit

$$r_{circ}\Omega_k^2(r_{circ}) = \frac{v_\phi^2(r_{circ})}{r_{circ}} = \frac{GM}{r_{circ}^2}$$

 Ω_k : Keplerian angular velocity in the circular orbit v_{ϕ} : Tangential velocity in the circular orbit

$$r_{circ}\Omega_{k}^{2}(r_{circ}) = \frac{v_{\phi}^{2}(r_{circ})}{r_{circ}} = \frac{GM}{r_{circ}^{2}}$$
$$v_{\phi}(r_{circ}) = \sqrt{\frac{GM}{r_{circ}}}$$

Conservation of angular momentum

Conservation of angular momentum

$$r_{circ}v_{\phi}=b^2\omega$$

Conservation of angular momentum

$$r_{circ}v_{\phi}=b^2\omega$$

$$\frac{r_{circ}}{a} = \frac{4\pi^2}{GM\tau} a^3 \left(\frac{b}{a}\right)^4$$

Conservation of angular momentum

$$r_{circ}v_{\phi}=b^2\omega$$

$$\frac{r_{\rm circ}}{a} = \frac{4\pi^2}{\rm GM}\tau a^3 \left(\frac{b}{a}\right)^4$$

and using Kepler's third law,

$$\frac{r_{circ}}{a} = (1+q) \left(\frac{b}{a}\right)^4$$

Conservation of angular momentum

$$r_{circ}v_{\phi}=b^2\omega$$

$$\frac{r_{circ}}{a} = \frac{4\pi^2}{GM\tau} a^3 \left(\frac{b}{a}\right)^4$$

and using Kepler's third law,

$$\frac{r_{circ}}{a} = (1+q) \left(\frac{b}{a}\right)^4$$

$$\frac{r_{circ}}{a} = (1+q) \left[0.500 - 0.227 \log_{10} q \right]^4$$

$$r_{circ} = (1+q)^{4/3} \left[0.500 - 0.227 \log_{10} q \right]^4 \left(\frac{M}{M_{\odot}} \right)^{1/3} \tau_{days}^{2/3} \left[R_{\odot} \right]$$

• The stream of gas moves in a ring with $r = r_{circ}$.

- The stream of gas moves in a ring with $r = r_{circ}$.
- In the ring the particles have collisions, shocks, viscous dissipation and other processes that transform some of the potential energy into heat (producing radiation).

- The stream of gas moves in a ring with $r = r_{circ}$.
- In the ring the particles have collisions, shocks, viscous dissipation and other processes that transform some of the potential energy into heat (producing radiation).
- However, this release of energy needs the loosing of angular momentum.

- The stream of gas moves in a ring with $r = r_{circ}$.
- In the ring the particles have collisions, shocks, viscous dissipation and other processes that transform some of the potential energy into heat (producing radiation).
- However, this release of energy needs the loosing of angular momentum.
- In the absence of external torques, the only possible process is a *transfer of angular momentum* from inner regions outwards by internal torques.

- The stream of gas moves in a ring with $r = r_{circ}$.
- In the ring the particles have collisions, shocks, viscous dissipation and other processes that transform some of the potential energy into heat (producing radiation).
- However, this release of energy needs the loosing of angular momentum.
- In the absence of external torques, the only possible process is a *transfer of angular momentum* from inner regions outwards by internal torques.
- The redistribution of angular momentum makes particles in the outer parts move outwards (gaining angular momentum) and the particles in the inner particles spiral inwards.

• The accretion disk will extend from $r_{in} \ge r_{ISCO}$ up to $r_{out} \le b$

- The accretion disk will extend from $r_{in} \ge r_{ISCO}$ up to $r_{out} \le b$
- Viscous torques may be modeled using different processes:

- The accretion disk will extend from $r_{in} \ge r_{ISCO}$ up to $r_{out} \le b$
- Viscous torques may be modeled using different processes:
 - Viscous torques due to differential rotation in the accretion disk (produced by the thermal motion of the fluid molecules). This is a local mechanism for angular momentum transport

- The accretion disk will extend from $r_{in} \ge r_{ISCO}$ up to $r_{out} \le b$
- Viscous torques may be modeled using different processes:
 - Viscous torques due to differential rotation in the accretion disk (produced by the thermal motion of the fluid molecules). This is a local mechanism for angular momentum transport
 - Magnetic loops that couple fluid elements located at macroscopic distances across the disk. This is a non-local mechanism for angular momentum transport.

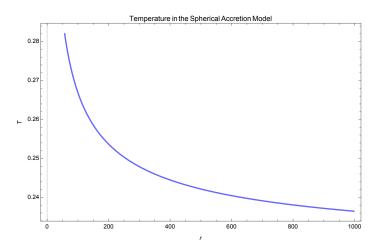
- The accretion disk will extend from $r_{in} \ge r_{ISCO}$ up to $r_{out} \le b$
- Viscous torques may be modeled using different processes:
 - Viscous torques due to differential rotation in the accretion disk (produced by the thermal motion of the fluid molecules). This is a local mechanism for angular momentum transport
 - Magnetic loops that couple fluid elements located at macroscopic distances across the disk. This is a non-local mechanism for angular momentum transport.
 - Turbulence in the fluid may be an origin of angular momentum transport. Turbulence may be produced by mechanisms as Themally driven convection, Pure hydrodynamic instabilities or Magnetohydrodynamic (MHD) turbulence.

- The accretion disk will extend from $r_{in} \ge r_{ISCO}$ up to $r_{out} \le b$
- Viscous torques may be modeled using different processes:
 - Viscous torques due to differential rotation in the accretion disk (produced by the thermal motion of the fluid molecules). This is a local mechanism for angular momentum transport
 - Magnetic loops that couple fluid elements located at macroscopic distances across the disk. This is a non-local mechanism for angular momentum transport.
 - Turbulence in the fluid may be an origin of angular momentum transport. Turbulence may be produced by mechanisms as Themally driven convection, Pure hydrodynamic instabilities or Magnetohydrodynamic (MHD) turbulence.
- However, this release of energy needs the loosing of angular momentum.

- The accretion disk will extend from $r_{in} \ge r_{ISCO}$ up to $r_{out} \le b$
- Viscous torques may be modeled using different processes:
 - Viscous torques due to differential rotation in the accretion disk (produced by the thermal motion of the fluid molecules). This is a local mechanism for angular momentum transport
 - Magnetic loops that couple fluid elements located at macroscopic distances across the disk. This is a non-local mechanism for angular momentum transport.
 - Turbulence in the fluid may be an origin of angular momentum transport. Turbulence may be produced by mechanisms as Themally driven convection, Pure hydrodynamic instabilities or Magnetohydrodynamic (MHD) turbulence.
- However, this release of energy needs the loosing of angular momentum.
 - In the absence of external torques, the only possible process is _{58/60}

- The accretion disk will extend from $r_{in} \ge r_{ISCO}$ up to $r_{out} \le b$
- Viscous torques may be modeled using different processes:
 - Viscous torques due to differential rotation in the accretion disk (produced by the thermal motion of the fluid molecules). This is a local mechanism for angular momentum transport
 - Magnetic loops that couple fluid elements located at macroscopic distances across the disk. This is a non-local mechanism for angular momentum transport.
 - Turbulence in the fluid may be an origin of angular momentum transport. Turbulence may be produced by mechanisms as Themally driven convection, Pure hydrodynamic instabilities or Magnetohydrodynamic (MHD) turbulence.
- However, this release of energy needs the loosing of angular momentum.
 - In the absence of external torques, the only possible process is _{58/60}

Temperature of the gas in the accretion structure



Next Lecture

10. Accretion Disks. Detailed Description