

Using the antisymmetry $R_{\sigma\alpha\beta\gamma} = -R_{\alpha\sigma\beta\gamma}$,

$$-4\mu^2 \left(1 + \frac{1}{4\mu^2} R_{\alpha\sigma\beta\gamma} S^{\alpha\sigma} S^{\beta\gamma} \right) S^{m\epsilon} \dot{P}_\epsilon = 2m S^{m\tau} R_{\sigma\alpha\beta\gamma} P^\alpha S^{\beta\gamma}$$

$$-S^{m\epsilon} \dot{P}_\epsilon = \frac{2m S^{m\tau} R_{\sigma\alpha\beta\gamma} P^\alpha S^{\beta\gamma}}{4\mu^2 \left(1 + \frac{1}{4\mu^2} R_{\alpha\sigma\beta\gamma} S^{\alpha\sigma} S^{\beta\gamma} \right)}$$

$$-S^{m\epsilon} \dot{P}_\epsilon = \frac{m S^{m\tau} R_{\sigma\alpha\beta\gamma} P^\alpha S^{\beta\gamma}}{2\mu^2 \left(1 + \frac{1}{4\mu^2} R_{\alpha\sigma\beta\gamma} S^{\alpha\sigma} S^{\beta\gamma} \right)}$$

$$-S^{m\epsilon} \dot{P}_\epsilon = \frac{1}{2\mu^2 \Delta} m S^{m\tau} R_{\sigma\alpha\beta\gamma} P^\alpha S^{\beta\gamma} \quad (\nabla)$$

where we defined

$$\Delta = \left(1 + \frac{1}{4\mu^2} R_{\alpha\sigma\beta\gamma} S^{\alpha\sigma} S^{\beta\gamma} \right)$$

Replacing (IV) into equation (II),

$$\mu^2 v^m - m p^m = -\dot{P}_\epsilon S^{m\epsilon}$$

$$\mu^2 v^m - m p^m = \frac{1}{2\mu^2 \Delta} m S^{m\tau} R_{\sigma\alpha\beta\gamma} P^\alpha S^{\beta\gamma}$$

$$\mu^2 v^m = m p^m + \frac{1}{2\mu^2 \Delta} m S^{m\tau} R_{\sigma\alpha\beta\gamma} P^\alpha S^{\beta\gamma}$$

$$v^m = \frac{m p^m}{\mu^2} + \frac{1}{2\mu^2 \Delta} \frac{m}{\mu^2} S^{m\tau} R_{\sigma\alpha\beta\gamma} P^\alpha S^{\beta\gamma}$$

The components of the angular momentum are given by the Killing vectors

$$\left\{ \begin{array}{l} K(x) = -\sin\varphi \frac{\partial}{\partial\theta} - \cot\theta \cos\varphi \frac{\partial}{\partial\varphi} \\ K(y) = \cos\varphi \frac{\partial}{\partial\theta} - \cot\theta \sin\varphi \frac{\partial}{\partial\varphi} \\ K(z) = \frac{\partial}{\partial\varphi} \equiv J \end{array} \right.$$

Working now with $K(x)$ and $K(y)$ we obtain the angular momentum components J_x and J_y :

$$K''(x) = -\sin\varphi \delta_\theta^\alpha - \cot\theta \cos\varphi \delta_\varphi^\alpha$$

$$C(x) = K''(x) P_m - \frac{1}{2} S^{mn} \nabla_m K_{n(x)} + \tilde{q} K''(x) \phi_m$$

$$C(x) = -\sin\varphi \delta_\theta^\alpha P_m - \cot\theta \cos\varphi \delta_\varphi^\alpha P_m + \frac{1}{2} S^{mn} \nabla_m K_{n(x)} + \tilde{q} K_{(x)}^\theta \phi_\theta + \tilde{q} K_{(x)}^\varphi \phi_\varphi$$

$$C(x) = -\sin\varphi P_\theta - \cot\theta \cos\varphi P_\varphi + \frac{1}{2} S^{mn} \partial_m K_{n(x)} - \frac{1}{2} S^{mn} \Gamma_{mu}^\alpha K_{\alpha(x)}$$

$$C(x) = -\sin\varphi P_\theta - \cot\theta \cos\varphi P_\varphi + \frac{1}{2} S^{mn} \partial_m K_{n(x)} \equiv J_x$$

Now,

$$K_{n(y)} = g_{v\alpha} K_{(y)}^\alpha = -g_{v\alpha} \sin\varphi \delta_\theta^\alpha - g_{v\alpha} \cot\theta \cos\varphi \delta_\varphi^\alpha$$

$$K_{n(y)} = -g_{v\theta} \sin\varphi - g_{v\varphi} \cot\theta \cos\varphi$$

Then

$$J_x = -P_\theta \sin \varphi - P_\varphi \cot \theta \cos \varphi - \frac{1}{2} S^{\theta\varphi} \partial_r (\partial_{\theta\varphi} \sin \varphi) - \frac{1}{2} S^{\theta\varphi} \partial_\theta (\partial_{\varphi\theta} \cot \theta \cos \varphi)$$

$$J_x = -P_\theta \sin \varphi - P_\varphi \cot \theta \cos \varphi - \frac{1}{2} S^{\theta\theta} \partial_r (\partial_{\theta\theta} \sin \varphi) - \frac{1}{2} S^{\theta\varphi} \partial_\theta (\partial_{\varphi\theta} \cot \theta \cos \varphi)$$

$$\begin{aligned} J_x = & -P_\theta \sin \varphi - P_\varphi \cot \theta \cos \varphi - \frac{1}{2} S^{\theta\theta} \partial_r (\partial_{\theta\theta} \sin \varphi) - \frac{1}{2} S^{\theta\theta} \partial_\varphi (\partial_{\theta\theta} \sin \varphi) \\ & - \frac{1}{2} S^{\theta\varphi} \partial_r (\partial_{\varphi\theta} \cot \theta \cos \varphi) - \frac{1}{2} S^{\theta\varphi} \partial_\theta (\partial_{\varphi\theta} \cot \theta \cos \varphi) \end{aligned}$$

$$\begin{aligned} J_x = & -P_\theta \sin \varphi - P_\varphi \cot \theta \cos \varphi - \frac{1}{2} S^{\theta\theta} \sin \varphi \partial_r \partial_{\theta\theta} - \frac{1}{2} S^{\theta\theta} \partial_{\theta\theta} \partial_\varphi \sin \varphi \\ & - \frac{1}{2} S^{\theta\varphi} \cot \theta \cos \varphi \partial_r \partial_{\varphi\theta} - \frac{1}{2} S^{\theta\varphi} \cos \varphi \partial_\theta (\partial_{\varphi\theta} \cot \theta) \end{aligned}$$

$$\begin{aligned} J_x = & -P_\theta \sin \varphi - P_\varphi \cot \theta \cos \varphi - \frac{1}{2} S^{\theta\theta} \sin \varphi 2r - \frac{1}{2} S^{\theta\theta} \partial_{\theta\theta} \cos \varphi \\ & - \frac{1}{2} S^{\theta\varphi} \cot \theta \cos \varphi 2r \sin \theta - \frac{1}{2} S^{\theta\varphi} \cos \varphi r^2 \partial_\theta (\sin^2 \theta \cot \theta) \end{aligned}$$

$$\begin{aligned} J_x = & -P_\theta \sin \varphi - P_\varphi \cot \theta \cos \varphi - r S^{\theta\theta} \sin \varphi - \frac{r^2}{2} S^{\theta\theta} \cos \varphi \\ & - r S^{\theta\varphi} \cos \varphi \sin \theta \cos \theta - \frac{r^2}{2} S^{\theta\varphi} \cos \varphi \partial_\theta (\sin \theta \cos \theta) \end{aligned}$$

$$\begin{aligned} J_x = & -P_\theta \sin \varphi - P_\varphi \cot \theta \cos \varphi - r S^{\theta\theta} \sin \varphi + \frac{r^2}{2} S^{\theta\theta} \cos \varphi \\ & - r S^{\theta\varphi} \cos \varphi \sin \theta \cos \theta - \frac{r^2}{2} S^{\theta\varphi} \cos \varphi (\cos^2 \theta - \sin^2 \theta) \end{aligned}$$

$$\begin{aligned} J_x = & -P_\theta \sin \varphi - P_\varphi \cot \theta \cos \varphi - r S^{\theta\theta} \sin \varphi + \frac{r^2}{2} S^{\theta\theta} \cos \varphi \\ & - r S^{\theta\varphi} \cos \varphi \sin \theta \cos \theta - \frac{r^2}{2} S^{\theta\varphi} \cos \varphi (1 - 2 \sin^2 \theta) \end{aligned}$$

$$\boxed{\begin{aligned} J_x = & -P_\theta \sin \varphi - P_\varphi \cot \theta \cos \varphi - r S^{\theta\theta} \sin \varphi \\ & + r S^{\theta\varphi} \cos \varphi \sin \theta \cos \theta + r^2 S^{\theta\varphi} \cos \varphi \sin^2 \theta \end{aligned}}$$

$$J_y = P_\theta \cos\varphi - P_\varphi \cot\theta \sin\varphi + \frac{1}{2} S^{\varphi\theta} \cos\varphi Zr - \frac{1}{2} S^{\varphi\theta} g_{\theta\theta} \sin\varphi$$

$$- \frac{1}{2} S^{\varphi r} \cot\theta \sin\varphi Zr \sin^2\theta - \frac{1}{2} S^{\theta\varphi} \sin\varphi r^2 \partial_\theta (\sin^2\theta \cot\theta)$$

$$J_y = P_\theta \cos\varphi - P_\varphi \cot\theta \sin\varphi + r S^{\varphi\theta} \cos\varphi - \frac{r^2}{2} S^{\varphi\theta} \sin\varphi$$

$$- r S^{\varphi r} \sin\varphi \sin\theta \cos\theta - \frac{r^2}{2} S^{\theta\varphi} \sin\varphi \partial_\theta (\sin\theta \cos\theta)$$

$$J_y = P_\theta \cos\varphi - P_\varphi \cot\theta \sin\varphi + r S^{\varphi\theta} \cos\varphi + \frac{r^2}{2} S^{\theta\varphi} \sin\varphi$$

$$- r S^{\varphi r} \sin\varphi \sin\theta \cos\theta - \frac{r^2}{2} S^{\theta\varphi} \sin\varphi (\cos^2\theta - \sin^2\theta)$$

$$J_y = P_\theta \cos\varphi - P_\varphi \cot\theta \sin\varphi + r S^{\varphi\theta} \cos\varphi + \frac{r^2}{2} S^{\theta\varphi} \sin\varphi$$

$$- r S^{\varphi r} \sin\varphi \sin\theta \cos\theta - \frac{r^2}{2} S^{\theta\varphi} \sin\varphi (1 - 2 \sin^2\theta)$$

$$J_y = P_\theta \cos\varphi - P_\varphi \cot\theta \sin\varphi + r S^{\varphi\theta} \cos\varphi$$

$$+ r S^{\varphi r} \sin\varphi \sin\theta \cos\theta + r^2 S^{\theta\varphi} \sin\varphi \sin^2\theta$$

Since the background is spherically symmetric, it is possible to choose the z-axis in the direction of the total angular momentum. Then

$$(J_x, J_y, J_z) = (0, 0, J) \quad J > 0$$

Hence, we have

$$J = P_\varphi + r \left[S^{\varphi\theta} + S^{\theta\varphi} r \cot\theta \right] \sin^2\theta \quad (I)$$

$$0 = -P_\theta \sin\varphi - P_\varphi \cot\theta \cos\varphi + r^2 S^{\theta\varphi} \sin^2\theta \cos\varphi + r S^{\varphi r} \sin\theta \cos\theta \cos\varphi - r S^{\varphi\theta} \sin\varphi \quad (II)$$

$$0 = P_\theta \cos\varphi - P_\varphi \cot\theta \sin\varphi + r^2 S^{\theta\varphi} \sin^2\theta \sin\varphi + r S^{\varphi r} \sin\theta \cos\theta \sin\varphi + r S^{\varphi\theta} \cos\varphi \quad (III)$$

