

Linking granulation performance with residence time and granulation liquid distributions in twin-screw granulation: an experimental investigation

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¹ **Abstract**

² Twin-screw granulation is a promising wet granulation technique for the continuous man-
³ ufacturing of pharmaceutical solid dosage forms. A twin screw granulator displays a short
⁴ residence time. Thus, the solid-liquid mixing must be achieved quickly by appropriate
⁵ arrangement of transport and kneading elements in the granulator screw allowing the pro-
⁶ duction of granules with a size distribution appropriate for tableting. The distribution of
⁷ residence time and granulation liquid is governed by the field conditions (such as location
⁸ and length of mixing zones) in the twin-screw granulator, thus contain interesting informa-
⁹ tion on granulation time, mixing and resulting sub-processes such as wetting, aggregation
¹⁰ and breakage. In this study, the impact of process (feed rate, screw speed and liquid-to-solid
¹¹ ratio) and equipment parameters (number of kneading discs and stagger angle) on the res-
¹² idence time (distribution), the granulation liquid-powder mixing and the resulting granule
¹³ size distributions during twin-screw granulation were investigated. Residence time and axial
¹⁴ mixing data was extracted from tracer maps and the solid-liquid mixing was quantified from
¹⁵ moisture maps, obtained by monitoring the granules at the granulator outlet using near
¹⁶ infra-red chemical imaging (NIR-CI). The granule size distribution was measured using the
¹⁷ sieving method. An increasing screw speed dominantly reduced the mean residence time.
¹⁸ Interaction of material throughput with the screw speed and with the number of kneading
¹⁹ discs led to most variation in the studied responses including residence time and mixing ca-
²⁰ pacity. At a high screw speed, granulation yield improved due to high axial mixing. However,
²¹ increasing material throughput quickly lowers the yield due to insufficient mixing of liquid
²² and powder. Moreover, increasing liquid-to-solid ratio resulted in more oversized granules,
²³ and the fraction of oversized granules further increased at higher throughput. Although
²⁴ an increasing number of kneading discs was found to be critical for achieving a uniform
²⁵ distribution of the granulation liquid, the granulation performance was hampered due to
²⁶ insufficient solid-liquid mixing capacity of the current kneading discs which is essential for

1 wet granulation. Thus, a balance between material throughput and screw speed should be
2 strived for in order to achieve a specific granulation time and solid-liquid mixing for high
3 granulation yield. Additionally, more efforts are needed both in modification of the screw
4 configuration as well as the geometry of the mixing elements to improve the mixing capacity
5 of the twin-screw granulator. The results from the current experimental study improved
6 the understanding regarding the interplay between granulation time and the axial and solid-
7 liquid mixing responsible for the granulation performance in twin-screw wet granulation.

8

9 *Keywords:* residence time distribution, axial mixing, NIR chemical imaging, solid-liquid
10 mixing

11 **1. Introduction**

12 Efforts towards switching from batch to continuous processing with 24/7 production ca-
13 pacity form one of the major considerations in the pharmaceutical industry for improving the
14 operational efficiency, including enhancing quality assurance (Poechlauer et al., 2012). How-
15 ever, a transformation to completely continuous processing requires all the unit operations
16 to be performed in a continuous mode with inter-compatibility, both in terms of capacity
17 and processing time. In this context, twin-screw granulation has emerged as a promising
18 technology for continuous wet granulation in continuous solid dosage manufacturing. A man-
19 ufacturing line with continuous twin-screw granulator (TSG) followed by (semi-)continuous
20 drying, milling and tabletting units is conceptualised for a continuous 'from powder to tablet'
21 manufacturing system. Several studies have shown that the mean residence time \bar{t} in a TSG
22 (which is generally between 2 and 40 seconds) is much shorter compared to the granulation
23 time available in a typical batch granulator, which is in the order of minutes (Kumar et al.,
24 2013). Thus, the solid-liquid mixing in the TSG must be achieved in a short period by ap-
25 propriate arrangement of transport and kneading elements in the granulator barrel allowing

1 the production of granules with a granule size distribution (GSD) suitable for downstream
2 operations (drying, tableting, etc.). Therefore, it is interesting to investigate how different
3 process and equipment settings lead to changes in the residence time distribution (RTD),
4 axial and solid-liquid mixing which consequently lead to a certain granulation yield. This
5 is particularly important as it could be concluded from an earlier study that a residence
6 time increase beyond a certain threshold is the result of a change in flow regime inside the
7 TSG, transitioning from mixed flow to plug flow (Kumar et al., 2014). As the plug flow
8 regime cannot be desired for mixing which is ultimately required for granulation, a detailed
9 study investigating the link between mixing and transport characteristics in the TSG and
10 the granulation performance is required.

11

12 Experimental investigation of twin-screw granulation RTD and its impact on granulation
13 performance has already been of interest for several other research groups. Dhenge et al.
14 (2010) measured the RTD using the sampling cup method under different processing con-
15 ditions and showed that process parameters such as screw speed and liquid-to-solid ratio
16 (L/S) have vital influence on the residence time. The same RTD measurement approach
17 was applied by El Hagrasy et al. (2013) to estimate the effect of changes in formulation
18 properties such as raw material composition as well as granulation liquid properties such as
19 viscosity on the granule properties. However, \bar{t} for a typical screw design is between 2-40 s
20 which is in the order of the sampling time in the sampling cup method, making this method
21 unsuitable for TSG studies (Li et al., 2014). In a remarkable attempt, Lee et al. (2012)
22 obtained the RTD for TSG using positron emission particle tracking (PEPT) to study the
23 axial mixing of the processed material inside the TSG barrel, which is essential information
24 for the optimisation of the obtained granule properties. Although PEPT is very powerful
25 technique, this method based on the single-particle tracking also suffers from major chal-
26 lenges as discussed by Kumar et al. (2014, 2015). Recently, Li et al. (2014) used a visual

1 technique based on digital video recording to measure RTD as a function of feed rate during
2 twin-screw granulation. Results from that study indicated a significant increase in \bar{t} and a
3 narrowing of RTD at higher feed rate. The study questioned the role of the kneading block
4 as mixing zone which is atypical since RTD can only be used to quantify axial mixing. Mix-
5 ing of solid-liquid is typically driven by a combination of both axial and transverse mixing
6 inside the TSG. Thus, this cannot be investigated solely from an RTD study. However, only
7 a small number of investigations have attempted to quantitatively describe the influence of
8 process parameters on solid-liquid mixing performance (Vercruyse et al., 2013). This is
9 mainly because of the lack of suitable techniques allowing detailed local flow characterisa-
10 tion in systems such as the TSG, especially due to their opacity. Vercruyse et al. (2013)
11 applied an image data collection method based on near infrared (NIR) chemical imaging to
12 evaluate the influence of the screw configuration, liquid addition method and rate, and the
13 barrel filling degree on the moisture homogeneity during twin-screw granulation. Applying
14 the same measurement approach, a tracer (theophylline anhydrate) was injected in the gran-
15 ulator and monitored to investigate the RTD of the tracer inside the barrel as a function of
16 screw speed, material throughput and number as well as stagger angle of the kneading discs
17 in the screw configuration of the TSG. Model-based analysis of these experimental data was
18 also performed to further investigate the mixing and flow behaviour inside the TSG (Kumar
19 et al., 2015). However, a relation between granulation time (measured as the mean residence
20 time) and the mixing quality (measured as the axial mixing and the solid-liquid mixing), all
21 responsible for the shape of the granule size distribution, is still not established.

22
23 In the present study, NIR chemical imaging was used as analytical technique to simulta-
24 neously and qualitatively and quantitatively characterise the flow and axial mixing of tracer
25 material as well as the mixing of the two phases, i.e. solid formulation material and gran-
26 ulation liquid, as function of process (screw speed, material throughput and liquid-to-solid

ratio) and equipment (number and stagger angle of kneading discs in the screw configuration) parameters of the twin-screw granulation. Since residence time and its distribution, as well as solid-liquid mixing dictate the final granulation yield, the resulting GSD was also measured to understand the overall influence of different flow and mixing conditions.

2. Materials and methods

2.1. Pharmaceutical formulation

α -Lactose monohydrate (Pharmatose 200M, Caldic, Hemiksem, Belgium) was used as model excipient. Distilled water was added as granulation liquid. To evaluate the residence time of the material inside the barrel, theophylline anhydride (Farma-Química Sur, Malaga, Spain) was used as tracer component.

2.2. Continuous twin screw granulation

Granulation experiments were performed using a 25 mm diameter co-rotating TSG, which is the granulation module of the ConsiGma-25 unit (GEA Pharma Systems, ColletteTM, Wommelgem, Belgium). The granulator screw has a length-to-diameter ratio of 20:1 (Fig. 1). The TSG barrel consists of a feed segment, where the powder enters the barrel and is transported through the conveying zone to the work segment, where the granulation liquid is added to the powder which is further intensively mixed by a combination of kneading discs and transport elements. The screw configuration is composed of kneading zones consisting of maximum 6 kneading discs in each zone (Length = $Diameter/4$ for each kneading element) at an angle of 30° and 60° (Fig. 1). Both kneading zones are separated by a conveying element (Length = 1.5 Diameter). When more than six kneading discs are used, an extra conveying element (Length = 1.5 Diameter) is implemented between the two mixing zones. Two narrow kneading discs (Length = $Diameter/6$) were placed at the end of each screw in order to reduce the amount of oversized agglomerates, as reported by Van Melkebeke

¹ et al. (2008). The barrel jacket is preheated to 25°C. During processing, pure α-lactose
² monohydrate is gravimetrically fed into the granulator by using a twin-screw feeder (KT20,
³ K-Tron Soder, Niederlenz, Switzerland). Distilled water as granulation liquid is pumped into
⁴ the screw chamber by using a peristaltic pump (Watson Marlow, Cornwall, UK) and silicon
⁵ tubings connected to the nozzles of diameter 1.6 mm. The granulation liquid is added before
⁶ the first kneading element by dripping through two liquid feed nozzles, each nozzle located
⁷ on top of each screw in the barrel (Kumar et al., 2014). A pulse of anhydrous theophylline
⁸ (2% (w/w) of the material throughput) used as tracer is manually added into the powder
⁹ inlet port of the granulator. The TSG has an inbuilt torque gauge and the steady state
¹⁰ criteria are decided on the equilibration of the measured torque of the granulator. The
¹¹ torque values obtained after equilibration of the process are averaged to give the overall
¹² torque during each run.

¹³ [Figure 1 about here.]

¹⁴ *2.3. Description of NIR chemical imaging setup*

¹⁵ Wet granules from the granulator output fall on a conveyor belt (Mini, ENP, Hjälteby,
¹⁶ Sweden) which is moving at a speed of 3.12 cm/s. Spectral images of the wet granules
¹⁷ are collected using a line-scanning (pushbroom) hyperspectral camera (SWIR, Specim Ltd.,
¹⁸ Oulu, Finland). The camera sees a row of 320 spatial pixels at a time, and disperses the
¹⁹ incoming light from each pixel in the spectral range 970-2500 nm onto one column of the
²⁰ 320×256-pixel mercury-cadmium-telluride (MCT) detector (14-bit readout, cooled to -70°C
²¹ with a 4-stage Peltier system). The camera-to-belt distance is set such that the imaged line
²² had a length of 10 cm on the conveyor belt, and the speed of the conveyor belt is adjusted to
²³ achieve a spatial resolution of 312×312 μm^2 per pixel at the maximum frame rate permitted
²⁴ by the camera (100 frames per second). The conveyor belt and the sample material on it
²⁵ were illuminated with two rows of three 75-W halogen lamps (Specim Ltd., Oulu, Finland)

1 at a distance of 35 cm, and the measurement is conducted in diffuse reflectance mode in the
2 45° - 0° - 45° geometry (For details see (Kumar et al., 2014)). Each collected spectral image
3 consists of 2500 frames (25 seconds measurement, 2500×320 spatial pixels, 256-element
4 spectrum at each spatial pixel) which corresponds to an area of 10×64 cm² on the conveyor
5 belt. At a material throughput of 10-25 kg/h the dry mass of material in one spectral image
6 is approximately 69-173 g.

7 *Extraction of relevant information from spectral data*

8 The analysis of the hyperspectral images from the RTD and solid-liquid measurements
9 is performed in two steps. In a first step, spatial pixels corresponding to the plastic con-
10 veyor belt were eliminated from the data set via partial least squares discriminant analysis
11 (PLS-DA) classification (Kumar et al., 2014). In the second step, the NIR spectra in the
12 remaining pixels corresponding to the granules were subjected to semi-quantitative anal-
13 ysis of theophylline content and moisture content. In both cases, the spectral range was
14 narrowed to 1100-2200 nm and the spectra were subjected to the standard normal variate
15 (SNV) pretreatment to eliminate the additive baseline offset variations and multiplicative
16 scaling effects in the spectra which may be caused by experimental conditions such as shad-
17 owed regions near large granules and possible differences in granule density. Subsequently, a
18 measure for the theophylline level was used to quantify the RTD using the spectral matched
19 filter (SMF) method which provides a highly selective response for the target analyte. A
20 measure for the moisture level was obtained for studying solid-liquid mixing using the band
21 ratio method (Fig. 2) (Vercruyse et al., 2013). The NIR chemical imaging measurement
22 setup and extraction of relevant information from chemical images was discussed in more
23 detail by Vercruyse et al. (2013) and is schematically shown by Kumar et al. (2014).

24 [Figure 2 about here.]

¹ 2.4. Experimental design

² 2.4.1. Experimental procedure

³ A full factorial experimental design was performed to evaluate the influence of screw
⁴ speed (500-900 rpm), material throughput (10-25 kg/h), L/S (6-8%), number (4, 6, 12) and
⁵ stagger angle (30°, 60°) of the kneading discs in the screw configuration on the RTD and
⁶ axial mixing of the material. Three center point experiments were performed as well, result-
⁷ ing in 48 + 3 = 51 experiments.

⁸

⁹ At the outlet of the granulator, the near infrared chemical imaging (NIR-CI) system was
¹⁰ used to measure solid-liquid mixing and the theophylline dynamics. A 25 s chemical imaging
¹¹ measurement without tracer injection for each design experiment (run) was used to measure
¹² the spatial distribution of the granulation liquid which was calculated using the band ratio
¹³ method explained in section 2.3. For the residence time measurements, anhydrous theo-
¹⁴ phylline (2% (w/w) of the material throughput per minute, corresponding to 3.33, 5.83 and
¹⁵ 8.33 g for throughputs of 10, 17.5 and 25 kg/h respectively) was spiked. Since it took 5 s for
¹⁶ the conveyor belt to move from below the granulator output to the location of the spectral
¹⁷ image collection, the chemical imaging measurements were started 5 s after injecting the
¹⁸ tracer (theophylline) for each experiment. Thus, the first frame of the spectral image cor-
¹⁹ responded to the instant of theophylline addition. The spatial distribution of theophylline
²⁰ during the 25 s measurement was calculated with the SMF method as explained in sec-
²¹ tion 2.3.

²²

²³ The intensity of the pixels in the obtained chemical map was thus proportional to the true
²⁴ moisture and theophylline levels. Hence, the moisture distribution and the RTD for each
²⁵ run was determined via inspecting the temporally scanned direction of the spectral image.

²⁶

¹ 2.4.2. *Estimation of RTD and axial mixing efficiency*

² Conventionally, a RTD is obtained by injecting a pulse of tracer into the system at the
³ inlet, and the residence time function, $e(t)$, is calculated as

$$e(t) = \frac{c(t)}{\int_0^\infty c(t)dt} \quad (1)$$

⁴ where $c(t)dt$ is the concentration of the tracer at the outlet between t and $t + \Delta t$. In this
⁵ study, the exit age distribution of the tracer molecule (theophylline) was derived from the
⁶ tracer concentration c_i (as estimated using the SMF method) between t and $t + \delta t$ in the
⁷ temporal profile of the discrete tracer map (top of Fig 2) calculated as

$$e(t) = \frac{c_i}{\sum_{i=1}^t c_i \Delta t} \quad (2)$$

⁸ This tracer map was transformed into the exit age distribution curve, i.e. the RTD based
⁹ on the mean tracer concentration, $e(t)$ between t and $t + dt$ (RTD plot in Fig 2), which was
¹⁰ then used to calculate the mean residence time \bar{t} as the ratio of the first and the zeroth
¹¹ moment using the following equation

$$\bar{t} = \frac{\int_0^\infty t \cdot e(t)dt}{\int_0^\infty e(t)dt} \quad (3)$$

¹² The RTD shape, was normalised as $e(\theta) = \bar{t} \cdot e(t)$, where dimensionless time $\theta = t/\bar{t}$ is
¹³ introduced. The degree of axial mixing in the granulator can be quantified by calculating
¹⁴ the dimensionless Péclet number Pe which represents the ratio of the rate of axial transport
¹⁵ by convection and axial transport by diffusion or dispersion. By treating the boundary
¹⁶ condition of the granulator as a closed system with no dispersion or radial variation in
¹⁷ concentration either upstream or downstream, the following equation can be derived (Fogler,

¹ 2006)

$$\frac{\sigma_t^2}{\bar{t}^2} \approx \frac{2Pe - 2 + 2 \cdot e^{-Pe}}{Pe^2} \quad (4)$$

² where, the σ_t^2 , which measures the width of the RTD, is calculated as:

$$\sigma_t^2 = \frac{\int_0^\infty (t - \bar{t})^2 \cdot e(t) dt}{\int_0^\infty e(t) dt} \quad (5)$$

³ and the σ_t^2/\bar{t}^2 in eq. 4 represents the normalised variance σ_θ^2 , which is the normalised second
⁴ central moment of the RTD curve. When σ_θ^2 approaches zero, Pe tends to infinity indicating
⁵ that the extent of axial mixing is low. Thus, when the Pe turns out to be large, the granulator
⁶ characteristics approach those of a plug-flow reactor (PFR). This regime is not favourable
⁷ in continuous processing as the existence of plug flow indicates poor axial mixing in the
⁸ granulator which is not desirable as discussed by Kumar et al. (2014). The study showed
⁹ that conditions leading to a greater extent of plug flow ultimately result in a complete
¹⁰ disruption due to jamming of the TSG.

¹¹ 2.4.3. Estimation of moisture distribution

¹² A large amount of chemical imaging data were collected resulting in spatio-temporal
¹³ moisture maps of wet granules for each experimental run (Fig. 2). The liquid-solid mixing
¹⁴ can be seen as a process in which a complex liquid exchange network between particles
¹⁵ of the processed material is generated. The pixel intensity values in the moisture maps
¹⁶ are indicative of this liquid exchange level or distribution. The statistical phenomena on
¹⁷ uncertainty of the pixel intensity at a randomly selected point on the moisture map can be
¹⁸ quantified as Shannon entropy (Guida et al., 2010) given as,

$$H(X) = \sum_{j=1}^n P(X_j) \log_{256}(1/P(X_j)) = - \sum_{j=1}^n P(X_j) \log_{256} P(X_j) \quad (6)$$

1 where X is the value of the pixel index j and n is total number of pixels in the moisture
2 map. The Shannon entropy, which is used in Information Theory, thus appears to be a useful
3 parameter for describing the mixing efficiency in a system (Guida et al., 2010). Since the
4 moisture maps were not calibrated for quantitative moisture content determination, entropy
5 was selected to evaluate the liquid distribution. Entropy only envisages the distribution itself
6 and not the values that pixel intensity may take. In this study, the logarithm to the base
7 256 was applied, as the 8-bit moisture map allows displaying the moisture distribution using
8 256 different intensities. Since a progression in mixing causes an increase in uncertainty
9 of pixel intensity transitions in the moisture map, a mixing index (MI) based on such an
10 uncertainty was defined as:

$$MI = -\frac{1}{\log_{256}(n)} \sum_{j=1}^n P(X_j) \log_{256} P(X_j) \quad (7)$$

11 The mixing index (MI) value lies between 0 and 1 indicating "no mixing" and "perfect mix-
12 ing" of the granulation liquid, respectively.

13
14 Since the MI is derived from the bulk solid-liquid mixing outcome, hereby completely
15 avoiding the dynamics of the mixing process which lead to variations in mean moisture con-
16 tent in the granules produced at different times, an additional method based on calculation
17 of frequency and amplitude of variations in the mean profile of the moisture content was
18 used to quantify the perturbations in the solid-liquid mixing (Fig. 3). A lowpass filter was
19 applied on the fast Fourier transform (FFT) of the mean moisture profile to remove noise
20 and only extract the main frequency and its amplitude value for every moisture mean profile
21 curve. An inverse FFT was then performed after the filtering to return to the time domain.
22 (Cooley and Tukey, 1965). An increase in either the frequency or corresponding amplitude,
23 indicated conditions leading to higher fluctuations.

1

[Figure 3 about here.]

2 *2.5. Quantification of effects and interactions of factors*

3 The factor effects upon the responses from the experimental design derived from the
4 CI-data and granule size measurements were estimated. Since multiple responses (\bar{t} , σ_θ^2 , Pe,
5 moisture entropy and GSD) were determined, it was helpful to fit a model simultaneously
6 representing the variation of all responses to the variation and interactions of the factors.
7 Therefore, using the Modde 10.1 software (Umetrics, Umeå, Sweden), partial least squares
8 (PLS) modelling taking all responses simultaneously into account, was employed.

9

10 The effect plots are used to display the change in the response (y-axis) when each process
11 factor (screw speed [RPM], material throughput [MFR], L/S [LSR], number of kneading
12 discs [NK] and stagger angle [SA]) varies from its low to its high level, keeping all other
13 factors at their center values of the interval (Fig.5 – 11). The y-axis indicates the estimated
14 effect which has a value of twice the corresponding coefficients of the regression model. For
15 each factor, the uncertainty of the effect is indicated by the 95% confidence interval error
16 bar. When an interaction effect prevails, the synergistic or antagonistic effect of one factor
17 depends on the level of another factor. The interaction effect represents the synergy or an-
18 tagonism between two factors in explaining a response. In these plots the effects of factors
19 on the response are sorted from the largest to the smallest. The factors and interaction
20 terms with insignificant effect (those where the confidence interval includes zero) were re-
21 moved from the model (Eriksson et al., 2000). Additionally, the interaction plot was used to
22 display the predicted change in the response when one factor varies, and the second factor is
23 set at both its low and high level, all other factors being set on their centre value. When in
24 such a plot the two lines are parallel one can conclude that there is no interaction between
25 the two factors, whereas when they cross each other there is a strong interaction. How-
26 ever, one should still be careful when interpreting the results, because sometimes, despite

- ¹ the interaction between the factors, their effect on the response may not be significant, i.e.
- ² resulting only in a minor variation of the response.

³ 3. Results and discussion

⁴ The performed design of experiments resulted in 51 residence time profiles (Fig. 4), and
⁵ solid-liquid mixing and granulation performance results (see the overview of the performed
⁶ experiments and obtained responses in the supplementary table S1). The power input
⁷ variation was indicated by the measured torque in the granulator drive and the granulation
⁸ time variation was expressed by the \bar{t} (Fig. 5). The variation in axial mixing was derived
⁹ from the width of the normalised RTD, i.e. the σ_θ^2 and the change in relative magnitude
¹⁰ of convective and dispersive transport capacities was given by Pe (Fig. 8). The change in
¹¹ solid-liquid mixing of the bulk material was quantified as effect on MI. The frequency and
¹² amplitude of the mean moisture profiles quantified the dynamics in the solid-liquid mixing
¹³ in the TSG (Fig. 10). To understand the role of process and screw design parameters on
¹⁴ granulation performance, it is important to first discuss the observed effects of the factors on
¹⁵ these responses (section 3.1-3.4). This will feed the detailed discussion to link granulation
¹⁶ time and mixing performance with the resulting granulation yield in the follow-up section 3.5.

¹⁷ [Figure 4 about here.]

¹⁸ 3.1. Change in torque at different process conditions

¹⁹ The torque of the granulator drive indicates the energy input to the granulation process
²⁰ by the motor drive. In this study, all the factors originating from the screw configuration
²¹ and process conditions had a significant influence on the measured torque level (Fig. 5). This
²² is in accordance with earlier studies on the effect of changing the process parameters on the
²³ torque level (Dhenge et al., 2010; Vercruyse et al., 2015; Kumar et al., 2014). An increase
²⁴ in the number of kneading discs most significantly increased the torque level and an increase

1 in L/S most significantly reduced the torque level. An increase in the material throughput
2 resulted in higher torque. However, the material throughput had a significant interaction
3 with L/S [LSR*MFR] (Fig. 6i). At a low material throughput increasing L/S resulted in
4 an increased torque, whereas at a high material throughput increasing L/S resulted in a
5 significant reduction in the torque. An increase in the screw speed led to a reduction of
6 the torque. However, due to the interaction between L/S and the screw speed [LSR*RPM],
7 a reduction in screw speed at a high L/S resulted in a sharp increase in the torque level
8 compared to low L/S (Fig. 6ii). Increasing stagger angle resulted in a reduction of torque.
9 However, this effect was found to be more pronounced at a low material throughput. At
10 high material throughput, an elevated flow restriction by increasing stagger angle resulted in
11 an increased torque level (Fig. 6iii). The interaction between the material throughput and
12 screw speed [MFR*RPM], which impacts the fill ratio, resulted in a reduction of the torque
13 when both screw speed and material throughput were increased simultaneously (Fig. 7i).
14 At a low material throughput, this interaction did not exist. The highest torque level (12.41
15 N.m) was observed at a throughput of 25 kg/h, L/S of 6%, screw configuration with 12
16 kneading discs at 60° and screw speed of 500 rpm. The torque level was lowest (0.38 N.m)
17 at a throughput of 25 kg/h, L/S of 8%, screw configuration with 4 kneading discs at 30° and
18 screw speed of 900 rpm.

19

20 [Figure 5 about here.]

21 These observations suggest that the load on the screws (based on screw speed and material
22 throughput) and the flow restriction (based on number of kneading discs and stagger angle)
23 dictate the torque level of the granulator drive. Besides, at low barrel fill ratio, i.e. when
24 the flow inertia is low, an increased moisture content at higher L/S causes sluggish flow and
25 consequently higher torque. However, at a high throughput when more material is present,
26 the inertial force is high and increasing L/S lubricates the granular flow leading to a reduc-

tion of the torque. The observed significant influence of all the factors on the torque level also suggests that the energy input to the system varied significantly for all the changes in process parameters. Thus, the studied experimental domain was suitable to investigate the effects of equipment and process parameters on other responses.

5

6 [Figure 6 about here.]

7 *3.2. Granulation time at different process conditions*

8 The granulation time in the TSG measured as \bar{t} was most influenced by the screw speed
9 and the number of kneading discs (Fig. 5). An increase in the screw speed resulted in a
10 lower \bar{t} , i.e. the RTD profiles consistently shifted to the left in Fig. 4, whereas an increase
11 in number of kneading discs led to an increase in the residence time. Increasing material
12 throughput resulted in a reduction in the \bar{t} , which was also observed in earlier studies (Ku-
13 mar et al., 2014; Dhenge et al., 2011). Additionally, \bar{t} was significantly reduced by the
14 interaction between material throughput and screw speed [MFR*RPM] (Fig. 7i). At a high
15 fill ratio (i.e., increasing throughput at low screw speed) this interaction effect was damp-
16 ened, but at lower fill ratio (i.e., increasing throughput at high screw speed), the \bar{t} reduced
17 significantly. An opposite effect on \bar{t} was detected when more kneading discs were included
18 in the screw configuration. An interaction between the number of kneading discs and the
19 material throughput [MFR*NK] resulted in a significant reduction in the \bar{t} when increasing
20 the material throughput at a lower number of kneading discs (Fig. 7ii). Similarly, due to a
21 significant interaction between the number of kneading discs and screw speed [NK*RPM],
22 the \bar{t} reduced when either the number of kneading discs was reduced at a low screw speed or
23 screw speed was increased at a high number of kneading discs. Interestingly, an increasing
24 L/S, which lowered the torque level of the granulator, resulted in an increase in \bar{t} . Although
25 the effect of change in L/S on \bar{t} was not very dominant, an increased sluggishness of powder

¹ at high L/S and elevated flow restriction at higher stagger angle interacted to raise the \bar{t} .
² The maximum \bar{t} (6.88 sec) was observed at a throughput of 25 kg/h, L/S of 8%, screw
³ configuration with 12 kneading discs at 60° and screw speed of 500 rpm. The minimum \bar{t}
⁴ (1.61 sec) was observed at a throughput of 10 kg/h, L/S of 8%, screw configuration with 4
⁵ kneading discs at 60° and screw speed of 900 rpm.

⁶

⁷ [Figure 7 about here.]

⁸ These results suggest that at a given process condition, the required residence time for
⁹ a good mixing and high granulation yield can mainly be achieved by either choosing the
¹⁰ number of kneading discs in the screw configuration before starting the granulation process
¹¹ or by changing the screw speed during the process. Also, the reduction in \bar{t} at low fill ratio
¹² indicates a synergy between throughput force and the drag force in the mixed flow condition.
¹³ The lowering of torque level at a high L/S despite an increase in \bar{t} , i.e. more material inside
¹⁴ the granulator, confirms that the granulation liquid at high fill ratio had a lubricating effect
¹⁵ on the screw rotation without increasing the conveying rate.

¹⁶

¹⁷ *3.3. Mixing at different process conditions*

¹⁸ *3.3.1. Axial mixing*

¹⁹ The axial mixing during the bulk flow inside the granulator was quantified as σ_θ^2 and Pe
²⁰ (Fig. 8). Increasing the screw speed resulted in an increase in σ_θ^2 , whereas a higher number of
²¹ kneading discs resulted in reduced σ_θ^2 . Visually this is reflected in a broadening of the RTD
²² with increasing screw speed (Fig. 4). The opposite effect on the RTD profile was observed
²³ with increasing number of kneading discs. Similar results were also obtained in our previous
²⁴ experimental and model-based study (Kumar et al., 2014, 2015). Besides, an interaction
²⁵ between material throughput and the screw speed was observed such that increasing the

¹ screw speed at a high material throughput, i.e. lowering the fill ratio, resulted in a high σ_θ^2
² (Fig. 7i). However, keeping the material throughput at a high level when the screw speed
³ was reduced resulted in a lower σ_θ^2 compared to the condition with low throughput and low
⁴ screw speed. The largest σ_θ^2 (0.84) was observed at a throughput of 25 kg/h, L/S of 6%,
⁵ screw configuration with 4 kneading discs at 60° and screw speed of 900 rpm. In contrast,
⁶ the minimum σ_θ^2 (0.05) was observed at a throughput of 25 kg/h, L/S of 8%, screw config-
⁷ uration with 12 kneading discs at 60° and screw speed of 500 rpm.

⁸
⁹ Beside σ_θ^2 quantifying mainly dispersive transport, the Pe, which is the ratio of convec-
¹⁰ tive to dispersive transport in a system, was also directly influenced by the screw speed and
¹¹ the number of kneading discs. An increase in the screw speed resulted in the dominance of
¹² dispersive over convective transport phenomena, whereas the opposite effect was observed
¹³ for increasing the number of kneading discs. Also, similar to σ_θ^2 , the interaction between
¹⁴ material throughput and the screw speed resulted in a fast reduction in Pe, i.e. dispersive
¹⁵ transport increased when the screw speed was increased at a high throughput (Fig. 7i). This
¹⁶ similarity in the effect of different factors on σ_θ^2 and Pe suggests that the dispersive trans-
¹⁷ port change was significantly larger than the convective transport change when variations
¹⁸ in the factors were introduced. At a low throughput, i.e. lower barrel filling, the observed
¹⁹ increase in dispersive transport was lower compared to a high material throughput. Due
²⁰ to a significant interaction between stagger angle and screw speed, increasing screw speed
²¹ resulted in a rapid decline in Pe at higher stagger angle (60°) compared to lower stagger
²² angle (30°).

²³
²⁴ The largest Pe (36.66) was observed at a throughput of 25 kg/h, L/S of 8%, screw con-
²⁵ figuration with 12 kneading discs at 60° and screw speed of 500 rpm. In contrast, the
²⁶ minimum Pe (0.55), which is lower than 1 indicating that the dispersive transport length

¹ was longer than the barrel size and exceeded the convective transport within the granulator
² barrel was observed at a throughput of 25 kg/h, L/S of 6%, screw configuration with 4
³ kneading discs at 60° and screw speed of 900 rpm.

⁴

⁵ [Figure 8 about here.]

⁶ These observations suggest that the flow regime inside the granulator is controlled both by
⁷ the screw design and the process conditions. Due to the change in the hindrance to the
⁸ axial flow by the fully filled zones around the kneading discs, dispersive transport was less
⁹ efficient for a high number of kneading discs. Increasing the throughput force and drag force
¹⁰ by the increasing material throughput and screw speed simultaneously and consequently a
¹¹ low fill ratio led to an increase in the wall slippage resulting in more axial mixing in the TSG.

¹²

¹³ *3.3.2. Solid-liquid mixing*

¹⁴ The solid-liquid mixing in the bulk mixture was quantified as MI and its dynamics during
¹⁵ continuous granulation were quantified as frequency and amplitude of the mean moisture
¹⁶ profile of each run. According to the effect plot for the MI, the bulk mixing was most sig-
¹⁷nificantly reduced by the increase in material throughput (Fig. 10). In contrast, increasing
¹⁸ the number of kneading discs significantly increased the bulk mixing, which is reflected by
¹⁹ an increase in the mixing index. Also the throughput and the number of kneading discs
²⁰ interacted [MFR*NK] significantly leading to an increase in the MI at a high throughput by
²¹ the increasing number of kneading discs (Fig. 7ii). Additionally, MI increased significantly
²² at a high L/S. The effect of a change in L/S also had significant interaction with the changes
²³ in material throughput. An increase in the material throughput at low L/S resulted in a
²⁴ lower MI than when a high L/S is applied. The effect of a change in the screw speed was
²⁵ not significant on the MI but its interaction with the change in the number of kneading

1 discs resulted in a significant reduction in MI when the screw speed was increased at a high
2 number of kneading discs (Fig. 9i). The stagger angle did not affect the MI significantly.
3 The highest MI (0.39) was observed at a throughput of 25 kg/h, L/S of 8%, screw configu-
4 ration with 12 kneading discs at 30° and screw speed of 500 rpm. In contrast, the minimum
5 MI (0.13) was observed at a throughput of 25 kg/h, L/S of 8%, screw configuration with 4
6 kneading discs at 60° and a screw speed of 900 rpm.

7

8 [Figure 9 about here.]

9 The effect plot for the frequency of mean moisture profile showed that, similar to the bulk
10 mixing, increasing the material throughput increased the frequency of the mean moisture
11 profile, i.e. indicating inferior solid-liquid mixing. The opposite effect occurred when the
12 number of kneading discs increased (Fig. 10). Also, an interaction between the through-
13 put and number of kneading discs [MFR*NK] significantly influenced MI. An increase in
14 the material throughput at a high number of kneading discs resulted in an increase in the
15 frequency, thus more variations in the dynamic profile, which is opposite to the observa-
16 tion for the bulk mixing as indicated by MI (Fig. 7ii). Additionally, due to a significant
17 interaction between the material throughput and stagger angle [MFR*SA], the frequency
18 of the mean moisture profile increased more rapidly by the increasing throughput at a high
19 stagger angle (60°) compared to a low stagger angle (30°) between kneading discs (Fig. 6iii).
20 Moreover, the interaction between the stagger angle and number of kneading discs in the
21 screw configuration at a low number of kneading discs resulted in an increase in frequency
22 when the stagger angle was increased. The opposite was observed when the stagger angle
23 was increased at a high number of kneading discs. The change in L/S, screw speed and
24 stagger angle had no significant effect on the variation frequency.

25

26 The effect plot for the amplitude of the mean moisture profile also showed that similar

1 to the bulk mixing, the material throughput most significantly resulted in a decrease in the
2 degree of variation. However, an increase in the number of kneading discs, screw speed and
3 stagger angle equally resulted in an increase in the variation and, hence, a higher amplitude.
4 A high L/S caused a reduction in the extent of fluctuation, i.e. a lower amplitude. Due to
5 the interaction between the material throughput and L/S [MFR*LSR], an increase in the
6 L/S resulted in a lower amplitude when the material throughput was increased.

7

8 These results suggest that although a high material throughput and a high screw speed
9 are desired for process efficiency, their exclusive increase may cause inefficient solid-liquid
10 mixing which will result in an inferior granulation yield. Similarly, an increase in the num-
11 ber of kneading discs should be considered to obtain good solid-liquid mixing by reducing
12 both the rate and degree of variations in the moisture content of the granules. Also, at
13 a higher L/S, bulk mixing is better and the degree of variation is less, indicating that a
14 proper amount of liquid addition is also required for good distribution of the liquid during
15 granulation. However, this improvement in solid-liquid mixing at high L/S also suggests an
16 active role of the pumping rate on the solid-liquid mixing. The effects of fluctuating pres-
17 sure and variation in the fluid flow by the peristaltic pump can be better compensated by the
18 axial mixing as this variation period is much smaller (i.e., high frequency) compared to the
19 residence time of the material in the TSG. In contrast, granulation liquid inflow variations
20 at a low frequency cannot be easily compensated by the axial mixing due to the small resi-
21 dence time of the material in the TSG. Similar significant variations in the moisture content
22 distribution were earlier observed by Vercruyse et al. (2013), and are thus critical to the
23 granulator design.

24 [Figure 10 about here.]

¹ 3.4. GSD at different process conditions

² In order to understand the effect of each factor on the GSD, the sieved granules were
³ classified in three fractions (fine (<150 µm), yield (150-1400 µm) and oversized (>1400 µm))
⁴ (Fig. 11). An increase in L/S and number of kneading discs resulted in a lower amount of
⁵ fines in the produced granules. On the other hand, an increase in the stagger angle and
⁶ screw speed led to more fines in the granules. Although material throughput independently
⁷ had no significant influence on the fines fraction, a significant interaction between material
⁸ throughput and the number of kneading discs [MFR*NK] resulted in a more rapid reduction
⁹ in the amount of fines with increasing number of kneading discs at high throughput (Fig. 7ii).
¹⁰ Also, the two factors with an opposite effect on fines i.e., the number of kneading discs and
¹¹ the screw speed interacted significantly [NK*RPM]. The amount of fines at a low number
¹² of kneading discs and a high screw speed was less, but the opposite was observed when
¹³ high screw speed was applied along with a high number of kneading discs (Fig. 9i). The
¹⁴ maximum amount of fines (55.0% when the yield and oversized fractions were 42.0 and 3.0 %
¹⁵ respectively) was observed at a throughput of 10 kg/h, L/S of 6%, screw configuration with
¹⁶ 12 kneading discs at 30° and a screw speed of 900 rpm. In contrast, the smallest amount of
¹⁷ fines (4.9% when the yield and oversized fractions were 41.7 and 53.4 % respectively) was
¹⁸ observed at a throughput of 25 kg/h, L/S of 8%, screw configuration with 12 kneading discs
¹⁹ at 30° and a screw speed of 500 rpm.

²⁰ The yield fraction was most significantly influenced by the screw speed and the material
²¹ throughput (Fig. 11). A higher screw speed resulted in an increase of the yield fraction,
²² whereas increasing the material throughput resulted in a reduction of the yield fraction.
²³ Additionally, an increase in stagger angle resulted in a reduction in the yield fraction and
²⁴ the opposite was observed when L/S was increased. A strong interaction between the num-
²⁵ ber of kneading discs and the screw speed resulted in a decrease in the yield fraction when
²⁶ the number of kneading discs was increased at a high screw speed (Fig. 9i). The yield frac-

tion increased when the number of kneading discs was increased at low screw speed. This indicates that an increase in the mechanical shear beyond a certain extent is not favourable to the granulation yield. Similarly, due to interaction between material throughput and number of kneading discs [MFR*NK], more yield fraction granules were produced when the number of kneading discs was increased at high throughput (Fig. 7ii). The change in yield fraction was also influenced by the interaction of material throughput with stagger angle and screw speed. Increasing the throughput at lower stagger angle resulted in a drastic reduction in the yield fraction (Fig. 6iii). Increasing the screw speed at a low throughput increased the yield fraction more than operation at a high throughput (Fig. 7i). The highest yield fraction (62.9% when the fines and oversized fractions were 18.8 and 18.2 % respectively) was observed at a throughput of 25 kg/h, L/S of 6%, screw configuration with 12 kneading discs at 60° and a screw speed of 500 rpm. In contrast, the lowest yield fraction (41.7% when the fines and oversized fractions were 4.9 and 53.4 % respectively) was observed at a throughput of 25 kg/h, L/S of 8%, screw configuration with 12 kneading discs at 30° and a screw speed of 500 rpm.

The effect plot for the oversized fraction shows that the additional liquid at a high L/S significantly increased the amount of oversized granules (Fig. 11). Similarly, increasing the number of kneading discs and the material throughput also resulted in increased production of oversized granules. This suggests ineffective mixing by the kneading discs despite an increase in the number of kneading discs. However, increasing stagger angle and screw speed lowered the oversized fraction. An interaction between L/S and stagger angle resulted in a rapid increase in the oversized fraction at low L/S when the stagger angle was reduced from 60° to 30° (Fig. 9ii). Additionally, the interaction between L/S and screw speed resulted in a reduction in the oversized fraction at high L/S when the screw speed was increased (Fig. 6ii). The highest fraction of oversized granules (53.4% when the fines and yield frac-

¹ tions were 4.9 and 41.7 % respectively) was observed at a throughput of 25 kg/h, L/S of
² 8%, screw configuration with 12 kneading discs at 30° and a screw speed of 500 rpm. The
³ smallest oversized granule fraction (3% when the fines and yield fractions were 55.0 and 42.0
⁴ % respectively) was observed at a throughput of 10 kg/h, L/S of 6%, screw configuration
⁵ with 12 kneading discs at 30° and a screw speed of 900 rpm.

⁶ [Figure 11 about here.]

⁷ *3.5. Link between granulation time, mixing and yield*

⁸ The purpose of granulation process design and optimisation is to maximize the process
⁹ efficiency, i.e. maximising the yield fraction. The results discussed so far (section 3.1 - 3.4)
¹⁰ suggest a correlation between the granulation time, mixing and the GSD. This was also
¹¹ reflected by the PLS loadings plot (Fig. 12). The measured torque of the granulator drive
¹² indicating power input to the system, Pe quantifying the axial mixing, MI quantifying the
¹³ solid-liquid mixing and \bar{t} quantifying average time spent by the material inside the granu-
¹⁴ lator are positively correlated as can be seen in the loadings plot. On the other hand, all
¹⁵ the three size fractions (fine, yield and oversized granules) are located in different regions
¹⁶ suggesting that they have different important contributing factors. Moreover, the desired
¹⁷ condition for the responses such as a high residence time, a good axial as well as solid-liquid
¹⁸ mixing and resulting high yield fraction are favoured by different factors. Therefore, the
¹⁹ connections between different factors and responses requires detailed discussion.

²⁰

²¹ [Figure 12 about here.]

²² As discussed in the introduction, due to the short residence time, the major challenge
²³ in twin-screw wet granulation is to achieve proper solid-liquid mixing in the shortest dis-
²⁴ tance along the granulator screw to allow more time for other constitutive mechanisms of

1 granulation to shape the final distribution. For this purpose, kneading discs were used in
2 the TSG which improved solid-liquid mixing both by increasing the bulk mixing and reduc-
3 ing the frequency of deviations in the moisture content of the granules (Fig. 10). A high
4 number of kneading discs also resulted in a relatively longer residence time. Despite this im-
5 provement in mixing and time, increasing the number of kneading discs did not significantly
6 contribute to an increased yield fraction (Fig. 11). Additionally, increasing the L/S had no
7 significant contribution to increasing the desired yield fraction since most of the additional
8 liquid resulted in the formation of oversized granules. This evidently indicates that despite
9 the contribution of kneading discs in the solid-liquid mixing, the required quality of mixing
10 inside the TSG barrel was still not achieved. Since the highest torque level (12.4 N.m) was
11 also observed by the screw configuration with 12 kneading discs at 60° and a screw speed
12 of 500 rpm, further increase in the number of kneading discs will for sure increase the bulk
13 mixing, but on the other hand significantly limit the operational ranges of the process set-
14 tings. Therefore, more efforts should be done to modify the TSG screw configuration both
15 using conventional (conveying and kneading elements) as well as non-conventional screw el-
16 ements with modified geometries to improve the solid-liquid mixing (Vercruyse et al., 2015;
17 Sayin et al., 2015; Meier et al., 2015). Moreover, the liquid feeding system in the TSGs
18 should be improved to prevent variations in granulation liquid inflow with a period larger
19 than the mean residence time of the material as discussed earlier in section 3.3.2. Instead of
20 peristaltic pumps which are being used currently and cause pulsating flow, a constant flow
21 pump, such as dual piston pump, should be used.

22
23 Increasing the screw speed not only lowered the torque, allowing greater flexibility in choos-
24 ing process settings but also most significantly increased the yield fraction of the granules
25 despite smaller \bar{t} . However, mixing at a high screw speed was more dispersive as indicated
26 by Pe than the bulk mixing indicated by MI (Fig. 8 and 10). Due to this, the fines fraction

1 increased as well. Increasing the material throughput (which will be the ultimate target in
2 industrial production) quickly changed the flow regime inside the granulator which conse-
3 quently reduced the yield fraction. Moreover, beside reducing the axial mixing, an increasing
4 material throughput also reduced the bulk mixing which was mostly driven by the distribu-
5 tive mixing by the kneading discs. Since the number of kneading discs significantly interacts
6 both with material throughput and screw speed, keeping the number of kneading discs at
7 a fixed level, a balance between material throughput and screw speed should be strived for
8 in order to achieve the required granulation time, axial mixing and solid-liquid mixing for
9 a high granulation yield. Moreover, although increasing stagger angle had a negative effect
10 on yield fraction, since increasing the stagger angle and screw speed simultaneously, lowered
11 both fines and the oversized fraction in the granules produced, the higher stagger angle (60°)
12 should be used in the screw configuration.

13

14 Additionally, considering the inability of experimental studies in visualising and measur-
15 ing the effects of screw configuration and elements on powder flow, mixing and granulation
16 rate processes at particle-scale, further studies based on application of mechanistic mod-
17 elling tools, such as discrete element simulations and population balance modelling should
18 be performed to improve the understanding of the governing constitutive mechanisms of the
19 twin-screw wet granulation process. These mechanistic tools can also be used for exploring
20 the effect of changes in the granulator screw design and the liquid addition strategy for an
21 improvement in the liquid distribution and consequently obtaining a higher wet granulation
22 yield.

23

¹ **4. Conclusions**

² NIR chemical imaging was shown to be an adequate tool for simultaneous characteri-
³ sation of the material flow, axial mixing and bulk mixing analysis during twin-screw gran-
⁴ ulation. This also allowed investigating the effect of RTD and solid-liquid mixing on the
⁵ resulting GSD to better understand the overall influence on different flow and mixing condi-
⁶ tions. According to the study, an interaction between screw speed, the material throughput,
⁷ liquid-to-solid ratio, number of kneading discs and stagger angle led to variation in the res-
⁸ idence time as well as mixing capacity. At a high screw speed, despite high axial mixing
⁹ leading to reduction of the oversized ($>1400 \mu\text{m}$) fraction and a higher yield fraction, a
¹⁰ low residence time resulted in increase in the fine ($<150 \mu\text{m}$) fraction. Similarly, increasing
¹¹ L/S led to more oversized granules, which increased further at higher throughput. This
¹² indicated insufficient solid-liquid mixing capacity of the current kneading discs which is ulti-
¹³ mately required for good granulation performance. Similarly, at high throughput improper
¹⁴ solid-liquid mixing resulted in more oversized particles. Thus, a balance between material
¹⁵ throughput and screw speed should be looked for to achieve the required granulation time
¹⁶ and solid-liquid mixing for high granulation yield. Additionally, more efforts should be done
¹⁷ both to modify the screw configuration as well as geometry of the mixing elements to improve
¹⁸ the mixing capacity of the TSG. The results from this experimental study improved the un-
¹⁹ derstanding regarding the interplay between granulation time, the axial and the solid-liquid
²⁰ mixing responsible for the granulation yield. However, only empirical qualitative insight is
²¹ gained, not detailed quantitative insight. Therefore, application of mechanistic modelling
²² tools, such as discrete element simulations and population balance modelling, needs to be
²³ further explored for further detailed investigation of material flow and mixing and their
²⁴ impact on granulation yield during twin-screw granulation.

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24	6	Predicted changes in the responses due to interaction (i) between the liquid- 25 to-solid ratio (L/S) and material throughput [MFR*LSR], (ii) between the 26 liquid-to-solid ratio (L/S) and screw speed [LSR*RPM] and (iii) between the 27 material throughput and stagger angle [MFR*SA] in the screw configuration.	38
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31	8	Effects plots showing predicted changes in the mean centered variance [N=46; 32 DF=39; R ² =0.87] and Péclet number [N=43; DF=35; R ² =0.84] when factors, 33 number of kneading discs (NK) [4, 6, 12], screw speed (RPM) [500-900 rpm], 34 throughput (MFR) [10-25 kg/h], liquid-to-solid ratio (LSR) [6-8%] and stag- 35 ger angle (SA) [30-60°], vary from a low to a high level, while keeping the 36 other factors at their center point value (confidence level=0.95).	40
37	9	Predicted changes in the responses due to interaction (i) between number 38 of kneading discs and screw speed [NK*RPM], and (i) between liquid-to- 39 solid ratio and stagger angle between kneading discs [LSR*SA] in the screw 40 configuration.	41

1	10	Effects plots showing predicted changes in the Shannon entropy based mixing index (MI) [N=43; DF=34; R2=0.80], frequency [N=41; DF=32; R2=0.84] and amplitude [N=45; DF=38; R2=0.88] of the mean moisture profiles when factors, number of kneading discs (NK) [4, 6, 12], screw speed (RPM) [500-900 rpm], throughput (MFR) [10-25 kg/h], liquid-to-solid ratio (LSR) [6-8%] and stagger angle (SA) [30-60°], vary from a low to a high level, while keeping the other factors at their center point value (confidence level=0.95).	42
2	11	Effects plots showing predicted changes in the fines (>150 µm) [N=49; DF=39; R2=0.93], yield [150-1400 µm] [N=38; DF=28; R2=0.84] and oversized (>1400 µm) [N=47; DF=38; R2=0.92] fractions of the resulting GSD produced when factors, number of kneading discs (NK) [4, 6, 12], screw speed (RPM) [500-900 rpm], throughput (MFR) [10-25 kg/h], liquid-to-solid ratio (LSR) [6-8%] and stagger angle (SA) [30-60°], vary from a low to a high level, while keeping the other factors at their center point value (confidence level=0.95).	43
3	12	Scatter plot with PLS loadings of the two first model dimensions	44

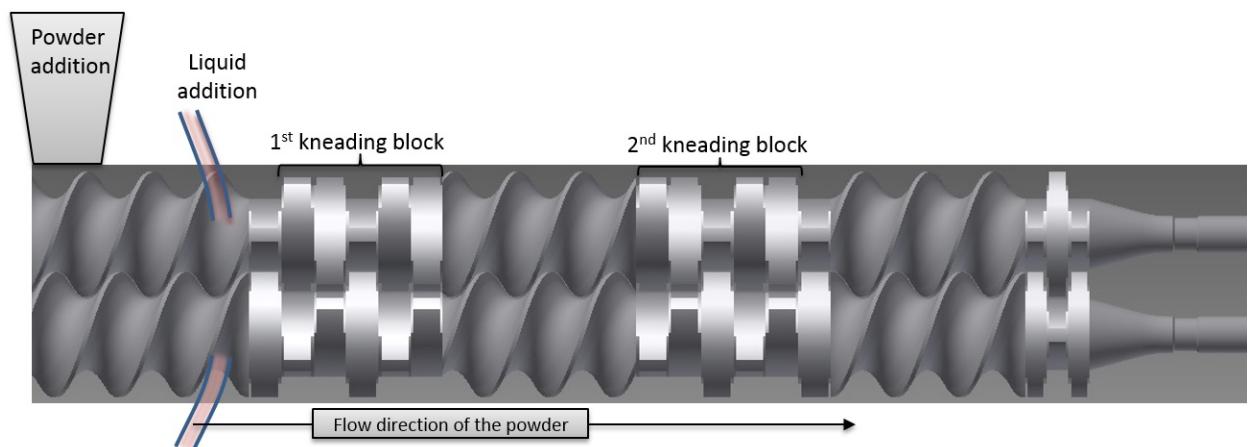


Figure 1: Screw configuration with 12 kneading discs (2 blocks) used in the twin-screw granulator during the study.

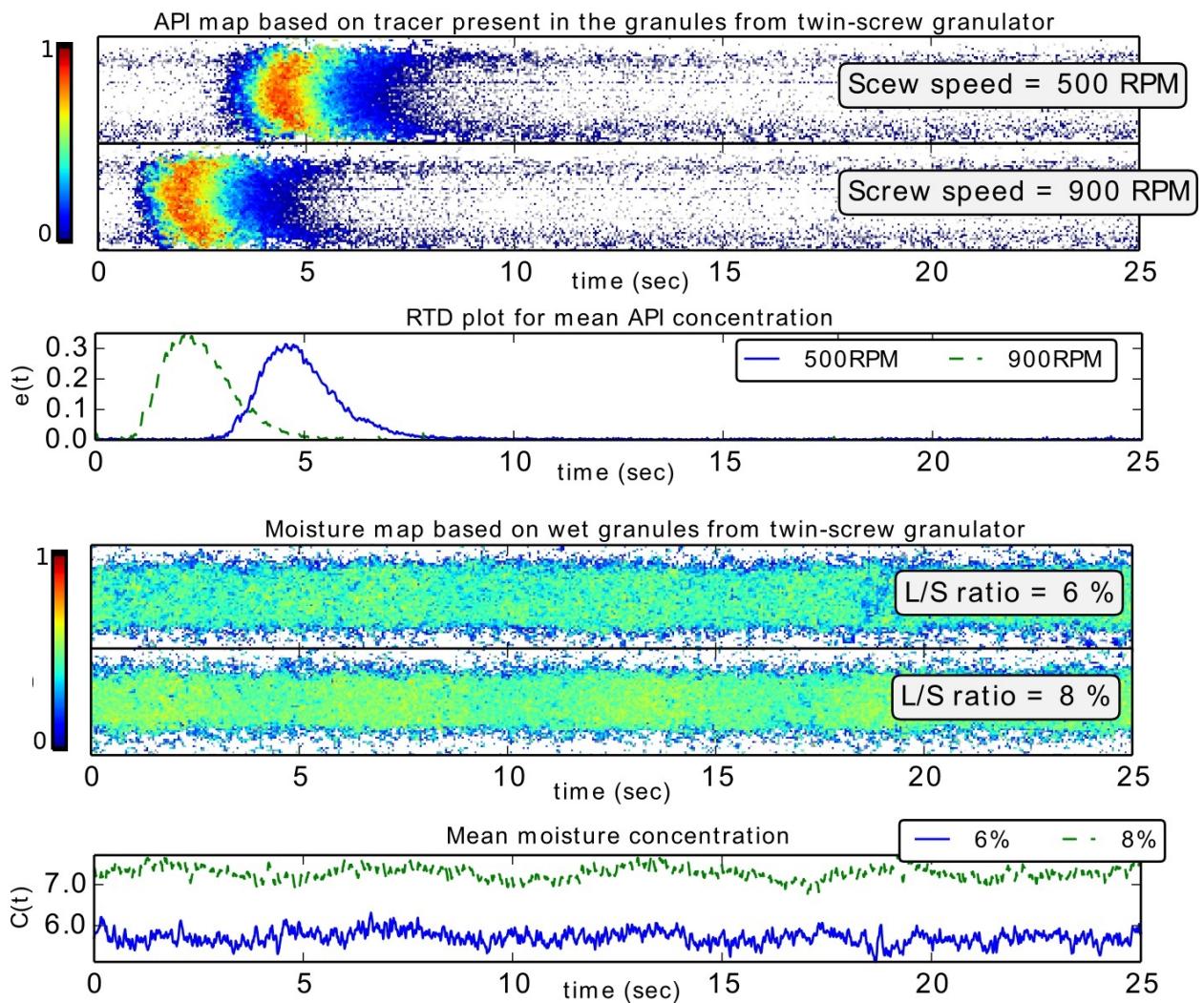


Figure 2: Representation of an active pharmaceutical ingredient (API)-map and a moisture map, the corresponding mean temporal profile, which were translated into the corresponding residence time distribution and moisture distribution for the twin screw granulator at fixed material throughput (25 kg/h), number of kneading discs (6), stagger angle (60°) and different screw speeds.

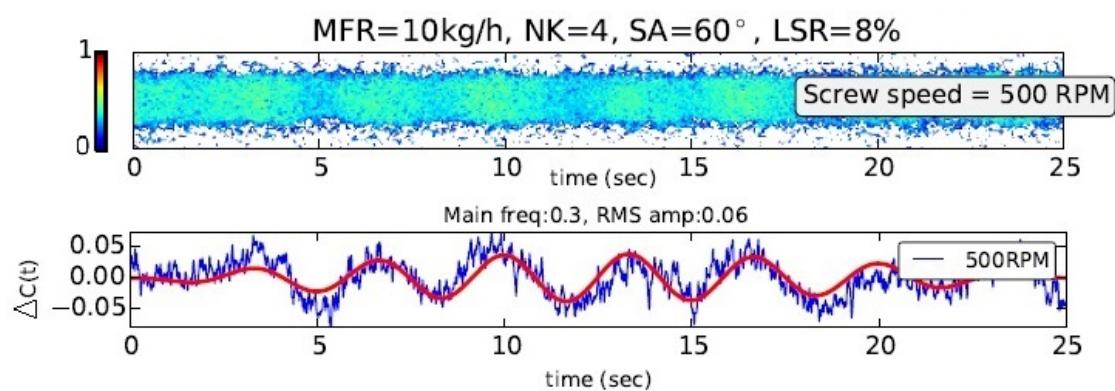


Figure 3: The FFT algorithm was used to remove noise from the mean moisture profiles, allowing the identification of the most dominant frequency band and corresponding amplitude.

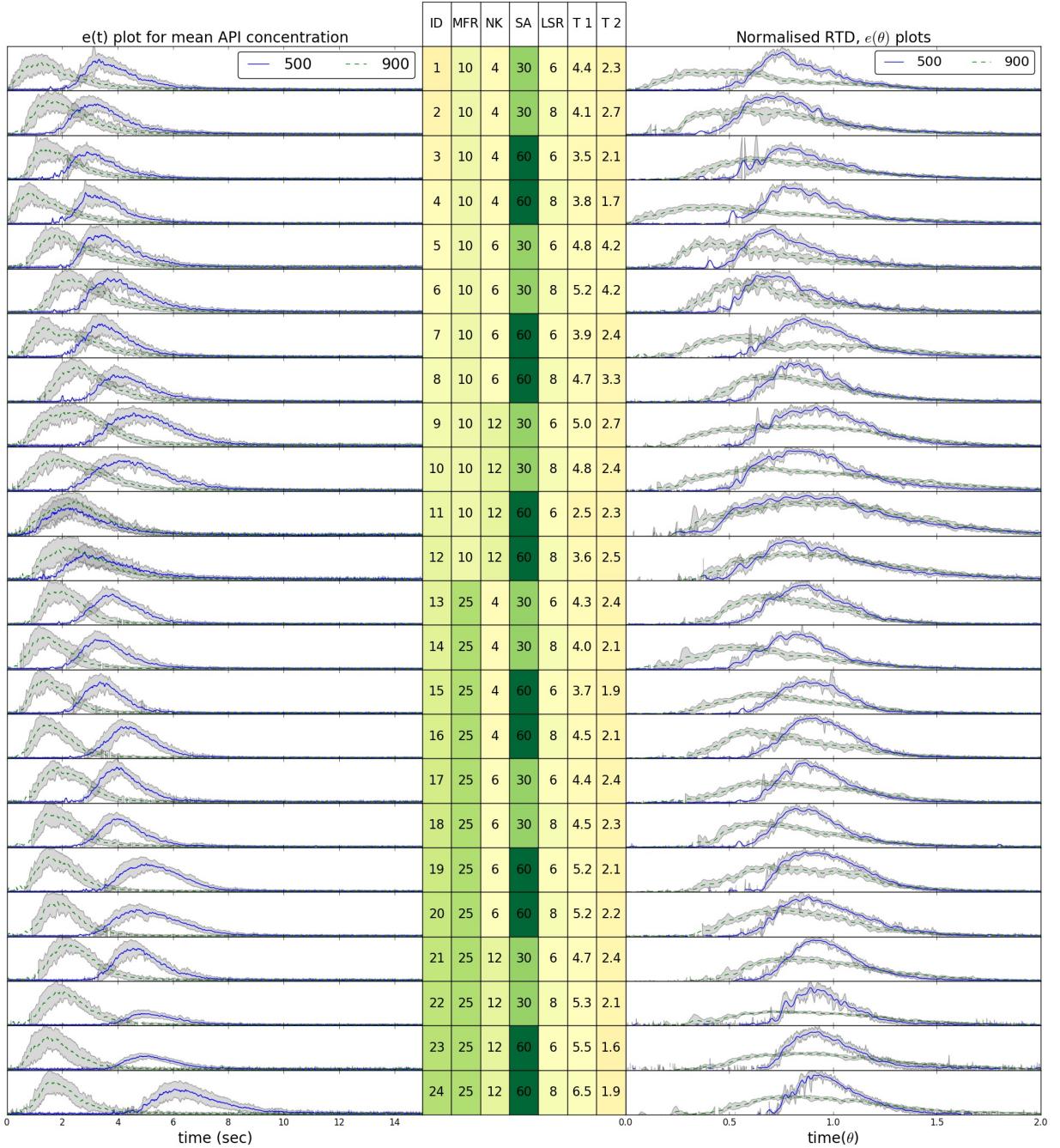


Figure 4: The age distribution (left) and normalised RTD (right) profiles with a shaded region denoting the standard deviation at different screw speed (500, 900 RPM) during various experiments (ID) using twin screw granulation [SA: stagger angle ($^{\circ}$), NK: number of kneading discs (-), MFR: material throughput (kg/h), LSR: liquid-solid ratio (%), T 1: mean residence time at 500 RPM (s), T 2: mean residence time at 900 RPM (s)].

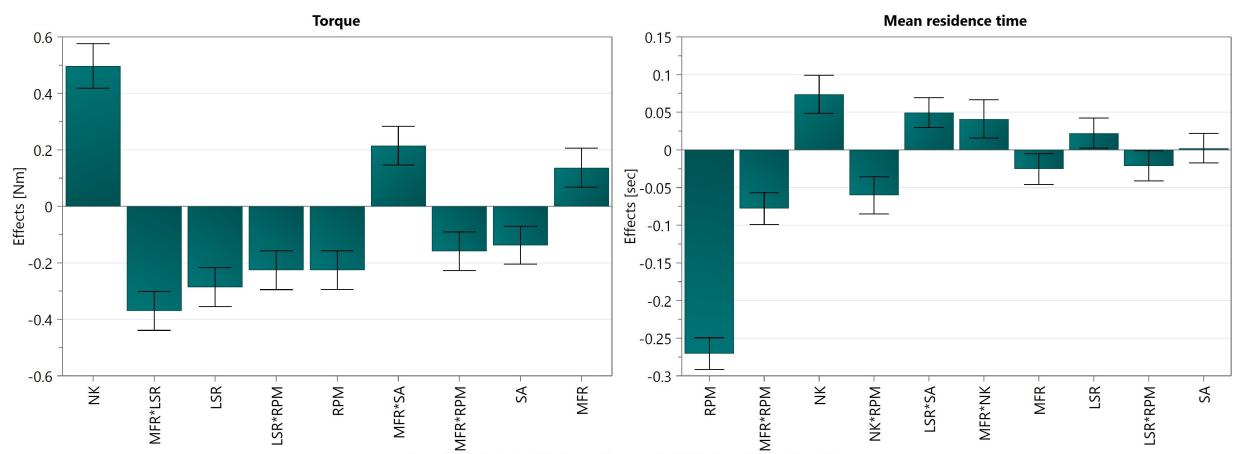
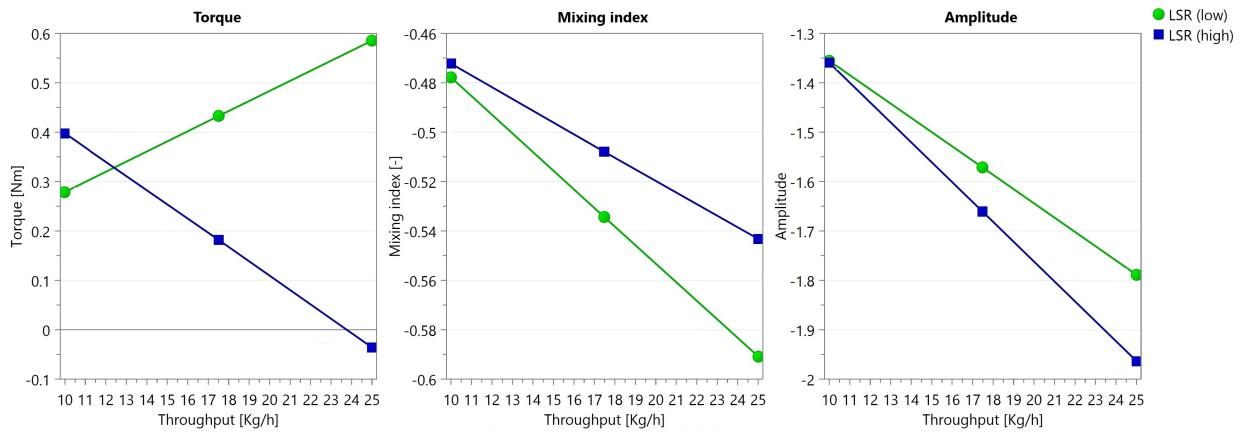
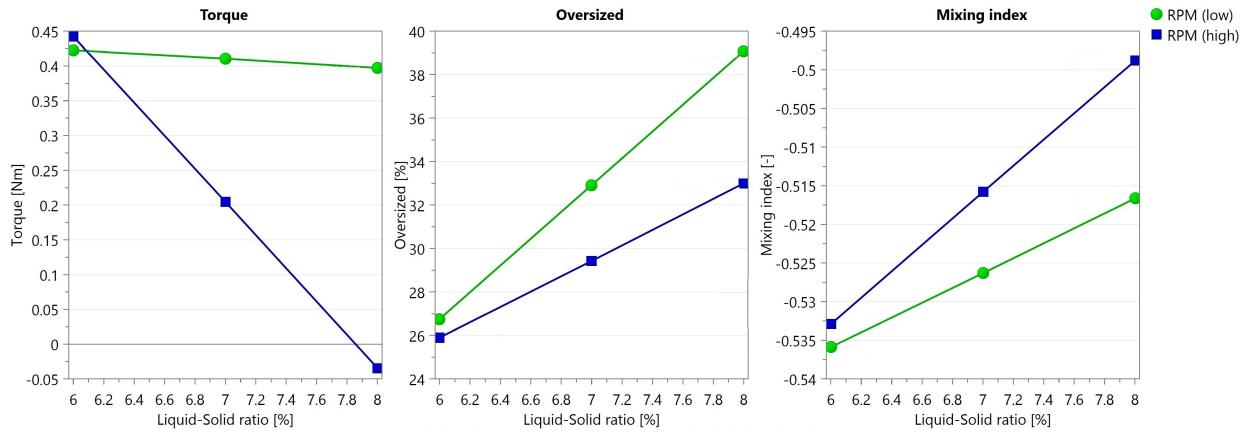


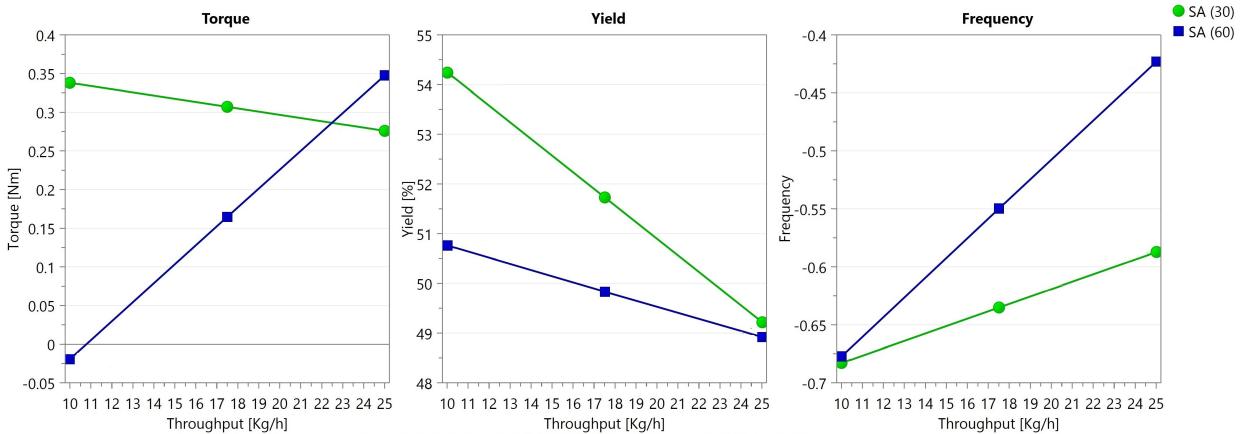
Figure 5: Effects plots showing predicted changes in the measured torque [N=42; DF=32; R²=0.95] and mean residence time [N=41; DF=30; R²=0.97] when factors, number of kneading discs (NK) [4, 6, 12], screw speed (RPM) [500-900 rpm], throughput (MFR) [10-25 kg/h], liquid-to-solid ratio (LSR) [6-8%] and stagger angle (SA) [30-60°], vary from the low to the high level, while keeping the other factors at their center point value (confidence level=0.95).



(i) Predicted changes in the measured torque, MI and amplitude of the mean moisture profile.

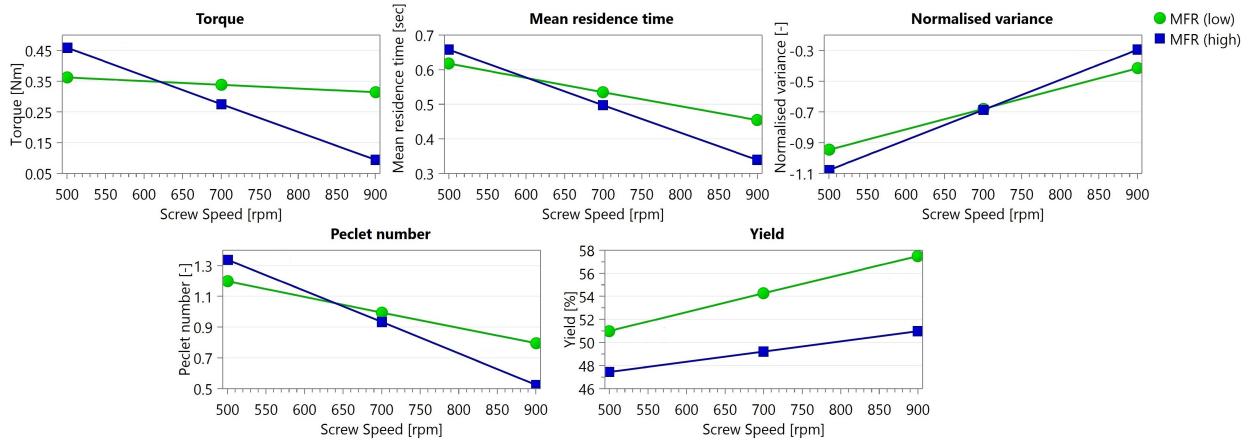


(ii) Predicted changes in the measured torque, oversized fraction of granules (>1400 µm) and mixing index (MI).

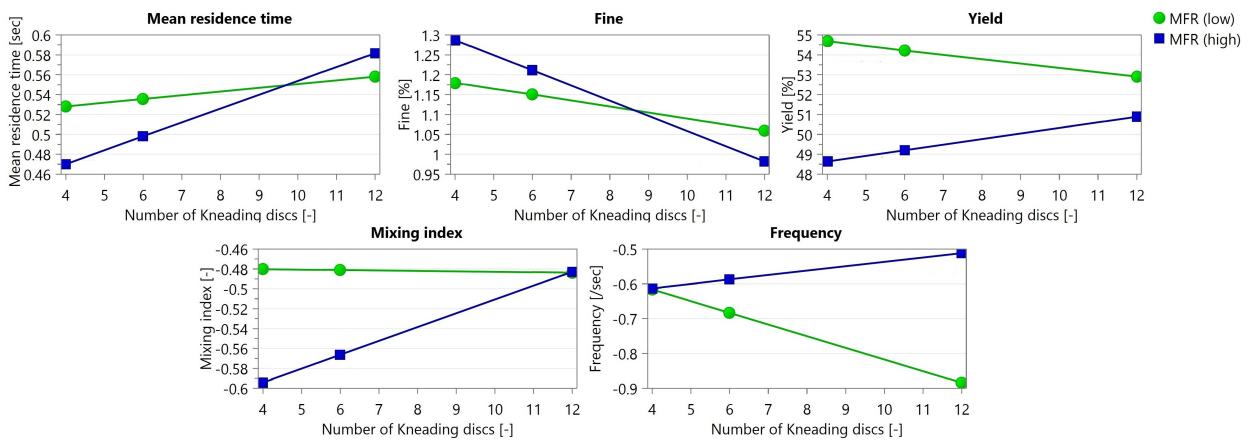


(iii) Predicted changes in the measured torque, yield fraction (>150µm to <1400 µm) of granules and frequency of the mean moisture profile.

Figure 6: Predicted changes in the responses due to interaction (i) between the liquid-to-solid ratio (L/S) and material throughput [MFR*LSR], (ii) between the liquid-to-solid ratio (L/S) and screw speed [LSR*RPM] and (iii) between the material throughput and stagger angle [MFR*SA] in the screw configuration.



(i) Predicted changes in the measured torque, mean residence time, Pe and yield fraction ($>150 \mu\text{m}$ to $<1400 \mu\text{m}$) of granules, mixing index (MI) and frequency of the mean moisture profiles.



(ii) Predicted changes in the mean residence time, and fine ($<150 \mu\text{m}$) and yield fractions ($>150 \mu\text{m}$ to $<1400 \mu\text{m}$) of granules.

Figure 7: Predicted changes in the responses due to interaction (a) between the material throughput and screw speed [MFR*RPM] and (b) between material throughput and number of kneading discs [MFR*NK] in the screw configuration.

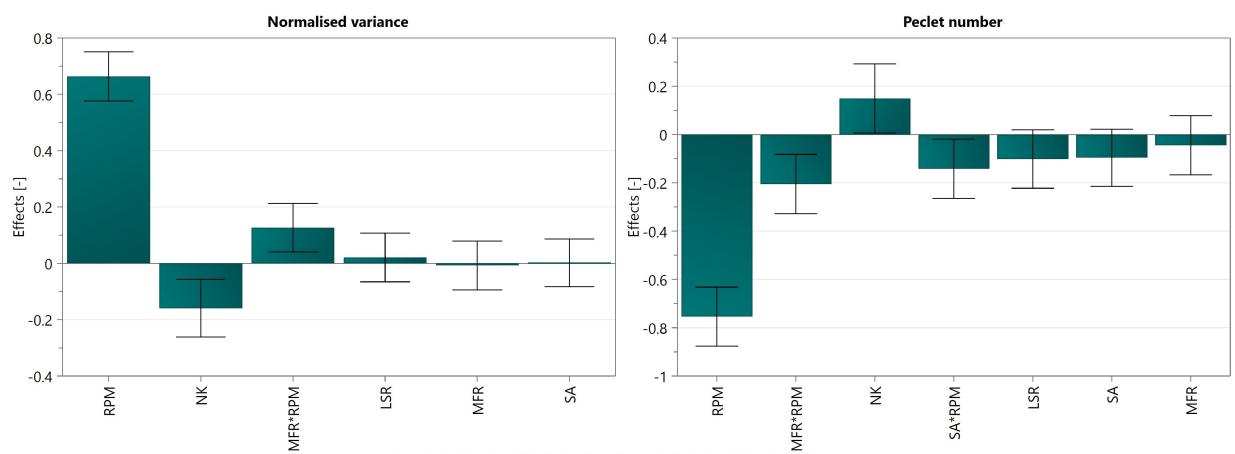
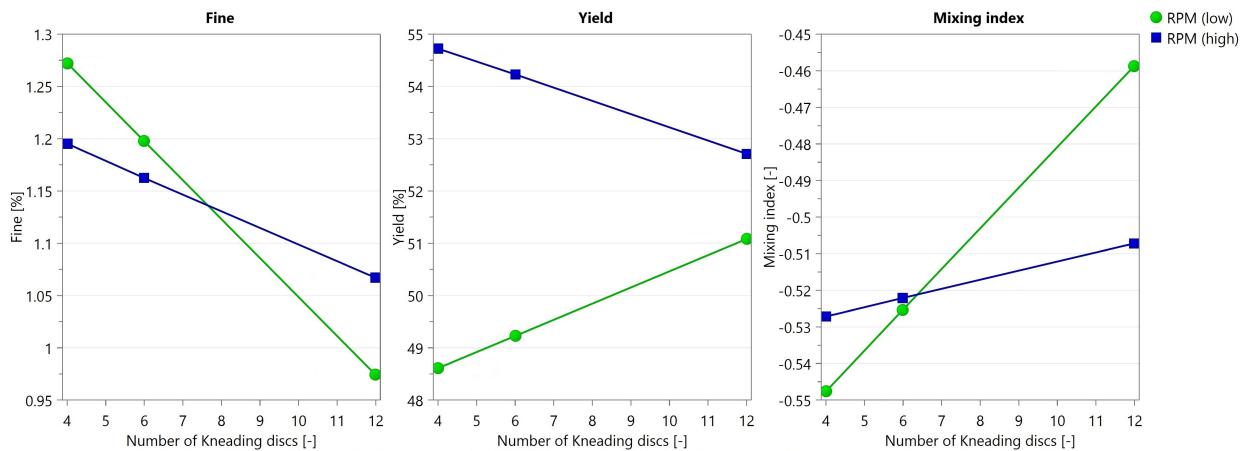
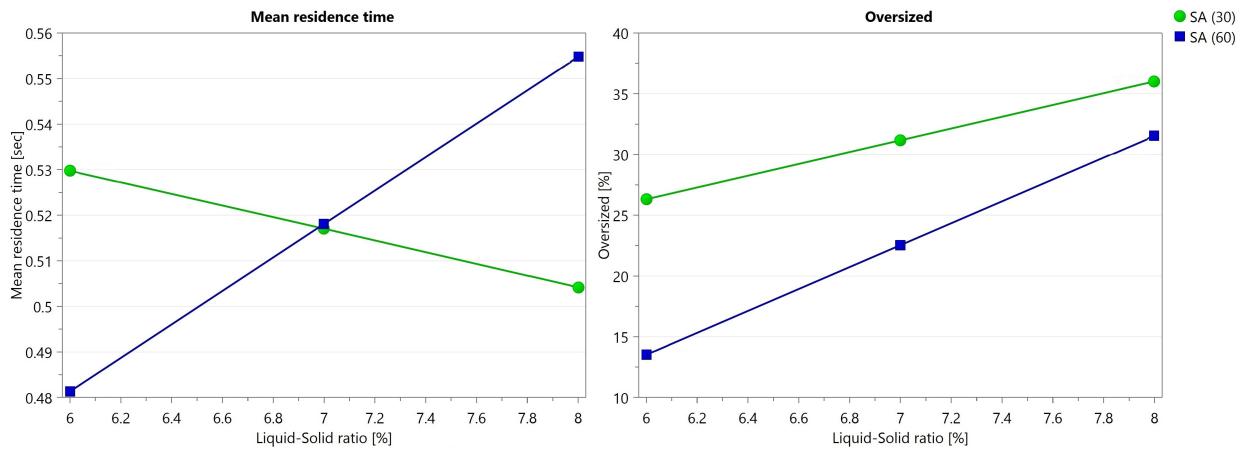


Figure 8: Effects plots showing predicted changes in the mean centered variance [N=46; DF=39; R²=0.87] and Péclet number [N=43; DF=35; R²=0.84] when factors, number of kneading discs (NK) [4, 6, 12], screw speed (RPM) [500-900 rpm], throughput (MFR) [10-25 kg/h], liquid-to-solid ratio (LSR) [6-8%] and stagger angle (SA) [30-60°], vary from a low to a high level, while keeping the other factors at their center point value (confidence level=0.95).



(i) Predicted changes in the mean residence time, and fine ($<150 \mu\text{m}$) and yield fractions ($>150 \mu\text{m}$ to $<1400 \mu\text{m}$) of granules.



(ii) Predicted changes in the mean residence time, and oversized granule fraction ($>1400 \mu\text{m}$).

Figure 9: Predicted changes in the responses due to interaction (i) between number of kneading discs and screw speed [NK^*RPM], and (ii) between liquid-to-solid ratio and stagger angle between kneading discs [LSR^*SA] in the screw configuration.

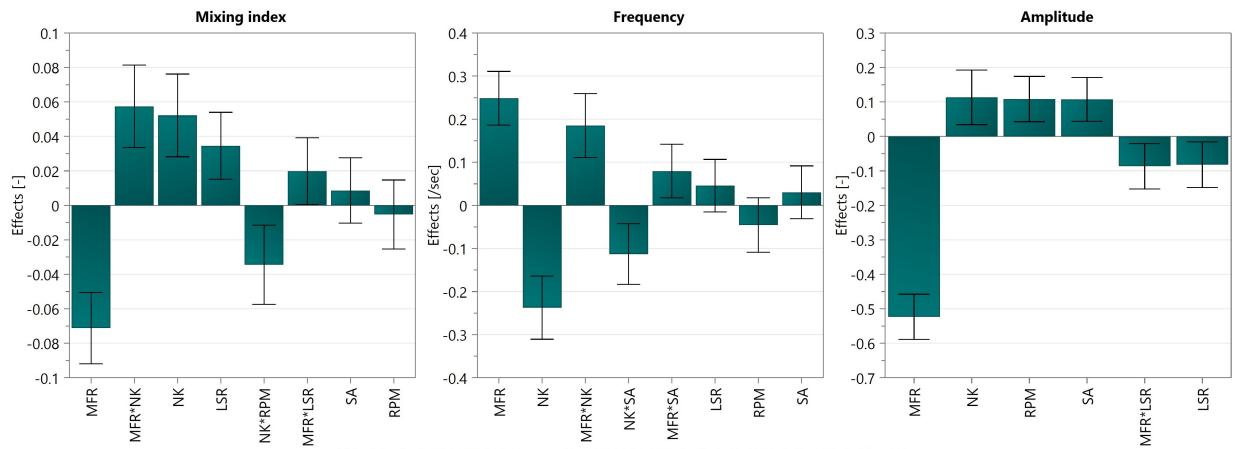


Figure 10: Effects plots showing predicted changes in the Shannon entropy based mixing index (MI) [N=43; DF=34; R²=0.80], frequency [N=41; DF=32; R²=0.84] and amplitude [N=45; DF=38; R²=0.88] of the mean moisture profiles when factors, number of kneading discs (NK) [4, 6, 12], screw speed (RPM) [500-900 rpm], throughput (MFR) [10-25 kg/h], liquid-to-solid ratio (LSR) [6-8%] and stagger angle (SA) [30-60°], vary from a low to a high level, while keeping the other factors at their center point value (confidence level=0.95).

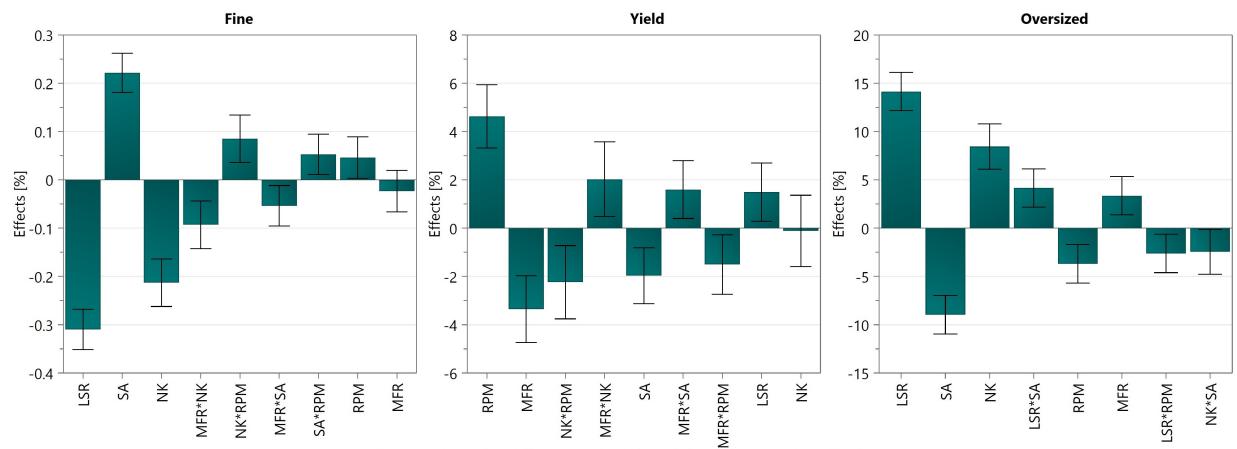


Figure 11: Effects plots showing predicted changes in the fines ($>150 \mu\text{m}$) [N=49; DF=39; R²=0.93], yield [150-1400 μm] [N=38; DF=28; R²=0.84] and oversized ($>1400 \mu\text{m}$) [N=47; DF=38; R²=0.92] fractions of the resulting GSD produced when factors, number of kneading discs (NK) [4, 6, 12], screw speed (RPM) [500-900 rpm], throughput (MFR) [10-25 kg/h], liquid-to-solid ratio (LSR) [6-8%] and stagger angle (SA) [30-60°], vary from a low to a high level, while keeping the other factors at their center point value (confidence level=0.95).

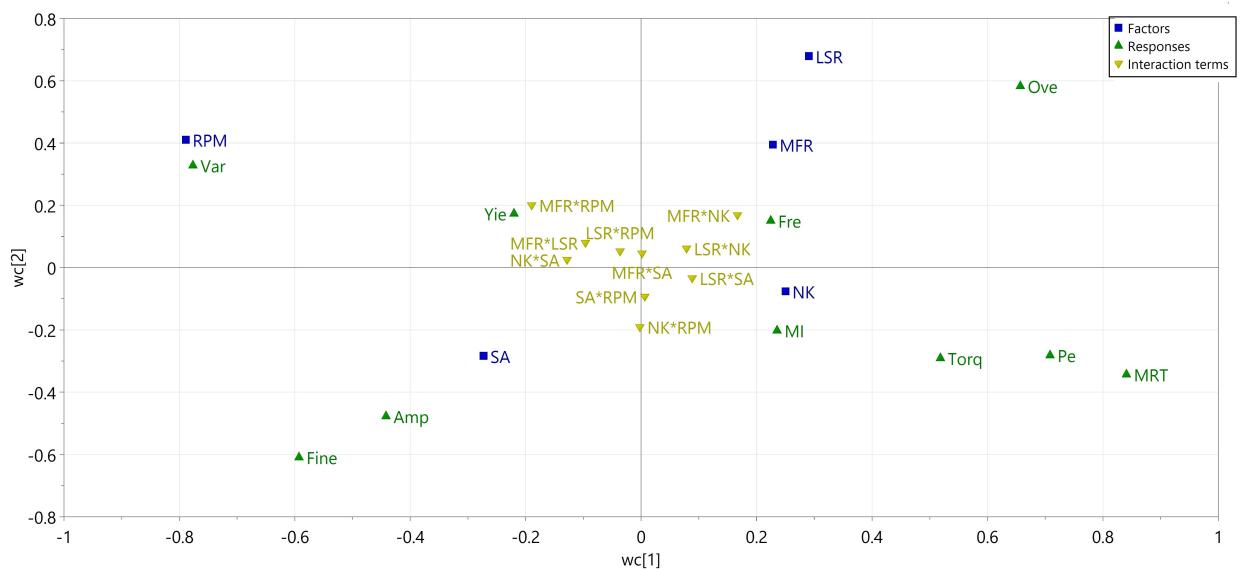


Figure 12: Scatter plot with PLS loadings of the two first model dimensions