



# Sparse resolutions to inconsistent datasets using L1-minimization

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This project is supported by the U.S. Department of Energy, National Nuclear Security Administration, under Award Number DE-NA0002375

# Overview

- Overview of Bound-to-Bound Data Collaboration (B2BDC)
  - models + data = *dataset (model-data system)*
- Dataset Consistency
  - scalar consistency measure
  -  • vector consistency measure
- Dataset examples:
  - GRI-Mech 3.0
  - DLR-SynG
- B2BDC protocol for model validation
  - suggested use of B2BDC tools for model validation

# Bound-to-Bound Data Collaboration

UQ as constrained optimization: parameters constrained by models and data

## Models

“True” QOI models

$$f_e : \mathbb{R}^n \rightarrow \mathbb{R}$$

Surrogate QOI models

$$M_e(x) \approx f_e(x)$$

Fitting error

$$|M_e(x) - f_e(x)| \leq \epsilon_e$$

$$e = 1, \dots, N$$



## Data

- Prior knowledge on uncertain parameters

$$x \in \mathcal{H} \subseteq \mathbb{R}^n$$

- QOI measurements (w/ uncertainty)

$$L_e \leq y_e \leq U_e$$

$$e = 1, \dots, N$$



## Dataset

$$x \in \mathcal{H} \subseteq \mathbb{R}^n$$

$$L_e - \epsilon_e \leq M_e(x) \leq U_e + \epsilon_e$$

$$\text{for } e = 1, \dots, N$$



$$\mathcal{F} \subseteq \mathcal{H}$$

**Feasible set** – parameters for which the models and data agree.

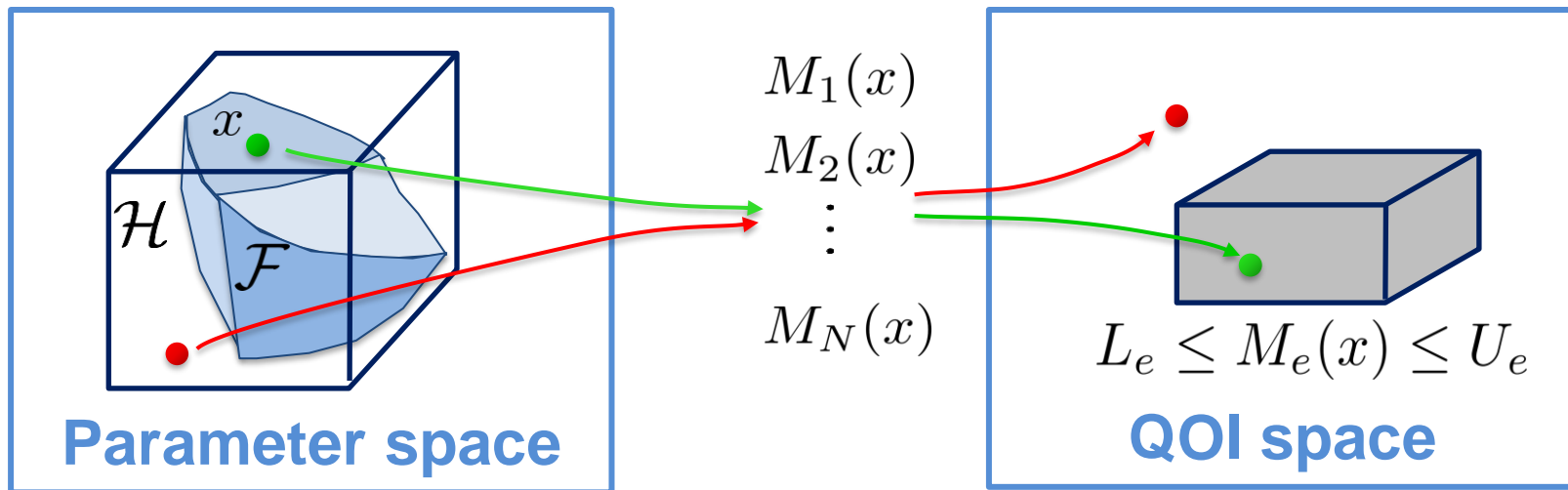
Prediction establishes the range of a model  $M_Q(x)$  subject to model-data constraints

$$\begin{aligned} \min \quad & M_Q(x) \\ \text{s.t.} \quad & x \in \mathcal{F} \end{aligned}$$

$$\begin{aligned} \max \quad & M_Q(x) \\ \text{s.t.} \quad & x \in \mathcal{F} \end{aligned}$$

# Consistency of a Dataset

- A dataset is **consistent** if it is feasible
  - Parameters exist for which model predictions match experimental observations



- Consistency analysis is quantifying **model validation**.

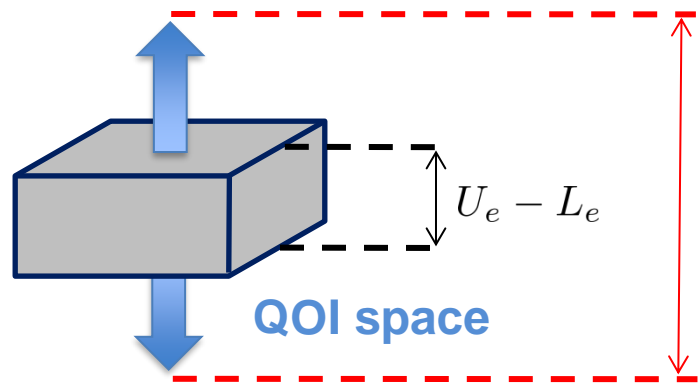
# Quantifying Consistency

**Q:** Does there exist a parameter vector  $x \in \mathcal{H}$  for which the models and data agree, within uncertainty?

**A:** Compute the *scalar consistency measure (SCM)*  $\rightarrow$

## Scalar Consistency Measure (SCM)\*

$$\begin{aligned} \max \quad & \gamma \\ \text{s.t.} \quad & L_e + \frac{(U_e - L_e)}{2}\gamma \leq M_e(x) \leq U_e - \frac{(U_e - L_e)}{2}\gamma \\ & x \in \mathcal{H}, \gamma \in \mathbb{R} \\ & \text{for } e = 1, \dots, N \end{aligned}$$




The SCM produces a symmetric tightening ( $\gamma > 0$ ) or stretching ( $\gamma < 0$ ) of all experimental bounds.

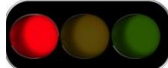
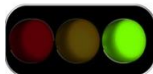
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- If consistent, go to prediction.
- If inconsistent, ???



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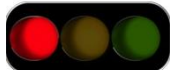
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**Next step:** identify which parts of this model-data system may be at fault.

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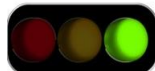
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Sensitivities\*

→ Local:  $\lambda_j \approx \frac{\partial(\text{SCM})}{\partial(\text{bound } j)}$


→ Global:  $\Delta(\text{SCM}) \leq \lambda^T \Delta(\text{bounds})$

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**Next step:** identify which parts of this model-data system may be at fault.


## New criteria can be used for the identification:

- How many experimental bounds do we need to change to become consistent?
  - search for a **sparse** resolution to the inconsistency
  - sparse solutions are **interpretable**

\* Feeley, R.; Seiler, P.; Packard, A.; Frenklach, M. *J. Phys. Chem. A* **2004**, 108, 9573-9583.


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If **inconsistent**, compute the *vector consistency measure (VCM)* 


- alternative consistency measure
- offers detailed analysis of inconsistency by allowing independent relaxations

## Vector Consistency Measure (VCM)

$$\begin{aligned} \min \quad & \|\Delta^L\|_1 + \|\Delta^U\|_1 \\ \text{s.t.} \quad & L_e - \Delta_e^L \leq M_e(x) \leq U_e + \Delta_e^U \\ & \Delta_e^L, \Delta_e^U \in \mathbb{R}, x \in \mathcal{H} \\ & \text{for } e = 1, \dots, N \end{aligned}$$


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# Examples\*

\* Hegde, A.; Li, W.; Oreluk, J.; Packard, A.; Frenklach, M. **2017**. *arXiv:1701.04695*.

# Comparison of Methods: GRI-Mech 3.0

GRI-Mech 3.0 dataset (77 QOIs, 102 uncertain parameters) for natural gas combustion.

## Scalar Consistency

- **Procedure:** Iteratively apply SCM, using sensitivities (Lagrange multipliers) to identify problems.

## Vector Consistency

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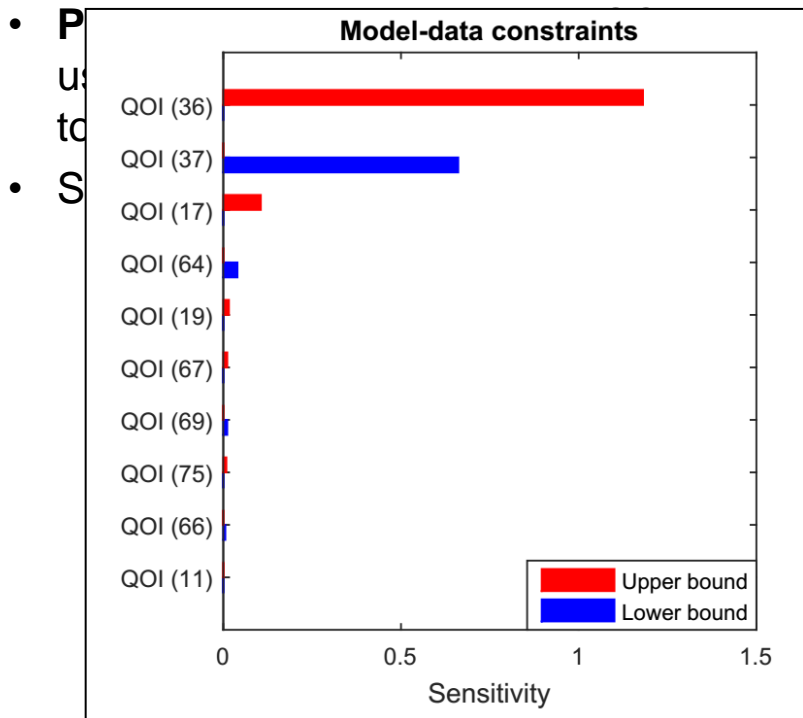
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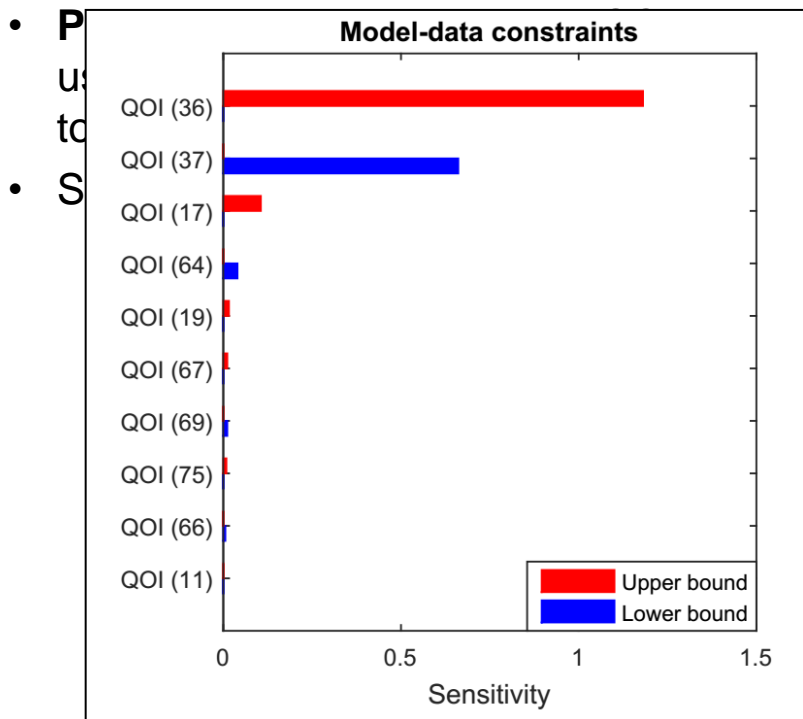


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(counter intuitive)

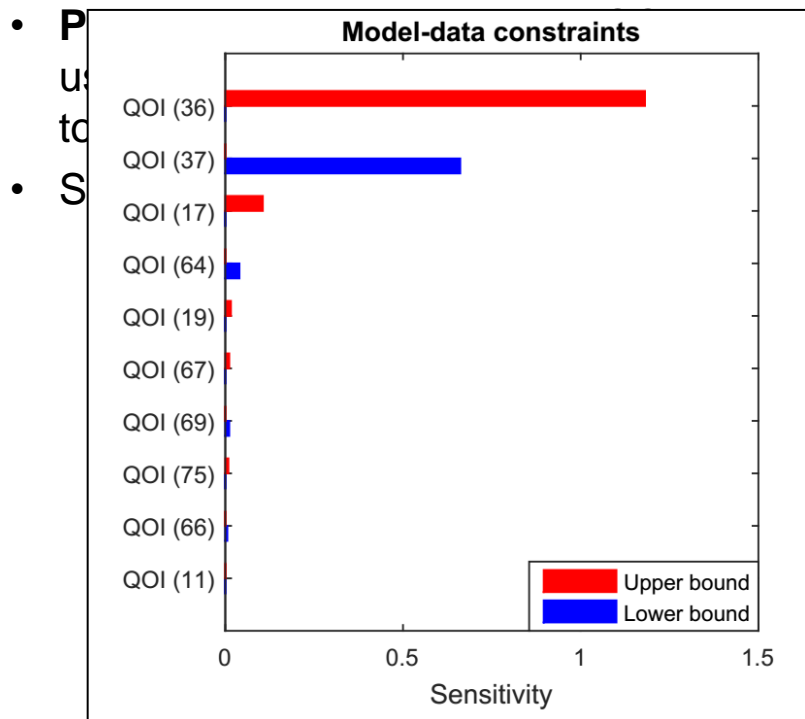
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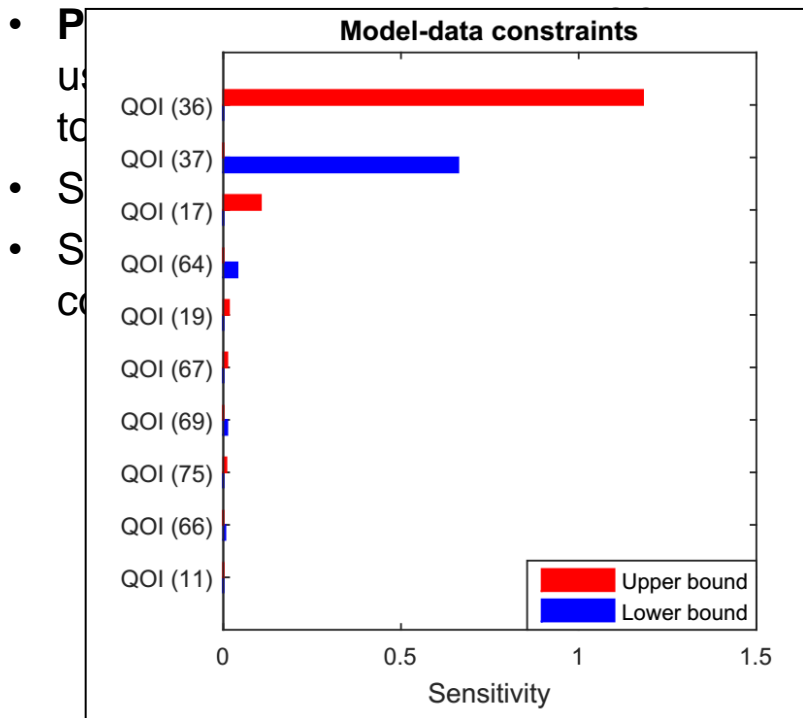
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- Compute VCM.

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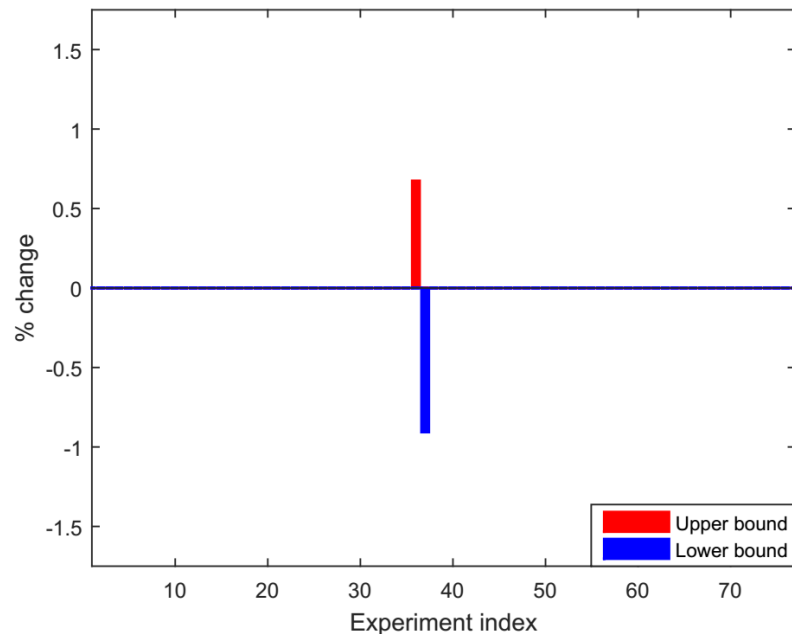
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- Compute VCM.
- Two QOIs relaxed (same as in SCM), dataset consistent.

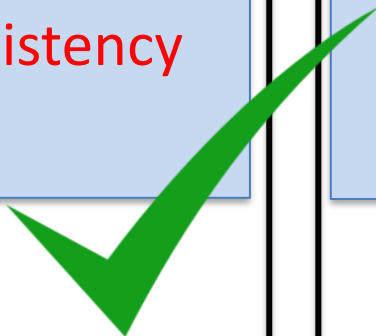
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Rapid and interpretable  
resolution of inconsistency



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# Advantages of VCM: DLR-SynG

DLR-SynG dataset\* (159 QOIs, 55 uncertain parameters) developed at DLR.

**Scalar Consistency**

**Vector Consistency**

\* Slavinskaya, N.; et al. *Energy & Fuels*. **2017**, vol. 31, pp 2274–2297

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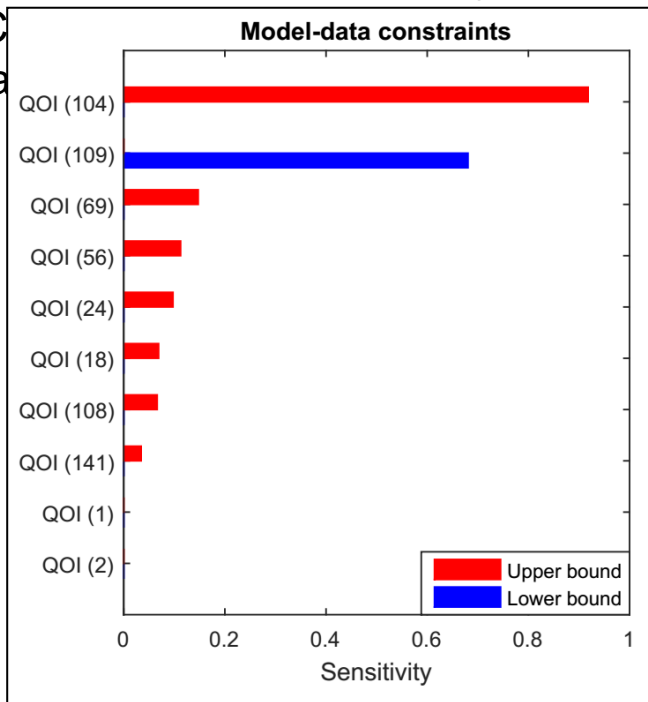


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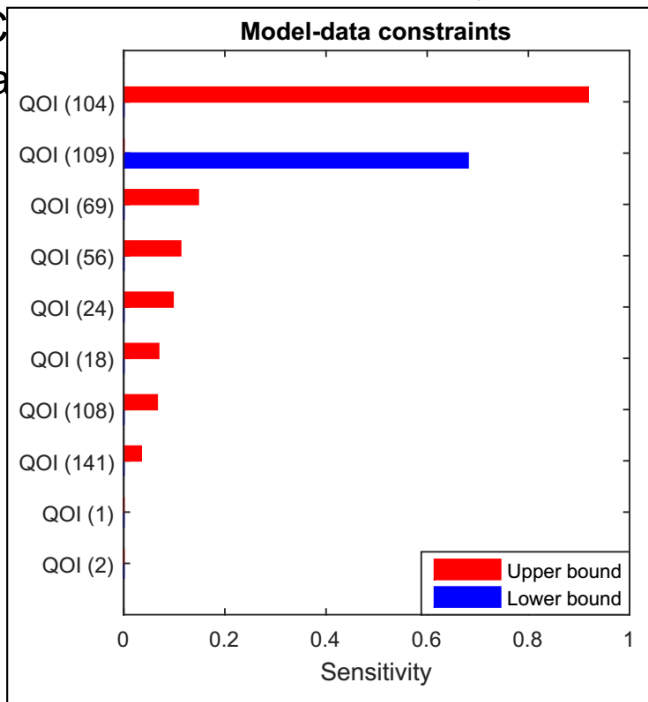
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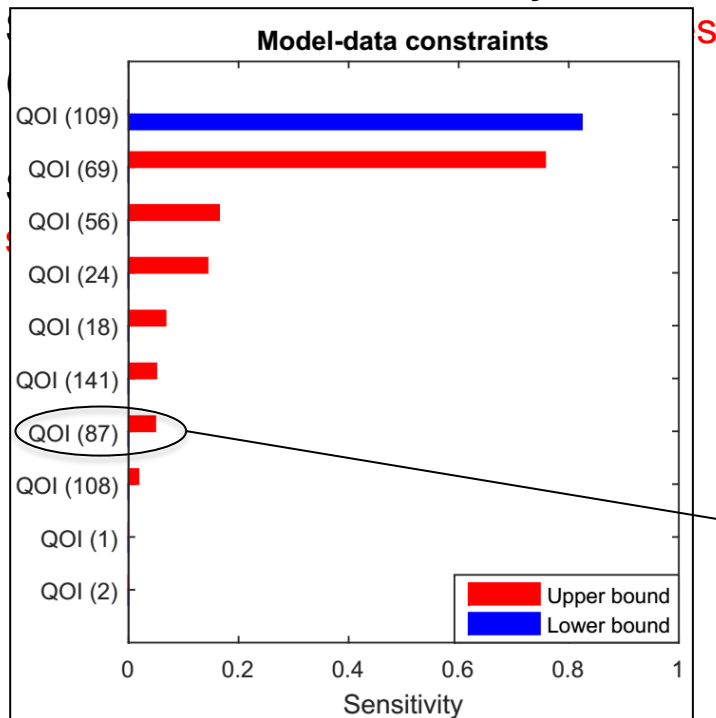
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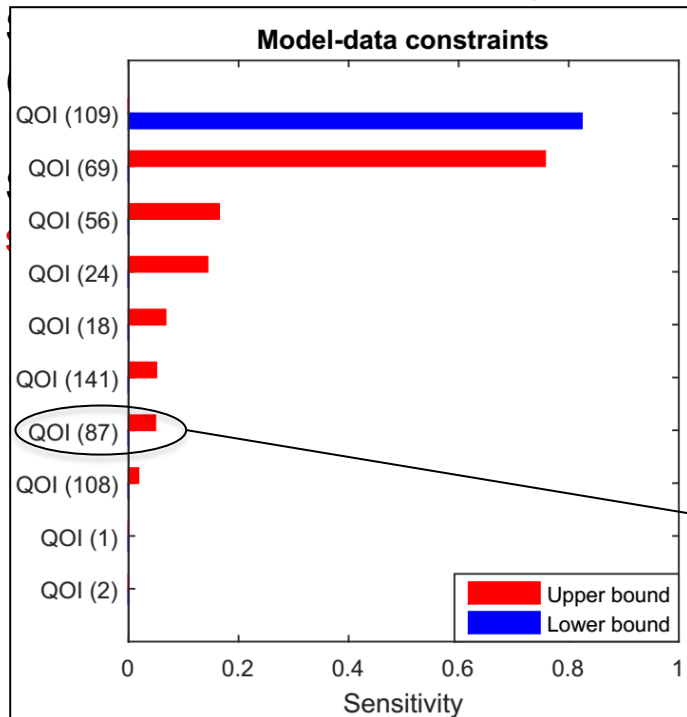
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→ Previously, not identified

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Repeat until  
consistent

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- This strategy results in the removal of 73 QOIs.

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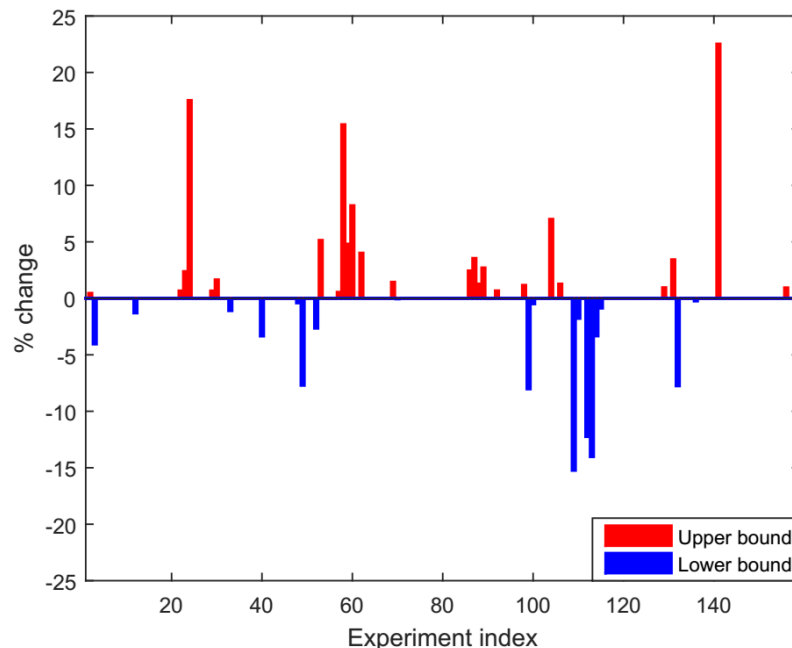
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Implementing the 43 relaxations results in  
a consistent dataset



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  - Recommends 43 relaxations (18 to lower bounds, 25 to upper bounds)

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Example of what we termed  
**massive inconsistency**

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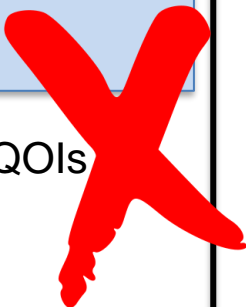
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Indirect and inefficient  
resolution of inconsistency

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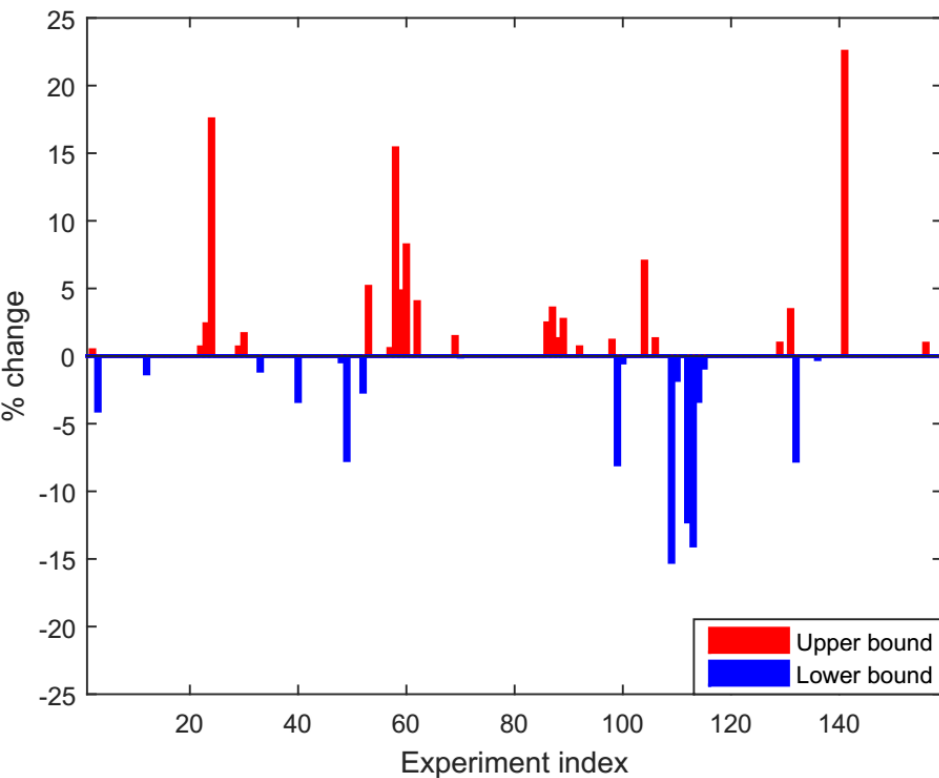
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Direct, one-shot resolution of  
inconsistency



# Including weights



What if we are unwilling to change certain experimental bounds?



# Including weights

- Domain expert knowledge and opinions enter VCM as weights.
- **Idea:** If a dataset is inconsistent, one should be less willing to relax model-data constraints they trust and more willing to relax constraints that are less reliable. The same goes for parameter bounds.

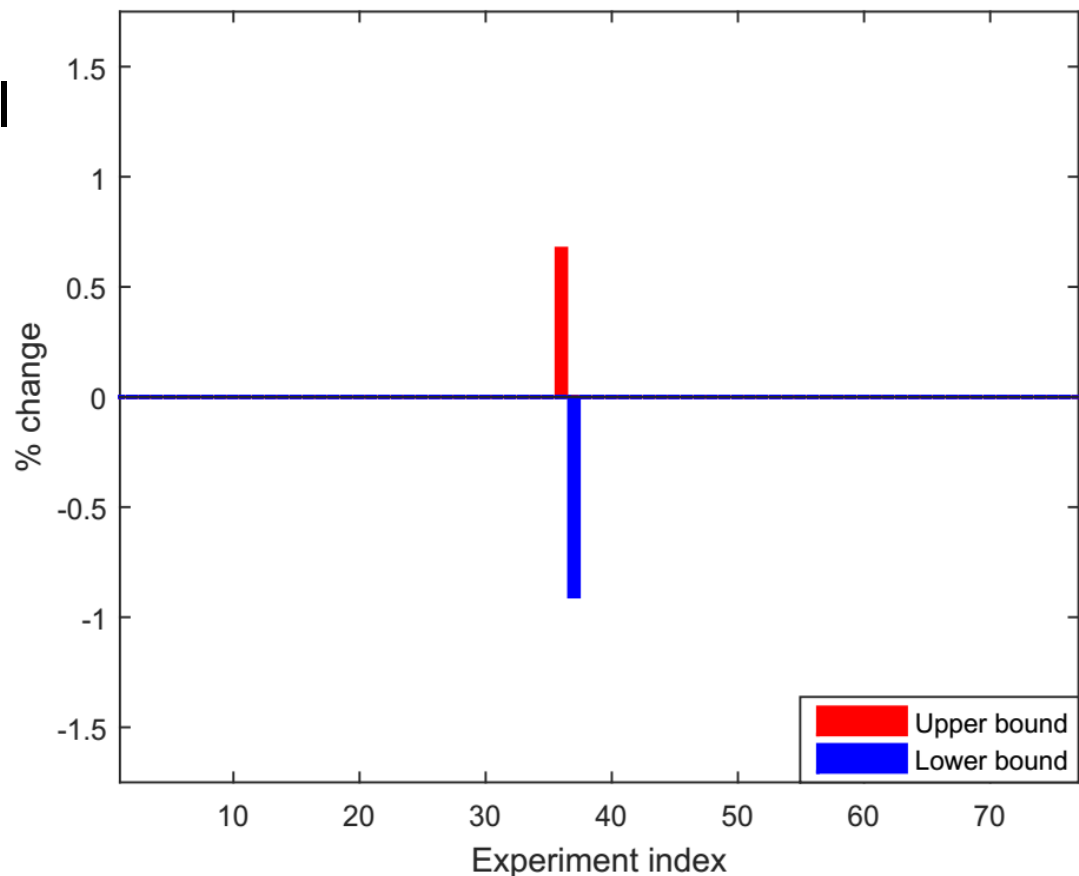
## Weighted VCM

$$\begin{aligned} \min_{x, \Delta^L, \Delta^U, \delta^l, \delta^u} & \|\Delta^L\|_1 + \|\Delta^U\|_1 + \|\delta^l\|_1 + \|\delta^u\|_1 \\ \text{s.t.} \quad & L_e - W_e^L \Delta_e^L \leq M_e(x) \leq U_e + W_e^U \Delta_e^U \quad \text{for } e = 1, \dots, N \\ & l_i - w_i^l \delta_i^l \leq x_i \leq u_i + w_i^u \delta_i^u \quad \text{for } i = 1, \dots, n \end{aligned}$$

- Small weight - less willing to change bound.
- Large weight - more willing to change bound.

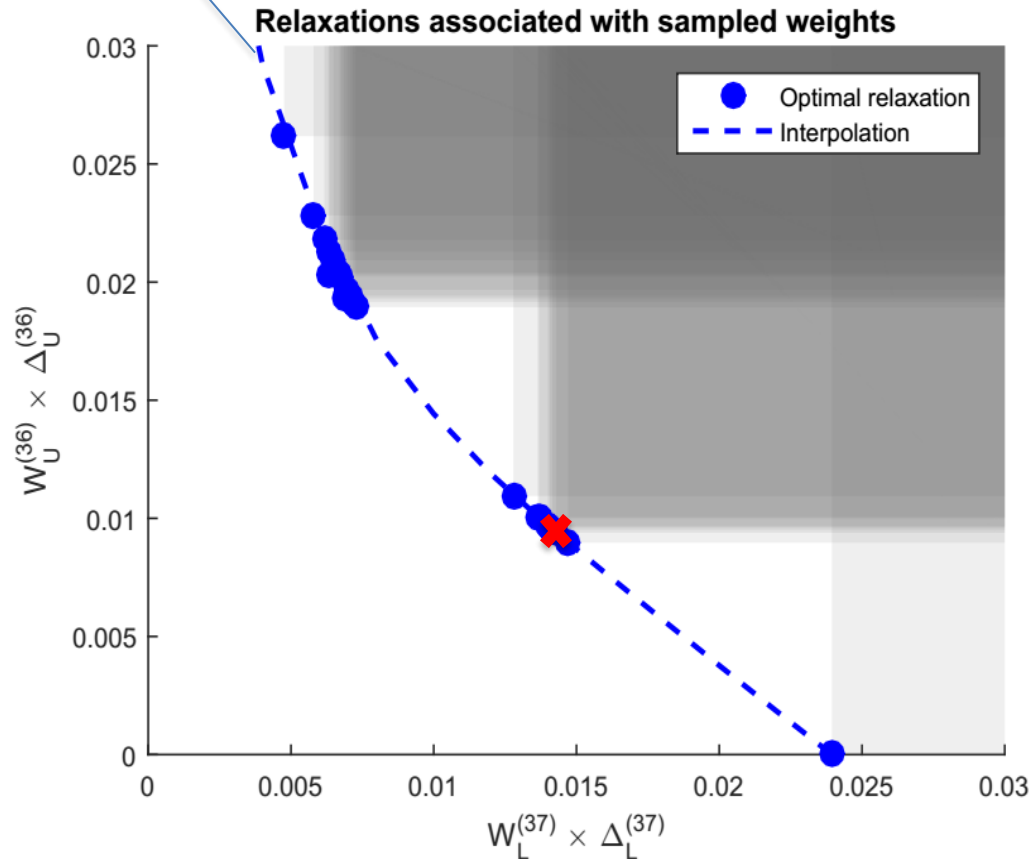
# Weights and GRI-Mech 3.0

- Single application of VCM identifies two experimental bounds.



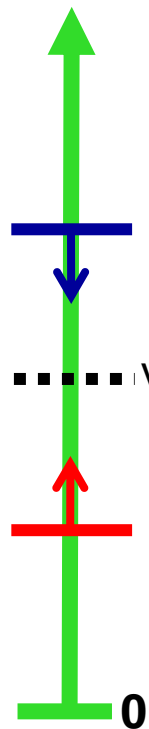
# Weights and GRI-Mech 3.0

- Single application of VCM identifies two experimental bounds.
- Weights applied to only the previous two bounds.



# Computing the VCM

For **quadratic surrogate models**, we can approximate the true solution (NP-hard) using convex lower bound and local optima.

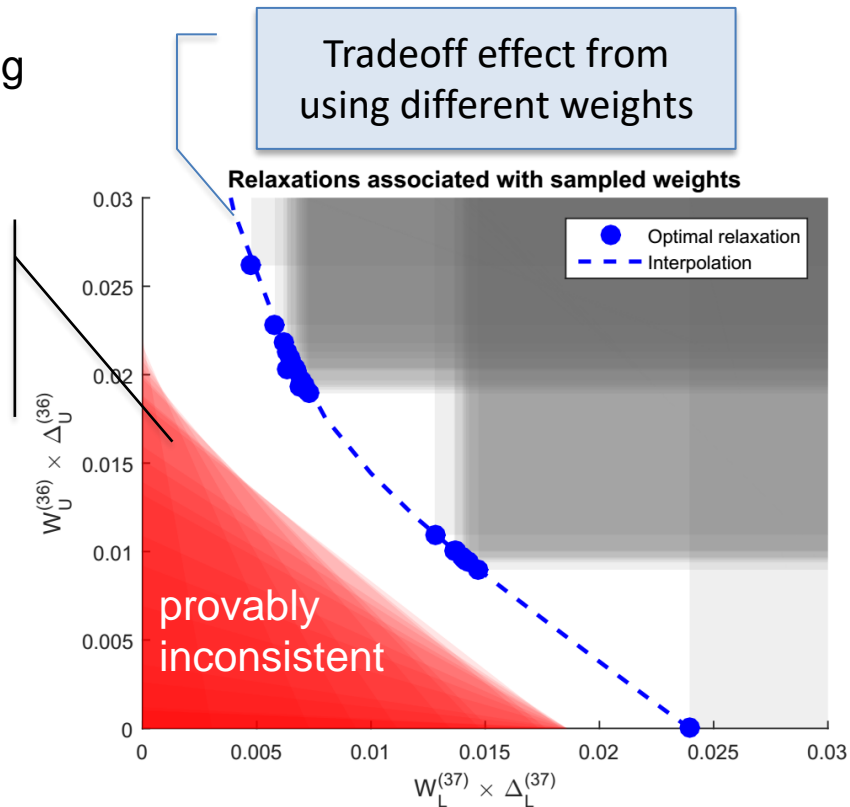


Local solver

VCM

Semidefinite Program  
(convex lower bound)

Shaded red region certified  
infeasible by SDP.



Example: GRI-Mech 3.0 dataset – VCM relaxations with varying weights, relaxations allowed to two constraints

## B2BDC protocol

- Step 1: Construct *dataset* - QOI selection, model building, data collection, etc.
- Step 2: Remove self-inconsistent QOIs
- Step 3: Scalar consistency (SCM) analysis  
IF **inconsistent**  
perform vector consistency (VCM) analysis
- Step 4: Prediction & further analysis

# Summary

- **Consistency** analysis is **model validation**
- **Vector Consistency** offers an efficient approach to resolving inconsistent datasets
  - particularly efficient for resolving massive inconsistency
  - incorporates expert knowledge through weights
  - examples: GRI-Mech 3.0, DLR-SynG
- Utilizing both the **SCM** and the **VCM** offers a powerful strategy for model validation

# Acknowledgements

This work is supported as a part of the CCMSC at the University of Utah, funded through PSAAP by the National Nuclear Security Administration, under Award Number DE-NA0002375.



# Questions?