



# ALLEVIATING THE COST OF BAYESIAN CALIBRATION WITH EMBEDDED MODEL ERROR

(USING GAUSSIAN PROCESS SURROGATES AND MULTILEVEL MCMC)



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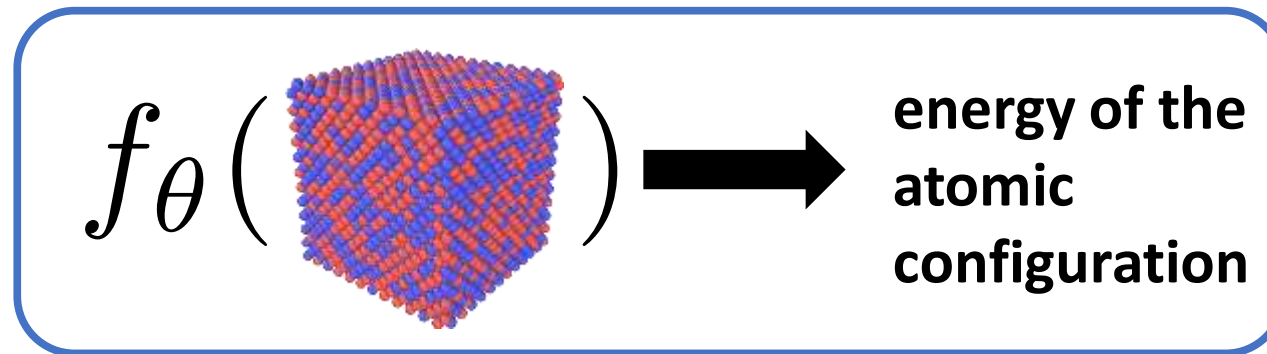
# OVERVIEW

- Motivating example: Bayesian calibration for *interatomic potentials*
- Review two model error frameworks
  - Additive model error
  - **Embedded model error**
- Computational strategy for Gaussian embedded model error
  - **Likelihood approximation**
  - Gaussian Process (GP) surrogates with Gaussian inputs
    - **Sparse GPs & multilevel MCMC** for inference
- Case study: calibrating an EAM potential with embedded model error

# MOTIVATING EXAMPLE: CALIBRATING INTERATOMIC POTENTIALS

Design of advanced energy storage devices often requires materials simulations at the *atomistic* level.

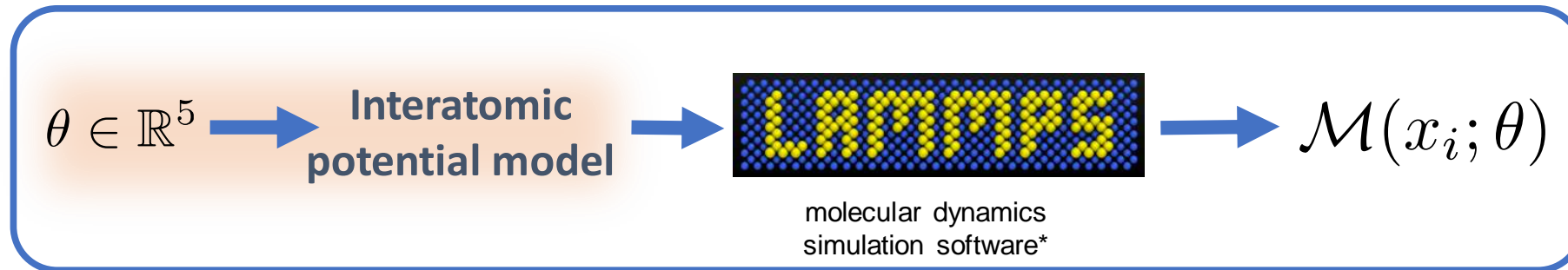
For practical scale systems, density functional theory (DFT) based simulations are untenable, motivating the use of empirical methods involving **interatomic potentials**.



Given their empirical nature, **effective calibration of such models** requires careful consideration of the **model error**\*.

\*Hegde, A., Weiss, E., Windl, W., Najm, H., & Safta, C. "Bayesian calibration of interatomic potentials for binary alloys." *Computational Materials Science* 214 (2022): 111660.

# MOTIVATING EXAMPLE: CALIBRATING INTERATOMIC POTENTIALS



5-parameter RAMPAGE\* Embedded Atom Method (EAM) potential.

$$E_i = \frac{1}{2} \sum_{j \neq i} V_{\alpha\beta}(r_{ij}) + F_{\alpha} \left( \sum_{j \neq i} \rho_{\alpha\beta}(r_{ij}) \right)$$

$$V_{AB}(r) = D \left( e^{-2\alpha(r-r_{eq})} - 2e^{-\alpha(r-r_{eq})} \right)$$

$$\rho_{BA}(r) = r^6 \left( e^{-S_A r} + 2^9 e^{-2S_A r} \right)$$

$$\rho_{AB}(r) = r^6 \left( e^{-S_B r} + 2^9 e^{-2S_B r} \right)$$

\*L. Ward, A. Agrawal, K.M. Flores, and W. Windl. Rapid production of accurate embedded-atom method potentials for metal alloys. (2012). arXiv:cond-mat.mtrl-sci/1209.0619

Model output: **102** quantities of interest (QoIs) total.

17 compositions ranging from **3%** Au to **97%** Au

For each composition, 6 physical properties:

- lattice parameter
- mixing enthalpy
- elastic constants C11, C12, C44
- bulk modulus

Indexing the 102 different **QOIs**:

finite composition space  $x \in \mathcal{X}$

physical properties  $i \in \{\text{lat, mix, } C_{11}, C_{12}, C_{44}, \text{bulk}\}$

# BAYESIAN CALIBRATION WITH ADDITIVE MODEL ERROR

$$\boxed{y(x_i)} = \boxed{\mathcal{M}(x_i; \theta)} + \boxed{\epsilon(x_i)}$$

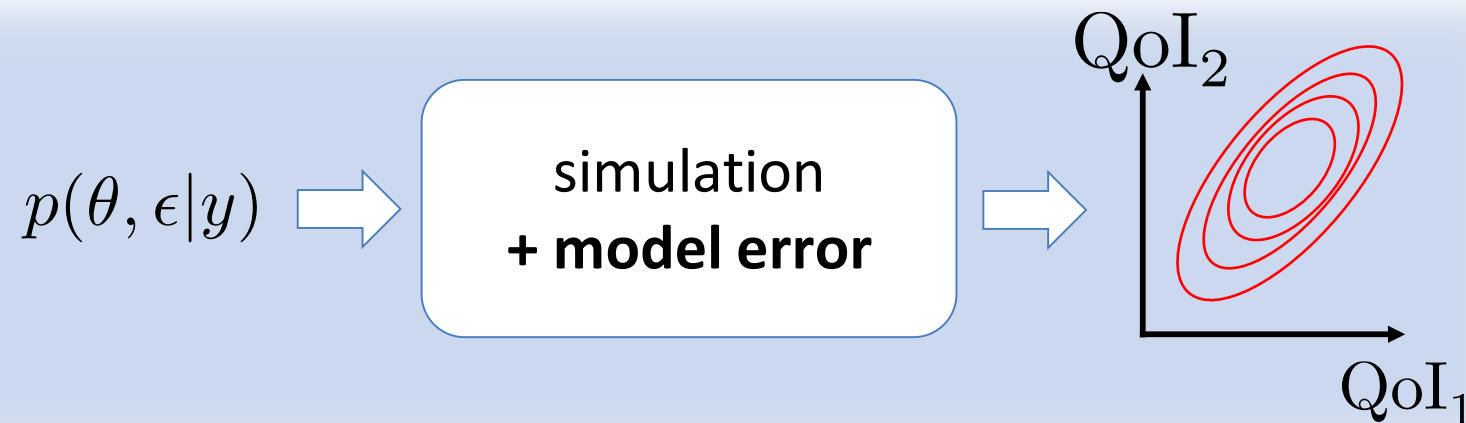
DFT data                      simulation                      model error

$$p(\theta, \epsilon | y) = \frac{p(y | \theta, \epsilon) p(\theta, \epsilon)}{p(y)}$$

Principal objective is to jointly infer the unknown parameters and the model error given DFT data.

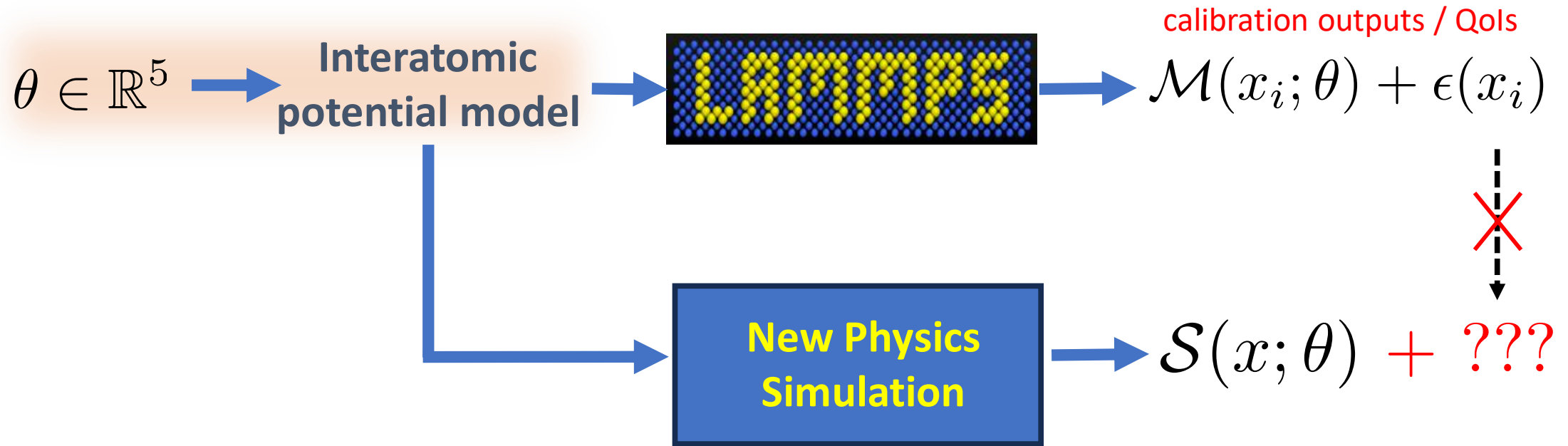
# BAYESIAN CALIBRATION WITH ADDITIVE MODEL ERROR

## Predictions w/ model error



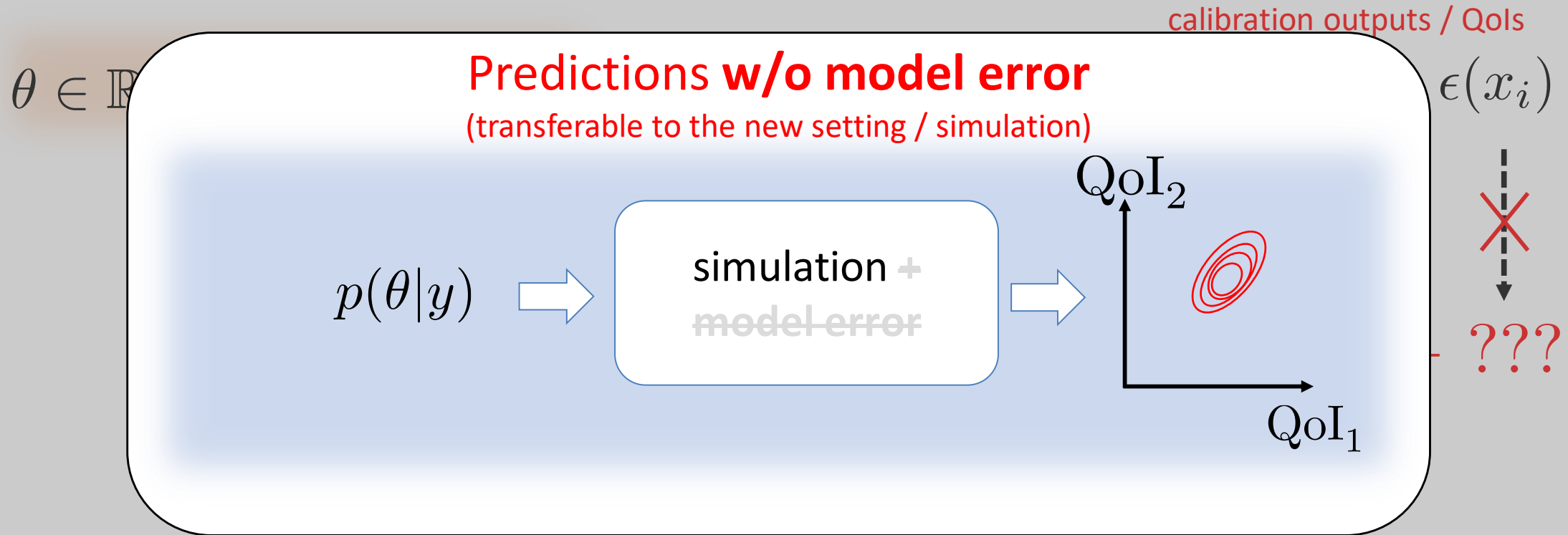
Objective is to jointly  
known parameters  
model error given DFT

# TRANSFERABILITY TO NEW PREDICTION DOMAINS



➤ An additive error model **does not always** transfer to new prediction domains, particularly when the new prediction Qols differ from the calibration Qols

# TRANSFERABILITY TO NEW PREDICTION DOMAINS

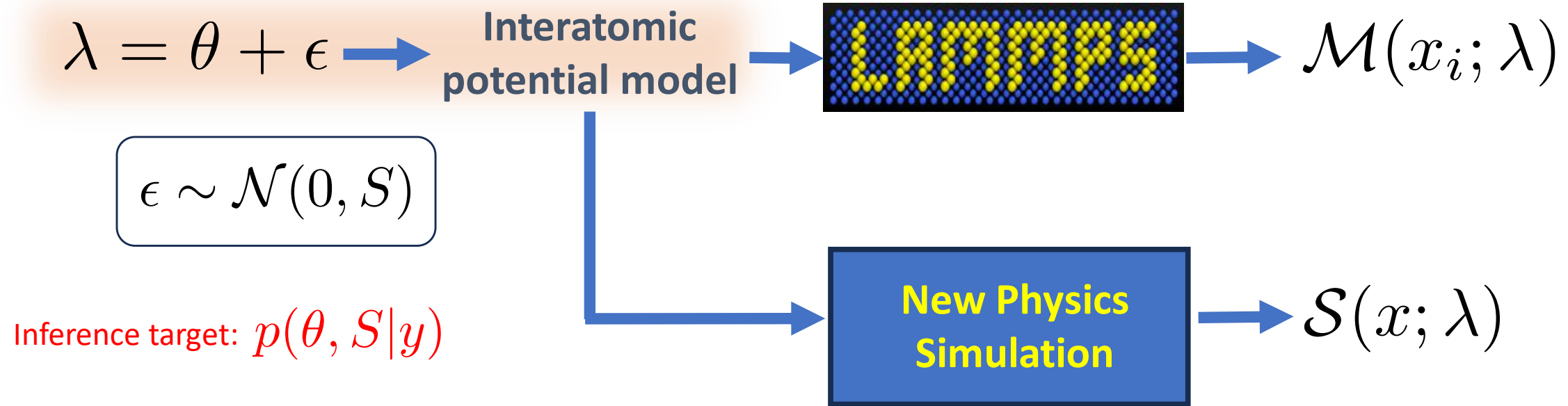


➤ An additive error model **does not always** transfer to new prediction domains, particularly when the new prediction QoIs differ from the calibration QoIs



# EMBEDDED MODEL ERROR: MULTIVARIATE GAUSSIAN

Simplified form of embedded model error --  
model error added to the model parameters



- Full uncertainty representation – model error entirely transferable to new prediction domains
- Predictions constrained by the model – predictive distributions supported only by values realizable by the model.
  - predictions with uncertainties satisfy the model constraints (e.g., conservation laws), but **also inherit the biases of the model.**

# ABC-BASED LIKELIHOOD APPROXIMATION

ABC = **A**pproximate **B**ayesian **C**omputation

**Challenge:** the corresponding likelihood does not have a closed form.

**Workaround:** use an ABC-based approximate likelihood strategy\*

$$p_{\text{ABC}}(y|x, \theta, S) = \frac{1}{\nu\sqrt{2\pi}} \prod_{x,i}^N \exp \left( - \frac{\overbrace{(\mu(x_i) - y(x_i))^2}^{\text{nominal error}} + \underbrace{(\sigma(x_i) - \gamma|\mu(x_i) - y(x_i)|)^2}_{\text{error coverage via uncertainty}}}{2\nu^2} \right)$$

$$\mu(x_i) = \mathbb{E}_{\lambda \sim \mathcal{N}(\theta, S)} [\mathcal{M}(x_i; \lambda)]$$

$$\sigma(x_i) = \sqrt{\mathbb{E}_{\lambda \sim \mathcal{N}(\theta, S)} [(\mathcal{M}(x_i; \lambda) - \mu(x_i))^2]}$$

# ABC-BASED LIKELIHOOD APPROXIMATION

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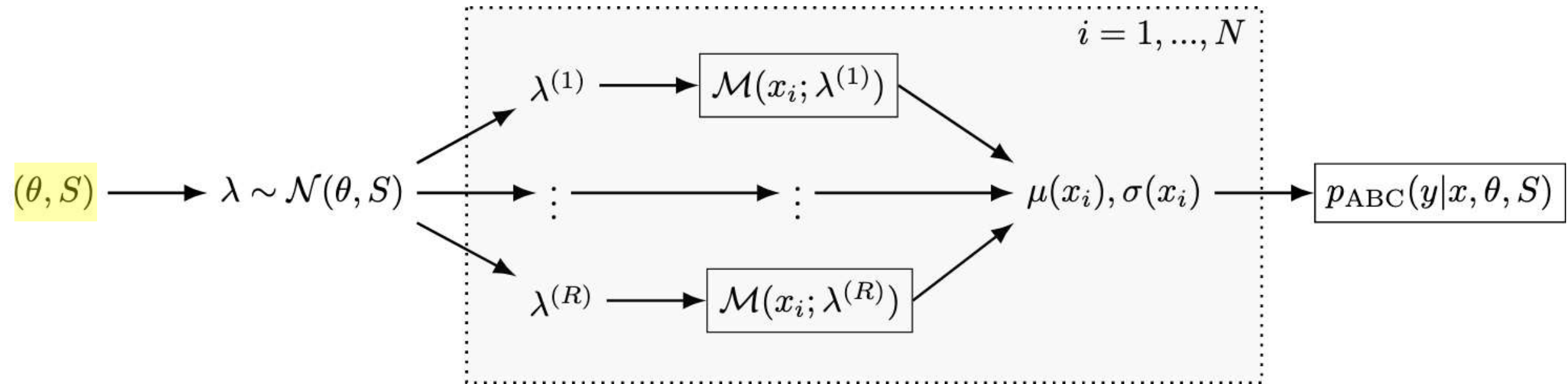
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**Expensive!** Many model evaluations (samples) required per likelihood evaluation.

$$\mu(x_i) = \mathbb{E}_{\lambda \sim \mathcal{N}(\theta, S)} [\mathcal{M}(x_i; \lambda)]$$

$$\sigma(x_i) = \sqrt{\mathbb{E}_{\lambda \sim \mathcal{N}(\theta, S)} [(\mathcal{M}(x_i; \lambda) - \mu(x_i))^2]}$$

# COST OF A SINGLE ABC-LIKELIHOOD EVALUATION



In the following slides, we will construct a surrogate encompassing this boxed region.

# GP SURROGATES WITH GAUSSIAN INPUTS

Computational expense of the simulation often necessitates the use of cheaper-to-evaluate **surrogate models** of the  $\theta$ -to- $\mathcal{M}(x_i; \theta)$  map.

When the surrogate models are Gaussian processes (GPs) with Gaussian/RBF kernels,

$$k(\theta, \theta'; \nu) = \sigma_k^2 \exp \left( -\frac{1}{2} (\theta - \theta')^T \Gamma^{-1} (\theta - \theta') \right)$$

The GP prediction equations at a new parameter value are Gaussian with mean:

$$m_{\star}(\theta) = m(\theta) + K(\theta, \Theta) \beta \text{ with } \beta = (K(\Theta, \Theta) + \sigma_n^2 I)^{-1} (q - m(\Theta))$$

training data:  $\{(\theta^j, q^j)\}_{j=1}^M$

and variance:

$$\sigma_{\star}^2(\theta) = \sigma_k^2 - K(\theta, \Theta) (K(\Theta, \Theta) + \sigma_n^2 I)^{-1} K(\Theta, \theta)$$

$\sigma_n^2$  is from the GP likelihood (additive noise)

# GP SURROGATES WITH GAUSSIAN INPUTS

Surrogate model:  ~~$\mathcal{M}(x_i; \lambda)$~~   $\rightarrow \mathcal{N}(m_\star(\lambda), \sigma_\star^2(\lambda))$   
 with embedding:  $\lambda \sim \mathcal{N}(\theta, S)$

induces a  
pushforward density  
on the surrogate  
output

If the embedded model error is Gaussian, then we can analytically\* compute the quantities that appeared in the ABC-likelihood,

$$m_{x_i}(\theta, S) = \mu(x_i) = \beta^T \ell$$

$$v_{x_i}(\theta, S) = \sigma^2(x_i) = \sigma_k^2 + \sigma_n^2 - \text{trace}((K(\Theta, \Theta) + \sigma_n^2 I)^{-1} L) \\ + \text{trace}((L - \ell \ell^T) \beta \beta^T)$$

where  $\ell \in \mathbb{R}^M$  and  $L \in \mathbb{R}^{M \times M}$  require  $\mathcal{O}(M)$  and  $\mathcal{O}(M^2)$  computations (with respect to the surrogate model training data).

\*Candela, J. Q., Girard, A., Larsen, J., & Rasmussen, C. E. (2003, April). Propagation of uncertainty in Bayesian kernel models-application to multiple-step ahead forecasting. In *2003 IEEE International Conference on Acoustics, Speech, and Signal Processing, 2003. Proceedings.(ICASSP'03)*. (Vol. 2, pp. II-701). IEEE.

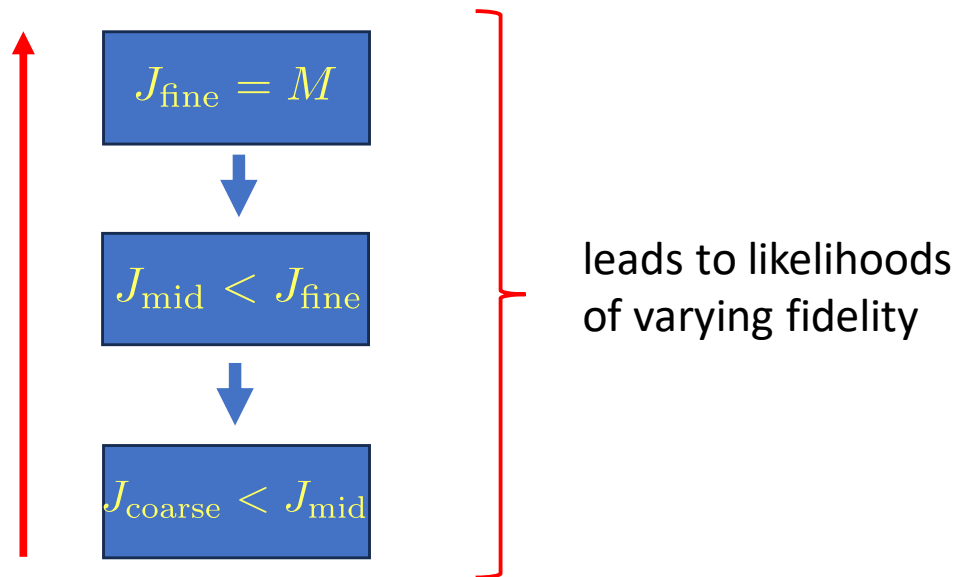
# REDUCTION THROUGH SPARSE GPS AND MULTI-LEVEL MCMC

**Challenge:** each ABC-likelihood evaluation requires  $N$  surrogate evaluation, where each surrogate costs  $\mathcal{O}(M^2)$  to evaluate.

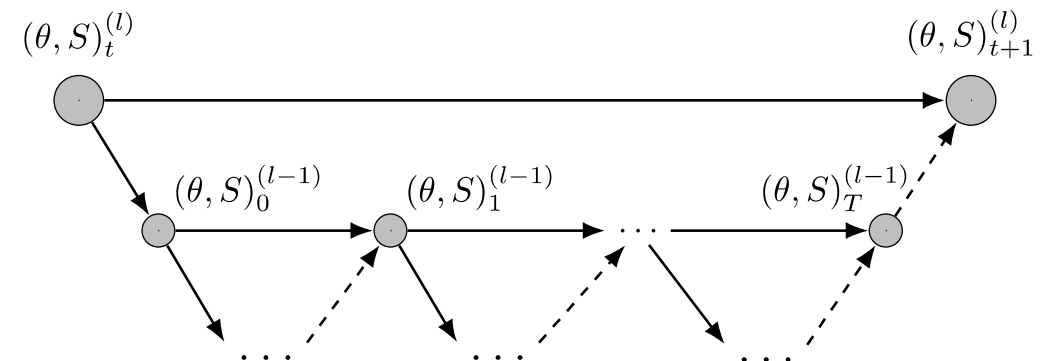
**Strategy:** Build reduced-cost surrogate models via inducing point (pseudo data) approximations to GPs.

- Evaluation cost  $\mathcal{O}(J^2)$  where  $J$  is the number of inducing points.

increasing fidelity,  
increasing evaluation cost



use multi-level MCMC algorithms for inference, e.g., multi-level delayed-acceptance (MLDA)\*



\*Lykkegaard, M. B., Dodwell, T. J., Fox, C., Mingas, G., & Scheichl, R. (2023). Multilevel delayed acceptance MCMC. *SIAM/ASA Journal on Uncertainty Quantification*, 11(1), 1-30.

# CASE STUDY: CALIBRATING POTENTIALS WITH EMBEDDED ERROR

Case 1: Embedding model error into the 5 parameters *individually*

v.s.

Case 2: Embedding into all 5 parameters *simultaneously*  
(includes all correlations between model parameters)

## Case 1 Setup

- model parameters + univariate embedding
- 102 Qols
- ABC-Likelihood w/ GP surrogates
- Adaptive MCMC
  - resulted in low autocorrelations, effective sample size > 2000

## Case 2 Setup

- model parameters + multivariate embedding
- 102 Qols
- ABC-Likelihood w/ GP surrogates
- Adaptive MCMC: very high autocorrelations, even after > 1 week of sampling

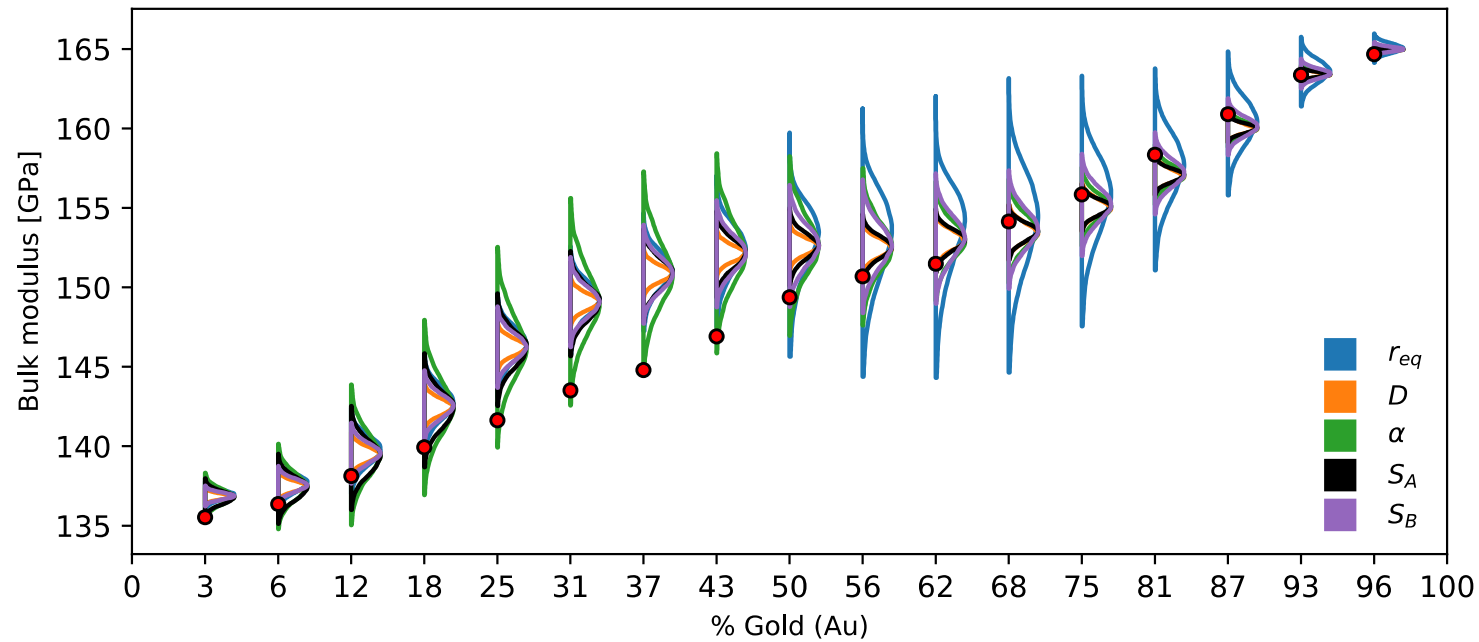


## **Sparse GPs + Multilevel MCMC (MLDA)**

- 3 levels (w/ 500 and 1000 inducing points)
- Very low autocorrelations, effective sample size > 2000

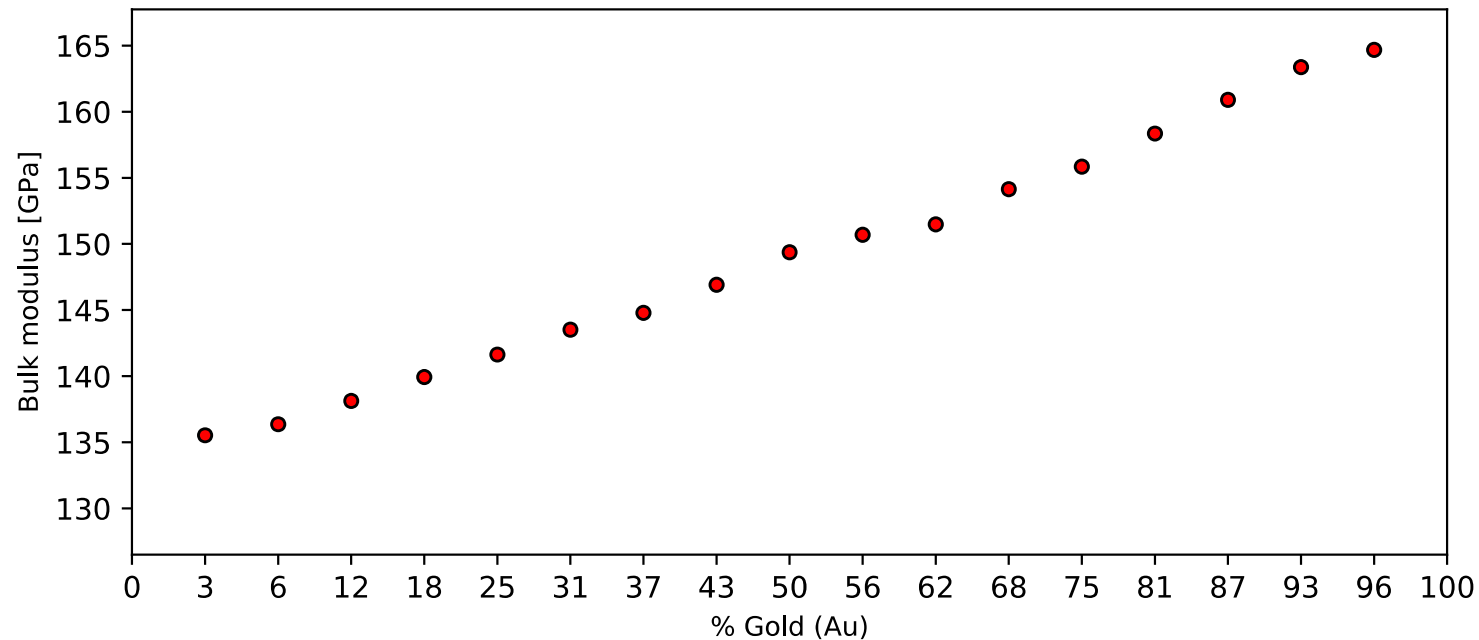


## Individual embedding



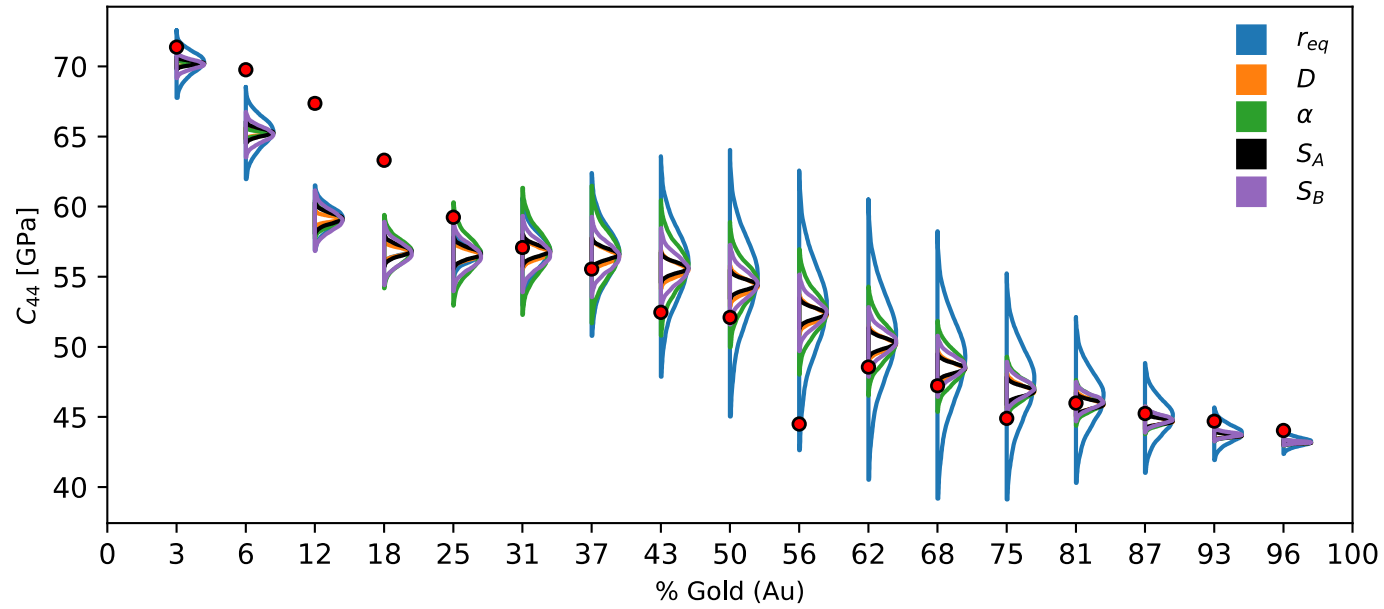
- Embedding-dependent predictive capabilities
- Composition-dependent trends
- Full embedding generally provides better coverage of the data

## Full embedding



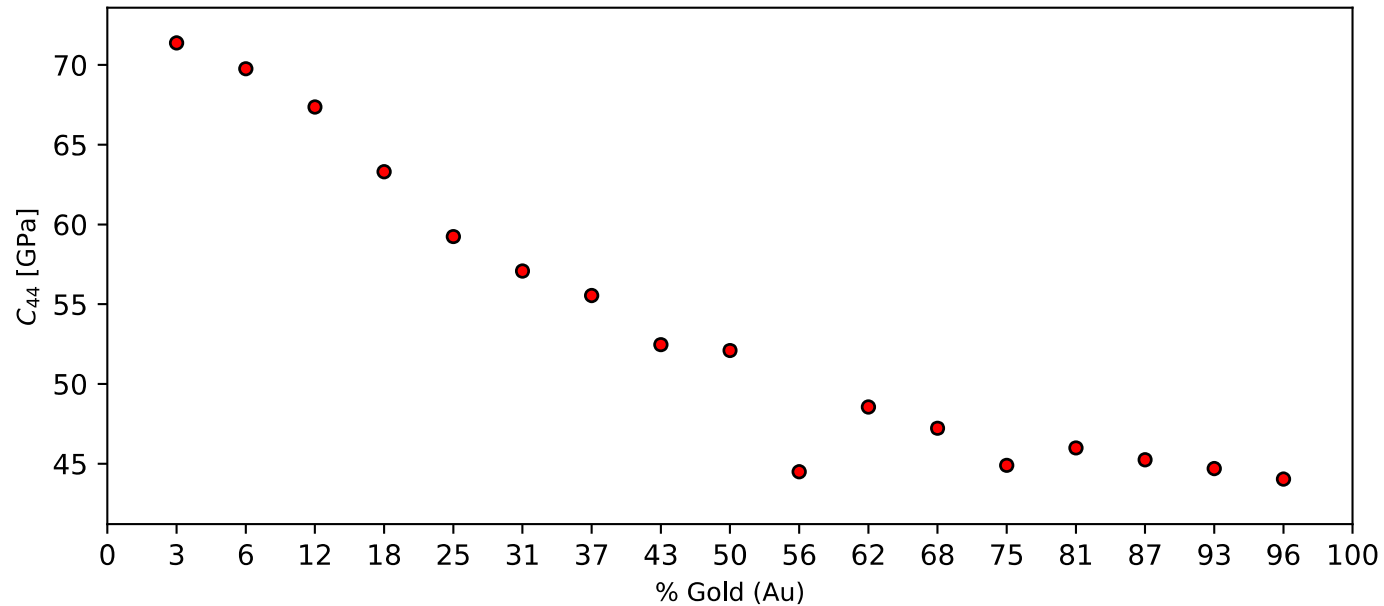
In comparison with the additive model error, this uncertainty is fully transferable.

## Individual embedding



- Embedding-dependent predictive capabilities
- Composition-dependent trends

## Full embedding



Even with the full embedding, the model struggles to predict the DFT data at low compositions gold – reflects limitations of the underlying potential model.

- UQ & calibration for interatomic potential models
- Embedded model error (Gaussian embedding)
  - ABC-likelihoods & GP surrogates
  - Further reduction through sparse GPs & multilevel MCMC
- Case study: predictive utility of embedded model error
  - **Full uncertainty representation** – new predictions account for the calibrated model error
    - ➡ **Depicted uncertainties are fully transferable to new prediction settings**
  - **Predictions constrained by the model** – predictions with uncertainties satisfy the model constraints, and in doing so also inherit the biases of the model.
    - ➡ **Embedding-dependence and composition-dependence in predictions**
    - ➡ **Inability to predict certain Qols within uncertainty**
  - Combined, these findings provide new and useful diagnostic information that was not present in our prior work.

# ACKNOWLEDGEMENTS

**Arun Hegde, Cosmin Safta, and Habib Najm** are supported by the U.S. Department of Energy, Office of Science:

- Advanced Scientific Computing Research (ASCR)
- Scientific Discovery through Advanced Computing (SciDAC) program through the FASTMath Institute
- National Energy Research Scientific Computing Center (NERSC)

**Elan Weiss and Wolfgang Windl** are supported by:

- Air Force Office of Scientific Research (AFOSR) under Contract No.FA9550-19-1-0378
- Ohio Supercomputer Center, Project No. PAS0072



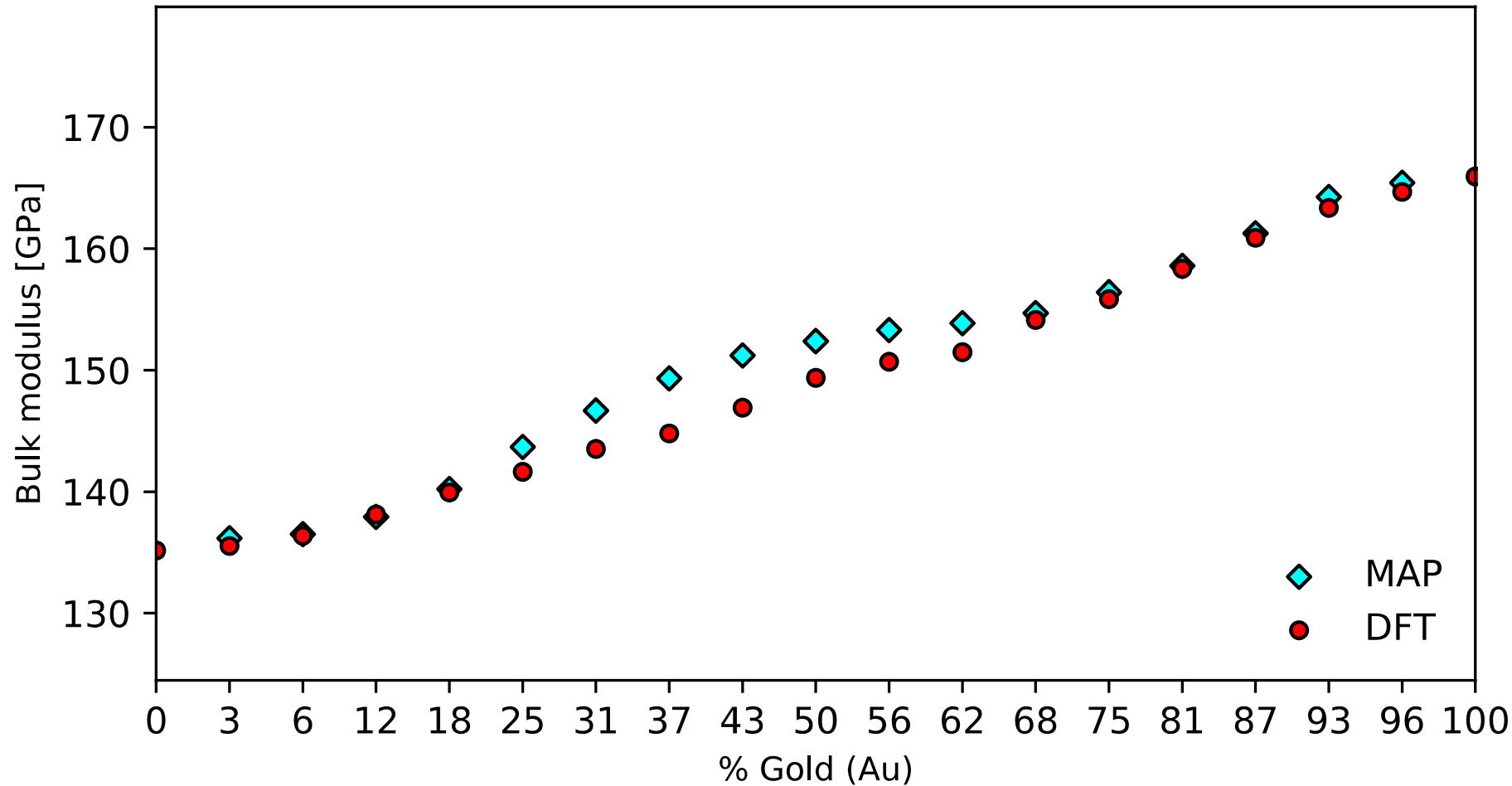
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# APPENDIX

# ILLUSTRATION: PREDICTIONS WITH AND WITHOUT MODEL ERROR

With (left, **grey**) and without (right, **blue**) a simple form of additive error (iid Gaussian)



Notably,

- **predictions w/o model error** under-represent uncertainty.
- **predictions with model error** provide coverage of the DFT data.

In *new* prediction settings – where additive model error cannot be transferred -- the uncertainty will be considerably under-represented.

# GP SURROGATES WITH GAUSSIAN INPUTS

Surrogate model:  ~~$\mathcal{M}(x_i; \lambda)$~~   $\rightarrow \mathcal{N}(m_\star(\lambda), \sigma_\star^2(\lambda))$

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$$v_{x_i}(\theta, S) = \sigma^2(x_i) = \sigma_k^2 + \sigma_n^2 - \text{trace}((K(\Theta, \Theta) + \sigma_n^2 I)^{-1} L) \\ + \text{trace}((L - \ell \ell^T) \beta \beta^T)$$

$$\ell_i = \sigma_k^2 \frac{1}{\sqrt{\det(\Gamma_{\mathcal{A}}^{-1} S + I)}} \exp\left(-\frac{1}{2}((\lambda_{\mathcal{A}^c} - \theta_{\mathcal{A}^c}^i)^T \Gamma_{\mathcal{A}^c}^{-1} (\lambda_{\mathcal{A}^c} - \theta_{\mathcal{A}^c}^i))\right) \exp\left(-\frac{1}{2}(\theta - \theta_{\mathcal{A}}^i)^T (S + \Lambda_{\mathcal{A}})^{-1} (\theta - \theta_{\mathcal{A}}^i)\right)$$

$$L_{ij} = k(\lambda|_{\lambda_{\mathcal{A}}=\theta}, \theta^i) k(\lambda|_{\lambda_{\mathcal{A}}=\theta}, \theta^j) \\ \cdot \frac{1}{\sqrt{\det(2\Gamma_{\mathcal{A}}^{-1} S + I)}} \exp\left(2\left(\theta - \frac{1}{2}(\theta_{\mathcal{A}}^i + \theta_{\mathcal{A}}^j)\right)^T \Gamma_{\mathcal{A}}^{-1} (2\Gamma_{\mathcal{A}}^{-1} + S^{-1})^{-1} \Gamma_{\mathcal{A}}^{-1} \left(\theta - \frac{1}{2}(\theta_{\mathcal{A}}^i + \theta_{\mathcal{A}}^j)\right)\right).$$

\*Candela, J. Q., Girard, A., Larsen, J., & Rasmussen, C. E. (2003, April). Propagation of uncertainty in Bayesian kernel models-application to multiple-step ahead forecasting. In *2003 IEEE International Conference on Acoustics, Speech, and Signal Processing, 2003. Proceedings.(ICASSP'03)*. (Vol. 2, pp. II-701). IEEE.

