

STL Implementation in C

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Instructor:
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Teaching Assistant: Monisha Singh Summary: The Standard Template Library (STL) is a set of C++ template classes to provide common programming data structures and functions such as maps, sets, vectors, etc. In this project we are trying to implement STL like containers in C. Their implementation includes memory allocation, inserting an element, searching for an element, deletion and many such operations. Further then we have done the time analysis and tried to optimise the complexities of our functions.

1. Introduction

The Standard Template Library (STL) is a well known set of classes which offer a variety of set of functions such as sets, maps, vectors ehich make many structures easy to use. The STL is a powerful set of C++ template classes to provide general-purpose classes and functions with templates that implement many popular and commonly used algorithms and data structures. A container is a holder object that stores a collection of other objects (its elements). The container manages the storage space for its elements and provides member functions to access them.

Since C does not provide us with any such library or template, implementation of these container elements of C + + in C is an interesting but also a challenging task. Each container element requires the implementation of some or the data structure. Various basic functions have been created like memory allocation, inserting an element, deletion, searching for an element, etc. All functions have been created maintaining optimised time complexities.

Many containers have several member functions in common, and share functionalities. The decision of which type of container to use for a specific need does not generally depend only on the functionality offered by the container, but also on the efficiency of some of its members (complexity).

VECTOR

Vectors are the same as dynamic arrays with the ability to resize itself automatically when an element is inserted or deleted, with their storage being handled automatically by the container. In vectors, data is inserted at the end. Inserting at the end takes differential time, as sometimes the array may need to be extended. Removing the last element takes only constant time because no resizing happens. Unlike arrays, their size can change dynamically, with their storage being handled automatically by the container.

SETS

Sets are a type of associative container in which each element has to be unique because the value of the element identifies it. The values are stored in a specific sorted order i.e. either ascending or descending. Sets are containers that store unique elements following a specific order. In a set, the value of an element also identifies it and each value must be unique. they can be inserted or removed from the container. Set implementation is based on implementing rb trees, a well recognised data structure.

MAPS

Maps are associative containers that store elements in a mapped fashion. Each element has a key value and a mapped value. No two mapped values can have the same key values. The types of key and mapped value may differ, and are grouped together. Internally unordered map is implemented using Hash Table, the key provided to map is hashed into indices of a hash table which is why the performance of data structure depends on the hash function.

2. Figures, Tables and Algorithms

2.1. Figures

The following figures demonstrate the working of containers like vector, map, set(using rb trees).

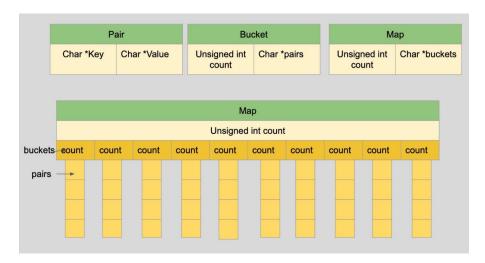


Figure 1: Demonstration of Map

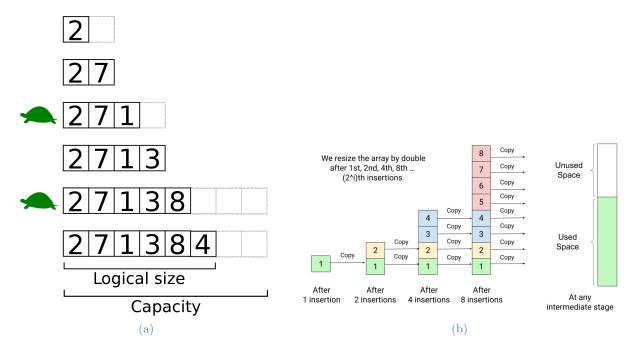


Figure 2: Resizing in vector

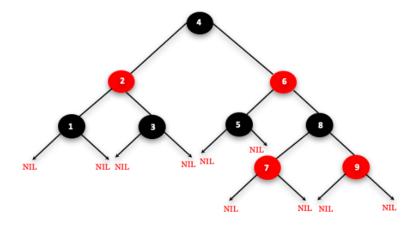


Figure 3: Demonstration of RB trees

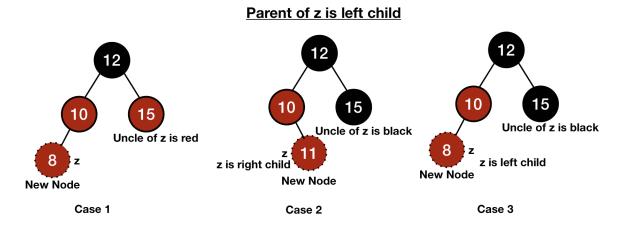


Figure 4: Insertion in RB trees

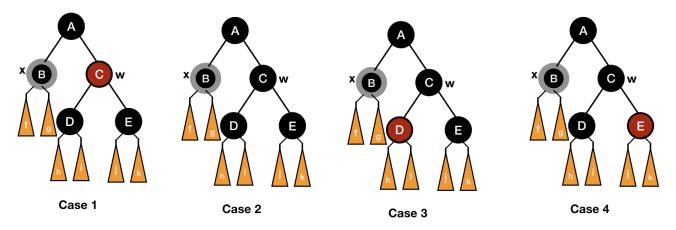


Figure 5: Deletion in RB trees

2.2. Time Complexity

Given below is the time complexity of various operation performed in vector, set and unordered map.

SET

FUNCTION	Complexity
set_insert	$O(\log(n)$
set_erase	$O(\log(n))$
$\operatorname{set}_{\mathbf{find}}$	$O(\log(n))$
set _size	O(1)
set _display	$O(\log(n))$
${ m set_begin}$	$O(\log(n))$
${ m set_end}$	$O(\log(n))$

Table 1: Time Complexity of functions of Set

VECTOR

FUNCTION	Complexity
vector_push_back	O(1)
vector_pop_back	O(1)
vector_display	O(N)
vector_at	O(N)
${f vector_find}$	O(N)
vector_clear	O(1)

Table 2: Time Complexity of functions of Vector

MAP

FUNCTION	Complexity
map_insert	O(1)
map_at	O(1)
map_erase	O(1)
map_size	O(1)
map display	O(N)

Table 3: Time Complexity of functions of Map

2.3. Algorithms

Pseudo-algorithms of our code are as follows:

 \mathbf{SET}

Algorithm 1 new node(key)

- 1: node*n = allocate memory to node n
- 2: n.color = red
- 3: n.data = key
- 4: n.left = NULL
- 5: n.right = NULL
- 6: n.parent = NULL
- 7: return n

Algorithm 2 create()

- 1: set t = allocate memory to t
- 2: node* null=allocate memory
- 3: n.color=black
- 4: n.left-NULL
- 5: n.right=NULL
- 6: n.parent=NULL
- 7: t.Null=NULL
- 8: t.root=t.Null
- 9: return t

Algorithm 3 LEFT ROTATE(T,X)

- 1: ptr = x.right
- $2: \mathbf{if} \ x.right.left! = NULL$
- 3: x.right.left.parent=x
- 4: **if** x.parent = NULL
- 5: t.root=x.right
- 6: **else if** x = s.parent.left
- 7: x.parent.right=x.right
- 8: **else**
- 9: x.parent.right=x.right
- 10: x.right.parent=x.right
- 11: x.parent=x.right
- 12: x.right=x.right.left
- 13: ptr.left=x

Algorithm 4 RIGHT ROTATE(T,X)

- 1: ptr = x.left
- 2: **if** x.left.right! = NULL
- 3: x.left.right.parent=x
- 4: **if** x.parent = NULL
- 5: t.root=x.left
- 6: else if x = s.parent.right
- 7: x.parent.left = x.left
- 8: **else**
- 9: x.parent.left=x.left
- 10: x.right.left=x.left
- 11: x.parent=x.left
- 12: x.left=x.left.right
- 13: ptr.right=x

Algorithm 5 INSERT FIXUP(T,x)

```
1: while x.parent.color = red
      if both x.parent.color and x.uncle.color is red
3:
         color x's grandparent red
         color x's parent and uncle black
4:
      else
5:
         if x's parent is the left child
6:
            if x is the right child
7:
8:
               q.x=x
               LEFT ROTATE(T,X)
9:
            color x's parent black
10:
            color x's grandparent red
11:
            RIGHT ROTATE(T,x's grandparent)
12:
         else
13:
            if x is left child
14:
15:
               q.x=x
               RIGHT ROTATE(T,x)
16:
            color x's parent black
17:
18:
            color x's grandparent red
            LEFT ROTATE(T,x's grandparent)
19:
20: t.root.color=black
```

Algorithm 6 INSERT(T,n)

```
1: create(z)
2: ptr=t->Null
3: ptr=t->root
4: whileptr!=t->NULL
      y=ptr
5:
6:
      \mathbf{if} \ z.data < ptr.data
7:
          ptr=ptr.left
      else if z.data = ptr.data
8:
9:
          return
      else z.data > ptr.data
10:
11:
          ptr=ptr.right
12: z->p=y
13: if y=t.Null
14:
      make z root
15: else if z.data < y.data
      y->l=z
16:
17: else
18:
      y->r=z
19: z.r=t.null
20: z.l=t.null
21: increment size
22: INSERT FIXUP(T,z)
```

Algorithm 7 rb TRANSPLANT(T,A,B)

```
1: if a is the root
      t.root=b
3: else if a is the right child
```

 $a.parent.right{=}b$

5: **else**

a.parent.left=b 6:

7: b.parent=a.parent

Algorithm 8 Successor(T,x)

```
1: \ \mathbf{while} \textit{x.left!} = NULL
```

x=x.left

3: return x

Algorithm 9 swap c(x,y)

```
1: int k=x.color
```

2: x.color=y.color

3: y.color = k

Algorithm 10 find(t,data)

```
1: node * ptr=t.root
```

2: while ptr!=t.Null

3: $\mathbf{if} \mathit{ptr.data} \!=\! \mathit{data}$

return ptr 4:

else if ptr.data < data5:

6: ptr=ptr.right

7: else

8: if ptr=ptr.Null

print not found

10: return ptr

Algorithm 11 erase(T,n)

```
1: node z= find n in t
2: node y=z
3: node x
 4: y.original.color=y.color
 5: \mathbf{if} z.left = t.NULL
      x=z.right
       rb TRANSPLANT(T,z,z.right
 8: else if z. right=t. NULL
      x=z.left
9:
10:
      {
m rb}\ {
m TRANSPLANT}({
m T,z,z.left}
11: else
       y=Successor(T,z.right)
12:
      y.original.color = y.color\\
13:
      x=y.right
14:
15:
      if y.parent=z
          x.parent=z
16:
17:
       else
18:
          rb TRANSPLANT(T,y,y.right)
          y.right=z.right
19:
          y.right.parent=y
20:
      rb TRANSPLANT(T,z,y)
21:
22:
      y.left=z.left
23:
      y.left.parent=y
       y.color=z.color
24:
25: \mathbf{if} y.original.color is black
       DELETE FIXUP(T,x)
26:
27: decrement size
```

Algorithm 12 delete fixup(T,x)

```
1: whilex is not root and x's color is double black
      if x is the left child
2:
          node sibling = x.parent.right
3:
             if sibling color is red
4:
                swap c(color of x.parent and sibling)
5:
                LEFT ROTATE(T,x.parent)
6:
                sibling = x.parent.right
 7:
             if color of both sibling child is black
8:
                color sibling red
9:
                x=x.parent
10:
11:
             else
                if color of sibling right child is black
12:
                   color sibling left child black
13:
                   color sibling red
14:
                   RIGHT ROTATE(T,x.parent)
15:
                   sibling=x.parent.right
16:
                color sibling right child black
17:
                LEFT ROTATE(T,x.parent)
18:
                sibling.color = x.parent.color
19:
                color x's parent black
20:
                x=t.root
21:
22:
      else
          node sibling = x.parent.left
23:
24:
             if sibling color is red
                swap c(color of x.parent and sibling)
25:
                RIGHT ROTATE(T,x.parent)
26:
                sibling = x.parent.left
27:
             if color of both sibling child is black
28:
29:
                color sibling red
30:
                x=x.parent
31:
             else
                if color of sibling left child is black
32:
                   color sibling right child black
33:
                   color sibling red
34:
                   LEFT ROTATE(T,x.parent)
35:
                   sibling=x.parent.left
36:
                color sibling left child black
37:
                RIGHT ROTATE(T,x.parent)
38:
39:
                sibling.color = x.parent.color
                color x's parent black
40:
                x=t.root
41:
42: color x black
```

```
Algorithm 13 begin(T)
```

```
1: x=Successor(t,t.root)
```

2: return x

Algorithm 14 end(T)

- 1: x=t.root
- 2: whilex.right!=t.Null
- 3: x=x.right
- 4: return x

Algorithm 15 display(T,n)

- 1: **if** *n!*=*t.Null*
- 2: display(T,n.left)
- 3: print n.data
- 4: display(T,n.right)

MAP

Algorithm 16 struct map * map_new(size)

- 1: map=(struct map*)malloc(sizeof(struct map))
- 2: map->count=size
- 3: map->buckets=(struct bucket*)malloc(map->count * sizeof(struct bucket))
- 4: memset(map->buckets, 0, map->count * sizeof(struct bucket))
- 5: return map

Algorithm 17 map insert(map,key,value)

```
1: index=hash(key)%map->count
```

- 2: bucket=&(map->buckets[index])
- 3: pair=get pair(bucket, key)
- 4: **if**(pair!=NULL)
- 5: **if**(length(pair->value)<length(value))
- 6: pair->value=(char *)realloc(pair->value, (strlen(value)+1)*sizeof(char))
- 7: pair->value=value
- 8: if(bucket->count==0)
- 9: bucket->pairs=(struct pair*)malloc(sizeof(struct pair))
- 10: bucket->count=1
- 11: **else**
- 12: bucket->pair=(struct pair*)realloc(bucket->pairs, (bucket->count+1) *sizeof(struct pair))
- 13: bucket->count++
- 14: pair=&(bucket->pairs[bucket->count-1])
- 15: pair->key=key
- 16: pair->value=value

Algorithm 18 char * map at(map,key)

- 1: index=hash(key)%map->count
- 2: bucket=&(map->buckets[index])
- 3: pair=get pair(bucket, key)
- 4: **if**(pair==NULL)
- 5: return NULL
- 6: return pair->value

```
Algorithm 19 map_erase(map,key,value)
```

```
1: index=hash(key)%map->count
2: bucket=&(map->buckets[index])
3: pair=get pair(bucket, key)
4: if(pair==NULL)
      return NULL
6: if(pair->value==value)
      temp=&(bucket->pairs[bucket->count-1])
7:
      if(temp!=pair)
8:
           pair->key=temp->key
9:
           pair->value=temp->value
10:
      bucket->pairs=(struct pair *)realloc(bucket->pairs,(bucket->count-1)*sizeof(struct pair))
11:
      bucket->count--
12:
```

Algorithm 20 map_size(map)

```
1: size=0
2: for(i=0 to map->count)
3: size+=(map->buckets[i]).count
4: return size
```

Algorithm 21 map_display(map)

```
    size=0
    for(i=0 to map->count)
    size=(map->buckets[i]).count
    bucket=&(map->buckets[i])
    pair=(bucket->pairs)
    for(j=0 to size)
    print(pair->key,pair->value)
```

Algorithm 22 hash(str)

```
1: hash=1
2: for(i=0 to length(str))
3: c=*str
4: hash = (hash*2) + c
5: str++
6: return hash
```

Algorithm 23 get_pair(bucket,key)

```
1: if bucket->count==0
2: return NULL
3: pair=bucket->pairs
4: for(i=0 to bucket->count)
5: if(pair->key!=NULL&&pair->value!=NULL)
6: if(pair->key==key)
7: return pair
8: pair++
9: return NULL
```

VECTOR

Algorithm 24 vector create(size)

- 1: Create vector node
- 2: Alloc memory
- 3: vec->capacity=size
- 4: vec->size=size
- 5: return vec

Algorithm 25 vector_push_back(vector,n)

```
1: if(vector->size==vector->capacity)
```

- 2: (realloc 2*size*sizeof(int))
- 3: (vector->capacity*=2)
- 4: vector->vector[vector->size]=n
- 5: vector->size++

Algorithm 26 vector_pop_back(vector,n)

1: vector->size--

Algorithm 27 vector at(vector,index)

- 1: v=vector->vector
- 2: if(index>=vector->size)
- 3: (return NULL)
- 4: return &v[index]

Algorithm 28 vector find(vector,n)

```
1: ind = -1
```

- 2: v=vector->vector
- 3: **for**(i=0 to vector->size)
- 4: (if v[i]==n)
- 5: (ind=i)
- 6: (break)
- 7: return ind

Algorithm 29 vector clear(vector)

1: vector->size=0

3. Conclusions

We have implemented C++ STL containers like structures like unordered map, sets and vectors in C. Their time complexities are as per the actual algorithms in the STL library.

4. Bibliography and citations

The following reference links were used:

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