

# HW CI-4 Clustering Algorithms

## Computational Intelligence - STRATEGOS UNIGE

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Date: 7 April 2022

## Assignment: Develop Hard and Fuzzy Clustering Algorithms from scratch

We will implement some clustering algorithms from scratch and we will test on two data sets constituted by some 2-dimensional distributions of points.

Then we will apply our algorithms to a real-word data set.

### TODO:

1. Generate data sets DS1 (non overlapping blobs), DS2 (overlapping blobs) and load DS3 from the file iris.csv.
2. Implement K-Means, Fuzzy C- Means and Graded Possibilistic C-Means.
3. Implement WTA and the  $\alpha$  - cut defuzzifiers of fuzzy partitions.
4. Implement RAND and Jaccard Indices for hard partition comparison
5. Apply K-Means, Fuzzy C-Means and Graded Possibilistic C-Means to the 3 data sets using a multi-start approach; search for 2, 3, and 4 clusters.
6. Defuzzify the soft partitions of Fuzzy C- Means and Graded Possibilistic C-Means using the WTA (Winner-Takes-All) criterion.
7. Visualize the results on the scatter plot, highlighting the centroids and using a different color for each cluster.
8. Measure the *accuracy* of the hard partitions by comparing them with the ground-truth constituted by the targets of the data sets. For the comparison use RAND and Jaccard indices.

For the Graded Possibilistic C-Means use a possibilistic degree  $\beta = 0.8$  and a value of  $\eta$  (identical for each cluster) comparable with the *standard\_dev*<sup>2</sup> for data sets DS1 and DS2. For DS3 (Iris data set)  $\eta$  must be selected by checking the value of the accuracy (model selection - grid search).

### Optional part A: Consensus Matrix

1. Implement the Consensus Matrix technique for partition ensembling.
2. For each data set, take the 9 best hard partitions (3 clusters) obtained for data set DS2 in Part A and construct an ensemble using the technique of the consensus matrix.
3. Visualize the results on the scatter plot, highlighting the centroids and using a different color for each cluster.
4. Measure the *accuracy* of the partition induced by the consensus matrix by comparing it with the ground-truth constituted by the targets of the data sets. For the comparison use RAND index. Find the best value for the threshold  $\alpha$ .

### Optional part B: Study of the Graded Possibilistic C-Means algorithm

see below

## Import libraries

In [ ]:

```
from sklearn.datasets import make_blobs
import matplotlib.pyplot as plt
import pandas as pd
import numpy as np
import time #timing the performances
import copy
```

## 1 Data sets generation

### Data set DS1: Separate blobs

- number of points in the dataset 400
- number of features in the dataset 2
- number of clusters in the dataset 3
- standard deviation of points of a cluster 0.70

In [ ]:

```
# Dataset setup crea nuovo dataset
number_of_points = 400 # number of points in the dataset
number_of_features = 2 # number of features in the dataset
number_of_clusters = 3 # number of clusters in the dataset
standard_dev = 0.70 # standard deviation of points of a cluster
# st dev alta mi alza le distanze

features, target = make_blobs(n_samples = number_of_points,
                              n_features = number_of_features,
                              centers = number_of_clusters,
                              cluster_std = standard_dev,
                              shuffle = True)
# il dataset ha features e target
# makeblobs è di sklearn
```

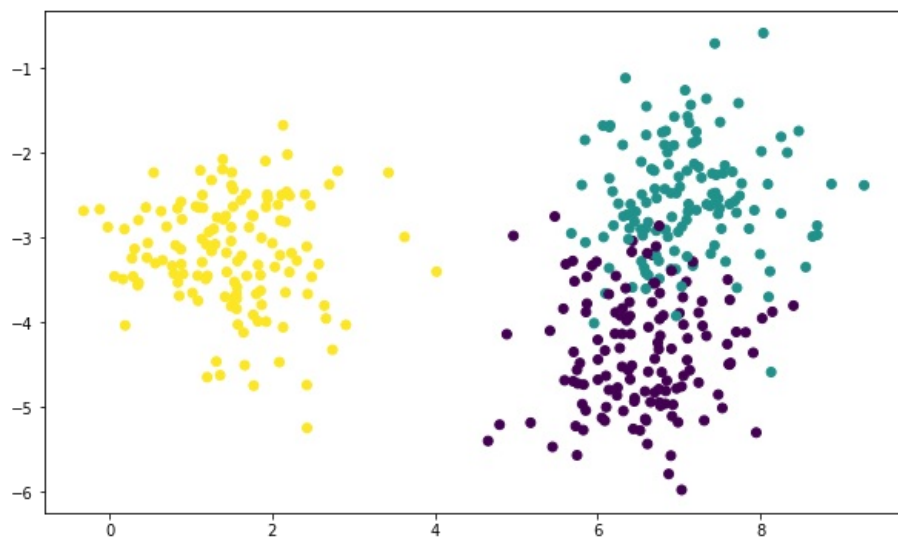
In [ ]:

```
# Create a scatterplot of first two features

#creating array of for c clusters and 400 features

plt.figure(figsize=(10,6))
plt.scatter(features[:,0], features[:,1], c=target)

# View scatterplot
plt.show()
```



In [ ]:

```
x_labels = ['Feature'+str(x) for x in range(features.shape[1])]
y_label = 'target'

feats = pd.DataFrame(features, columns=x_labels)
tgts = pd.Series(target, name=y_label)
dataset1 = pd.concat([feats,tgts],axis=1)
dataset1.head()
```

Out[ ]:

	Feature0	Feature1	target
0	5.702309	-4.698122	0
1	7.340054	-4.161537	0
2	7.410921	-2.245790	1
3	1.314874	-4.465950	2
4	2.742432	-4.326481	2

## Data set DS2: Overlapping blobs

- number of points in the dataset 400
- number of features in the dataset 2
- number of clusters in the dataset 3
- standard deviation of points of a cluster 1.70

In [ ]:

```
# Dataset setup
number_of_points = 400      # number of points in the dataset
number_of_features = 2      # number of features in the dataset
number_of_clusters = 3      # number of clusters in the dataset
standard_dev = 1.70         # standard deviation of points of a cluster

features, target = make_blobs(n_samples = number_of_points,
                              n_features = number_of_features,
                              centers = number_of_clusters,
                              cluster_std = standard_dev,
                              shuffle = True)
```

In [ ]:

```
ZeroList = np.zeros((3,400))

#print (ZeroList)
#creating a list of all the zeros for the number of targets we have so that we can run our test later

for i in range(0,len(target)):
    el = target[i]
    ZeroList[el,i] = 1

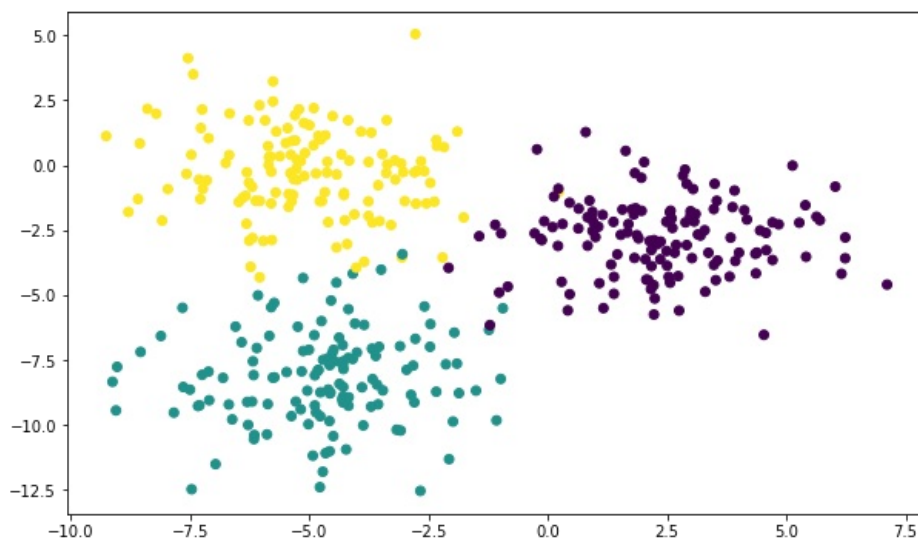
GT_list= list()
GT_list.append(ZeroList)
print(GT_list)

[array([[1., 1., 1., ..., 0., 0., 0.],
        [0., 0., 0., ..., 0., 0., 0.],
        [0., 0., 0., ..., 0., 0., 0.]])]
```

In [ ]:

```
# Create a scatterplot of first two features
plt.figure(figsize=(10,6))
plt.scatter(features[:,0], features[:,1], c=target)

# View scatterplot
plt.show()
```



In [ ]:

```
x_labels = ['Feature'+str(x) for x in range(features.shape[1])]
feats = pd.DataFrame(features, columns=x_labels)
tgts = pd.Series(target, name='target')
dataset2 = pd.concat([feats,tgts],axis=1)
dataset2.head()
```

Out[ ]:

	Feature0	Feature1	target
0	-7.501660	-8.644862	1
1	-8.207185	1.977507	2
2	-5.692888	1.293990	2
3	4.173844	-2.094026	0
4	-4.227330	-10.947644	1

## Data set DS3: Iris Data set

Read the data set from the file *iris.csv* as done in *HW-CI-3-KNN.ipynb*

In [ ]:

```
# insert code here
# see DEMO CI3-a kNN classifier

col_names = ['sepal-length', 'sepal-width', 'petal-length', 'petal-width', 'class']
dataset = pd.read_csv('iris.csv', names=col_names)

#print (tgts)
target = 'class'

#creating dataset for petal width and length
x = dataset.get('petal-length')
y = dataset.get('petal-width')

TargetMatrix = dataset.get(target)
ModMatrix = list()
#we will run a loop for every target value and assign number and append to a new column

#identifying each feature with a number 0,1,2
for tgts in TargetMatrix:
    if tgts=='Iris-setosa':
        ModMatrix.append(0)
    if tgts=='Iris-versicolor':
        ModMatrix.append(1)
    if tgts=='Iris-virginica':
        ModMatrix.append(2)

target = pd.Series(ModMatrix, name='target') #created a new series with the appended data
datasetIris = pd.concat([x,y,target],axis=1)

print(datasetIris)
```

	petal-length	petal-width	target
0	1.4	0.2	0
1	1.4	0.2	0
2	1.3	0.2	0
3	1.5	0.2	0
4	1.4	0.2	0
..	...	...	...
145	5.2	2.3	2
146	5.0	1.9	2
147	5.2	2.0	2
148	5.4	2.3	2
149	5.1	1.8	2

[150 rows x 3 columns]

In [ ]:

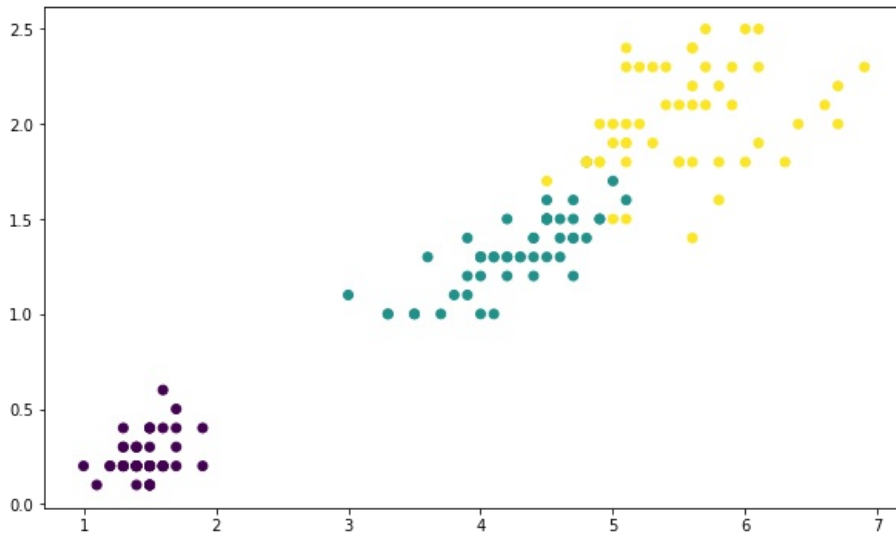
```
# after downloaded the Iris data set uncomment the code in this box
```

```
#Create a scatterplot of first two features
```

```
plt.figure(figsize=(10,6))  
plt.scatter(x,y,c=target)
```

```
# View scatterplot
```

```
plt.show()
```



In [ ]:

```
GT_iris = np.zeros((3,150), dtype=int)
```

```
for i in range(0,len(target)):  
    el = target[i]  
    GT_iris[el,i] = 1
```

```
GT_list.append(GT_iris)
```

```
print(GT_list)
```

[illegible]

In [ ]:

```
# after downloaded the Iris data set uncomment the code in this box
```

```
x_labels = ['Feature'+str(x) for x in range(features.shape[1])]
feats = pd.DataFrame(features, columns=x_labels)
tgts = pd.Series(target, name='target')
dataset2 = pd.concat([feats,tgts],axis=1)
dataset2.head()
```

Out[ ]:

	Feature0	Feature1	target
0	-1.171644	2.434095	0.0
1	5.465683	-1.854309	0.0
2	-1.875120	-5.813020	0.0
3	-2.913915	-7.217382	0.0
4	10.391301	0.238920	0.0

## 2 Implentation of clustering algoritms

### K-Means (aka Hard C-Means)

K-Means minimizes the functional

$$E(X) = \sum_{i=1}^K \sum_{\mathbf{x} \in \pi_i} \|\mathbf{x} - \mathbf{v}_i\|^2 = \sum_{ih} u_{ih} \|\mathbf{x}_h - \mathbf{v}_i\|^2, \text{ with } u_{ih} = \begin{cases} 1 & \text{if } \mathbf{x}_h \in \pi_i \\ 0 & \text{otherwise} \end{cases}$$

where  $\mathbf{x}$  is a point of the data set,  $n$  is the size of the data set,  $K$  is the number of clusters,  $\mathbf{v}_i$  are the centroids, and  $\pi_i$  is the subset of the data set belonging to cluster  $i$ . Note that  $E(X)$  is proportional to the expectation of distortion.

In this implementation we will initialize the cluster centers by selecting at random  $K$  points from the data set, and then we will iterate the re-evaluation of all  $\pi_i$  and of  $\mathbf{v}_i$ , until a STOP CRITERION holds.

The STOP CRITERION can be:

1. Stop when the variation of  $E(X)$  in two subsequent cycles ( $\Delta E$ ) is under an assigned threshold  $\tau > 0$ .
2. Stop when the maximum variation of the centroids  $\mathbf{v}_i$  in two subsequent cycles ( $\Delta \mathbf{v}$ ) is under an assigned threshold  $\tau > 0$ .
3. Stop after an assigned number  $S$  of iterations.

We suggest to use the following combined STOP CRITERION: **Stop after an assigned numer  $S$  of iterations AND Stop when the variation of  $< E > = \frac{E(X)}{K \cdot n}$  in two subsequent cycles ( $\Delta < E >$ ) is under an assigned threshold  $\tau > 0$ .**

In [ ]:

```
# add here the required imports
import sys
import matplotlib.pyplot as plt
import pandas as pd
import numpy as np
from scipy.spatial import Voronoi, voronoi_plot_2d #for voronoi tessellation
```

In [ ]:

```
class KMeans:
```

```
    def __init__(self, k=3, tau=0.001, max_iter=300, verbose=False):
        self.k = k # number of centroids
        self.tau = tau # stopping threshold
        self.max_iter = max_iter # maximum number of iterations in case of no convergence
        self.verbose = verbose # detailed printout
        self.cost = list() # service variable to store cost history
        self.centroids = None # centroids after fitting
        self.U = None # membership matrix (for K-Means U is hard, i.e. its element are 0/1)

        # additional variable shared among the various functions
        self.n = 0 # holds the dataset size
        self.prev_error = np.inf # assign initial error as infinite
        self.iteration = None # interation number
        self.error = None # private variable to hold error E(X)
        self.distances = None # private variable to hold distances
        self.prev_centroids = None
        self.x_map = None
```

```

def get_centroids(self):
    return self.centroids

def get_U(self):
    UU = copy.deepcopy(self.U)
    return UU.transpose()

def get_cost_history(self):
    return self.cost

def plot_cost_history(self, size_x = 15, size_y = 6, data=None, label=None):
    if data==None:
        data= self.cost
    if label==None:
        label = 'Cost History'

    # simply plot the cost history
    fig, ax = plt.subplots(figsize=(size_x,size_y))

    ax.plot(data, color='r', label=label)      # cost line
    ax.legend()
    plt.show()
    return ax

def calc_cost(self):
    # reset distances for items for farther clusters
    # define the cluster index list for data items
    x_map = np.argmin(self.distances,axis=1)

    # define the membership matrix from cluster index list
    # u becomes 1 for items in given cluster and zero for the others
    u = np.zeros_like(self.distances)
    u[np.arange(self.n),x_map] = 1
    # set the distances other than minimal to zero
    dist = np.multiply(self.distances,u) # optimized multiplication
    if self.verbose: sys.stderr.write('dist: {}\n'.format(dist))
    # compute the error - <E> expectation of distortion

    self.error = np.sum(dist)/(self.k*self.n)
    #self.error = np.sum(dist)

    #delta_e = np.abs(self.prev_error - error)
    delta_e = self.prev_error - self.error
    #print ("error= ", error, " delta_error= ", delta_e)
    self.cost.append(self.error)
    self.prev_error = self.error
    return delta_e

def predict(self,x):
    # checks the test samples and return the list of centroid indexes
    # which each sample belongs to

    if self.verbose: sys.stderr.write('centroids: {}\n'.format(self.centroids))

    # compute distances from centroids
    for j in range(self.n):
        for i in range(self.k):
            self.distances[j][i] = np.sqrt(np.sum((x[j]-self.centroids[i])**2))
            #self.distances[j][i] = np.sum((x[j]-self.centroids[i])**2)
            self.distances[j][i] = np.sum(np.dot(x[j]-self.centroids[i],x[j]-self.centroids[i]))

    #print (self.distances)
    # assign the points of the data sets to the k clusters (nearest centroid)
    self.x_map = np.argmin(self.distances,axis=1)
    return self.x_map # lista delle predizioni

def get_centroids_distance(self):
    # controllo le distanze da centroidi
    clu_dist = 0
    for c, pc in zip(self.centroids,self.prev_centroids): clu_dist += np.sqrt(np.dot(c-pc,c-pc))
    return clu_dist

def fit (self, x):
    # performs kmeans clustering on training samples and assign centroids
    self.n = x.shape[0] # number of training items
    c = x.shape[1] # number of features

    # initialize the K centroids by selecting at random K points from the data_set
    idx = np.random.randint(self.n,size=self.k)
    self.centroids = x[idx].copy()
    self.prev_centroids = self.centroids.copy()

```



```

# initialize the membership matrix with n rows and k columns
self.U = np.zeros((self.n,self.k), dtype=int)
# create a distance matrix with the same shape as the membership one
self.distances = np.zeros_like(self.U,dtype=float)

# iterate while DELTA E > tau (STOP CRITERION #1) or max_iter not reached
loop = True
self.iteration = 0
while (loop):
    # match training data to the current centroids and update their
    # membership index list
    self.x_map = self.predict(x)
    if self.verbose: sys.stderr.write('x_map: {}\n'.format(self.x_map))

    # calculate the new k centroids
    for i in range(self.k):
        # perform the average only if the centroid has assigned elements
        # otherwise NaN is assigned and the algorithm has errors
        if (self.x_map == i).any():
            self.centroids[i] = np.average(x[self.x_map == i],axis=0)

    delta_cost = self.calc_cost()
    self.iteration +=1
    # break the loop if the stopping conditions are met
    clu_dist = self.get_centroids_distance()
    self.prev_centroids = self.centroids.copy()
    if self.verbose:
        print(self.iteration, "error= ", self.error, " delta_error= ", delta_cost, "tau = ", self.tau)
    loop = (abs(delta_cost) > self.tau) and (self.iteration < self.max_iter)

    #loop = (delta_cost > self.tau) and (clu_dist > self.tau) and (self.iteration < self.max_iter)

# set the membership matrix for the final configuration
self.U[np.arange(self.n),self.x_map] = 1

return self

```

## Fuzzy C-Means

Fuzzy C-Means minimizes the functional

$$J(U, V) = \sum_{h=1}^n \sum_{i=1}^c \left( u_{ih} \right)^m \| \mathbf{x}_h - \mathbf{v}_i \|^2, \quad \forall h = 1, \dots, n \quad \forall i = 1, \dots, c$$

with the probabilistic constraint

$$\sum_{i=1}^c u_{ih} = 1$$

where  $\mathbf{x}_h$  are the point of the data set,  $c$  is the number of clusters,  $\mathbf{v}_i$  are the centroids, and  $u_{ih}$  are the memberships of data points to clusters.

In this implementation we will initialize the cluster centers  $\mathbf{v}_i$  by selecting at random  $c$  points from the data set, and then we will iterate the re-evaluation of all  $u_{ih}$  and of  $\mathbf{v}_i$ ,

$$u_{ih} = \frac{1}{\sum_{j=1}^c \left( \frac{\| \mathbf{x}_h - \mathbf{v}_i \|}{\| \mathbf{x}_h - \mathbf{v}_j \|} \right)^{\frac{2}{m-1}}}$$
$$\mathbf{v}_i = \frac{\sum_{h=1}^n \left( u_{ih} \right)^m \mathbf{x}_h}{\sum_{h=1}^n \left( u_{ih} \right)^m}$$

until a STOP CRITERION holds.

The STOP CRITERION can be either:

1. Stop when the variation of  $J(U, V)$  in two subsequent cycles ( $\Delta J$ ) is under an assigned threshold  $\tau > 0$ .
2. Stop when the variation of

$$E(X) = \sum_{ih} u_{ih} \| \mathbf{x}_h - \mathbf{v}_i \|^2$$

in two subsequent cycles ( $\Delta E$ ) is under an assigned threshold  $\tau > 0$ .

3. Stop when the maximum variation of the centroids  $\mathbf{v}_i$  in two subsequent cycles ( $\Delta \mathbf{v}$ ) is under an assigned threshold  $\tau \geq 0$ .
4. Stop when the maximum variation of the memberships  $u_{ih}$  in two subsequent cycles ( $\Delta u$ ) is under an assigned threshold  $\tau \geq 0$ .
5. Stop after an assigned number  $S$  of iterations.

We suggest to use the following combined STOP CRITERION: **Stop after an assigned number  $S$  of iterations AND Stop when the variation of  $\frac{E(X)}{c \cdot n}$  in two subsequent cycles ( $\Delta < E >$ ) is under an assigned threshold  $\tau > 0$ .**

In [ ]:

```
class FuzzyCMeans:
```

```
def __init__(self, m=2, k=3, tau=0.001, max_iter=300, verbose=False):
    self.m = m #corresponds to the degree of fuzziness of the solutio
    self.c = k # number of centroids
    self.tau = tau # stopping threshold
    self.max_iter = max_iter # maximum number of iterations in case of no convergence
    self.verbose = verbose # detailed printout
    self.cost = list() # service variable to store cost history

    self.centroids = None # centroids after fitting
    self.U = None # membership matrix (for K-Means U is hard, i.e. its element are 0/1)

    # additional variable shared among the various functions
    self.n = 0 # holds the dataset size
    self.iteration = None # interation number

    self.prev_error = np.inf # assign initial error as infinite
    self.prev_error_j = np.inf # for j parameter
    self.error = None # private variable to hold error E(X)
    self.error_j = None # for j parameter

    self.distances = None # private variable to hold distances
    self.prev_centroids = None
    self.x_map = None

def distance(self, vect1, vect2): # return the square distance of two arrays
    distance=0
    for i in range(len(vect1)):
        distance = distance + (vect1[i] - vect2[i])**2
    return distance
```

```

def calc_U(self, list_x): # calculate the membership matrix
    # initialize the matrix
    matrix = copy.deepcopy(np.zeros((self.c, self.n)))
    # calculate coeff.
    m_exponent = 2/(self.m -1)
    #modify the centroid by calculating distance among each point
    for i in range(0,self.c): # for all the rows
        for h in range(0, self.n): # for all the columns
            sum = 0
            for j in range(0,self.c):

                centroidi = np.array(self.centroids[i])
                centroidj = np.array(self.centroids[j])
                dist1 = self.distance(list_x[h],centroidi)
                dist2 = self.distance(list_x[h], centroidj)
                if dist2==0: # if element = voronoi
                    sum=sum
                if dist2!=0 and dist1!=0:
                    sum = sum + (dist1 / dist2)**m_exponent

            if sum!=0:
                matrix[i][h] = matrix[i][h]+ (1/sum) # ematrix element
    self.U = matrix.transpose()
    #print(self.U)
    return matrix

def get_U(self):
    return self.U

def get_centroids(self):
    return self.centroids

def get_cost_history(self):
    return self.cost

def plot_cost_history(self, size_x = 15, size_y = 6, data=None, label=None):
    if data==None:
        data= self.cost
    if label==None:
        label = 'Cost History'

    # simply plot the cost history
    fig, ax = plt.subplots(figsize=(size_x,size_y))
    ax.plot(data, color='r', label=label) # cost line
    ax.legend()
    plt.show()
    return ax

def calc_cost(self):

    uj = copy.deepcopy(self.U).transpose()

    # errors
    #if self.verbose: sys.stderr.write('dist: {}\n'.format(dist)) #
    # <E> computation
    dist = np.multiply(self.distances,uj)

    self.error = np.sum(dist)/(self.c*self.n)
    delta_e = abs(self.prev_error - self.error)

    self.cost.append(self.error)
    self.prev_error = self.error
    #-----

    # <J> computation
    distj= np.multiply(self.distances,np.power(uj,self.m))
    self.error_j = np.sum(distj)

    if self.iteration>=2:
        delta_j = abs(self.prev_error_j - self.error_j)
    else:
        delta_j = 100

    return [delta_e,delta_j] # compare treshold

def predict(self,x):
    if self.verbose: sys.stderr.write('centroids: {}\n'.format(self.centroids))
    # compute distances from centroids
    for j in range(self.n):
        for i in range(self.c):
            self.distances[j][i] = np.sum(np.dot(x[j]-self.centroids[i],x[j]-self.centroids[i]))

```

```

# assign the points of the data sets to the k clusters (nearest centroid)

self.x_map = np.argmin(self.distances,axis=1)
return self.x_map

def get_centroids_distance(self):
    # check distance of centroids
    clu_dist = 0
    for c, pc in zip(self.centroids,self.prev_centroids): clu_dist += np.sqrt(np.dot(c-pc,c-pc))
    return clu_dist

def fit (self, x): #this code was edited
    # performs kmeans clustering on training samples and assign centroids
    self.n = x.shape[0] # number of training items
    c = x.shape[1] # number of features

    # initialize the K centroids by selecting at random K points from the data_set
    idx = np.random.randint(self.n,size=self.c)
    self.centroids = x[idx].copy()
    self.prev_centroids = self.centroids.copy()

    # initialize the membership matrix with n rows and k columns
    self.U = np.zeros((self.n,self.c), dtype=float) #
    # create a distance matrix with the same shape as the membership one
    self.distances = np.zeros_like(self.U,dtype=float)
    #-----

    # iterate while DELTA E > tau (STOP CRITERION #1) or max_iter not reached
    loop = True
    self.iteration = 0
    while (loop):
        # match training data to the current centroids and update their
        # membership index list
        self.x_map = self.predict(x)
        if self.verbose: sys.stderr.write('x_map: {}\n'.format(self.x_map))

        #-----
        # calculate the new k centroids
        #for this we create a loop for each element and calculate the centroid using the formula
        matrix= self.calc_U(x)
        for i in range(0,self.c):
            zero = np.zeros(len(x[0])) # zero array that will be updated

            numerator = copy.deepcopy(zero)
            denominator = 0
            for h in range(0,self.n):
                u_ij = matrix[i][h]**self.m #multiplying it by fuzzy component
                numerator = numerator + u_ij*x[h] #calculate the numerator
                denominator = denominator + u_ij
            self.centroids[i] = numerator/denominator #centroid is updated everytime
        self.U = matrix
        #-----

        deltas= self.calc_cost() # an array of delta_e and delta_j
        self.iteration +=1
        # break the loop if the stopping conditions are met
        clu_dist = self.get_centroids_distance()
        self.prev_centroids = self.centroids.copy()
        if self.verbose:
            print(self.iteration, "error= ", self.error, " delta_error= ", delta_cost, "tau = ", self.tau)
        # condition of loop, that takes delta_e, delta_j and the iterations
        loop = (abs(deltas[0]) > self.tau) and (abs(deltas[1]) > self.tau) and (self.iteration < self.max_it
er)

    return self

```

## Graded Possibilistic C-Means (GPCM)

### Graded Possibilistic C-Means (GPCM)

In this implementation we will initialize the cluster centers  $\mathbf{v}_i$  by selecting at random  $c$  points from the data set, and then we will iterate the re-evaluation of all  $u_{ih}$  and of  $\mathbf{v}_i$ ,

$$u_{hi} = \frac{\mathbf{O}_{matrix_{hi}}}{Z_h}, \quad \mathbf{O}_{matrix_{hi}} = e^{-\|\mathbf{x}_h - \mathbf{v}_i\|^2 / \eta_i}, \quad Z_h = \left( \sum_{i=1}^c \mathbf{O}_{matrix_{hi}} \right)^\beta, \quad \beta \in [0, 1]$$

$$\mathbf{v}_i = \frac{\sum_{h=1}^n u_{ih} \mathbf{x}_h}{\sum_{h=1}^n u_{ih}}$$

until until a STOP CRITERION holds.

$\beta \in [0, 1]$  is the *possibilistic degree* and establishes the grade between possibilistic and probabilistic clustering.

$\eta_j > 0$  is the spread of clusters. It can be set a-priori or estimated by using

$$\eta_i = \gamma \frac{\sum_{h=1}^n u_{ih} \|\mathbf{x}_h - \mathbf{v}_i\|^2}{\sum_{i=1}^n u_{ih}}$$

after an initialization with a Fuzzy C-Means algorithm ( $\gamma > 0$ , try  $\gamma \approx 1$ ).

The STOP CRITERION for the GPCM can be either:

1. Stop when the variation of

$$E(X) = \sum_{ih} u_{ih} \|\mathbf{x}_h - \mathbf{v}_i\|^2.$$

in two subsequent cycles ( $\Delta E$ ) is under an assigned threshold  $\tau > 0$ .

2. Stop when the maximum variation of the centroids  $\mathbf{v}_i$  in two subsequent cycles ( $\Delta \mathbf{v}$ ) is under an assigned threshold  $\tau \geq 0$ .
3. Stop when the maximum variation of the memberships  $u_{ih}$  in two subsequent cycles ( $\Delta u$ ) is under an assigned threshold  $\tau \geq 0$ .
4. Stop after an assigned number  $S$  of iterations.

We suggest to use the following combined STOP CRITERION: **Stop after an assigned number  $S$  of iterations AND Stop when the variation of  $\langle E \rangle = \frac{E(X)}{c \cdot n}$  in two subsequent cycles ( $\Delta \langle E \rangle$ ) is under an assigned threshold  $\tau > 0$ .**

In [ ]:

```
class GPCM:
```

```
    def __init__(self, k=3, tau=0.001, max_iter=300, eta=[0.1,0.1,0.1], gamma=1, beta=0.4, verbose=False):
```

```
        self.c = k # number of centroids
        self.tau = tau # stopping threshold
        self.max_iter = max_iter # maximum number of iterations in case of no convergence
        self.eta = eta # eta array
        self.gamma = gamma # gamma value
        self.beta = beta # beta value
        self.verbose = verbose # detailed printout
        self.cost = list() # service variable to store cost history
```

```
        self.centroids = None # centroids after fitting
        self.U = None # membership matrix
```

```
        # additional variable shared among the various functions
        self.n = 0 # holds the dataset size
        self.iteration = None # interation number
```

```
        self.prev_error = np.inf # assign initial error as infinite
        self.error = None # private variable to hold error E(X)
        self.distances = None # private variable to hold distances
        self.prev_centroids = None
        self.x_map = None
```

```
    def distance(self, vect1, vect2): # return square distance
        dist=0
        for i in range(len(vect1)):
            dist = dist + (vect1[i] - vect2[i])**2
        return dist
```

```
    def calc_U(self, x):
        # calculation of the membership matrix
        matrix = conv.deconv(np.zeros((self.n, self.c)))
```

```

matrix = copy.deepcopy(np.zeros((self.n, self.c)))
O_matrix = copy.deepcopy(np.zeros((self.n, self.c)))

for h in range(0,self.n):
    sum_O_matrix = 0
    for i in range (0,self.c):
        O_matrix[h][i]= np.exp( (-1)*(self.distance(x[h], self.centroids[i])) / self.eta[i])
        sum_O_matrix = sum_O_matrix + O_matrix[h][i]
    Z = sum_O_matrix**self.beta

    for i in range(0,self.c):
        matrix[h][i] = O_matrix[h][i]/ Z
self.U = matrix
return matrix

def get_U(self):
    UU = copy.deepcopy(self.U)

    return UU.transpose()

def get_centroids(self):
    return self.centroids

def get_cost_history(self):
    return self.cost

def plot_cost_history(self, size_x = 15, size_y = 6, data=None, label=None):
    if data==None:
        data= self.cost
    if label==None:
        label = 'Cost History'
    # simply plot the cost history
    fig, ax = plt.subplots(figsize=(size_x,size_y))
    ax.plot(data, color='r', label=label) # cost line
    ax.legend()
    plt.show()
    return ax

def calc_cost(self):

    x_map = np.argmin(self.distances,axis=1)
    # define the membership matrix from cluster index list
    # u becomes 1 for items in given cluster and zero for the others
    u = np.zeros_like(self.distances)
    u[np.arange(self.n),x_map] = 1

    #u = copy.deepcopy(self.U)
    dist= np.multiply(self.distances,u)
    # set the distances other than minimal to zero
    #dist = np.multiply(self.distances,u) # fa la mltiplicazione in modo semplice
    if self.verbose: sys.stderr.write('dist: {}\n'.format(dist))
    # compute the error - <E> expectation of distortion
    self.error = np.sum(dist)/(self.c*self.n)
    #self.error = np.sum(dist)

    #delta_e = np.abs(self.prev_error - error)
    delta_e = self.prev_error - self.error
    #print ("error= ", error, " delta_error= ", delta_e)
    self.cost.append(self.error)
    self.prev_error = self.error
    return delta_e

def predict(self,x):
    if self.verbose: sys.stderr.write('centroids: {}\n'.format(self.centroids))
    # compute distances from centroids
    for j in range(self.n):
        for i in range(self.c):
            self.distances[j][i] = np.sum(np.dot(x[j]-self.centroids[i],x[j]-self.centroids[i]))
    # assign the points of the data sets to the k clusters (nearest centroid)
    self.x_map = np.argmin(self.distances,axis=1)
    return self.x_map # lista delle predizioni

def get_centroids_distance(self):
    # check centroids distance
    clu_dist = 0
    for c, pc in zip(self.centroids,self.prev_centroids): clu_dist += np.sqrt(np.dot(c-pc,c-pc))
    return clu_dist

def fit (self, x):
    # performs kmeans clustering on training samples and assign centroids
    self.n = x.shape[0] # number of training items
    c = x.shape[1] # number of features

```

```

# initialize the K centroids by selecting at random K points from the data_set
idx = np.random.randint(self.n,size=self.c)
self.centroids = x[idx].copy()
self.prev_centroids = self.centroids.copy()

# initialize the membership matrix with n rows and k columns
self.U = np.zeros((self.n,self.c), dtype=float) # <==== perchè di nuovo ?
# create a distance matrix with the same shape as the membership one
self.distances = np.zeros_like(self.U,dtype=float)
#-----

# iterate while DELTA E > tau (STOP CRITERION #1) or max_iter not reached
loop = True
self.iteration = 0
while (loop):
    # match training data to the current centroids and update their
    # membership index list
    self.x_map = self.predict(x) # da qua escono gli indici di cluster
    if self.verbose: sys.stderr.write('x_map: {}\n'.format(self.x_map))

    #-----
    # calculate the new k centroids
    #omega needs to be calculated
    matrix= self.calc_U(x).transpose() # now is a 3 x 9
    for i in range(0,self.c):

        zero = np.zeros(len(x[0])) # then will update
        numerator = copy.deepcopy(zero)

        denominator = 0
        for h in range(0,self.n):
            u_ij = matrix[i][h]
            numerator = numerator + u_ij*x[h]
            denominator = denominator + u_ij
        self.centroids[i] = numerator/denominator
    self.U = matrix.transpose()
    #-----

    # calculate self.eta array
    matrix = copy.deepcopy(self.U).transpose()
    eta= np.zeros(self.c)

    for i in range(0,self.c):
        numerator = 0
        denominator = 0

        for h in range(0, self.n):
            u_ij = matrix[i][h]
            numerator = numerator + u_ij* self.distance(x[h], self.centroids[i]) #updated as according t
o GPCM formula
            denominator = denominator + u_ij
        eta[i]=self.gamma * (numerator / denominator)

    if eta[0]>0 and eta[1]>0 and eta[2]>0: #control loop
        self.eta=eta
    #-----
    delta= self.calc_cost()
    self.iteration +=1
    # break the loop if the stopping conditions are met
    clu_dist = self.get_centroids_distance()
    self.prev_centroids = self.centroids.copy()
    if self.verbose:
        print(self.iteration, "error= ", self.error, " delta_error= ", delta_cost, "tau = ", self.tau)
    # loop conditions
    loop = (abs(delta) > self.tau) and (self.iteration < self.max_iter)

return self

```

### 3 Defuzzification of fuzzy partitions

The output of a fuzzy clustering algorithm is a soft (fuzzy) partition of the data set defined by the partition matrix  $U$ .

To transform a soft partition of data set in a hard partition, we must apply the winner take all (WTA) or the  $\alpha$ -cut rules:

- the winner take all (WTA) rule for each data point finds the clustering with higher membership value and change this value to 1 and set the memberships to the other clusters to 0;
- the  $\alpha$ -cut rule compares the membership of each data point to a cluster and if it is larger than  $\alpha$  change it to 1, otherwise set it to 0.

In [ ]:

```
def WTA(U): # Winner Take All rule. U is the membership matrix
    # U matrix [num_cluster x el_dataset]
    # take one column: look for higher value and then set 1

    def Column_largest(rows):
        # find the position of largest inside array
        max_pos= 0
        maxm= rows[0] #initize the rows
        #loop till the maximum position is found
        for i in range(0,len(rows)):
            if rows [i] > maxm:
                max_pos = i
                maxm = rows[i]
        return max_pos

    #-----
    size = np.shape(U)
    # initialize W matrix with same rows/columns as U
    W= np.zeros((size[0], size[1]))

    #create a loop for all the rows
    for h in range(0, size[1]): # every columns
        position= Column_largest(U[:,h]) # every positions of the higher value
        for i in range(0, size[0]):
            if i!= position:
                W[i][h] = 0
            else:
                W[i][h] = 1
    return W
```

In [ ]:

```
def alpha_cut(U, alpha): # alpha-cut rule. U is the membership matrix, alpha is the threshold

#calcualte the size of the shape
size =np.shape(U)
#create number of 0's according to size
matrix= np.zeros((size[0], size[1]))
for i in range(0, size[1]): # for every columns
    for j in range(0, size[0]):

        if U[j,i] > alpha: #if row and column and greater than alpha then append 1 to the matrix
            matrix[j,i] = 1
    return matrix
```

## 4 Partition similarity indeces

### Rand Index

Given two hard partitions  $A$  and  $B$  of a data set  $Z$ , we call

- $n_{11}$  number of pairs of data points in  $Z$  both in the same cluster in  $A$  and in the same cluster in  $B$
- $n_{00}$  number of pairs of data points in  $Z$  both in different clusters in  $A$  and in different clusters in  $B$
- $n_{01}$  number of pairs of data points in  $Z$  both in different clusters in  $A$  and in the same cluster in  $B$
- $n_{10}$  number of pairs of data points in  $Z$  both in the same cluster in  $A$  and in different clusters in  $B$

the Rand index is defined as

$$r(A, B) = \frac{n_{00} + n_{11}}{n_{00} + n_{11} + n_{01} + n_{10}}$$

NOTE: If  $A$  and  $B$  are identical  $r(A, B) = 1$ .



In [ ]:

```
import numpy as np
from scipy.special import comb

def rand(actual, pred):
    # Uih are matrix i x h    or j x h con j>i

#define Rand index function
#code source from internet i tried to implement but it was creating an error, however i have understood the following code and can implement on my own

    tp_plus_fp = comb(np.bincount(actual), 2).sum()
    tp_plus_fn = comb(np.bincount(pred), 2).sum()
    A = np.c_[actual, pred]
    tp = sum(comb(np.bincount(A[:, 0] == i, 1), 2).sum()
              for i in set(actual))
    fp = tp_plus_fp - tp
    fn = tp_plus_fn - tp
    tn = comb(len(A), 2) - tp - fp - fn
    return (tp + tn) / (tp + fp + fn + tn)
```

## Jaccard Index

Given the same definitions as for the Rand Index, the Jaccard Index is defined as:

$$J(A, B) = \frac{n_{11}}{n_{11} + n_{01} + n_{10}}$$

In [ ]:

```
def jaccard(U1,U2):
    # each is a ixh matrix

    #Calculate hard matrix using the WTA
    A = WTA(U1)
    B = WTA(U2)

    # hard matrix conversion
    A1= np.shape(U1)
    rowsA = A1[0]
    columns = A1[1]

    #Return the shape of U2
    B1= np.shape(U2)
    #append 0
    rowsB = B1[0]

    A_Vector= np.zeros(columns) # array that will be updated
    B_Vector= np.zeros(columns) # when will find the element 1 in matrix

    for h in range(0,columns):
        A_Vector[h]= h
        for i in range(0,rowsA):
            u1 = A[:,h]
            if u1[i]== 1:
                A_Vector[h] = i

        for i in range(0,rowsB):
            u2 = B[:,h]
            if u2[i]== 1:
                B_Vector[h] = i

    #-----
    # permutations
    # the different values:
    #intialize the values
    n11 = 0
    n01 = 0
    n10 = 0

    for h in range(0,columns):
        A_element= A_Vector[h] # fixed elements in the following loop
        B_element= B_Vector[h]
        #calculate AnB and AUB to compute the index

        for i in range(h,columns): # for permutations
            if h!= i:
                notA= A_Vector[i] # elements that change during the loop
                notB= B_Vector[i]

                if A_element==notA and B_element==notB:
                    n11+=1
                if A_element==notA and B_element!=notB:
                    n01+=1
                if A_element!=notA and B_element==notB:
                    n10+=1

    SUM = n11+n01+n10 #sum of all the numbers
    r= n11/SUM #using the formula

    return r
```

## Clustering Accuracy

Accuracy of a clustering algo can be evaluated as similarity of the obtained partition to a known labeling of the data.

Rand and Jaccard indeces can be used to evaluate clustering accuracy.

## 5, 6, 7, 8 Experiments

Note: Depending on the initialization, a clustering algorithm could trap in alocal minimum. **Multi-start euristics** consists in multiple num\_iter of the algorithm with random inzializations and in the selection of the best one, on the basis ,e.g., of the minimum evaluation of  $\langle E \rangle$  after training.

## 5, 7, 8 - Experiments with K-Means

```

In [ ]:

U_ds1 = list()
U_ds2 = list()
U_Iris = list()

#create 3 for data to store

def multi_start(x,k=3,tau=.0001, num_iter=10):
    # constants assignement
    precision = 4
    #create E constant
    E = np.inf

    runs = num_iter # number of re-starts
    #initiate a cluster k
    clusters=k
    #initate value of tau
    tau_val=tau

    #calculate the running time of the code
    t_before = time.time()
    for i in range(num_iter):
        #loop for until number of iteration is completed
        #call k mean algorithm
        km = KMeans(k=clusters, tau=tau_val, verbose=False)
        #fit algorithm will assign centroids
        # performs kmeans clustering on training samples and assign centroids
        km.fit(x)

        EE= km.error
        Niter= km.iteration
        #print("run = {} - <E> = {:.{}}f".format(i, EE, precision))
        print("run = {} - iterations = {} - <E> = {:.{}}f".format(i, Niter-1, EE, precision))

        if EE < E:
            # store the best instance of trained model
            #
            kmi = km
            E=EE
            best_run=i

    print ('\n best run = {} - <E> = {:.{}}f'.format(best_run, E, precision))
    t_after = time.time()
    ## Compute training time
    t_training = t_after - t_before
    print("Time for multi-start training (seconds): {:.{}}f - runs = {}\n".format(t_training, precision, runs))

    return kmi, E, best_run

```

```

In [ ]:

from scipy.spatial import Voronoi, voronoi_plot_2d
import matplotlib.pyplot as plt
def plot_clustered_data(x,y,c,preds):
    size_x = 16
    size_y = 6
    #call voronoi which is imported from the library Voronoi diagram is a partition of a plane into regions close to
    #each of a given set of objects
    vor = Voronoi(c)
    #create plots, sub plotting graphs
    fig, (ax1, ax2) = plt.subplots(1,2,figsize=(size_x,size_y))
    ax1.scatter(x[:,0], x[:,1], c=y, alpha=0.5)
    ax1.set_title('Original Data')
    #ax1.legend()
    #plot data for Predictions and showing centroids
    ax2.scatter(x[:,0], x[:,1], c=preds, alpha=0.5, label='Predictions')
    ax2.scatter(c[:,0], c[:,1], marker='P', c='red', label='Centroids')
    ax2.set_title('Clustered Data')
    ax2.legend()
    #plotting a voronoi 2d plot
    voronoi_plot_2d(vor, ax2, show_points=False, line_width=1, show_vertices=False)
    ax2.set_xlim(min(x[:,0])-1,max(x[:,0])+1)
    ax2.set_ylim(min(x[:,1])-1,max(x[:,1])+1)

    plt.show()

```

In [ ]:

```
# simplified test datasets (for debugging aims)
simpleTest = False
if simpleTest:
    d1a = [[-1.0,-1.0],[-1.1,-1.2],[-1.2,-1.1],[1.0,1.0],[1.1,1.2],[1.2,1.1],[-1.0,1.0],[-1.1,1.2],[-1.2,1.1]]
    target = [0,0,0,1,1,1,2,2,2]
    feats = pd.DataFrame(d1a, columns=x_labels)
    tgts = pd.Series(target, name=y_label)
    dataset1 = pd.concat([feats,tgts],axis=1)
    d2a = [[-0.3,-0.2],[-0.2,-0.25],[-0.35,-0.3],[0.3,0.25],[0.2,0.2],[0.35,0.3],[-0.3,0.2],[-0.35,0.2],[-0.2,0.2
5],[-0.25,-0.2],[0.3,0.2],[-0.3,0.25]]
    target = [0,0,0,1,1,1,2,2,2,0,1,2]
    feats = pd.DataFrame(d2a, columns=x_labels)
    tgts = pd.Series(target, name=y_label)
    dataset2 = pd.concat([feats,tgts],axis=1)
```

In [ ]:

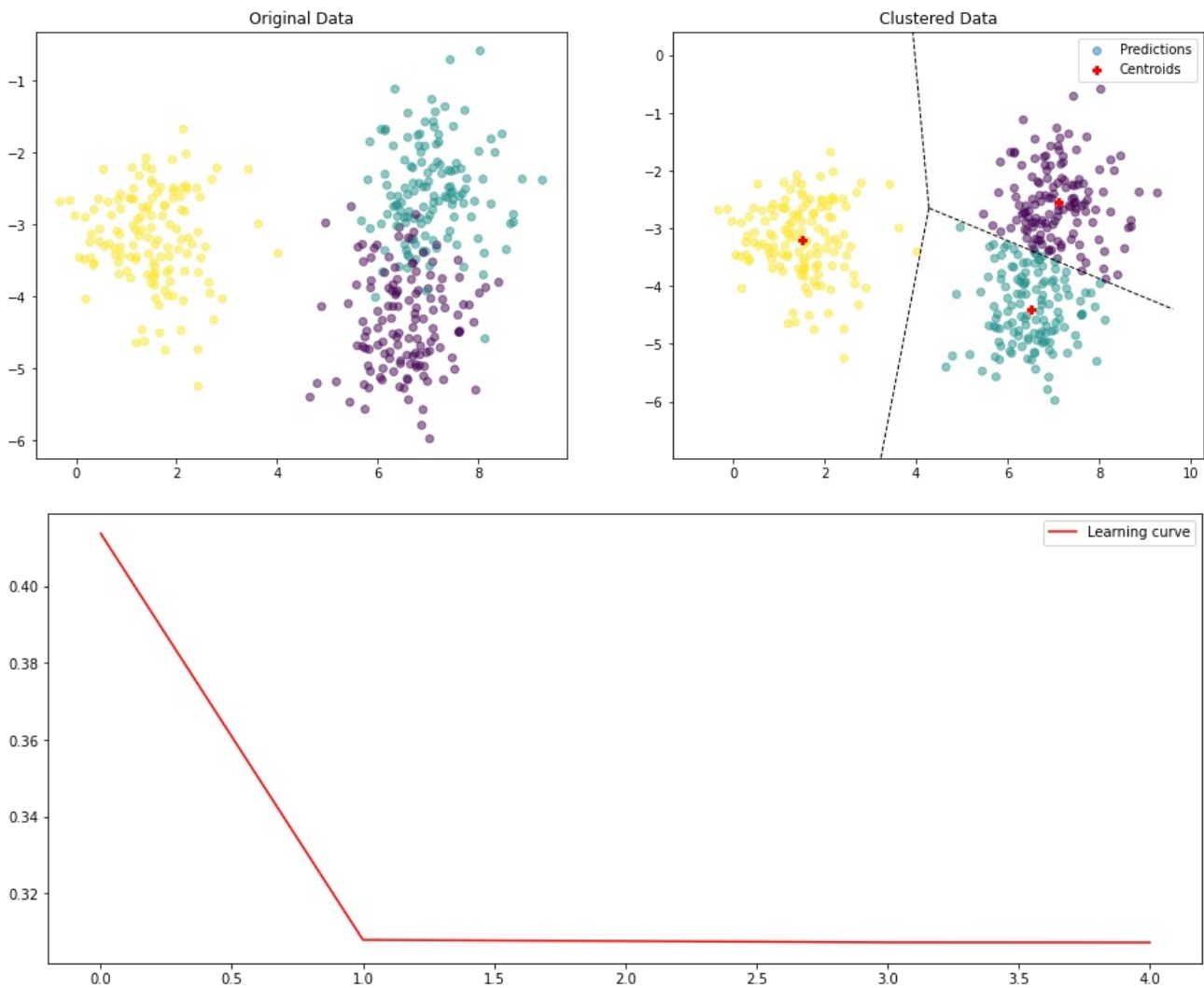
```
ds = dataset1
print("Data set DS")
print()
x = np.array(ds[x_labels].copy())
y = np.array(ds[y_label].copy())
#calling all the function to initiate k mean algorithm
km, E, best_run = multi_start(x, num_iter=10) #3 clusters
c = km.get_centroids()
U = km.get_U()
hist = km.get_cost_history()
p = km.predict(x)
#calling jaccard and rand function and print
print( '\n RandIndex:', (GT_list[0], U), ' ', 'jaccard index:',jaccard(GT_list[0], U))
U_dsl.append(U)
#plotting the iris data to visualize and show the clusters and centroid in the image
plot_clustered_data(x,y,c,p)
#plot a line graph that shows the learning curve, the less the learning curve the better it is
km.plot_cost_history(data=hist, label="Learning curve")
```

Data set DS

```
run = 0 - iterations = 6 - <E> = 0.3072
run = 1 - iterations = 6 - <E> = 0.3073
run = 2 - iterations = 9 - <E> = 0.3073
run = 3 - iterations = 3 - <E> = 0.4779
run = 4 - iterations = 8 - <E> = 0.3073
run = 5 - iterations = 4 - <E> = 0.3072
run = 6 - iterations = 5 - <E> = 0.4830
run = 7 - iterations = 9 - <E> = 0.3073
run = 8 - iterations = 5 - <E> = 0.3073
run = 9 - iterations = 7 - <E> = 0.3072
```

best run = 5 - <E> = 0.3072  
Time for multi-start training (seconds): 1.4347 - runs = 10

```
RandIndex: (array([[1., 1., 1., ..., 0., 0., 0.],
 [0., 0., 0., ..., 0., 0., 0.],
 [0., 0., 0., ..., 0., 0., 0.]]), array([[0, 0, 1, ..., 0, 0, 0],
 [1, 1, 0, ..., 0, 1, 1],
 [0, 0, 0, ..., 1, 0, 0]]))    jaccard index: 0.2696279213850549
```



Out[ ]:  
<matplotlib.axes.\_subplots.AxesSubplot at 0x7fca0aa84e50>

## 5, 6, 7, 8 - Experiments with Fuzzy C-Means

In [ ]:

```
# to do
def multi_startFuzzyCMeans(x, k=3,tau=.0001, num_iter=10):
    #-----
    # constants assignement
    precision = 4
    E = np.inf
    num_iter = num_iter # number of re-starts
    clusters=k
    tau_val=tau
    #-----
    t_before = time.time()
    #run until number of iterations are done
    for i in range(num_iter):
        #call Cmean functions to initiate
        km = FuzzyCMeans( k=clusters, tau=tau_val, verbose=False)
        #fit will compute the predicted centroid
        km.fit(x)
        EE= km.error
        Niter= km.iteration
        #print("run = {} - <E> = {:.{}}f ".format(i, EE, precision))
        print("run = {} - iterations = {} - <E> = {:.{}}f ".format(i, Niter-1, EE, precision))

        if EE < E:
            # store the best instance of trained model
            kmi = km
            E=EE
            best_run=i

    print ( '\n best run = {} - <E> = {:.{}}f'.format(best_run, E, precision))
    t_after = time.time()
    ## Compute training time
    t_training = t_after - t_before
    #print("Time for multi-start training (seconds): {:.{}}f - num_iter = {}\n".format(t_training, precision, num_iter))

    return kmi, E, best_run
```

In [ ]:

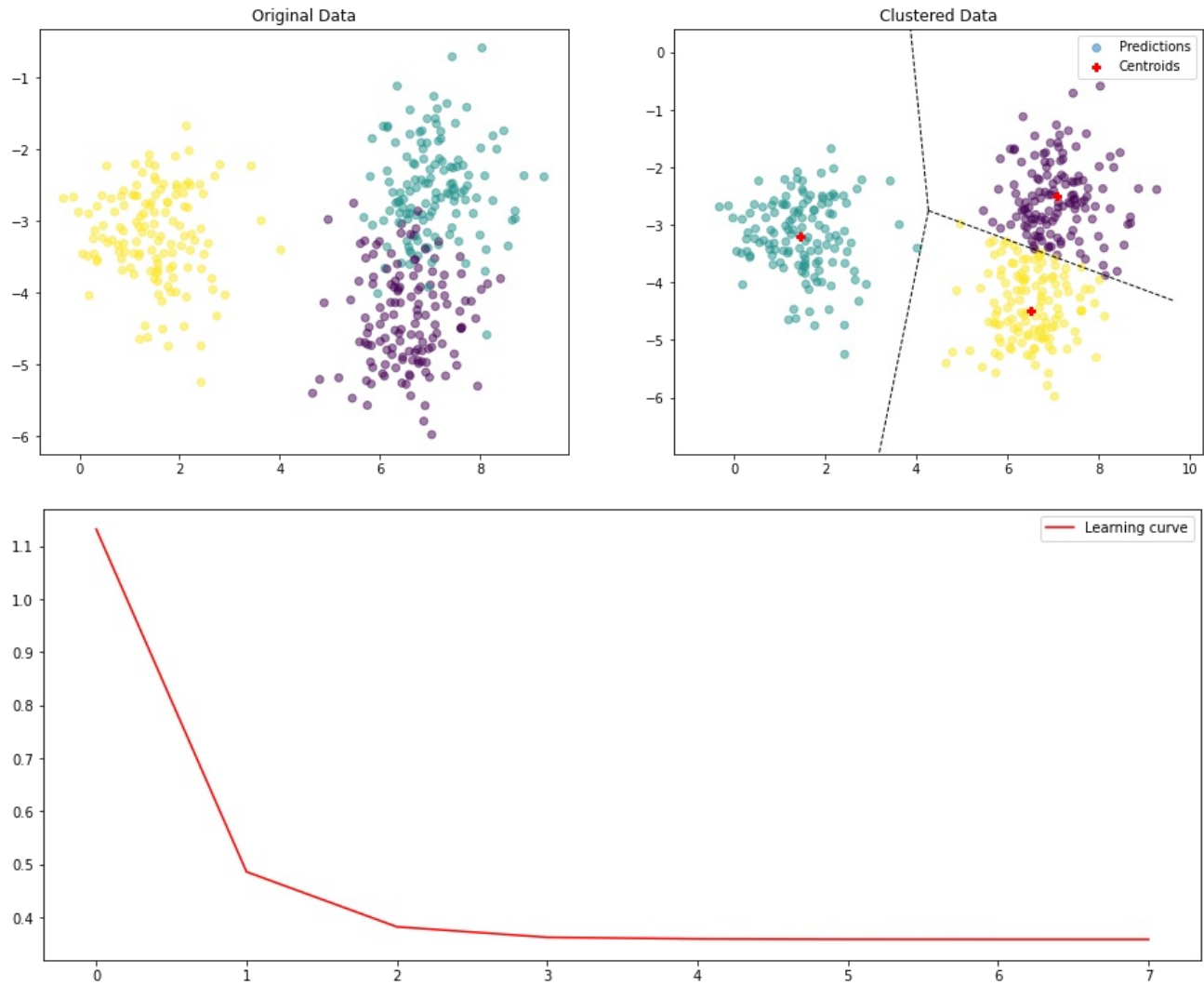
```
ds_l=dataset1
#dataset of iris is dataset1
print("Data set DS 1")
print()
#create 2 copies of arrays and copy rows of dataset in to a new array
x = np.array(ds_l[x_labels].copy())
y = np.array(ds_l[y_label].copy())
#run the cmean algorith
km, E, best_run = multi_startFuzzyCMeans(x,k=3, num_iter=10)
#calculate the centroids
c = km.get_centroids()
U = km.get_U()
hist = km.get_cost_history()
p = km.predict(x)
#print(U, '\n',p)
#run the rand and jaccard index code to calculate the accuracy
print( '\n rand index:',(GT_list[0], U), ' ', 'jaccard index:',jaccard(GT_list[0], U))
U_ds1.append(U)
plot_clustered_data(x,y,c,p)
km.plot_cost_history(data=hist, label="Learning curve")
```

Data set DS 1

```
run = 0 - iterations = 6 - <E> = 0.3585
run = 1 - iterations = 6 - <E> = 0.3585
run = 2 - iterations = 8 - <E> = 0.3585
run = 3 - iterations = 6 - <E> = 0.3585
run = 4 - iterations = 7 - <E> = 0.3585
run = 5 - iterations = 6 - <E> = 0.3585
run = 6 - iterations = 6 - <E> = 0.3585
run = 7 - iterations = 6 - <E> = 0.3585
run = 8 - iterations = 6 - <E> = 0.5630
run = 9 - iterations = 12 - <E> = 0.5630
```

best run = 4 - <E> = 0.3585

```
rand index: (array([[1., 1., 1., ..., 0., 0., 0.],
 [0., 0., 0., ..., 0., 0., 0.],
 [0., 0., 0., ..., 0., 0., 0.]]), array([[1.04309152e-02, 6.98825339e-02, 9.99234430e-01, ...,
 1.60385953e-04, 1.02247610e-04, 1.63961764e-03],
 [1.19556987e-03, 4.60146136e-04, 1.90739357e-05, ...,
 9.99602171e-01, 1.89931423e-06, 4.97795927e-05],
 [9.88373515e-01, 9.29657320e-01, 7.46496127e-04, ...,
 2.37443191e-04, 9.99895853e-01, 9.98310603e-01]])) jaccard index: 0.2697994663912557
```



Out[ ]:

<matplotlib.axes.\_subplots.AxesSubplot at 0x7fca0aeb1d50>

5, 6, 7, 8 - Experiments with Graded Possibilistic C-Means

In [ ]:

```
# to do
def multi_startGPCM(x, k=3,tau=.0001,num_iter=10, eta_array=[0.1,0.1,0.1] ,gamma_value=1, beta_value=0.8):
    #-----
    # constants assignement
    #initialize the params required
    precision = 4
    E = np.inf
    num_iter = num_iter # number of re-starts
    clusters=k
    eta= eta_array
    gamma= gamma_value
    beta= beta_value
    clusters=k
    tau_val=tau
    #-----
    t_before = time.time()
    for i in range(num_iter):
        #run GPCM code using the given params
        km = GPCM(k=3, tau=tau_val, eta=eta_array,gamma=1, beta=0.8, verbose=False)
        #run the fit algorithm to calculate the centroids
        #In central clustering data objects are points or vectors in data space, and c clusters are represented by means of their "central" points or centroids yj . The
        #Graded Possibilistic model is a soft central clustering method, implying that cluster membership can be partial.
        #This is usually represented by means of cluster
        #indicators (or membership functions) which are real-valued rather than integer.
        km.fit(x)
        EE= km.error
        Niter= km.iteration
        #print("run = {} - <E> = {:.{}}f" .format(i, EE, precision))
        print("run = {} - iterations = {} - <E> = {:.{}}f" .format(i, Niter-1, EE, precision))

        if EE < E:
            # store the best instance of trained model
            kmi = km
            E=EE
            best_run=i

    print ('\n best run = {} - <E> = {:.{}}f' .format(best_run, E, precision))
    t_after = time.time()
    ## Compute training time
    t_training = t_after - t_before
    #print("Time for multi-start training (seconds): {:.{}}f - num_iter = {} \n" .format(t_training, precision, num_iter))

    return kmi, E, best_run
```

In [ ]:

```
ds_l = dataset1

print("Data set DS 1")
print()
x = np.array(ds_l[x_labels].copy())
y = np.array(ds_l[y_label].copy())
km, E, best_run = multi_startGPCM(x, k=3, eta_array=[0.7,0.7,0.7],num_iter=10)
c = km.get_centroids()
U = km.get_U()
hist = km.get_cost_history()
p = km.predict(x)
#print(U,'\n',p)
print( '\n rand index:',(GT_list[0], U), ' ', 'jaccard index:',jaccard(GT_list[0], U))
U_dsl.append(U)
plot_clustered_data(x,y,c,p)
km.plot_cost_history(data=hist, label="Learning curve")
```

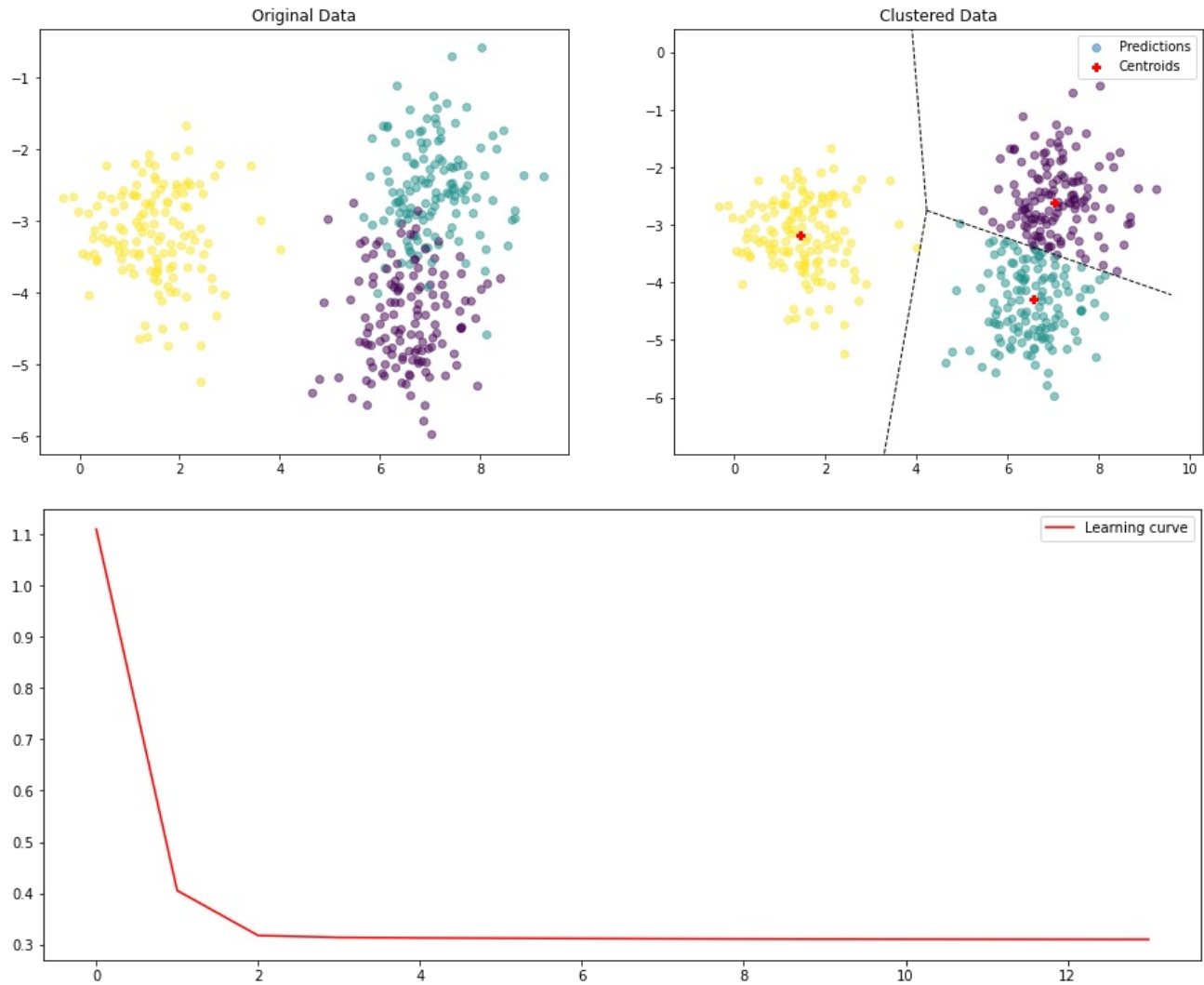


Data set DS 1

```
run = 0 - iterations = 13 - <E> = 0.3101
run = 1 - iterations = 18 - <E> = 0.4850
run = 2 - iterations = 7 - <E> = 0.4888
run = 3 - iterations = 13 - <E> = 0.4839
run = 4 - iterations = 19 - <E> = 0.4850
run = 5 - iterations = 16 - <E> = 0.3102
run = 6 - iterations = 19 - <E> = 0.4850
run = 7 - iterations = 68 - <E> = 1.8294
run = 8 - iterations = 18 - <E> = 0.3107
run = 9 - iterations = 11 - <E> = 0.3106
```

best run = 0 - <E> = 0.3101

```
rand index: (array([[1., 1., 1., ..., 0., 0., 0.],
 [0., 0., 0., ..., 0., 0., 0.],
 [0., 0., 0., ..., 0., 0., 0.]]), array([[8.10355186e-04, 6.26308251e-02, 9.29560519e-01, ...,
 1.88032396e-22, 1.15042962e-02, 2.32515663e-03],
 [8.05191449e-01, 8.15198867e-01, 4.14516610e-03, ...,
 1.42705360e-17, 9.81288112e-01, 9.18684919e-01],
 [1.48097945e-11, 4.21381216e-20, 1.32952731e-20, ...,
 8.77622065e-01, 9.31488499e-17, 5.03111261e-18]])) jaccard index: 0.27043689403984916
```



Out[ ]:

<matplotlib.axes.\_subplots.AxesSubplot at 0x7fca0ad7bd50>

## Optional Part A

### Clustering Ensembling

# Partition Diversity

We exploit **clustering algorithms diversity** to obtain ensemble models with high stability

Possible strategies to increase diversity:

- Different clustering algorithms and weak clustering algos, e.g., only few iterations of k-means to avoid convergence;
- Randomizing using different initializations; different n. of clusters to look for;
- Different data sets: resampling with replacement (bagging); resampling without replacement;
- Different feature subsets (random subspace method).

## A1 - Consensus Matrix implementation

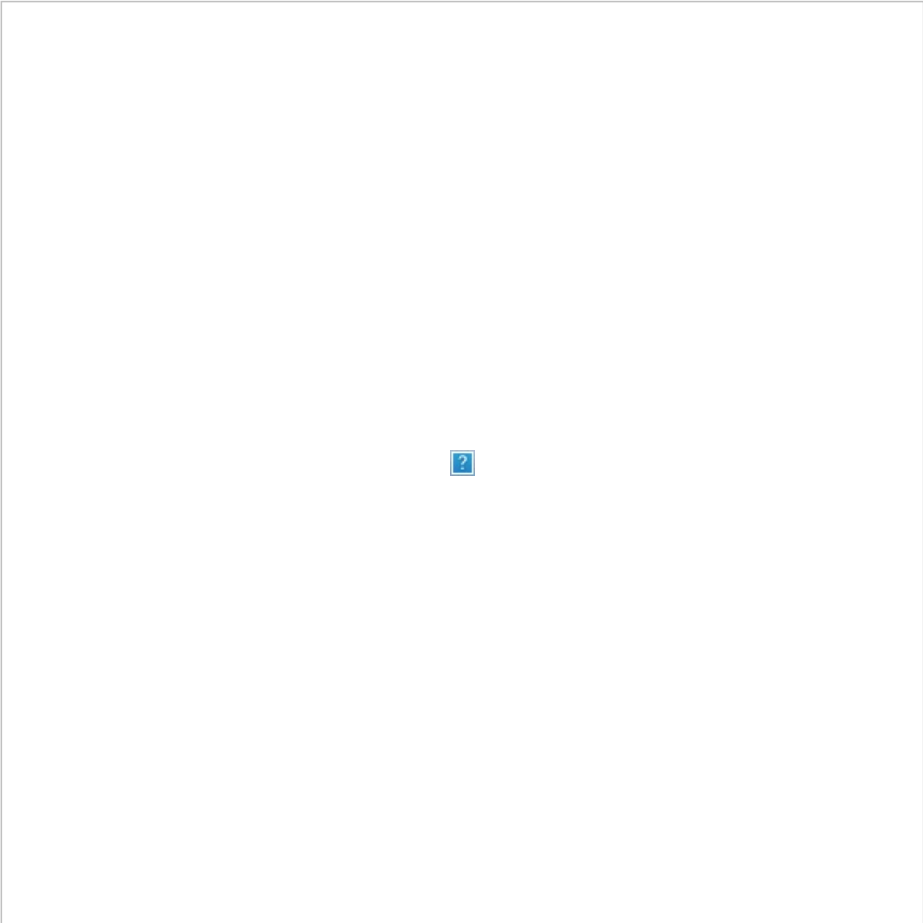
### A1

A popular use of the Consensus Matrix:

- Given data set  $Z = z_1, \dots, z_N$  with N elements.
- Pick the ensemble size L and the number of clusters  $c$ .
- Generate  $L$  hard partitions of  $Z$  in  $c$  clusters.
- Form a co-association matrix for each partition,  $M(k) = m_{ij}(k)$  of size  $N \times N$ ,  $k = 1, \dots, L$ , where

$$m_{ij}(k) = \begin{cases} 1, & \text{if } z_i \text{ and } z_j \text{ are in the same cluster in partition } k, \\ 0, & \text{if } z_i \text{ and } z_j \text{ are in different clusters in partition } k. \end{cases}$$

- Form a final co-association matrix M (consensus matrix) by averaging the  $L$  co-association matrices  $M(k)$ .
- Derive the final clustering using this matrix by applying an  $\alpha$ -cut rule.



In [ ]:

```
def coassoc_matrix(U):
    #input: hard membership matrix
    #output: co-association matrix

    # insert code here

    return C

def cons_matr(CC, alpha):
    # input: CC list of L co-association matrices representing L partitions,
    # alpha threshold
    # output ensemble co-association matrix

    # insert code here

    # consensus matrix C as average the L co-association matrices in CC
    # compare the elements of C with threshold alpha.
    #If larger set the element to 1 otherwise to 0
    # tranform C in an hard membership matrix
    return C
```

## A2, A3, A4 - Experiments on Consensus Matrix ensembling

- **A2.** For each data set, take the 9 hard best partitions obtained for data set DS2 in Part A and construct an ensemble using the technique of the consensus matrix.
- **A3.** Visualize the results on the scatter plot, highlighting the centroids and using a different color for each cluster.
- **A4.** Measure the *accuracy* of the partition induced by the consensus matrix by comparing it with the ground-truth constituted by the targets of the data sets. For the comparison use RAND index. Find the best value for the threshold  $\alpha$ .

In [ ]:

```
#For each data set, take the 9 hard partitions obtained for data set DS2 in Part A

# insert code here

# using coassoc-matrix obtain the 9 co-association matrices

# insert code here

# using cons_matr (with alpha=.4) obtain the ensemble co-association matrix

# insert code here

# Create a scatterplot of first two features

# insert code here

# display learning curve

# insert code here

# Measure the accuracy of the hard partitions (GT is the ground-truth)

# insert code here
```

## Optional Part B: Study of the Graded Possibilistic C-Means algorithm

Implement a soft transition from probabilistic clustering to possibilistic clustering:

- Define a scheduling for  $\beta$ , e.g. (1, .8, .6, .4, .2, 0) and for any value of  $\beta$  run the GPCM starting from the results obtained in the previous run.
- After each run evaluate the accuracy.
- Test on the 3 data sets.

## (h) Discussion

- What are the best results?

K-Means Clustering is a hard clustering algorithm Fuzzy C-Means clustering is a soft clustering approach, where each data point is assigned a likelihood or probability score to belong to that cluster Fuzzy c-means clustering has can be considered a better algorithm compared to the k-Means algorithm. Unlike the k-Means algorithm where the data points exclusively belong to one cluster, in the case of the fuzzy c-means algorithm, the data point can belong to more than one cluster with a likelihood. Fuzzy c-means clustering gives comparatively better results for overlapped data sets.

In our above results we also find out that  
K mean jaccard index: 0.2700055092624475  
Cmean jaccard index: 0.2696279213850549  
GPCM jaccard index: 0.27043689403984916

My results shows that GPCM turns out to be most accurate representations of the clusters

- Additional discussion here