Memory Management

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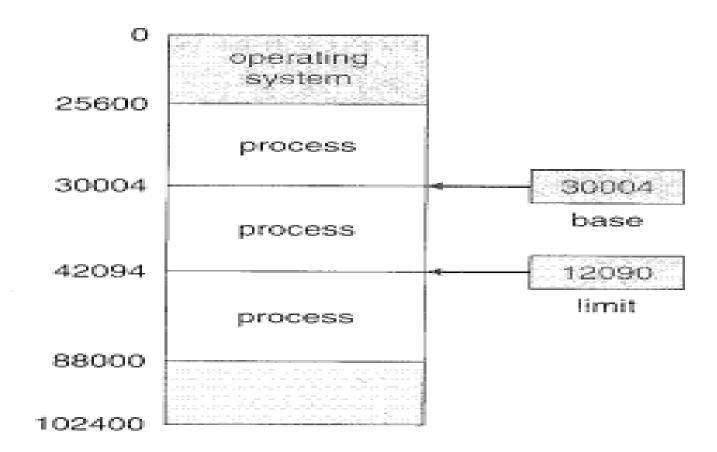




- Every process is given a separate memory address which can be represented by Base and Limit;
- Limit specifies the size whereas Base gives the starting physical address of the memory;
- The processes can access only those memory locations that fit in this range;

Memory allocation for processes





Allocation



Fixed Size

Variable Size

Memory allocation



Every partition is allocated to a process. Only one process at any given instance of time.

After allocation whichever partitions are available are called as holes.

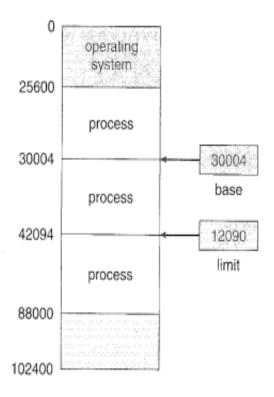
The hole size will be variable or fixed depending upon the allocation method used.

Operating system maintains the list of holes along with their sizes.

Continuous Memory allocation

- Usually memory is divided into two partitions: one for resident OS programs and other for user programs.
- There is a choice of keeping in the low memory or high memory. Since the interrupt vectors are there in the lower memory the OS is stored in the low memory.
- For allocation, memory is divided into varying size blocks to cater the need of different types and hence size of processes.





Memory Allocation Algorithms



First Fit

 A process is allocated to the first partition in the list that is big enough to accommodate it.

Best Fit

 Most appropriate sized partition is selected from the list to allocate it to the process

Worst Fit

• Largest partition is selected and allocated to the process.

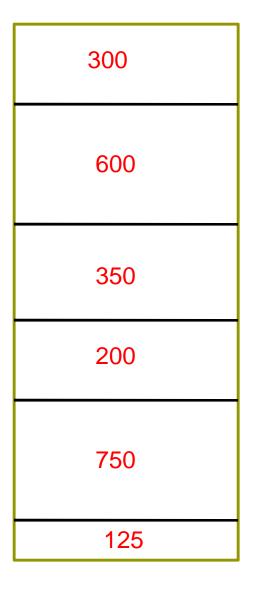
Example – First Fit, Best Fit Worst Fit

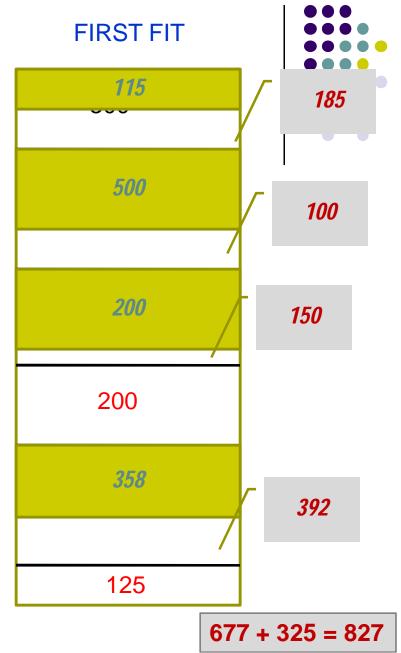


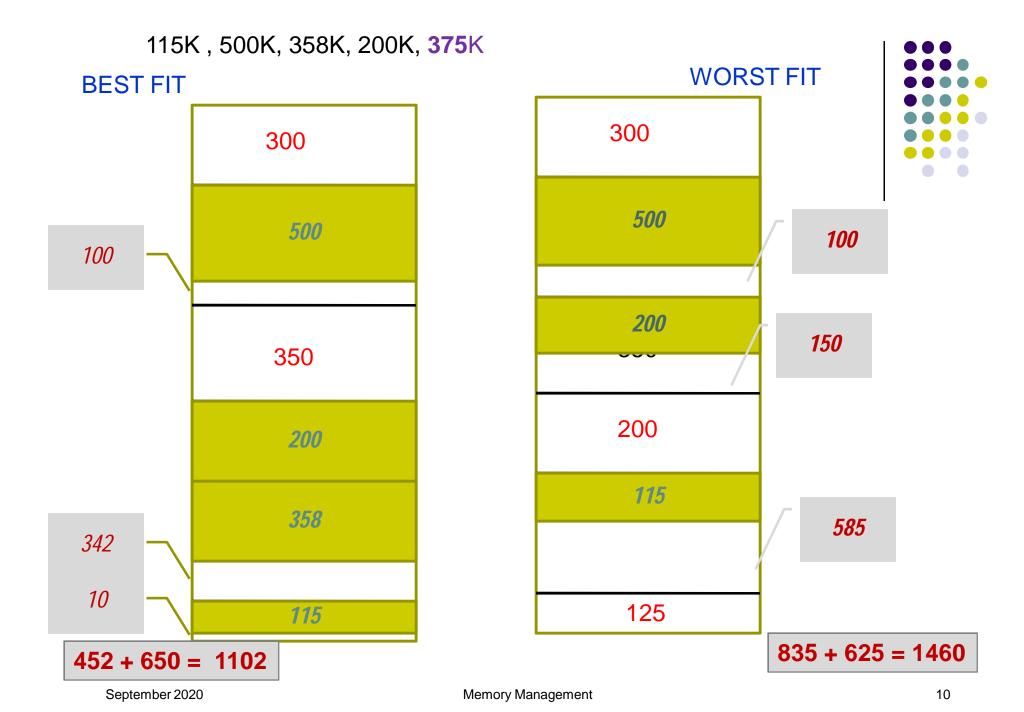
Memory partitions available — 300K, 600K, 350K, 200K, 750k, 125K

Processes – 115K,500K, 358K, 200K, 375K

115K, 500K, 358K, 200K, **375K**





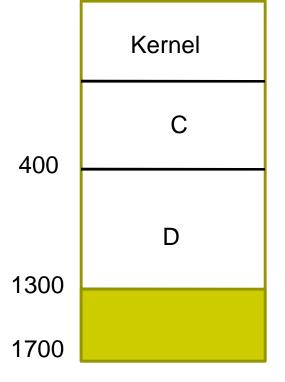


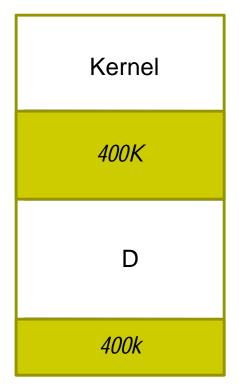


Program	Size
\mathcal{C}	400 K
D	900K
Ε	550K
F	700 K



Assume that the system has 1.7M free for programs.





Fragmentation



Inefficient memory utilization results in Fragmentation

External

Enough memory but not continuous

Compaction

Internal

Allocated large memory and hence unutilized



Point	Internal Fragmentation	External Fragmentation
Definition	When the allocated memory is more than the required memory, it gives rise to internal fragmentation.	In the memory, there are small but un-continuous blocks available if combined they can suffice the memory need of the next program.
Memory Size	Occurs when memory is divided into fixed sized blocks.	Occurs when the blocks allocation is of varying size.
Solution	Best Fit allocation	Compaction

Compaction

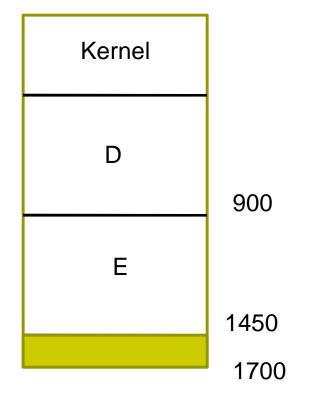
• Moving the program for one memory location to another in order to get the continuous memory is

called as

"Compaction".

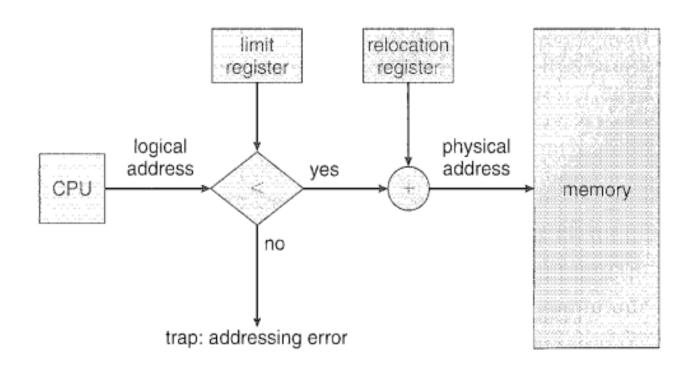
C
400
D

1700



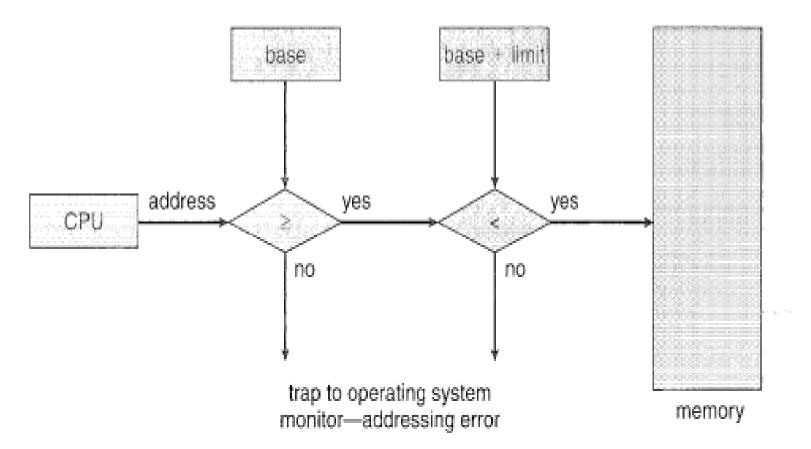
Hardware support for Dynamic Allocation





Hardware Support for Memory Access Protection









Memory is divided into small fixed sized blocks called as frames and the process is divided into pages.

The size of the page is a power of 2 varying between 512 bytes to 1 GB

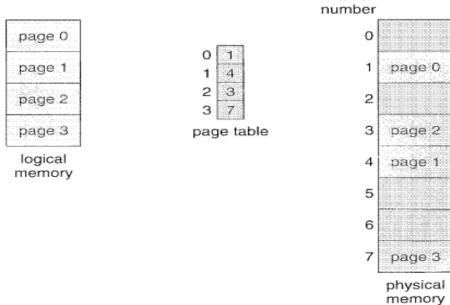
Typically is it 4KB to 8 KB

To get the page size in the system

- getconf PAGESIZE
- or use a system call getpagesize();

Paging





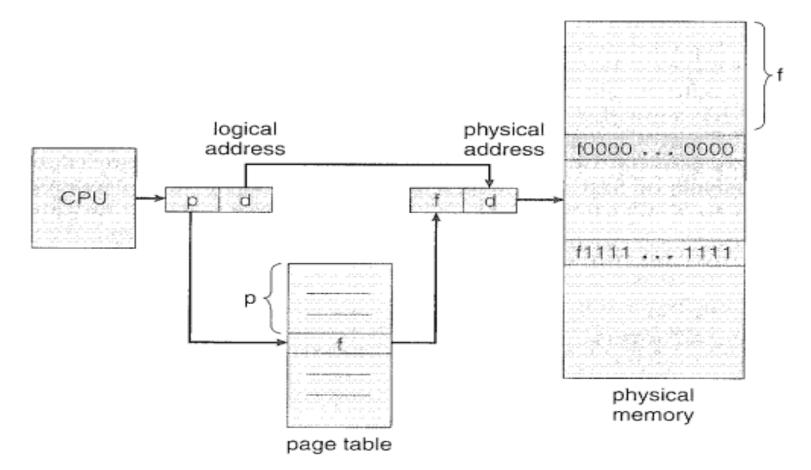
page number	page offset
p	d
111 - 11	n

Logical pages are mapped to frames in the physical memory.

frame

Paging





Frame table



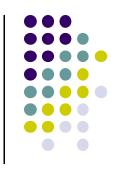
free-frame list 14 13 18 20 15 page 0 page 1 page 2 page 3 new process	13	01100117 001 00 01100117 001 00	free-frame list 15	13 page 1
	14	14	14 page 0	
	15			15
	16		page 0 page 1	16
	17		page 2 page 3	17
	18		new process	18 page 2
	19		0[14]	19
	20		1 13 2 18 3 20	20 page 3
	21		new-process page table	21
	(a)		(b)	

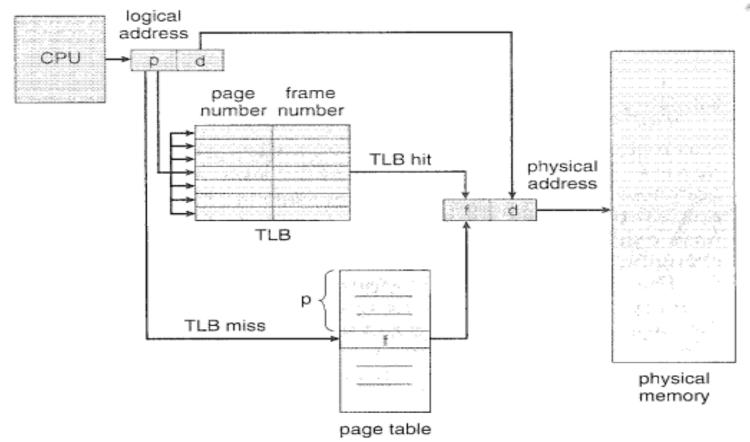
Hardware support for Paging



- Page table base register (PTBR) This contains the address of the page table. To change the page table only the entry in this register needs to be changed. It is done as a part of context switching.
- Translation Look aside Buffer (TLB)

Transition Look aside Buffer (TLB)







Effective memory access time = Percentage of TLB hit * time required to access the memory with TLB hit

+

percentage of TLB miss * time required to access memory with TLB miss

Search TLB = 20ns

Accessing page table = 100 ns

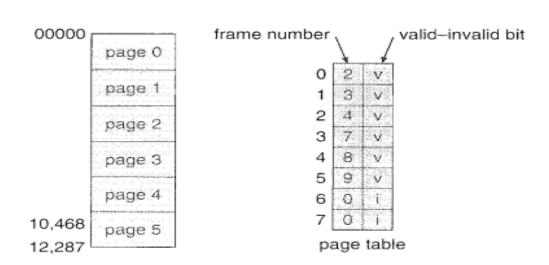
Accessing memory = 100ns

TLB hit = 60%

Find EMAT





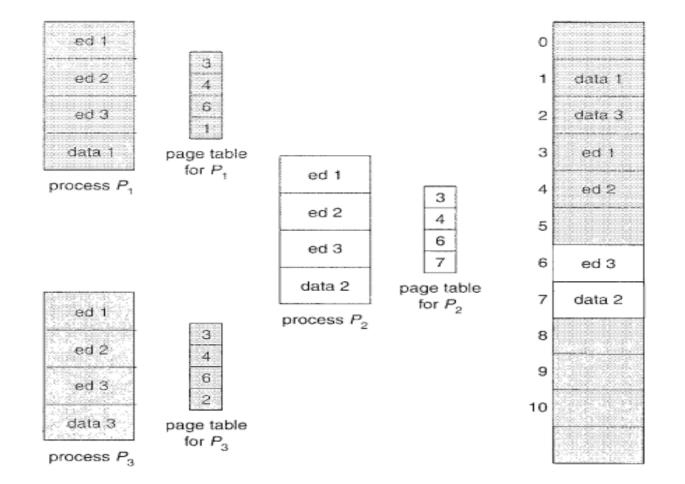


0 page 0 page 1 page 2 5 6 page 3 page 4 page 5 page n

Valid /invalid bit is used to identify valid pages



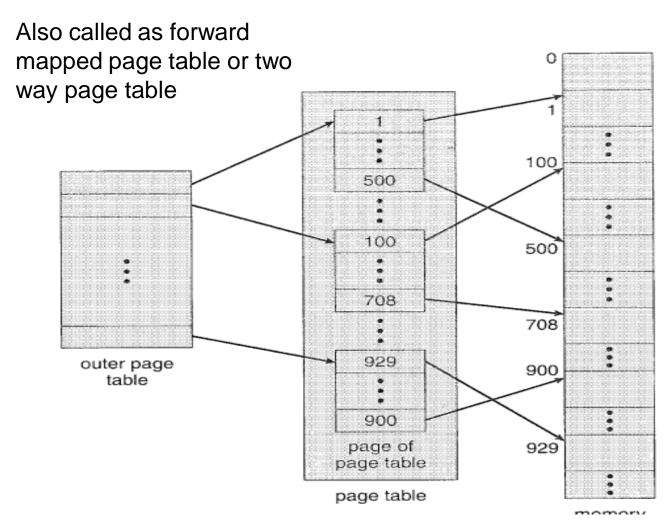




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Page Table Structure

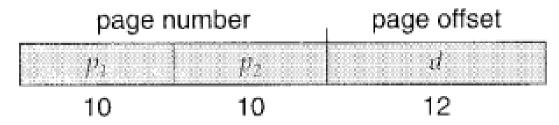


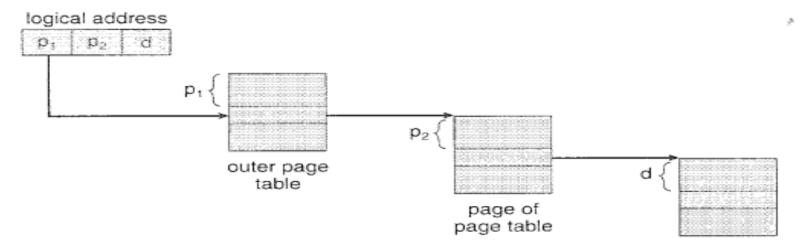






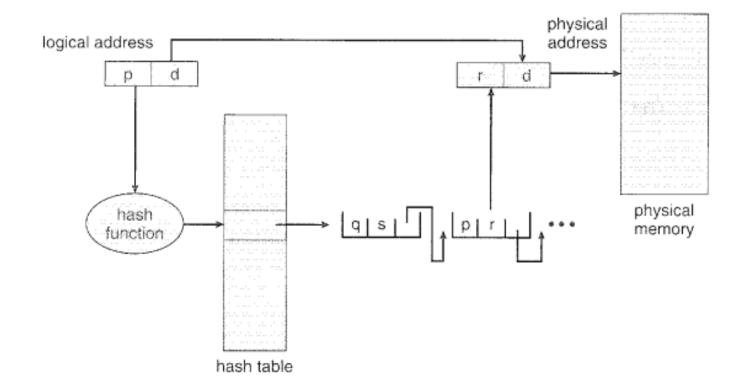
• Example – 32 bit machine with page size of 4Kb





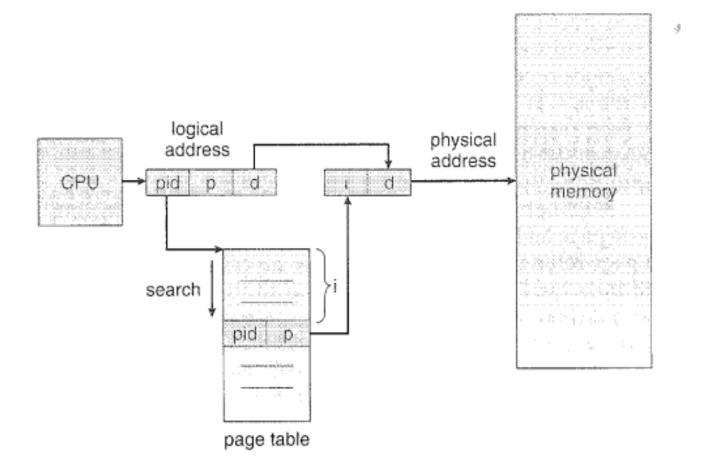
Hashed Page Table





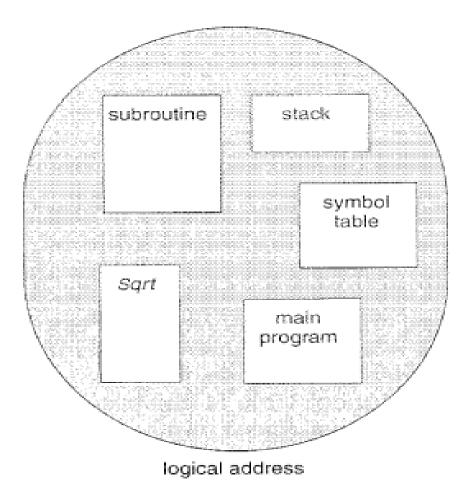
Inverted Page Table





Segmentation

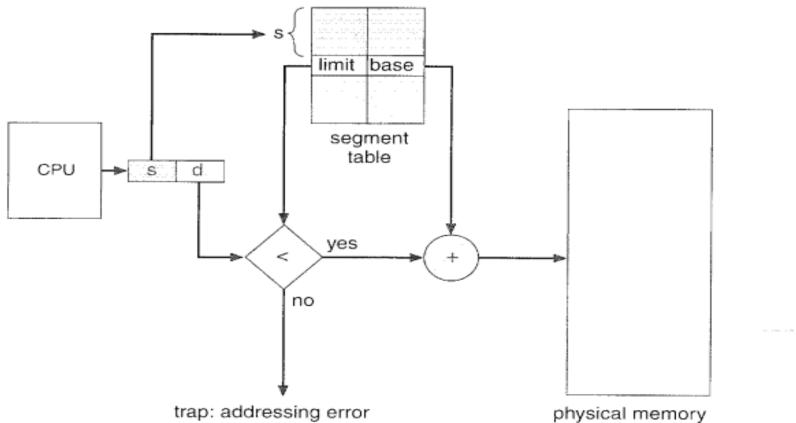




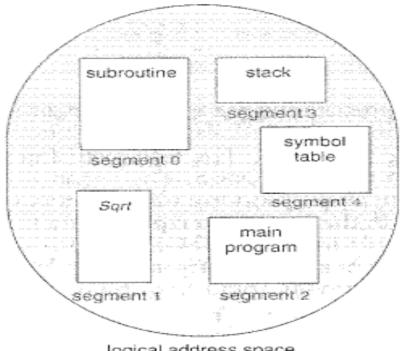
<segment-number, offset>.











		-	
	limit	base	
0	1000	1400	
1	400	6300	
2	400	4300	
3	1100	3200	
4	1000	4700	
9	segment table		

logical address space

1400		
2400	segment 0	
3200		
	segment 3	
4300	V44885555	
4700	segment 2	
	segment 4	
5700		
6300	segment 1	
6700	cogiment 1	
physical memory		

Address Binding

• Compile time — if you know at compile time where will the process reside in the memory, an absolute address may be given by the compiler to every instruction;

When the absolute address is not known at the compile time it provides the relocatable code during compilation.

- Load time Here the binding of the code with memory location is delayed to load time.
- Linking Time or execution time

Dynamic Loading and Linking



- A routine is loaded only when it is called;
- All routines are kept in relocatable load format;
- Unused routine never loaded;
- Stubs



• Dynamic Link Libraries - system libraries that are linked at run time;

Logical Vs Physical Memory



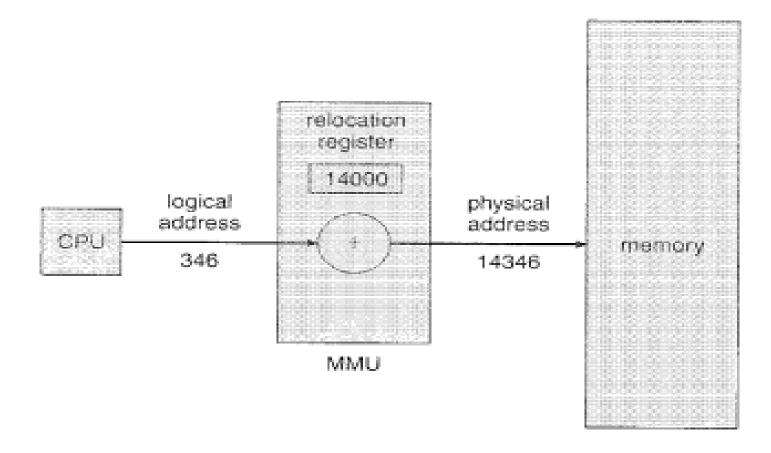
- Address generated by CPU
- Also called as Virtual address

- Address seen by Memory
 Management Unit (MMU)
- Loaded into Memory
 Address Register (MAR)

Logical and Physical address is same for the address generated in compile and load time whereas they differ for link time binding.

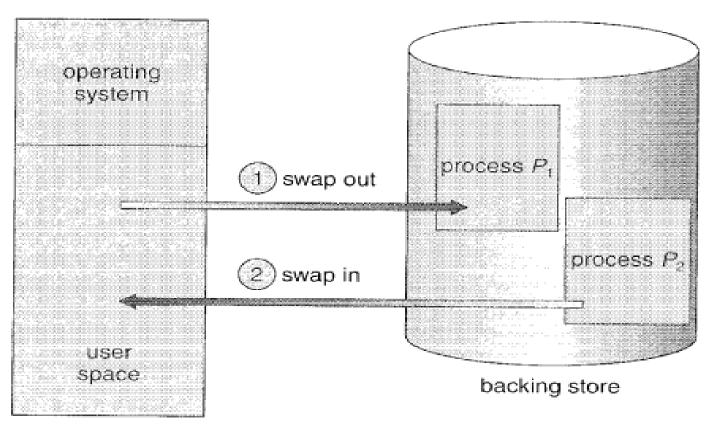
Logical Address and Physical Address





Swapping





main memory

Swapping



Context switching usually takes more time



THANK YOU