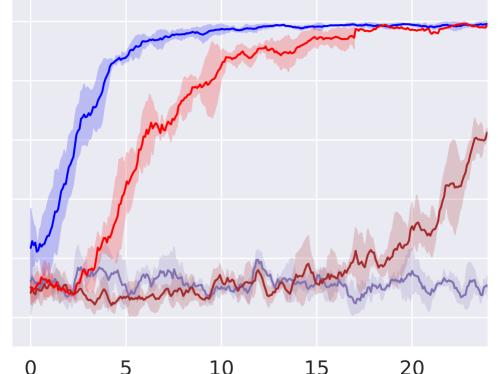Point Navigation with Dense Reward