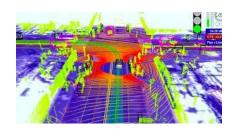


## Autonomous Decision Making in the Real World, ABE 598, Spring 2018

## Instructor: Dr. Girish Chowdhary (girishc@illinois.edu)







Want to learn how to make UAVs and Robots that solve complex tasks on their own? Then Autonomous Decision Making is the course for you. We will survey state-of-the-art techniques in autonomy, machine learning, and decision making, including:





- Introduction to automatic reasoning
- Applied Machine learning:
  - Supervised Learning:
     (Deep/Convolutional) Neural Networks for classification, Gaussian processes
  - Unsupervised Learning: Clustering using K-means, Dirichlet Processes, DNNs
  - Mixture modeling: Hierarchic Bayesian models, Hidden Markov Models
  - Dynamic ML: (deep) Recurrent Neural Networks, Evolving Gaussian Processes
- Applied Sequential decision making:
  - Markov Decision Processes: Value/Policy iteration, trajectory based methods
  - Reinforcement Learning: SARSA, Qlearning, Model based methods
  - Multi-agent and partially observed MDPs
- Software implementation of autonomy algorithms on resource-constrained hardware

This is a project based course. Students can choose final-projects from:

- UAS applications to agriculture and asset monitoring
- Ground robotics and autonomous vehicle systems
- Other autonomy projects related to your research

Prerequisites: Graduate Standing or Consent of Instructor