ASHISH KUMAR GAURAV

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EDUCATION

2016 - 2021(July)

Indian Institute of Technology Kharagpur

CGPA: 8.58/10 Integrated Master of Science in Mathematics and Computing



EXPERIENCE

July 2020

Microsoft, India Development Center | Software Engineer Internship

May 2020

Worked on prediction analysis of Top of rack (ToR) devices, as a part of Azure Networking Team.

- > Collected and processed various types of signal data.
- > Designed a comparative analytical method for analysing signals in different time ranges.
- > Researched and developed a predictive model to predict ToR device reboot before it happens.

Predictive Analysis | Machine Learning | Network Data | Python

March 2020 October 2019

Awl, Inc. Japan | Remote Internship - Part Time

Awl, Inc is a Japanese company, working on Artificial Intelligence in retail stores.

- > Developed a computer vision model for person re-identification.
- > Researched and prepared models for age and gender estimation from facial images.
- > Successfully ran these models on various edge devices.

Computer Vision | Deep Learning | Caffe | Keras

July 2019 May 2019

Awl, Inc. Japan | Artificial Intelligence Internship

- > Created an algorithm to select images for training using Autoencoders and Clustering, which enhanced the performance of semi-supervised learning.
- > Developed an user-interactive visualisation tool for visualising distribution of images using Autoencoders, t-SNE and scatter plot.

Computer Vision Autoencoder Data Visualisation Keras Matplotlib

August 2018

Google Summer of Code 2018 | Student Developer

May 2018

As a part of this program, worked on Sympy. Sympy is a python library for symbolic mathematics.

- > Improved Sympy by adding new features and fixing bugs.
- > Structured and implemented rule based integration in python as a sub-module of Sympy.
- > Wrote parsers which automatically generate rules and test-cases in python from mathematica rules.

Python | Mathematica | Parsers | Object Oriented Design

May 2019 March 2017

Kharagpur RoboSoccer Students' Group | Software Team Member

The aim of this group is to research on autonomous soccer-playing robots and participate in international competitions like Robocup.

- > Contributed to the development of software architecture for controlling autonomous bots.
- > Implemented variations of RRT (Rapidly-exploring random trees) in path planning.
- > Developed an interactive simulator in PyQt with current state of game and various user control.
- > Implemented a fuzzy logic based multi agent passing.

Robot Operating System C++ Python Qt



Skills and Interests

C, C++, Python **Programming Languages**

> Tools and Libraries Git, OpenCV, Keras, Tensorflow, Caffe, Pandas, Scikit Learn, Qt, Docker

> > Data Science, Machine Learning, Software Development, Computer Vision Interests