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# Single Source Shortest Paths

### Introduction:

In a **shortest- paths problem**, we are given a weighted, directed graphs G = (V, E), with weight function **w**:  $E \rightarrow R$  mapping edges to real-valued weights. The weight of path  $p = (v_0, v_1, ...., v_k)$  is the total of the weights of its constituent edges:

$$W(P) = \sum_{i=1}^{k} W(v_{i-1}v_i)$$

We define the shortest - path weight from u to v by  $\delta(u,v) = \min(w(p): u \rightarrow v)$ , if there is a path from u to v, and  $\delta(u,v) = \infty$ , otherwise.

The **shortest path** from vertex s to vertex t is then defined as any path p with weight w (p) =  $\delta(s,t)$ .

The **breadth-first- search algorithm** is the shortest path algorithm that works on unweighted graphs, that is, graphs in which each edge can be considered to have unit weight.

In a **Single Source Shortest Paths Problem**, we are given a Graph G = (V, E), we want to find the shortest path from a given source vertex  $s \in V$  to every vertex  $v \in V$ .

## Variants:

There are some variants of the shortest path problem.

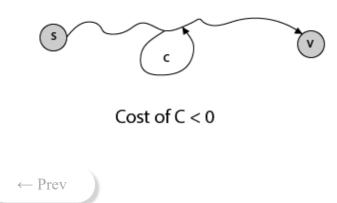
- **Single- destination shortest paths problem:** Find the shortest path to a given destination vertex t from every vertex v. By shift the direction of each edge in the graph, we can shorten this problem to a single source problem.
- **Single pair shortest path problem:** Find the shortest path from u to v for given vertices u and v. If we determine the single source problem with source vertex u, we clarify this

problem also. Furthermore, no algorithms for this problem are known that run asymptotically faster than the best single - source algorithms in the worst case.

• **All - pairs shortest - paths problem:** Find the shortest path from u to v for every pair of vertices u and v. Running a single - source algorithm once from each vertex can clarify this problem; but it can generally be solved faster, and its structure is of interest in the own right.

## Shortest Path: Existence:

If some path from s to v contains a negative cost cycle then, there does not exist the shortest path. Otherwise, there exists a shortest s - v that is simple.



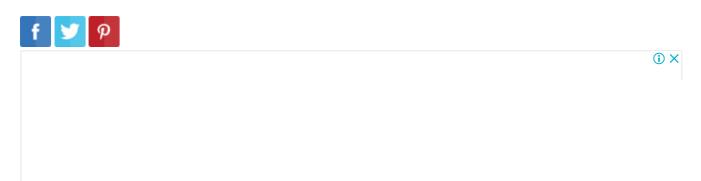
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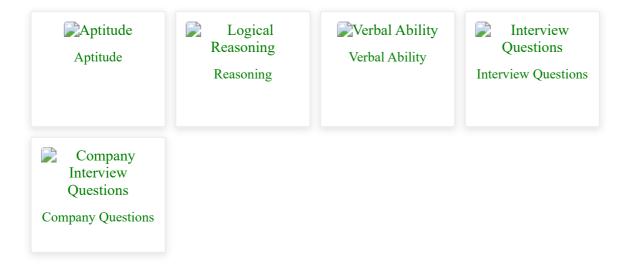


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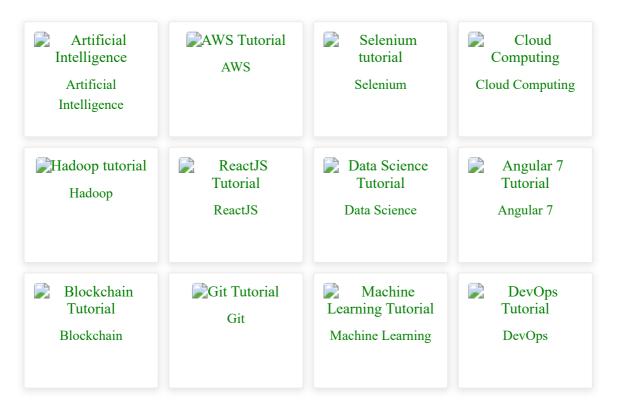
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