

# Problem Solving – State-Space Search and Control Strategies

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# Problem Characteristics

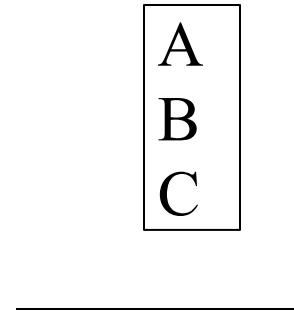
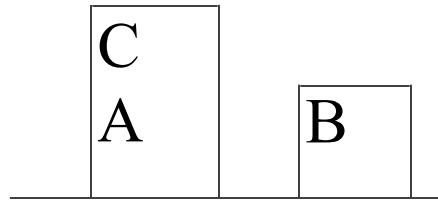
- Heuristic search is a very general method applicable to a large class of problem.
- In order to choose the most appropriate method (or combination of methods) for a particular problem it is necessary to analyze the problem along several key dimensions.
  - Is the problem decomposable into a set of independent smaller sub problems?

## Contd..

- ❑ Decomposable problems can be solved by the **divide-and-conquer** technique.
  - Each sub-problem is simpler to solve.
  - Each sub-problem can be handed over to a different processor. Thus can be solved in parallel processing environment.
- ❑ Is problem non decomposable? Need different strategies
  - For example, Block world problem is non decomposable.

Initial State (State0)

Goal State



Start:  $\text{ON}(\text{C}, \text{A}) \dots$

Goal:  $\text{ON}(\text{B}, \text{C}) \wedge \text{ON}(\text{A}, \text{B})$

## Contd..

- Can solution steps be ignored or at least undone if they prove to be unwise?
- In real life, there are three types of problems:
  - Ignorable,
  - Recoverable and
  - Irrecoverable.

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## Example - Ignorable

- **(Ignorable): In theorem proving -**  
(solution steps can be ignored)
    - Suppose we have proved some lemma in order to prove a theorem and eventually realized that lemma is no help at all, then ignore it and prove another lemma.
    - Can be solved by using simple **control strategy**?
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## Example - Recoverable

- **8 puzzle game** - (solution steps can be undone)
  - Objective of 8 puzzle game is to rearrange a given initial configuration of eight numbered tiles on 3 X 3 board (one place is empty) into a given final configuration (goal state).
    - Rearrangement is done by sliding one of the tiles into empty square.
  - Steps can be undone if they are not leading to solution.
  - Solved by backtracking, so control strategy must be implemented using a **push down stack**.

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## Example - Irrecoverable

- **Chess** (solution steps cannot be undone)
  - A stupid move cannot be undone.
  - Can be solved by **planning process**.



# Contd..

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- What is the Role of knowledge?
    - In Chess game, knowledge is important to constrain the search
    - Newspapers scanning to decide some facts, a lot of knowledge is required even to be able to recognize a solution.
  - Is the knowledge Base consistent?
    - Should not have contradiction
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# Contd...

- Is a good solution Absolute or Relative ?
  - In water jug problem there are two ways to solve a problem.
    - If we follow one path successfully to the solution, there is no reason to go back and see if some other path might also lead to a solution.
    - Here a solution is **absolute**.
  - In travelling salesman problem, our goal is to find the shortest route/path. Unless all routes are known, the shortest is difficult to know.
    - This is a best-path problem whereas water jug is any-path problem.

## Contd...

- Any path problem can often be solved in reasonable amount of time using heuristics that suggest good paths to explore.
- Best path problems are in general computationally harder than any-path.

# Problem Solving

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- AI programs have a clean separation of
    - computational components of data,
    - operations & control.
  - Search forms the core of many intelligent processes.
  - It is useful to structure AI programs in a way that facilitates describing the search process.
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# Production System - PS

- PS is a formation for structuring AI programs which facilitates describing search process.
- It consists of
  - Initial or start state of the problem
  - Final or goal state of the problem
  - It consists of one or more databases containing information appropriate for the particular task.
- The information in databases may be structured
  - using knowledge representation schemes.

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# Production Rules

- PS contains set of production rules,
    - each consisting of a left side that determines the applicability of the rule and
    - a right side that describes the action to be performed if the rule is applied.
    - These rules operate on the databases.
    - Application of rules change the database.
  - A control strategy that specifies the order in which the rules will be applied when several rules match at once.
  - One of the examples of Production Systems is an **Expert System**.
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# Advantages of PS

- In addition to its usefulness as a way to describe search, the production model has other advantages as a formalism in AI.
  - It is a good way to model the strong state driven nature of intelligent action.
  - As new inputs enter the database, the behavior of the system changes.
  - New rules can easily be added to account for new situations without disturbing the rest of the system, which is quite important in real-time environment.

# Example : Water Jug Problem

## ■ Problem statement:

- Given two jugs, a 4-gallon and 3-gallon having no measuring markers on them. There is a pump that can be used to fill the jugs with water. How can you get exactly 2 gallons of water into 4-gallon jug.

## ■ Solution:

- State for this problem can be described as the set of ordered pairs of integers  $(X, Y)$  such that
  - $X$  represents the number of gallons of water in 4-gallon jug and
  - $Y$  for 3-gallon jug.
- Start state is  $(0,0)$
- Goal state is  $(2, N)$  for any value of  $N$ .



# Production Rules

- Following are the production rules for this problem.

R1:(X, Y |  $X < 4$ )      □    (4, Y)  
{Fill 4-gallon jug}

R2:(X, Y |  $Y < 3$ )      □    (X, 3)  
{Fill 3-gallon jug}

R3:(X, Y |  $X > 0$ )      □    (0, Y)  
{Empty 4-gallon jug}

R4:(X, Y |  $Y > 0$ )      □    (X, 0)  
{Empty 3-gallon jug}

R5:(X, Y |  $X+Y \geq 4 \wedge Y > 0$ )    □(4,  $Y - (4 - X)$ )

{Pour water from 3- gallon  
jug into 4-gallon jug until                      4-gallon jug is full}

## Contd..

R6:  $(X, Y \mid X+Y \geq 3 \wedge X > 0) \sqsubseteq (X - (3 - Y), 3)$   
    { Pour water from 4-gallon jug into 3-  
    gallon jug until 3-gallon jug is full }

R7:  $(X, Y \mid X+Y \leq 4 \wedge Y > 0) \sqsubseteq (X+Y, 0)$

    { Pour all water from 3-gallon jug  
    into 4-gallon jug }

R8:  $(X, Y \mid X+Y \leq 3 \wedge X > 0) \sqsubseteq (0, X+Y)$

    { Pour all water from 4-gallon jug  
    into 3-gallon jug }

**Superficial Rules:** {May not be used in this problem}

R9:  $(X, Y \mid X > 0) \sqsubseteq (X - D, Y)$   
    { Pour some water D out from 4-gallon jug }

R10:  $(X, Y \mid Y > 0) \sqsubseteq (X, Y - D)$   
    { Pour some water D out from 3- gallon jug }

# Trace of steps involved in solving the water jug problem - First solution

| <i>Number<br/>of Steps</i>                      | <i>Rules applied</i> | <i>jug</i> | <i>jug</i> | <i>4-g</i> | <i>3-g</i>        |
|---|----------------------|------------|------------|------------|-------------------|
| 1. Initial State                                |                      | 0          | 0          |            |                   |
| 2. R2 {Fill 3-g jug}                            |                      | 0          | 3          |            |                   |
| 3. R7 {Pour all water from 3 to 4-g jug }       |                      | 3          | 0          |            |                   |
| 4. R2 {Fill 3-g jug}                            |                      | 3          | 3          |            |                   |
| 5. R5 {Pour from 3 to 4-g jug until it is full} |                      | 4          | 2          |            |                   |
| 6. R3 {Empty 4-gallon jug}                      |                      | 0          | 2          |            |                   |
| 7. R7 {Pour all water from 3 to 4-g jug}        |                      | 2          | 0          |            | <b>Goal State</b> |

# Trace of steps involved in solving the water jug problem - Second solution

- Note that there may be more than one solutions.

| <i>Number<br/>of steps</i> | <i>Rules applied</i>                         | <i>4-g<br/>jug</i> | <i>3-<br/>g<br/>jug</i> |                   |
|----------------------------|--|--------------------|-------------------------|-------------------|
| 1                          | <b>Initial State</b>                         | 0                  | 0                       |                   |
| 2                          | R1 {Fill 4-gallon jug}                       | 4                  | 0                       |                   |
| 3                          | R6 {Pour from 4 to 3-g jug until it is full} | 1                  | 3                       |                   |
| 4                          | R4 {Empty 3-gallon jug}                      | 1                  | 0                       |                   |
| 5                          | R8 {Pour all water from 4 to 3-gallon jug}   | 0                  | 1                       |                   |
| 6                          | R1 {Fill 4-gallon jug}                       | 4                  | 1                       |                   |
| 7                          | R6 {Pour from 4 to 3-g jug until it is full} | 2                  | 3                       |                   |
| 8                          | R4 {Empty 3-gallon jug}                      | 2                  | 0                       | <b>Goal State</b> |

# Important Points

- For each problem
  - there is an initial description of the problem.
  - final description of the problem.
  - more than one ways of solving the problem.
  - a path between various solution paths based on some criteria of goodness or on some heuristic function is chosen.
  - there are set of rules that describe the actions called production rules.
    - Left side of the rules is current state and right side describes new state that results from applying the rule.

- **Summary:** In order to provide a formal description of a problem, it is necessary to do the following things:
  - ❑ Define a state space that contains all the possible configurations of the relevant objects.
  - ❑ Specify one or more states within that space that describe possible situations from which the problem solving process may start. These states are called **initial states**.
  - ❑ Specify one or more states that would be acceptable as solutions to the problem called **goal states**.
  - ❑ Specify a set of rules that describe the actions. Order of application of the rules is called control strategy.
  - ❑ Control strategy should cause motion towards a solution.