Assignment 2

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As the data consists of 1s and 0s, it is a safe assumption to try out a Bernoulli Distribution. The equations and steps followed are given below

Step 1: Initialise the variables:

 Π_k : Proportion of the mixture which follows the kth distribution

O: Params to define the distribution

X: lambda

Step 2:

Find the probability distribution function (bernoulli) for each data point according to the initialized params

$$P(x \mid \{\theta_k\}, \{\pi_k\}) = \sum_{k=1}^K \pi_k \cdot \theta_k^x (1 - \theta_k)^{1-x}$$

$$\gamma(z_{nk}) = rac{\pi_k \prod_{i=1}^5 P(x_{ni}| heta_{ki})}{\sum_{j=1}^K \pi_j \prod_{i=1}^5 P(x_{ni}| heta_{ji})}$$

Step 3:

$$egin{aligned} heta_{ki} &= rac{\sum_{n=1}^{10} \gamma(z_{nk}) x_{ni}}{\sum_{n=1}^{10} \gamma(z_{nk})} \ \pi_k &= rac{1}{10} \sum_{n=1}^{10} \gamma(z_{nk}) \end{aligned}$$

Calculate the new theta and pi for the new iteration

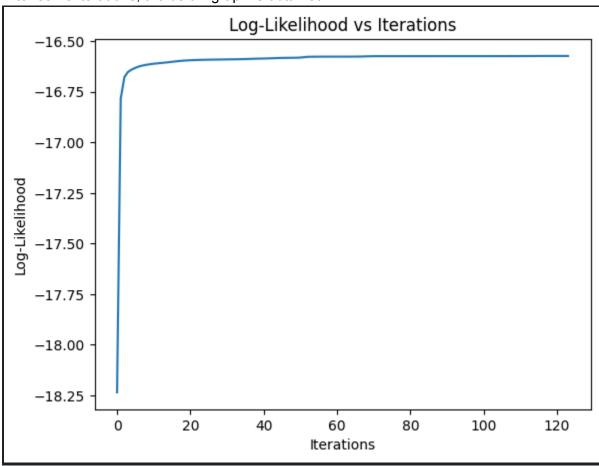
Step 4:

FInd the likelihoods and the log likelihood

likelihoods
$$[i] = \sum_{k=1}^K \pi_k \cdot P(x_i \mid heta_k)$$

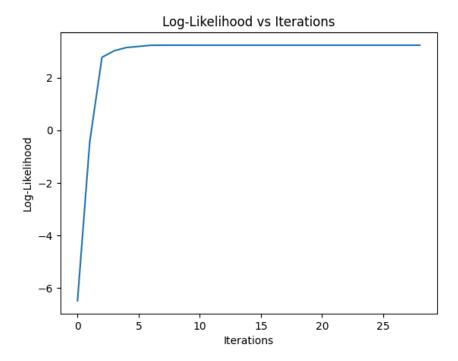
$$\log_{\text{likelihood}} = \frac{1}{N} \sum_{i=1}^{N} \log \left(\text{likelihoods}[i] \right)$$

After some iterations, the below graph is obtained



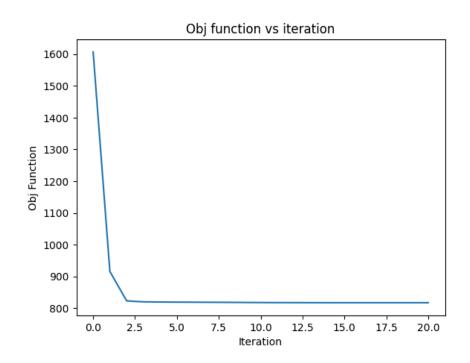
ii) Follow the same steps above but with Gaussian distribution:

$$f(\mathbf{x} \mid oldsymbol{\mu}, \Sigma) = rac{1}{(2\pi)^{d/2} \sqrt{\det(\Sigma)}} \exp\left(-rac{1}{2} (\mathbf{x} - oldsymbol{\mu})^T \Sigma^{-1} (\mathbf{x} - oldsymbol{\mu})
ight)$$



The Gaussian Distribution seems to have a better fit than the Bernoulli Distribution because we have obtained a positive log likelihood (~3) in the second qn compared to a negative (~-16.5) log likelihood.

iii) Is with K-Means Algorithm



iv) The first approach took much more iterations and has a negative log likelihood. So that can be considered as not the best algorithm. Between K- means and GMM, GMM can model much more complex data than K-means hence we can choose GMM for this data.

Q2)

i) Least Squared Solution is obtained as:



ii) With gradient descent:

Step 1: initialize w

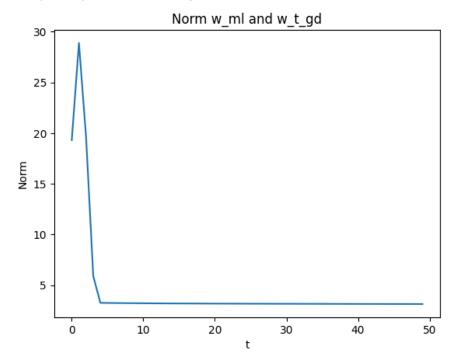
Step 2: use step size as 1/t (t -> iteration number)

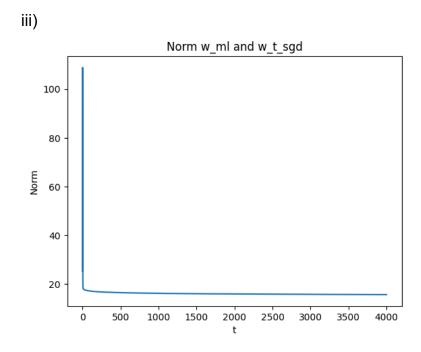
Step 3: Iterate with

$$\nabla F(\omega) = \left[2 \left(x x^{T} \right) \omega - 2 x y \right]$$

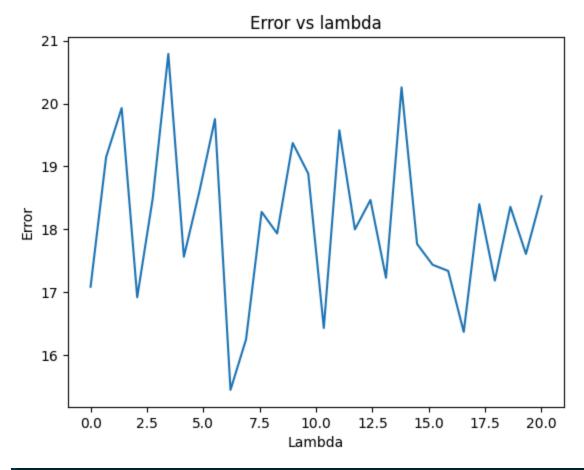
$$\nabla V = \left[x x^{T} \right] \omega - 2 x y$$

The w values obtained through this approach converges to to that obtained analytically after reaching a peak.





There is a smooth decrease in the norm and reaching a constant minima. iv)



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error for W_ml is 19.921456237616056
error for W_r 41.30573639172386
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The analytically obtained coefficients is better. Probably the params such as learning rate and initialisation affects the error.