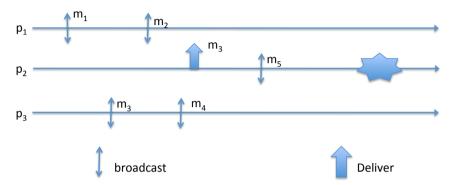
Dependable Distributed Systems Master of Science in Engineering in Computer Science

AA 2022/2023

Lecture 11 – Exercises October 20th, 2022

Ex 1: Consider the partial execution depicted in the following figure:



- 1. Complete the execution in order to obtain a run satisfying *Best Effort Broadcast* but *not Reliable Broadcast*.
- 2. Complete the execution in order to obtain a run satisfying *Regular Reliable Broadcast* but *not Uniform Reliable Broadcast*.
- 3. Complete the execution in order to obtain a run satisfying *Uniform Reliable Broadcast*.

Ex 2: Consider a distributed system composed by n processes $\{p_1, p_2, ..., p_n\}$. Each process is connected to all the others trough fair-loss point-to-point links and has access to a perfect failure detector.

Write the pseudo-code of an algorithm implementing a Uniform Reliable Broadcast primitive.

Additionally, answer to the following questions:

- 1. Is it possible to provide a quiescent implementation of the Uniform Reliable Broadcast primitive?
- 2. Given the system model described here, is it possible to provide an implementation that uses only data structure with finite size?

Ex 3: Consider a distributed system composed by N servers $\{s_1, s_2, ... s_n\}$ and M clients $\{c_1, c_2, ... c_m\}$.

Each client c_i runs its algorithm and it can request to servers the execution of a particular task T_i . Servers will execute the task T_i and, after that, a notification will be sent to c_i that T_i has been completed.

The Figure shows the code executed by a generic client c_i.

Operation executeTask (T _i)	Upon pp2pdeliver (TASK_COMPLETED, T _i) from s _j
$ \begin{array}{cccccccccccccccccccccccccccccccccccc$	1. trigger completedTask (T _i);

Write the pseudo-code of an algorithm, executed by servers, able to allocate tasks assuming that:

- Once clients ask for a task execution, they remain blocked until the task is not terminated.
- Any two clients c_i and c_j can concurrently require the execution of two different tasks T_i and T_j ;
- Each task is univocally identified by the pair (T_i, c_i);
- Each server can manage at most one task at every time;
- At most N-1 servers can crash;
- Servers can use a uniform consensus primitive;
- Servers can use a failure detector P;
- Servers communicate through a uniform reliable broadcast primitive.

Note that, if a server crashes while executing a task, such task needs to be re-allocated and re-processed by a different server.

Ex 4: Consider a distributed system formed by n processes $p_1, p_2, ..., p_n$ connected along a ring i.e., a process p_i is initially connected to a process $p_{(i+1) \text{mod } n}$ through a unidirectional perfect point-to-point link.

Write the pseudo-code of a distributed algorithm implementing a consensus primitive.