

ELEC 3300 – Tutorial for LAB5

Department of Electronic and Computer Engineering
HKUST

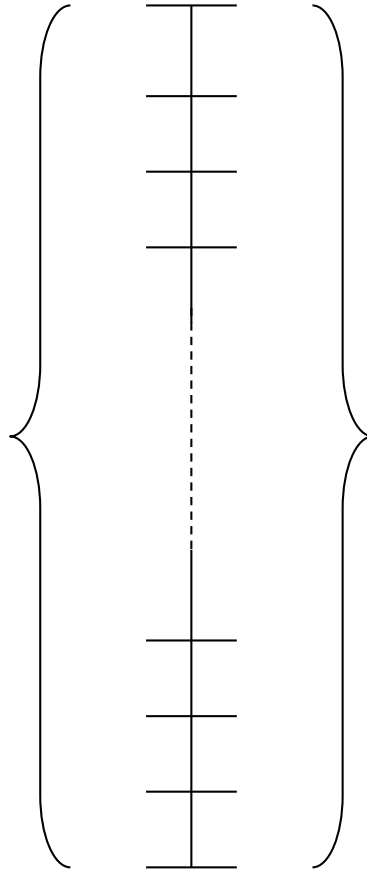
by WU Chi Hang 

Terminology

Analogue

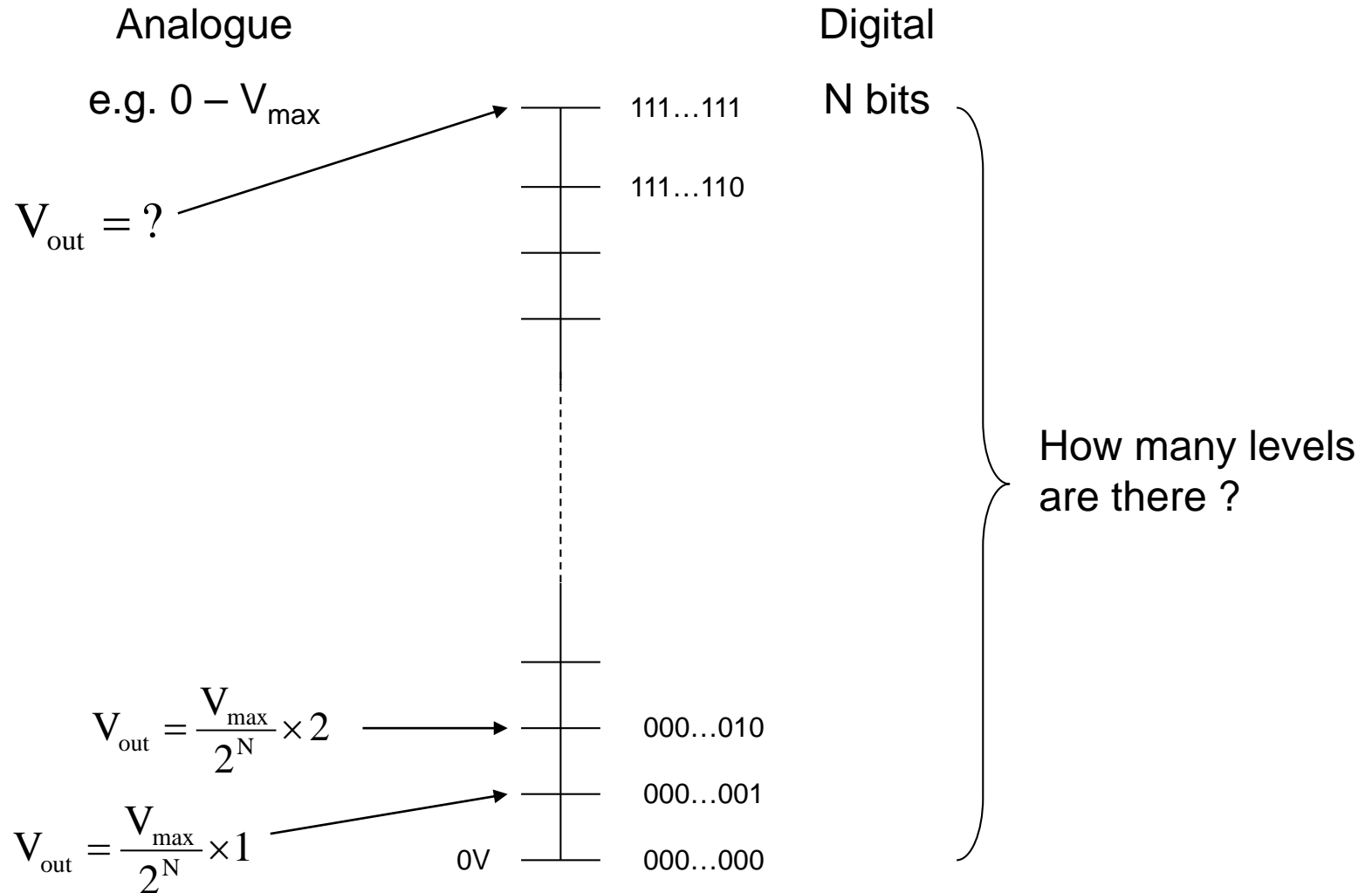
Digital

The whole analogue range that you want to chop into



How many levels depends on the number of bits used.

An N-bit Linear DAC/ADC



Digital to Analogue Converter (DAC)

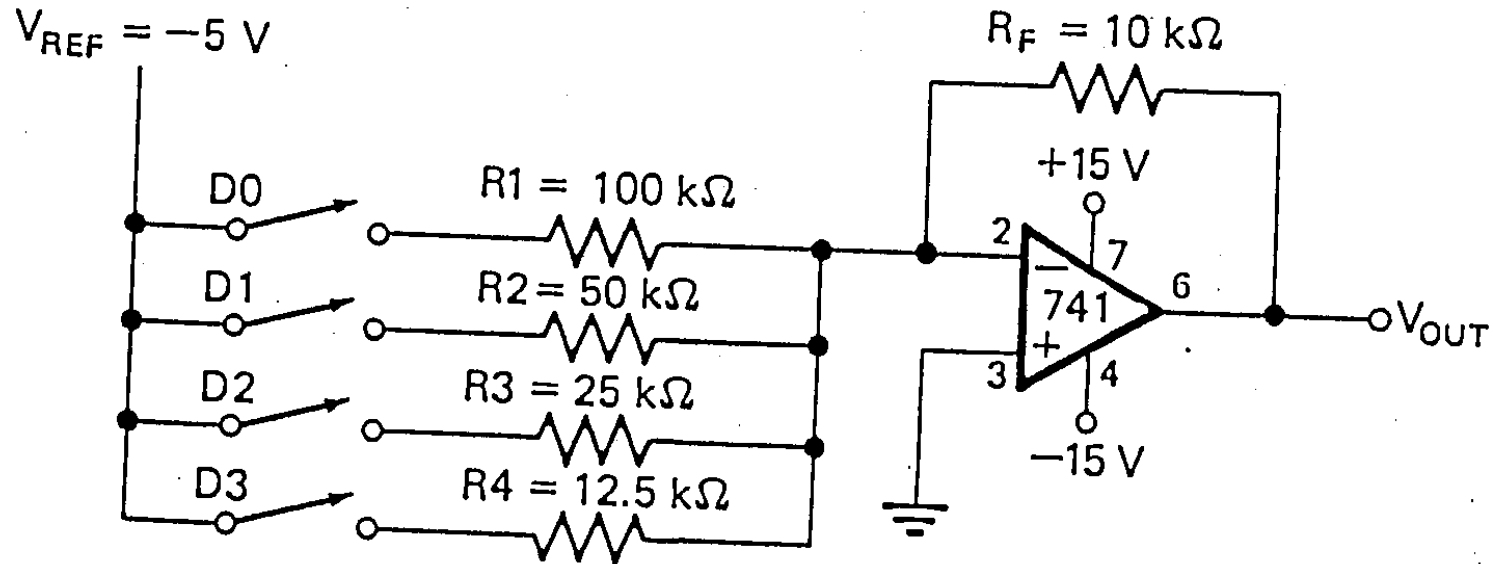


FIGURE 10-14 Simple 4-bit D/A converter.

Terminology

■ Resolution

- Number of bits in the binary word used in the sample.

■ Full Scale Output Voltage (for DAC)

- Maximum output voltage of the D/A convertor. (Always 1 LSB below the stated value)

■ Setting Time (for DAC)

- When you change a binary word applied to the input of a converter, the output will change to appropriate new value. (Time the output takes to get within $\pm \frac{1}{2}$ LSB)

■ Conversion Time (for ADC)

- Time that convertor takes to produce a valid output binary code for an applied input voltage.

Analogue to Digital Converter (ADC)

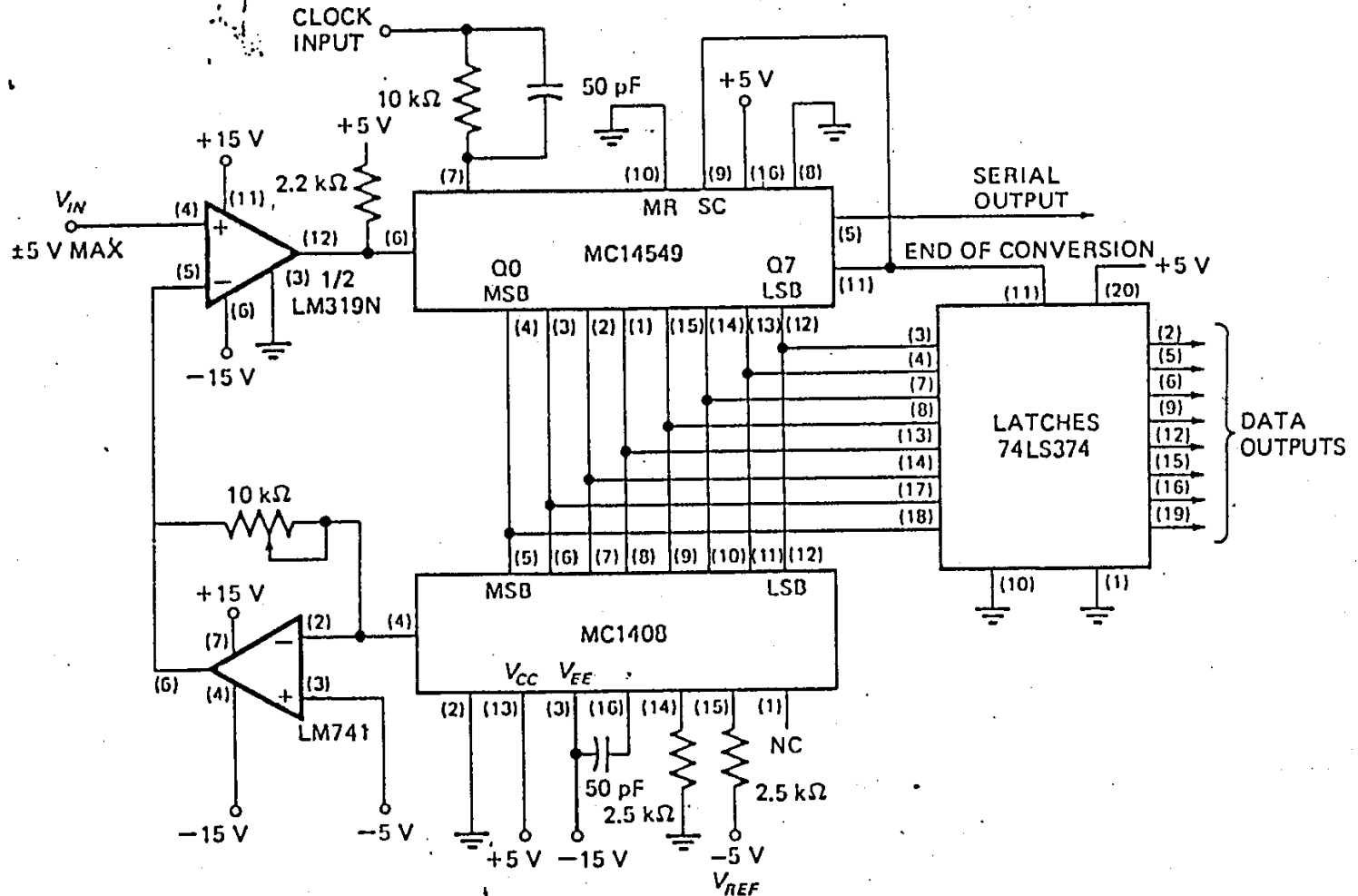


FIGURE 10-20 Successive-approximation A/D converter circuit.

Analogue to Digital Convertor (ADC)

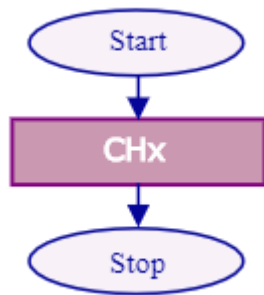
- In STM32 there are three ADCs inside. Each ADC is 12-bit. It has up to 18 multiplexed channels allowing it measure signals from 16 external and two internal sources.
- A/D conversion of the various channels can be performed in single, continuous, scan or discontinuous mode.
- The result of the ADC is stored in a left-aligned or right-aligned 16-bit data register.
- The conversion time is around $1\mu\text{s}$ (refer to page 207 of the reference manual)

About Conversion Mode

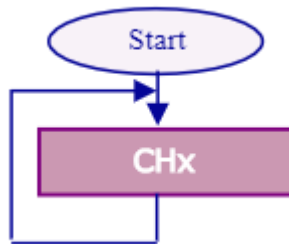
- A/D conversion of the various channels can be performed in single, continuous, scan or discontinuous mode.
 - Single conversion mode
 - ADC does one conversion, after finished conversion, ADC stopped.
 - Continuous conversion mode
 - ADC starts another conversion as soon as it finishes one.
 - Scan mode
 - This mode is used to scan a group of analog channels. A single conversion is performed for each channel of the group. After each end of conversion the next channel of the group is converted automatically.
 - When using scan mode, DMA bit must be set and the direct memory access controller is used to transfer the converted data of regular group channels to SRAM after each update of the ADC_DR register.
- Please refer to Reference Manual Section 11.3 for details.

About Conversion Mode

Single Channel
Single Conversion Mode

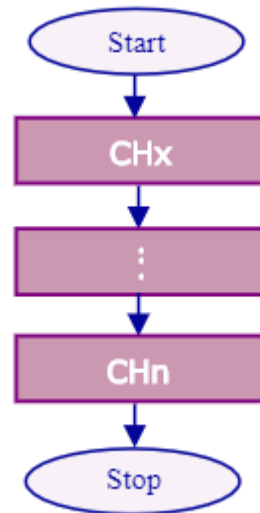


Single Channel
Continuous Conversion Mode

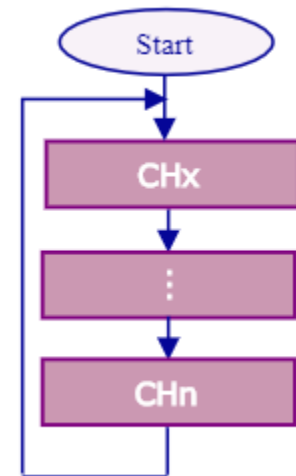


Scan mode

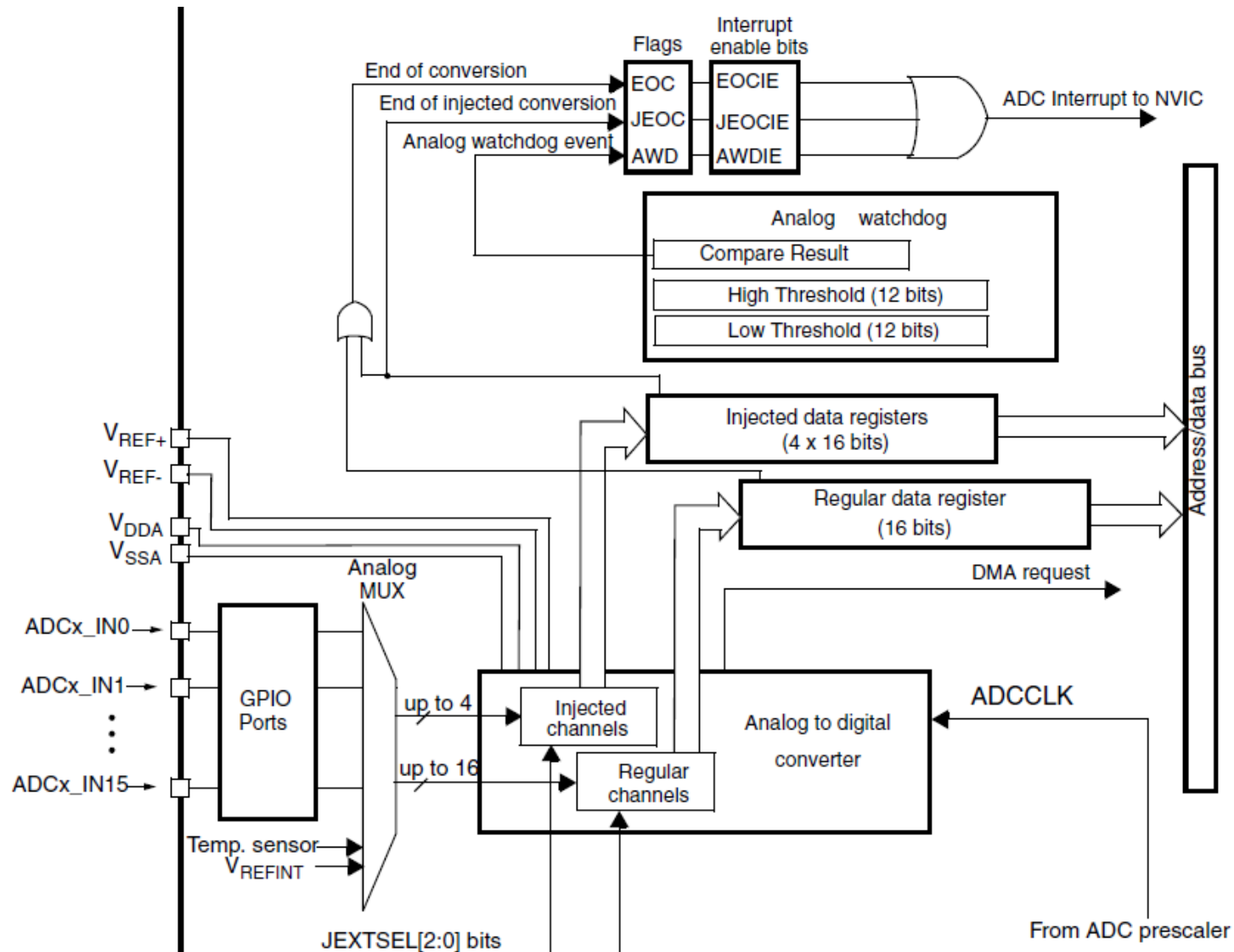
Multi-channel
Single Conversion Mode



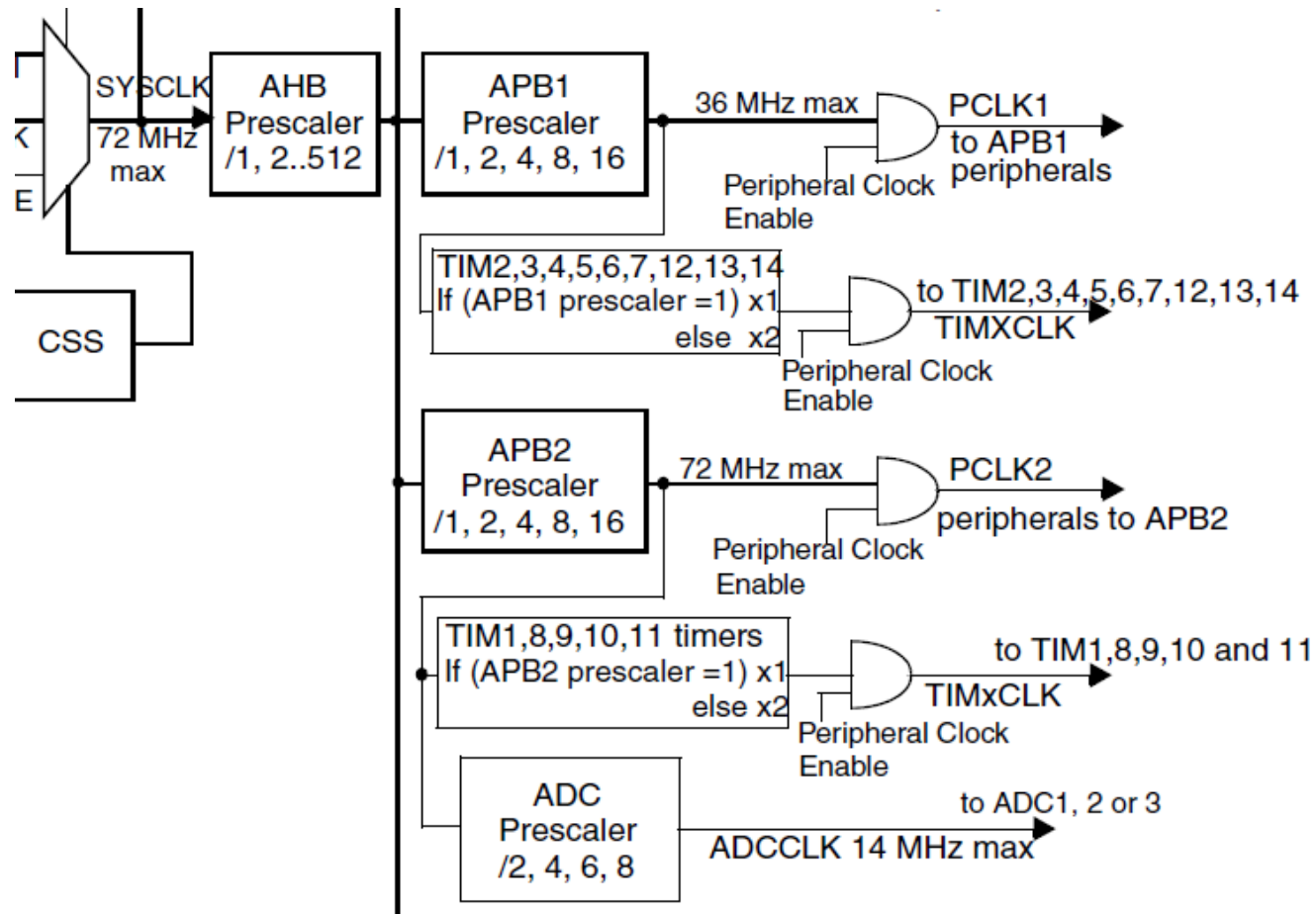
Multi-channel
Continuous Conversion Mode



Block Diagram (Ref. Man. P. 208)



Clock Tree



Where is the ADCCLK source ? APB1/APB2 ?

What is the Max value of ADCCLK ?

Note on ADCCLK

Refer to Page 207 of the Reference Manual, it said

- ADC conversion time:
 - STM32F103xx performance line devices: 1 μ s at 56 MHz (1.17 μ s at 72 MHz)
- Question
 - Why the SYSCLK faster, but conversion time is longer ?

Refer to last page.

- ADCCLK originates from APB2
- The Prescaler of ADCCLK can only be /2, 4, 6, 8
- If APB2 = 72MHz, what the max ADCCLK can be ?
- If APB2 = 56MHz, what the max ADCCLK can be ?

Total Conversion Time

Refer to Section 11.6 of the Reference Manual.

- Each channel can be sampled with a different sample time.
- The total conversion time is calculated as follows:
 - $T_{\text{conv}} = \text{Sampling time} + 12.5 \text{ cycles}$
- The sampling time can be set via the SMP[2:0] bits in the ADC_SMPR1 and ADC_SMPR2 registers.
- Example:
- With an ADCCLK = 14 MHz and a sampling time of 1.5 cycles:
 - $T_{\text{conv}} = 1.5 + 12.5 = 14 \text{ cycles} = 1 \mu\text{s}$

Sampling Time

11.12.4 ADC sample time register 1 (ADC_SMPR1)

Address offset: 0x0C

Reset value: 0x0000 0000

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
Reserved								SMP17[2:0]			SMP16[2:0]			SMP15[2:1]	
								rw	rw	rw	rw	rw	rw	rw	rw
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
SMP15_0	SMP14[2:0]			SMP13[2:0]			SMP12[2:0]			SMP11[2:0]			SMP10[2:0]		
rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw

Bits 31:24 Reserved, must be kept at reset value.

Bits 23:0 **SMPx[2:0]**: Channel x Sample time selection

These bits are written by software to select the sample time individually for each channel. During sample cycles channel selection bits must remain unchanged.

000: 1.5 cycles

001: 7.5 cycles

010: 13.5 cycles

011: 28.5 cycles

100: 41.5 cycles

101: 55.5 cycles

110: 71.5 cycles

111: 239.5 cycles

Note: ADC1 analog Channel16 and Channel 17 are internally connected to the temperature sensor and to V_{REFINT} , respectively.

ADC2 analog input Channel16 and Channel17 are internally connected to V_{SS} .

ADC3 analog inputs Channel14, Channel15, Channel16 and Channel17 are connected to V_{SS} .

About Data Alignment

- The data alignment means how the ADC data is being put into the register.

Figure 27. Right alignment of data

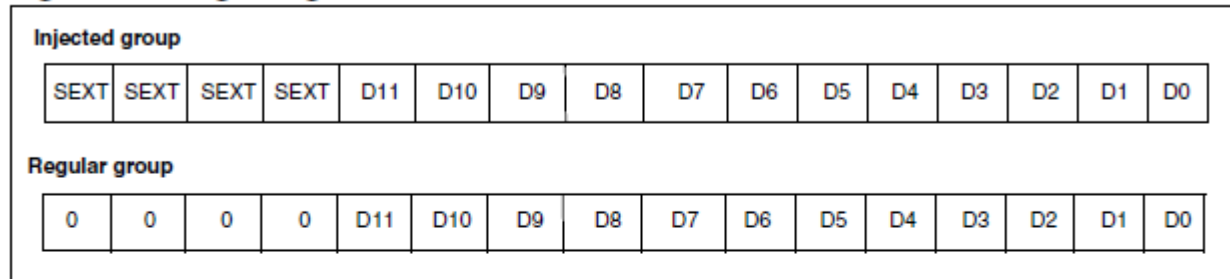
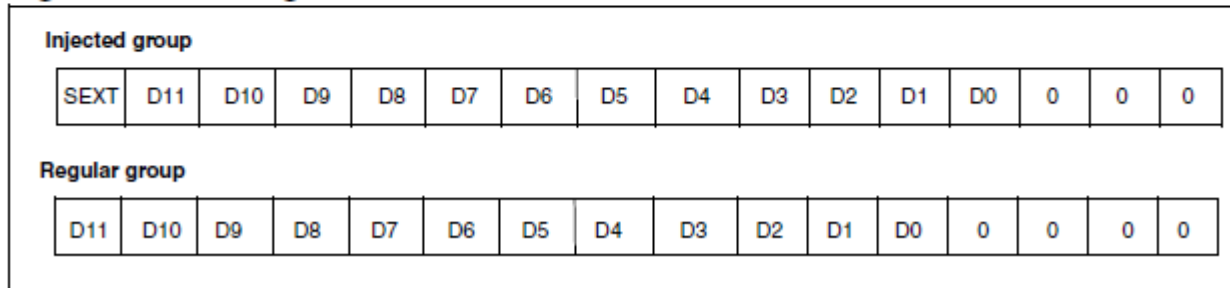
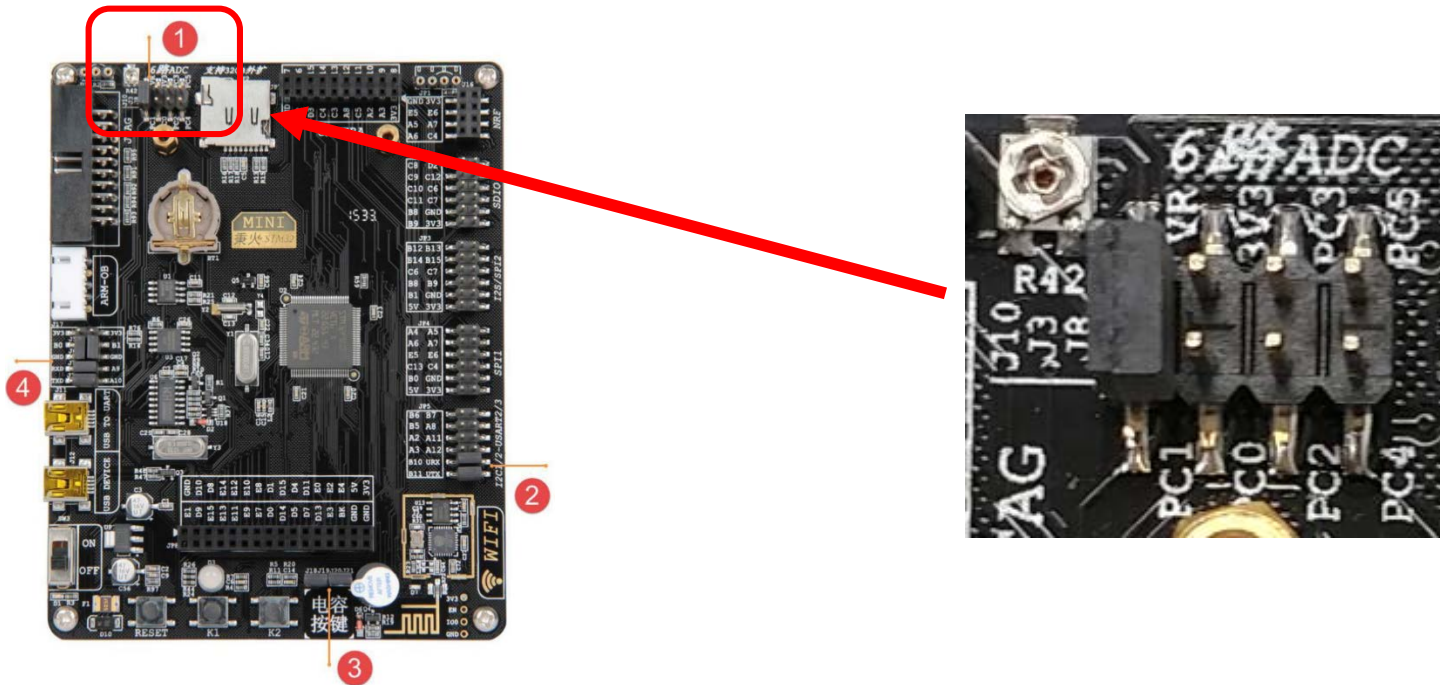


Figure 28. Left alignment of data



ADC in MINI-V3

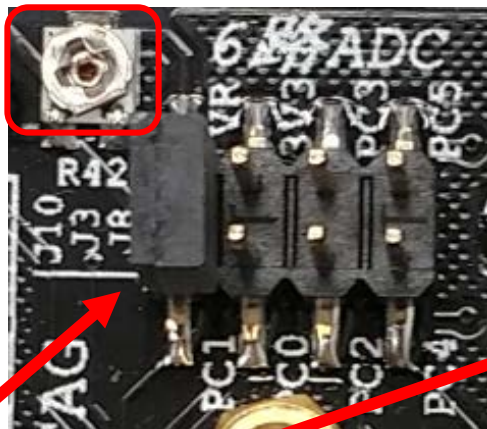
- In MINI-V3, there are different ADC channels located at position 1 of the figure below



ADC in MINI-V3

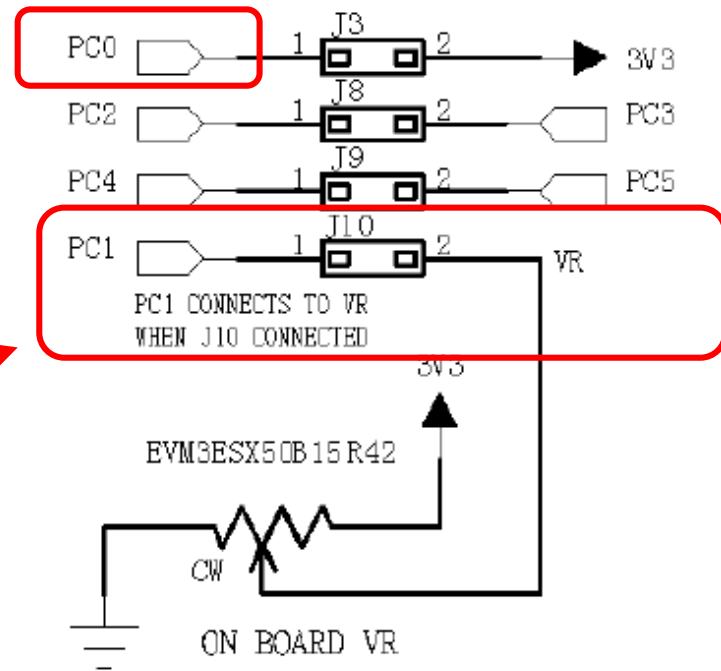
- The corresponding schematic is also shown here, note that it is not pin to pin correspondence to the board.

ON BOARD VR



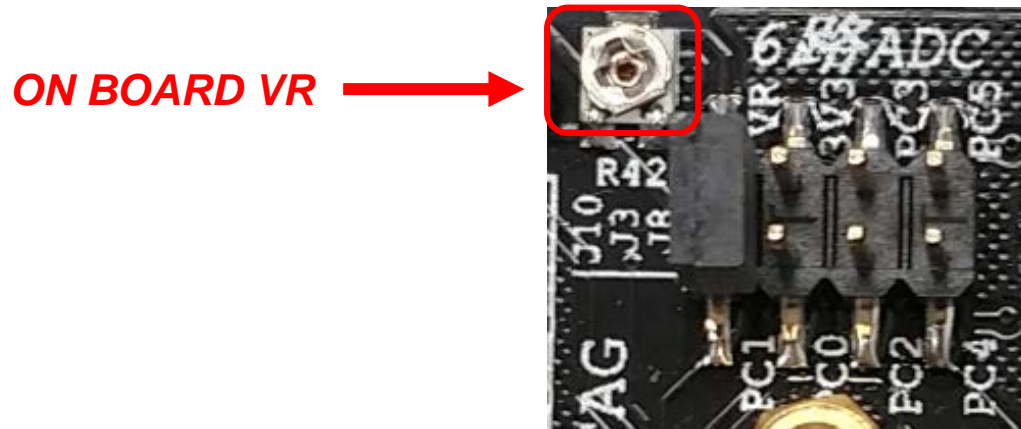
As you see there is a jumper at J10 connected to PC1 and VR

Note: PC0 has a 4.7kΩ to 3V3



ADC in MINI-V3

- The on board VR is not good to use and easy to be damaged. As a result, we will use an outside circuit to connect the analogue input to one of the channels



- Actually there are many ADC channels (not limited to the one shown above) in STM32 that you can use.

ADC in STM32

- Refer to STM32 Datasheet,
 - ❑ ADC1 and ADC2 have 16 channels (from IN0 to IN15) to use
 - ❑ ADC3 have 13 channels (from IN0 to IN8, IN10 to IN13)

	IN0	IN1	IN2	IN3	IN4	IN5	IN6	IN7	IN8	IN9	IN10	IN11	IN12	IN13	IN14	IN15
ADC1																
ADC2																
ADC3										N/A					N/A	N/A

- In Datasheet
 - ❑ ADC123_IN10 → means Channel 10 shared by ADC1 ADC2 and ADC3
 - ❑ ADC12_IN5 → means Channel 5 shared by ADC1 and ADC2 only
 - ❑ ADC3_IN8 → means Channel 8 for ADC3 only
- Question : If one shared channel means one I/O pin, if we use all the channels available, how many I/O pins will be used by ADC ?



ADC in STM32

- In this LAB, we will use **ADC1** and **ADC2**, you need to use the channel according to the last digit of your student ID

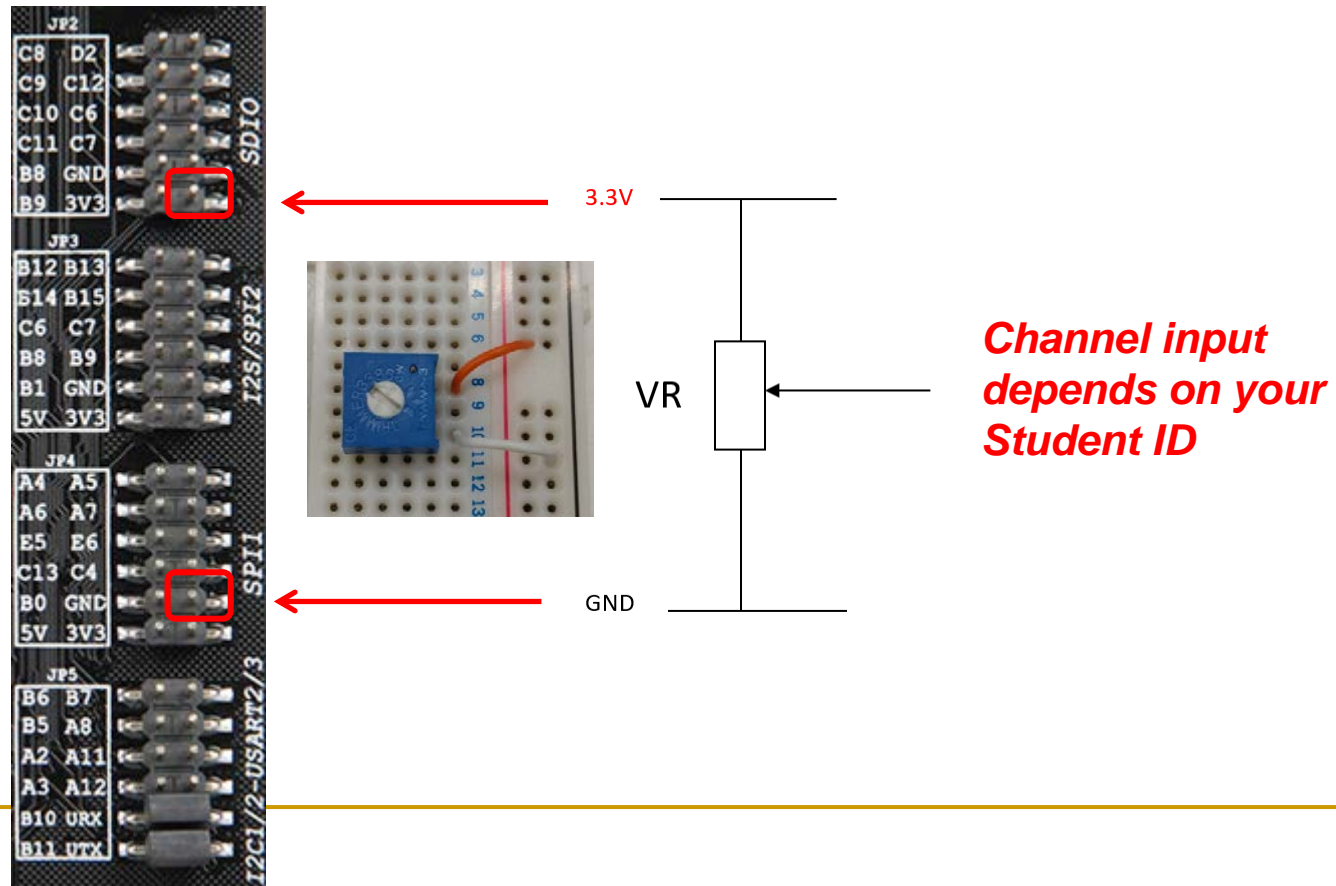
Last digit of your student ID	0	1	2	3	4	5	6	7	8	9
Channel number	12	13	2	3	4	5	6	7	14	15
Corresponding I/O pin in STM32 ? 🤔										

- Check the corresponding I/O pin from datasheet then check the location of that pin on MINI V3 board



Using VR as input

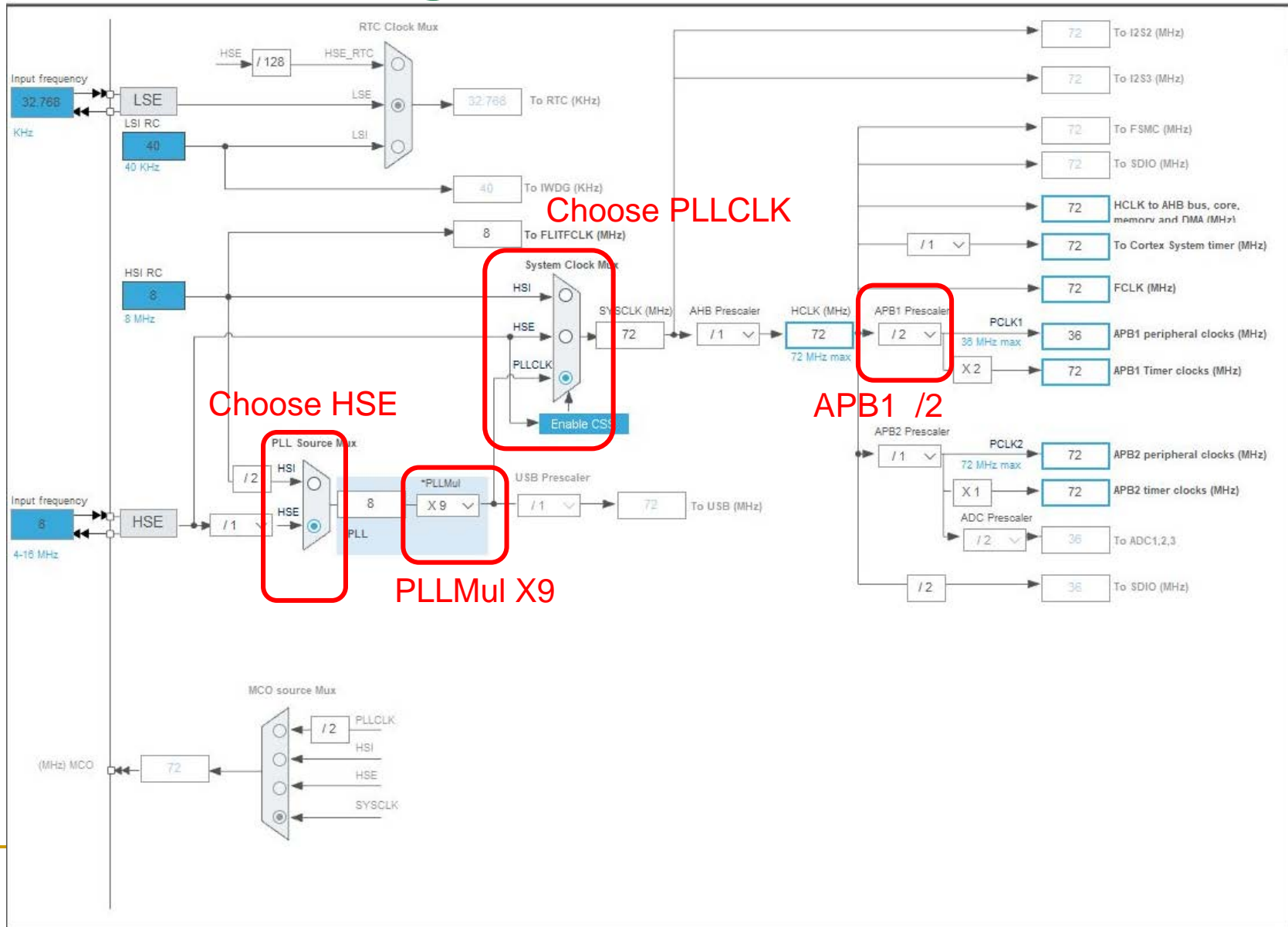
- Using your breadboard, assemble the following circuit, this would be used for your Task 1 and Task 2.



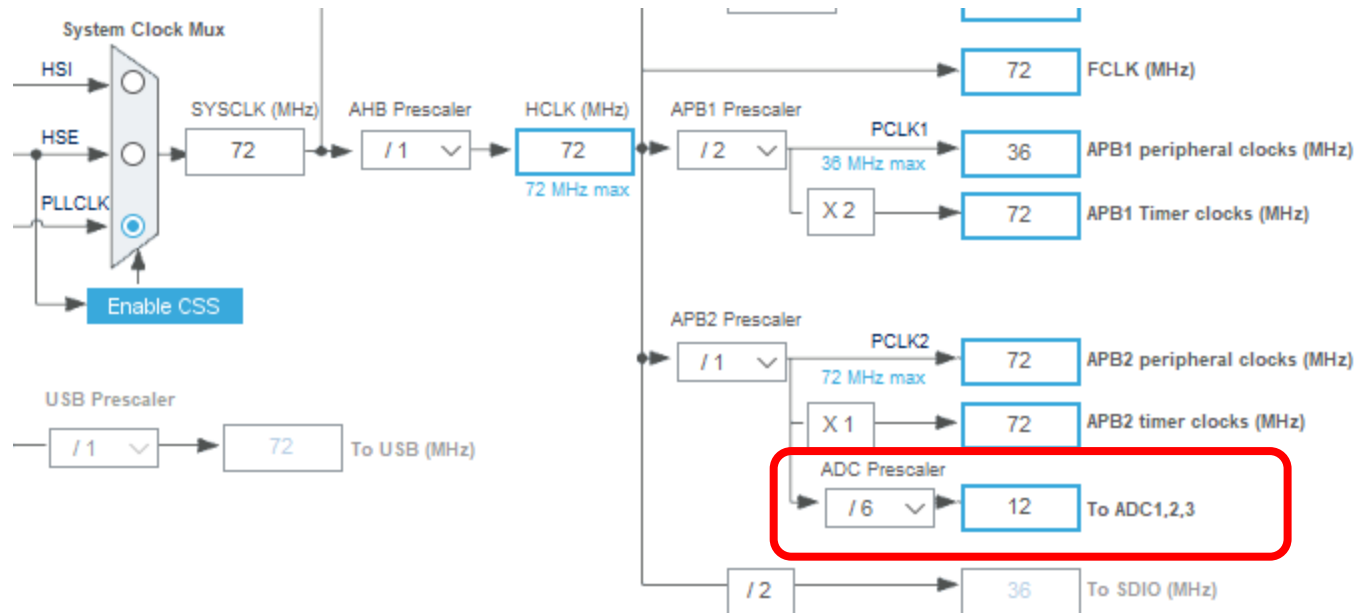
Configuration of LCD

- In this LAB, we need to use the LCD to display the value.
- Please refer to the Tutorial for CubeIDE and Tutorial for LAB3 to create a project that allows you to use the LCD Display.
- Or you may start your LAB5 by using the LAB3 as a starting point.

Clock Configuration



Setting the clock of ADC in CubeIDE



- Is it the fastest setting of ADCCLK?
- How can you change it to fastest ?



Configuration of ADC

The screenshot displays the STM32CubeMX configuration tool. The top navigation bar includes 'Pinout & Configuration', 'Clock Configuration', 'Additional Software', and 'Pinout'. The left sidebar shows the 'System Core' tree with 'ADC1' selected under the 'Analog' category. The main panel is titled 'ADC1 Mode and Configuration' and is divided into 'Mode' and 'Configuration' sections. In the 'Mode' section, 'IN14' is selected. In the 'Configuration' section, 'Independent mode' is selected for 'Data Alignment', and 'Regular Conversion launched by software' is selected for 'External Trigger Conversion Source'. Red annotations highlight these specific settings.

Pinout & Configuration

Clock Configuration

Additional Software

Pinout

Categories A-Z

System Core

DMA

GPIO

IWDG

NVIC

✓ RCC

✓ SYS

WWDG

Analog

ADC1

ADC2

ADC3

DAC

Timers

Connectivity

CAN

FSMC

I2C1

I2C2

SDIO

SPI1

SPI2

SPI3

UART4

UART5

USART1

ADC1 Mode and Configuration

Mode

IN12

IN13

✓ IN14

IN15

Temperature Sensor Channel

Vrefint Channel

Configuration

Reset Configuration

Parameter Settings

User Constants

NVIC Settings

DMA Settings

GPIO Settings

Configure the below parameters :

Search (Ctrl+F)

ADCs_Common_Settings

Mode

ADC_Settings

Data Alignment

Scan Conversion Mode

Continuous Conversion Mode

Discontinuous Conversion Mode

ADC_Regular_ConversionMode

Enable Regular Conversions

Number Of Conversion

External Trigger Conversion Source

Rank

Channel

Sampling Time

ADC_Injected_ConversionMode

Number Of Conversions

WatchDog

Enable Analog WatchDog Mode

Independent mode

Right alignment

Disabled

Disabled

Disabled

Enable

1

Regular Conversion launched by software

1

Channel 14

55.5 Cycles

Channel number you use

Mode and
Alignment
Selection

Conversion
Selection

About Calibration

- The ADC has an built-in self calibration mode. Calibration significantly reduces accuracy errors due to internal capacitor bank variations.
- During calibration, an error-correction code (digital word) is calculated for each capacitor, and during all subsequent conversions, the error contribution of each capacitor is removed using this code.
- Once calibration is over, the CAL bit is reset by hardware and normal conversion can be performed. It is recommended to calibrate the ADC once at power-on. The calibration codes are stored in the ADC_DR as soon as the calibration phase ends.

About Calibration

- The datasheet suggested to perform a self calibration at the startup, so, you may want to add the following line before the while(1) loop of your code.

```
HAL_ADCEx_Calibration_Start(&hadc1);
```

Depends on which ADC you use

How to start a conversion and get the result ?

- The ADC conversion can be initiated by

```
HAL_ADC_Start(&hadc1);
```

Depends on which ADC you use

- Please note that there is a time needed for the conversion, you can use the following line to poll the end of conversion.

```
HAL_ADC_PollForConversion(&hadc1, 1000);
```

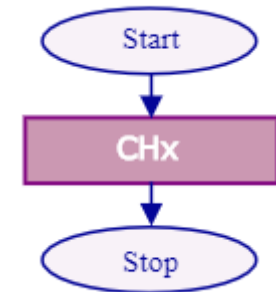
Timeout in milliseconds

- You can read the conversion result by calling the procedure

```
uint32_t HAL_ADC_GetValue(&hadc1);
```

Task 1 – Single Conversion on ADC1

- You are required to use **Single Conversion Mode** of **ADC1** to finish Task 1
- You need to write a program to display an ADC conversion result **of the external VR** in both **decimal and hex**.
- When K2 is pressed, ADC1 will start the conversion and result will be displayed on LCD.
- ADC1 should NOT be working if K2 is NOT pressed
- You need to show to your TA your main.c for verifying the mode used



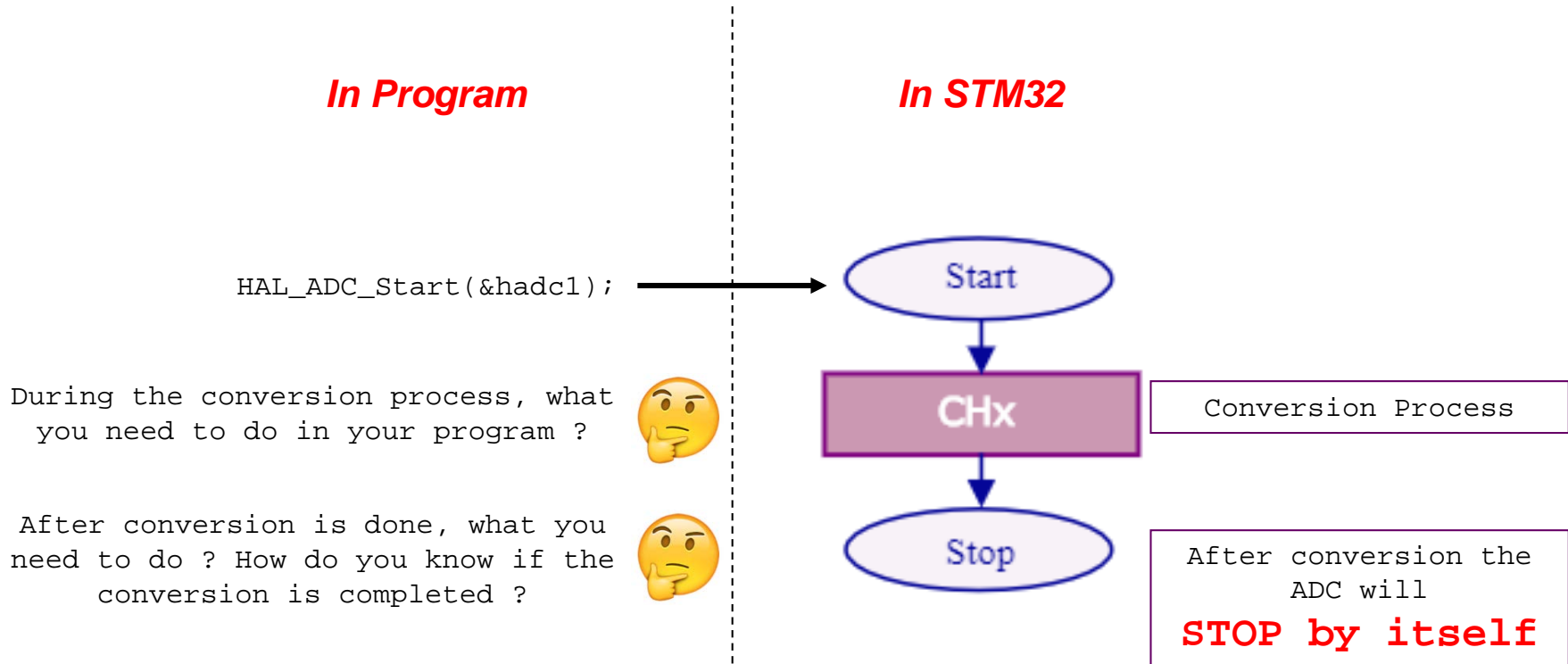
Task 1 – Display the Result

- You need to think about how to decompose the value to display. The following functions and table might help you. Details refer back to lcd.c in the lcd.zip

```
void LCD_DrawChar(uint16_t usC, uint16_t usP, const char cChar);  
void LCD_DrawString(uint16_t usC, uint16_t usP, const char * pStr);
```

- You can also use stdlib function like sprintf() to help you.

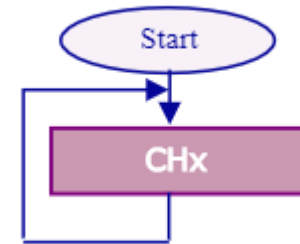
Task 1 – Relation between SW and ADC



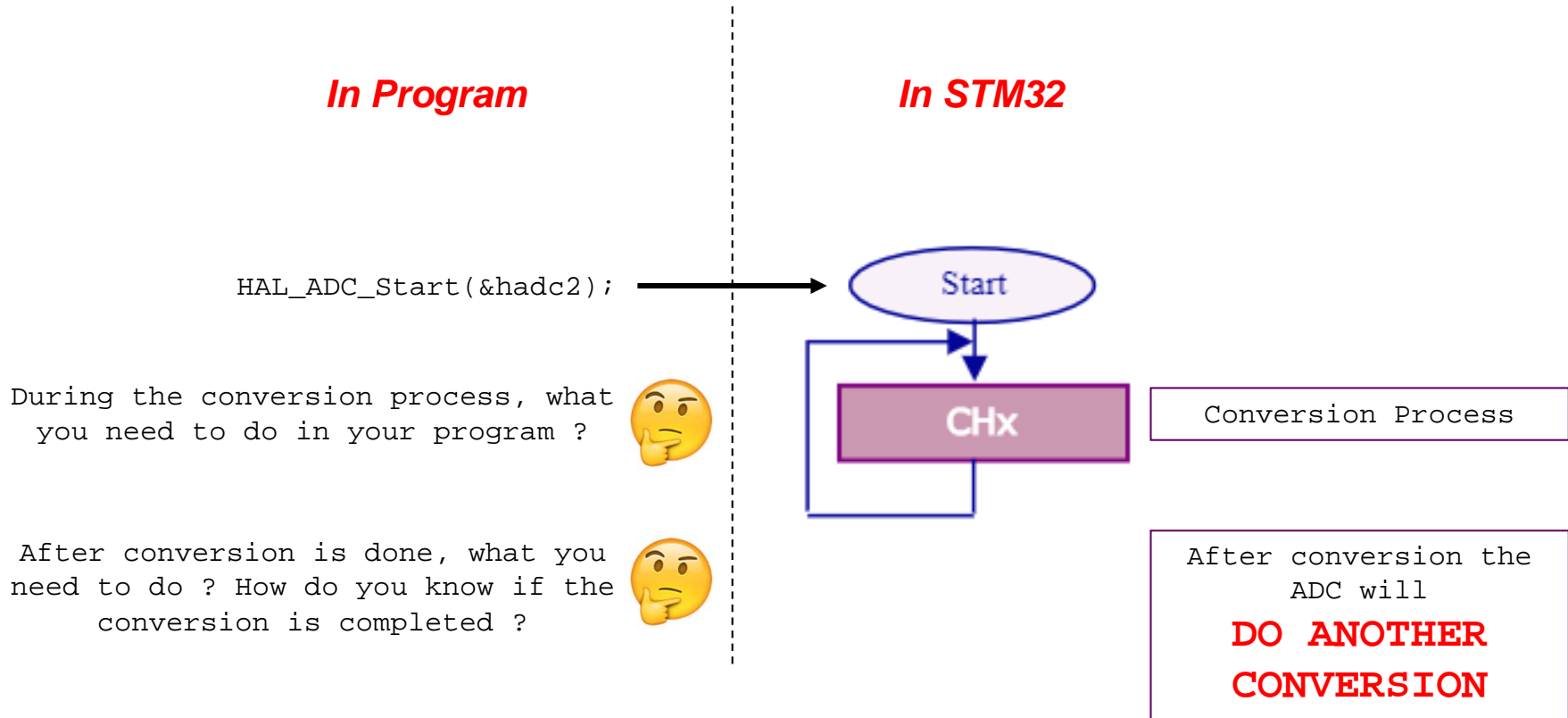
NOTE : For Task 1, the whole PROCESS should be done when K2 is PRESSED
Question : How can I make the ADC work again ?

Task 2 – Continuous Conversion on ADC2

- You are required to use **Continuous Conversion Mode** of **ADC2** to finish Task 2
- You need to write a program to display an ADC2 conversion result of the external VR in both **decimal and hex**.
- You need to show to your TA your main.c for verifying the mode used



Task 2 – Relation between SW and ADC



Question: Do you think you need to ask the ADC to start again ?



IMPORTANT: ADCs are working in **DIFFERENT MODES** for Task 1 and Task 2

Task 1 and 2 – Note

The result you displayed should be

1. From _____ to _____ for DEC
2. From _____ to _____ for HEX
3. 1 and 2 should be **SAME** value but **DIFFERENT REPRESENTATION ONLY**

If there exists (\exists) a result violating **any of above 3 conditions**, it means your program have BUG.



Please think out why 🤔and FIX it.



DEC	HEX	Correct ?
0	000	
10	0a0	
0004	000	
1234	4d2	
6013	177D	
7129	2c8	

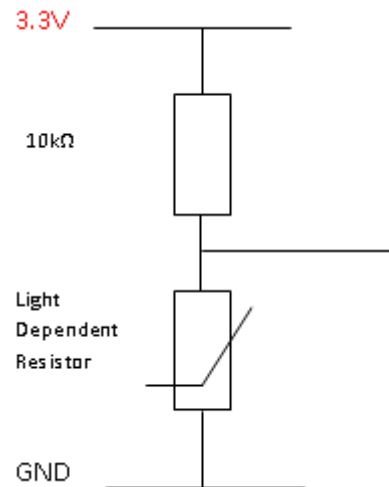
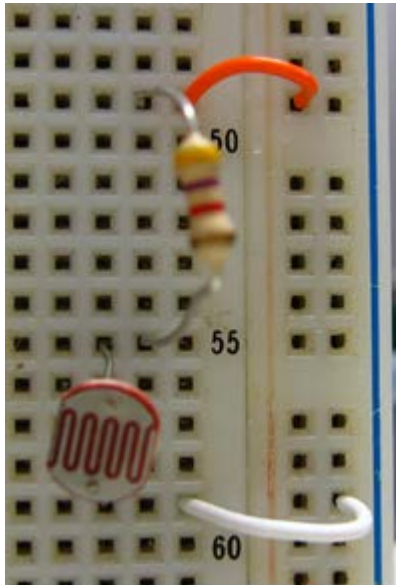
Connecting to LDR

- Light Dependent Resistor is a resistor that the resistance will depends on the light intensity. In this part, you need to use the LDR as an analogue input to the system.



Using LDR as input

- Replace your VR with a fixed resistor and a LDR



*Channel input
depends on your
Student ID*

Task 3: Using LDR as input

- Following the steps listed on the LAB Sheet, fill the corresponding data.
- You might need to try to swap the LDR and the resistor.

Task 4: Light Intensity System

- Using your knowledge from Task 3 and LAB2, together with the RGB LED on MINI V3 Development Board, implement a five-level Light Intensity System such that..

	Light Intensity				
	Very Dark	Dark	Medium	Bright	Very Bright
RGB LED COLOR	WHITE	RED	GREEN	BLUE	OFF

- You can use either Figure 1 or Figure 2 on Page 2 of the LAB sheet to implement the system, as long as it follows above requirement.
- You are free to choose the boundary for the system, but you need to clearly show the TA the five different levels according to the above requirement during the demo.

After finishing LAB5 you are expected to...

1. Use CubeIDE to initialize different ADC modes.
2. Understand the difference between Single Conversion mode and Continuous Conversion mode, and how to program them.
3. Calculate the sampling frequency for a conversion based on the relation between input clock and the sample time.
4. Get the analogue input from the ADC for further processing.
5. Understand why and when we need ADC as an input to STM32.
6. Integrate the knowledge of LAB2 (RGB LED), LAB3 (LCD) add to LAB5.

END