

All MATLAB code used to generate answers for this assignment can be found at

github.com/ashlynns/ECE403/tree/master/A2

1.4

a) $f(x_1, x_2) = x_1^2 - 2x_2 \sin x_1 + 100$

$$\nabla f(x_1, x_2) = \begin{bmatrix} \frac{\partial f}{\partial x_1} \\ \frac{\partial f}{\partial x_2} \end{bmatrix} = \begin{bmatrix} 2x_1 - 2x_2 \cos x_1 \\ -2 \sin x_1 \end{bmatrix}$$

$$\nabla^2 f(x_1, x_2) = \begin{bmatrix} \frac{\partial^2 f}{\partial x_1^2} & \frac{\partial^2 f}{\partial x_1 \partial x_2} \\ \frac{\partial^2 f}{\partial x_2 \partial x_1} & \frac{\partial^2 f}{\partial x_2^2} \end{bmatrix} = \begin{bmatrix} 2 + 2x_2 \sin x_1 & -2 \cos x_1 \\ -2 \cos x_1 & 0 \end{bmatrix}$$

b) $f(\mathbf{x}) = \frac{1}{2} \mathbf{x}^T \mathbf{H} \mathbf{x} + \mathbf{x}^T \mathbf{b} + k$, $\mathbf{H} \in \mathbb{R}^{n \times n}$, $\mathbf{b} \in \mathbb{R}^{n \times 1}$, $k \in \mathbb{R}^{1 \times 1}$

Let $\mathbf{x} = [x_1, x_2, \dots, x_n]^T$, $\mathbf{H} = \begin{bmatrix} \mathbf{h}_1 \\ \mathbf{h}_2 \\ \vdots \\ \mathbf{h}_n \end{bmatrix} = \begin{bmatrix} h_{1,1} & h_{1,2} & \cdots & h_{1,n} \\ h_{2,1} & h_{2,2} & \cdots & h_{2,n} \\ \vdots & \vdots & \ddots & \vdots \\ h_{n,1} & h_{n,2} & \cdots & h_{n,n} \end{bmatrix}$, $\mathbf{b} = [b_1, b_2, \dots, b_n]^T$

$$\begin{aligned} \nabla f(\mathbf{x}) &= \nabla \frac{1}{2} \mathbf{x}^T \mathbf{H} \mathbf{x} + \nabla \mathbf{x}^T \mathbf{b} + \nabla k \\ &= \frac{1}{2} \cdot \nabla \mathbf{x}^T [\mathbf{h}_1 \mathbf{x}, \mathbf{h}_2 \mathbf{x}, \dots, \mathbf{h}_n \mathbf{x}] + \nabla (x_1 b_1 + x_2 b_2 + \dots + x_n b_n) + 0 \\ &= \frac{1}{2} \cdot \nabla (x_1 \mathbf{h}_1 \mathbf{x} + x_2 \mathbf{h}_2 \mathbf{x} + \dots + x_n \mathbf{h}_n \mathbf{x}) + \mathbf{b} \\ &= \frac{1}{2} \left[\begin{array}{c} \frac{d}{dx_1} (x_1 \mathbf{h}_1 \mathbf{x} + x_2 \mathbf{h}_2 \mathbf{x} + \dots + x_n \mathbf{h}_n \mathbf{x}) \\ \frac{d}{dx_2} (x_1 \mathbf{h}_1 \mathbf{x} + x_2 \mathbf{h}_2 \mathbf{x} + \dots + x_n \mathbf{h}_n \mathbf{x}) \\ \vdots \\ \frac{d}{dx_n} (x_1 \mathbf{h}_1 \mathbf{x} + x_2 \mathbf{h}_2 \mathbf{x} + \dots + x_n \mathbf{h}_n \mathbf{x}) \end{array} \right] + \mathbf{b} \\ &= \frac{1}{2} \left[\begin{array}{c} \mathbf{h}_1 \mathbf{x} + (x_1 h_{1,1} + x_2 h_{1,2} + \dots + x_n h_{1,n}) \\ \mathbf{h}_2 \mathbf{x} + (x_1 h_{2,1} + x_2 h_{2,2} + \dots + x_n h_{2,n}) \\ \vdots \\ \mathbf{h}_n \mathbf{x} + (x_1 h_{n,1} + x_2 h_{n,2} + \dots + x_n h_{n,n}) \end{array} \right] + \mathbf{b} \\ &= \frac{1}{2} (\mathbf{H} \mathbf{x} + \mathbf{H}^T \mathbf{x}) + \mathbf{b} \\ &= \frac{1}{2} (\mathbf{H} + \mathbf{H}^T) \mathbf{x} + \underline{\mathbf{b}} \end{aligned}$$

$$\begin{aligned}
\nabla^2 f(x) &= \nabla(\nabla^T f(x)) \\
&= \nabla(\frac{1}{2} (H + H^T)x + b)^T \\
&= \nabla(\frac{1}{2}x^T (H + H^T) + b^T) \\
&= \frac{1}{2} \nabla x^T (H + H^T) + 0
\end{aligned}$$

$$\begin{aligned}
&= \frac{1}{2} \nabla \left[\begin{array}{c} x_1 h_{1,1} + x_2 h_{2,1} + \dots + x_n h_{n,1} \\ x_1 h_{1,2} + x_2 h_{2,2} + \dots + x_n h_{n,2} \\ \vdots \\ x_1 h_{1,n} + x_2 h_{2,n} + \dots + x_n h_{n,n} \end{array} \right]^T + \frac{1}{2} \nabla \left[\begin{array}{c} x_1 h_{1,1} + x_2 h_{1,2} + \dots + x_n h_{1,n} \\ x_1 h_{2,1} + x_2 h_{2,2} + \dots + x_n h_{2,n} \\ \vdots \\ x_1 h_{n,1} + x_2 h_{n,2} + \dots + x_n h_{n,n} \end{array} \right]^T \\
&= \frac{1}{2} \begin{bmatrix} h_{1,1} & h_{1,2} & \dots & h_{1,n} \\ h_{2,1} & h_{2,2} & \dots & h_{2,n} \\ \vdots & \vdots & \ddots & \vdots \\ h_{n,1} & h_{n,2} & \dots & h_{n,n} \end{bmatrix} + \frac{1}{2} \begin{bmatrix} h_{1,1} & h_{2,1} & \dots & h_{n,1} \\ h_{1,2} & h_{2,2} & \dots & h_{n,2} \\ \vdots & \vdots & \ddots & \vdots \\ h_{n,1} & h_{n,2} & \dots & h_{n,n} \end{bmatrix} \\
&= \frac{1}{2} (\underline{H + H^T})
\end{aligned}$$

c) $f(\theta) = \frac{1}{P} \sum_{p=1}^P \log(1 + e^{-\theta^T z_p})$, $\theta \in \mathbb{R}^{N \times 1}$, $\{z_p \text{ for } p=1, 2, \dots, P\}$
 $z_i \in \mathbb{R}^{N \times 1}$

$$\begin{aligned}
\nabla f(\theta) &= \nabla \frac{1}{P} \sum_{p=1}^P \log(1 + e^{-\theta^T z_p}) \\
&= \frac{1}{P} \sum_{p=1}^P \nabla \log(1 + e^{-\theta^T z_p}) \\
&= \frac{1}{P} \sum_{p=1}^P \begin{bmatrix} -(1 + e^{-\theta^T z_p})^{-1} e^{-\theta^T z_p} z_{p,1} \\ -(1 + e^{-\theta^T z_p})^{-1} e^{-\theta^T z_p} z_{p,2} \\ \vdots \\ -(1 + e^{-\theta^T z_p})^{-1} e^{-\theta^T z_p} z_{p,P} \end{bmatrix}
\end{aligned}$$

$$\nabla f(\theta) = -\frac{1}{P} \sum_{p=1}^P \frac{e^{-\theta^T z_p}}{1 + e^{-\theta^T z_p}} z_p = -\frac{1}{P} \sum_{p=1}^P \frac{1}{1 + e^{-\theta^T z_p}} z_p$$

$$\begin{aligned}
\nabla^2 f(\theta) &= \nabla \left(-\frac{1}{P} \sum_{p=1}^P \frac{1}{1 + e^{-\theta^T z_p}} z_p \right)^T = -\frac{1}{P} \sum_{p=1}^P \nabla \frac{1}{1 + e^{-\theta^T z_p}} z_p^T \\
&= -\frac{1}{P} \sum_{p=1}^P \begin{bmatrix} -(1 + e^{-\theta^T z_p})^{-2} e^{-\theta^T z_p} z_{p,1} \\ -(1 + e^{-\theta^T z_p})^{-2} e^{-\theta^T z_p} z_{p,2} \\ \vdots \\ -(1 + e^{-\theta^T z_p})^{-2} e^{-\theta^T z_p} z_{p,P} \end{bmatrix} \cdot z_p^T
\end{aligned}$$

$$\nabla^2 f(\theta) = \frac{1}{P} \sum_{p=1}^P \frac{e^{\theta^T z_p}}{(1 + e^{\theta^T z_p})^2} z_p z_p^T$$

$$1.5 \quad a) \quad f(x) = 2x_1^2 + x_2^2 - 2x_1x_2 + 2x_1^3 + x_1^4$$

$$\nabla f(x) = \begin{bmatrix} 4x_1 - 2x_2 + 6x_1^2 + 4x_1^3 \\ 2x_2 - 2x_1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \Rightarrow x_1^* = \begin{bmatrix} 0 \\ 0 \end{bmatrix}, x_2^* = \begin{bmatrix} -0.5 \\ -0.5 \end{bmatrix}, x_3^* = \begin{bmatrix} -1 \\ -1 \end{bmatrix}$$

$$\nabla^2 f(x) = \begin{bmatrix} 4 + 12x_1 + 12x_1^2 & -2 \\ -2 & 2 \end{bmatrix}$$

$$\nabla^2 f(x_1^*) = \begin{bmatrix} 4 & -2 \\ -2 & 2 \end{bmatrix} \rightarrow \lambda = \det \left(\begin{bmatrix} 4-\lambda & -2 \\ -2 & 2-\lambda \end{bmatrix} \right) = 0 \quad \left. \begin{array}{l} \lambda = (4-\lambda)(2-\lambda) - 4 = 0 \\ \lambda = \lambda^2 - 6\lambda + 4 = 0 \\ \lambda = \begin{bmatrix} 5.24 \\ 0.76 \end{bmatrix} \end{array} \right\} \text{Positive } \lambda \text{ means } x_1^* = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \text{ is a minimizer}$$

$$\nabla^2 f(x_2^*) = \begin{bmatrix} 1 & -2 \\ -2 & 2 \end{bmatrix} \rightarrow \lambda = \det \left(\begin{bmatrix} 1-\lambda & -2 \\ -2 & 2-\lambda \end{bmatrix} \right) = 0 \quad \left. \begin{array}{l} \lambda = (1-\lambda)(2-\lambda) - 4 = 0 \\ \lambda = \lambda^2 - 3\lambda - 2 = 0 \\ \lambda = \begin{bmatrix} 3.56 \\ -0.56 \end{bmatrix} \end{array} \right\} \text{Mixed } \lambda \text{ means } x_2^* = \begin{bmatrix} -0.5 \\ -0.5 \end{bmatrix} \text{ is a saddle point}$$

$$\nabla^2 f(x_3^*) = \begin{bmatrix} 4 & -2 \\ -2 & 2 \end{bmatrix} \rightarrow \text{See } \lambda \text{ calculations for } \nabla^2 f(x_1^*) \quad \left. \begin{array}{l} \lambda = (4-\lambda)(2-\lambda) - 4 = 0 \\ \lambda = \lambda^2 - 6\lambda + 4 = 0 \\ \lambda = \begin{bmatrix} 5.24 \\ 0.76 \end{bmatrix} \end{array} \right\} \text{Positive } \lambda \text{ means } x_3^* = \begin{bmatrix} -1 \\ -1 \end{bmatrix} \text{ is a minimizer}$$

$$b) f(x) = x_1^2 x_2^2 - 4x_1^2 x_2 + 4x_1^2 + 2x_1 x_2^2 + x_2^2 - 8x_1 x_2 + 8x_1 - 4x_2$$

$$\nabla f(x) = \begin{bmatrix} 2x_1 x_2^2 - 8x_1 x_2 + 8x_1 + 2x_2^2 - 8x_2 + 8 \\ 2x_1^2 x_2 - 4x_1^2 + 4x_1 x_2 + 2x_2 - 8x_1 - 4 \end{bmatrix}$$

$$= \begin{bmatrix} x_1 (2x_2^2 - 8x_1 + 8) + (2x_2^2 - 8x_2 + 8) \\ 2(x_2(x_1 + 2x_1 + 1) - 2x_1^2 - 4x_1 - 2) \end{bmatrix} = \begin{bmatrix} 2(x_2^2 - 4x_1 + 4)(x_1 + 1) \\ 2(x_2 - 2)(x_1^2 - 2x_1 - 1) \end{bmatrix}$$

$$\nabla f(x) = \begin{bmatrix} 2(x_2 - 2)^2(x_1 + 1) \\ 2(x_2 - 2)(x_1 + 1)^2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \rightarrow \text{These eq's will both be zero at any pt where } x_1 = -1 \text{ or } x_2 = 2. \text{ Since they are lines with a continuous } \nabla f(x) = 0, \text{ they will share a min/max behavior. All that to say we can test this using } x^* = \begin{bmatrix} -1 \\ 2 \end{bmatrix} \text{ (using } \begin{bmatrix} -1 \\ 2 \end{bmatrix) \text{ causes } \nabla^2 f(x^*) \text{ to zero out)} \begin{bmatrix} -1 \\ 3 \end{bmatrix}$$

$$\nabla^2 f(x) = \begin{bmatrix} 2(x_2 - 2)^2 & 4(x_1 + 1)(x_2 - 2) \\ 4(x_1 + 1)(x_2 - 2) & 2(x_1 + 1)^2 \end{bmatrix}$$

$$\nabla^2 f(x^*) = \begin{bmatrix} 2 & 0 \\ 0 & 0 \end{bmatrix} \rightarrow \lambda = \det \left(\begin{bmatrix} 2-\lambda & 0 \\ 0 & -\lambda \end{bmatrix} \right) = 0 \\ = (2-\lambda)(-\lambda)$$

$$\lambda = \begin{bmatrix} 2 \\ 0 \end{bmatrix} \rightarrow \text{Positive semi-definite } \lambda \text{ means that the lines where } x_1 = -1 \text{ or } x_2 = 2 \text{ are minimizers}$$

$$c) f(x) = (x_1^2 - x_2)^2 + x_1^5$$

$$\nabla f(x) = \begin{bmatrix} 4x_1 \cdot (x_1^2 - x_2) + 5x_1^4 \\ -2(x_1^2 - x_2) \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \rightarrow x^* = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\nabla^2 f(x) = \begin{bmatrix} 4(3x_1^2 - x_2) + 20x_1^3 & -4x_1 \\ -4x_1 & 2 \end{bmatrix}$$

$$\nabla^2 f(x^*) = \begin{bmatrix} 0 & 0 \\ 0 & 2 \end{bmatrix} \rightarrow \lambda = \det \left(\begin{bmatrix} -\lambda & 0 \\ 0 & 2-\lambda \end{bmatrix} \right) = 0$$

$$= (-\lambda)(2-\lambda)$$

$$= \lambda^2 - 2\lambda$$

$$\lambda = \begin{bmatrix} 2 \\ 0 \end{bmatrix} \rightarrow \begin{array}{l} \text{Positive means that } x^* = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \text{ is a} \\ \text{minimizer} \end{array}$$

semi-definite

$$1.6 \quad a) f(x) = x_1^2 + \cosh(x_2)$$

$$\nabla f(x) = \begin{bmatrix} 2x_1 \\ \sinh(x_2) \end{bmatrix} \quad \nabla^2 f(x) = \begin{bmatrix} 2 & 0 \\ 0 & \cosh(x_2) \end{bmatrix}$$

$$\lambda = \det \left(\begin{bmatrix} 2-\lambda & 0 \\ 0 & \cosh(x_2)-\lambda \end{bmatrix} \right) = 0$$

$$= (2-\lambda)(\cosh(x_2)-\lambda)$$

$$= \lambda^2 - \lambda(\cosh(x_2) + 2) + 2\cosh(x_2)$$

$$\lambda = \begin{bmatrix} 2 \\ \cosh(x_2) \end{bmatrix}$$

$\cosh(x_2)$ will always return a positive value $\therefore \lambda$ is positive definite and $f(x)$ is convex.

$$b) f(x) = x_1^2 + 2x_2^2 + 2x_3^2 + x_4^2 - x_1x_2 + x_1x_3 - 2x_2x_4 + x_1x_4$$

$$\nabla f(x) = \begin{bmatrix} 2x_1 - x_2 + x_3 + x_4 \\ 4x_2 - x_1 - 2x_4 \\ 4x_3 + x_1 \\ 2x_4 - 2x_2 + x_1 \end{bmatrix} \quad \nabla^2 f(x) = \begin{bmatrix} 2 & -1 & 1 & 1 \\ -1 & 4 & 0 & -2 \\ 1 & 0 & 4 & 0 \\ 1 & -2 & 0 & 2 \end{bmatrix}$$

From MATLAB, the eigenvalues of $\nabla^2 f(x)$ and $\nabla^2 - f(x)$ respectively are $\lambda = \begin{bmatrix} 0.6099 \\ 1.3281 \\ 4.2427 \\ 5.8192 \end{bmatrix}$ and $\lambda = \begin{bmatrix} -5.8192 \\ -4.2427 \\ -1.3281 \\ -0.6099 \end{bmatrix}$

Since the set of eigenvalues corresponding to $\nabla^2 f(x)$ is positive definite, a subset of positive semi-definite, $f(x)$ is convex.)

$$c) f(x) = x_1^2 - 2x_2^2 - 2x_3^2 + x_4^2 - x_1x_2 + x_1x_3 - 2x_2x_4 + x_3x_4$$

$$\nabla f(x) = \begin{bmatrix} 2x_1 - x_2 + x_3 + x_4 \\ -4x_2 - x_1 - 2x_4 \\ -4x_3 + x_1 \\ 2x_4 - 2x_2 + x_3 \end{bmatrix} \quad \nabla^2 f(x) = \begin{bmatrix} 2 & -1 & 1 & 1 \\ -1 & -4 & 0 & -2 \\ 1 & 0 & -4 & 0 \\ 1 & -2 & 0 & 2 \end{bmatrix}$$

From MATLAB, the eigenvalues of $\nabla^2 f(x)$ and $\nabla^2 - f(x)$ are $\lambda = \begin{bmatrix} -4.6939 \\ -4.1453 \\ 1.1797 \\ 3.6595 \end{bmatrix}$ and $\lambda = \begin{bmatrix} -3.6595 \\ -1.1797 \\ 4.1453 \\ 4.6939 \end{bmatrix}$ respectively.

Since neither set of eigenvalues is non-negative, which corresponds to a positive semi definite hessian, $f(x)$ is neither convex nor concave.

$$1.7 \quad f(x) = (x_1 + x_2)^2 + [2(x_1^2 + x_2^2 - 1) - \frac{1}{3}]^2$$

$$a) \nabla f(x) = \begin{bmatrix} 2(x_1 + x_2) + 8x_1(2x_1^2 + 2x_2^2 - \frac{7}{3}) \\ 2(x_1 + x_2) + 8x_2(2x_1^2 + 2x_2^2 - \frac{7}{3}) \end{bmatrix}$$

$$2(x_1 + x_2) + 8x_1(2x_1^2 + 2x_2^2 - \frac{7}{3}) = 2(x_1 + x_2) + 8x_2(2x_1^2 + 2x_2^2 - \frac{7}{3})$$

$$8(x_1 - x_2)(2x_1^2 + 2x_2^2 - \frac{7}{3}) = 0$$

$$\text{If } 2x_1^2 + 2x_2^2 - \frac{7}{3} = 0; \\ 2(x_1 + x_2) = 0 \\ \text{so, } x_1 = x_2$$

$$\text{If } x_1 = x_2 :$$

$$\begin{aligned} 4x_1 + 8x_1(4x_1^2 - \frac{7}{3}) &= 0 \\ x_1 + 2x_1(4x_1^2 - \frac{7}{3}) &= 0 \\ 8x_1^3 - \frac{14}{3}x_1 + x_1 &= 0 \\ x_1(8x_1^2 - \frac{11}{3}x_1) &= 0 \\ x_1(x_1^2 - \frac{11}{24}x_1) &= 0 \\ \text{so, } x_1 = x_2 = 0 \quad \text{or } &\pm \sqrt{\frac{11}{24}} \end{aligned}$$

$$x_1^* = \begin{bmatrix} 0 \\ 0 \end{bmatrix}, \quad x_2^* = \begin{bmatrix} \sqrt{\frac{11}{24}} \\ \sqrt{\frac{11}{24}} \end{bmatrix}, \quad x_3^* = \begin{bmatrix} -\sqrt{\frac{11}{24}} \\ -\sqrt{\frac{11}{24}} \end{bmatrix}$$

$$b) \nabla^2 f(x) = \begin{bmatrix} 48x_1^2 + 16x_2^2 - 50/3 & 2 + 32x_1x_2 \\ 2 + 32x_1x_2 & 48x_2^2 + 16x_1^2 - 50/3 \end{bmatrix}$$

$$\nabla^2 f(x_1^*) = \begin{bmatrix} -50/3 & 2 \\ 2 & -50/3 \end{bmatrix}$$

$$\lambda = \det \left(\begin{bmatrix} -50/3 - \lambda & 2 \\ 2 & -50/3 - \lambda \end{bmatrix} \right) = 0$$

$$= (-50/3 - \lambda)(-50/3 - \lambda) - 4$$

$$= \lambda^2 + 100/3 \lambda + 2464/9$$

$$\lambda = \begin{bmatrix} -14.67 \\ -18.67 \end{bmatrix} \rightarrow x_1^* \text{ is a } \underline{\text{maximizer}}$$

$$\nabla^2 f(x_2^*) = \begin{bmatrix} 38/3 & 50/3 \\ 50/3 & 38/3 \end{bmatrix}$$

$$\lambda = \det \left(\begin{bmatrix} 38/3 - \lambda & 50/3 \\ 50/3 & 38/3 - \lambda \end{bmatrix} \right) = 0$$

$$= (38/3 - \lambda)(38/3 - \lambda) - 2500/9$$

$$= \lambda^2 + 76/3 \lambda - 352/3$$

$$\lambda = \begin{bmatrix} 4 \\ -29.3 \end{bmatrix} \rightarrow x_2^* \text{ is a } \underline{\text{saddle point}}$$

$$\nabla^2 f(x_3^*) = \begin{bmatrix} 38/3 & 50/3 \\ 50/3 & 38/3 \end{bmatrix}$$

\hookrightarrow See calculations for x_2^* ,
 x_3^* is a saddle point