

CS218- Data Structures

Week 13

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December 01, 2020

Agenda

- BST – Pros n Cons
 - BST Motivation
 - AVL Tree
 - Different Rotations
-

Binary Search Tree (BST)

■ Pros

- max, min, search, insertion, and deletion all operations can be performed in $O(\log h)$, where h is the height of a BST.

■ Cons

- BST structures very much depends on the order of keys inserted into the BST.

Binary Search Tree (BST)

■ Motivation

- Can we do something to retain the balance of a BST?
 - Reconstruct the BST when your accounting of access suggests some bad performance
 - Allow a little out of balance and keep the operations cost to at least $O(\log(h+1))$. Follow the insertion of BST.
 - Restrict the tree to be balanced all the time.

■ Solution

- AVL Trees
- Red Black Trees

AVL Trees

- Adelson-Velskii and Landis (AVL) trees (height-balanced trees) – it is a kind of self balancing tree.
- In an AVL tree, the heights of the two child subtrees of any node differ by at most one.
- If at any time they differ by more than one, rebalancing is done to restore this property.
- Idea is to keep the tree almost balance all the time to gives $O(\log h+1)$ operations.

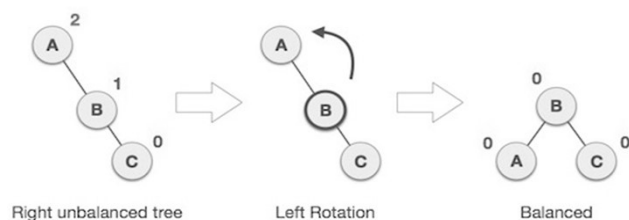
AVL Trees

- Insertion in AVL Tree
 - The insertion is same as BST but after this we try to restrict the condition on balance factor.
 - The absolute (height of left subtree – the height of right subtree) should not be greater than 1.
 - If the insertion violated the restriction – the tree is rearranged to obey the conditions.

AVL Trees

■ Left Rotation

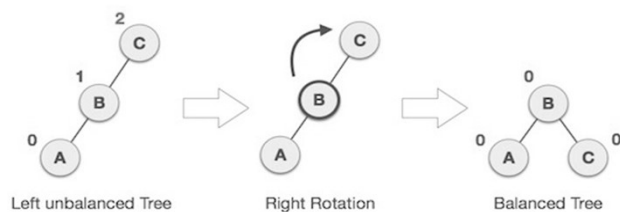
- if a tree becomes unbalanced, when a node is inserted into the right subtree of the right subtree, then we perform a single left rotation



AVL Trees

■ Right Rotation

- AVL tree may become unbalanced, if a node is inserted in the left subtree of the left subtree. The tree then needs a right rotation.



AVL Trees

```
template <class T>
class AVLNode {

    private:
        T key;
        AVLNode<T> *left;
        AVLNode<T> *right;
        int bF; //balance factor = left height - right height
};

template <class T>
class AVLTree {
    private:
        AVLNode<T> * root;

}
}
```

AVL Trees – RightRotation

```
AVLNode * RightRotate(AVLNode *y)
{
    AVLNode *x = y->left;
    AVLNode *T2 = x->right;

    x->right = y;
    y->left = T2;

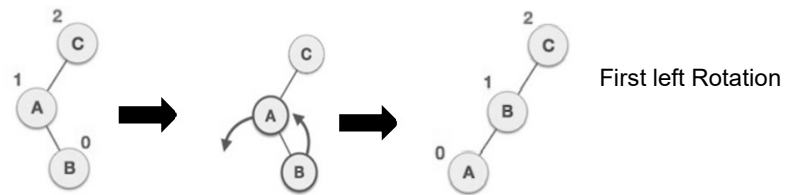
    // Update balance factor
    y->bF = max(bF(y->left) ,
               bF(y->right)) + 1;
    x->bF = max(bF(x->left) ,
               bF(x->right)) + 1;

    // Updated Node
    return x;
}
```

AVL Trees

■ Double Rotation (Left-Right Rotation)

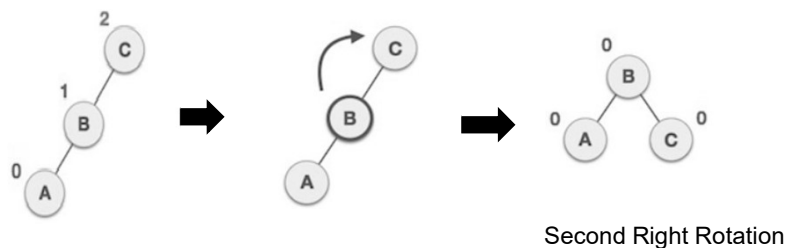
- A left-right rotation is a combination of left rotation followed by right rotation.
- The result of this double rotation is perfectly balance tree.



AVL Trees

■ Double Rotation (Left-Right Rotation)

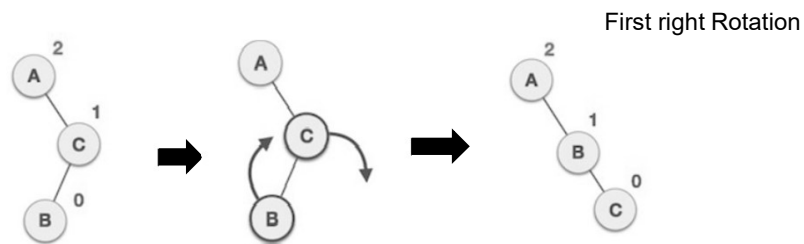
- A left-right rotation is a combination of left rotation followed by right rotation.
- The result of this double rotation is perfectly balance tree.



AVL Trees

■ Double Rotation (Right-Left Rotation)

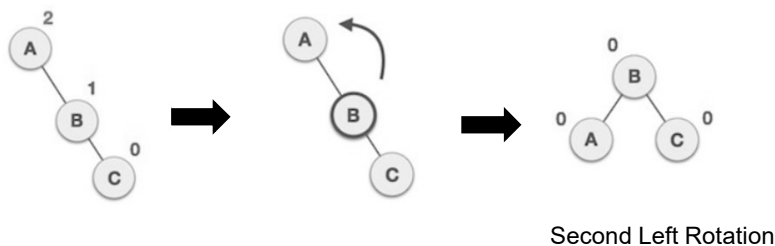
- A right-left rotation is a combination of right rotation followed by left rotation.
- The result of this double rotation is perfectly balance tree.



AVL Trees

■ Double Rotation (Right-left Rotation)

- A right-left rotation is a combination of right rotation followed by left rotation.
- The result of this double rotation is perfectly balance tree.



AVL Animation

<https://www.cs.usfca.edu/~galles/visualization/AVLtree.html>