view_frames Result
Recorded at time: 1363129991.630
/odom_combined
/bridge
Broadcaster: /robot_pose_ekf
Average rate: 5.604 Hz
Most recent transform: 1363129950.236 sec old
Buffer length: 4.818 sec
Broadcaster: /robot_state_publisher
Average rate: 50.206 Hz
Most recent transform: 1363129949.576 sec old
Buffer length: 4.860 sec
/base_footprint
/bridge_bottom
Broadcaster: /robot_state_publisher
Average rate: 50.206 Hz
Most recent transform: 1363129949.576 sec old
Buffer length: 4.860 sec
/base_link
Broadcaster: /robot_state_publisher
Average rate: 50.206 Hz
Most recent transform: 1363129949.576 sec old
Buffer length: 4.860 sec
Broadcaster: /robot_state_publisher
Average rate: 50.206 Hz
Most recent transform: 1363129949.576 sec old
Buffer length: 4.860 sec
Broadcaster: /robot_state_publisher
Average rate: 40.084 Hz
Most recent transform: 1363129950.117 sec old
Buffer length: 4.790 sec
Broadcaster: /robot_state_publisher
Average rate: 40.084 Hz
Most recent transform: 1363129950.117 sec old
Buffer length: 4.790 sec
Broadcaster: /robot_state_publisher
Average rate: 40.084 Hz
Most recent transform: 1363129950.117 sec old
Buffer length: 4.790 sec
Broadcaster: /robot_state_publisher
Average rate: 40.084 Hz
Most recent transform: 1363129950.117 sec old
Buffer length: 4.790 sec
Broadcaster: /robot_state_publisher
Average rate: 40.084 Hz
Most recent transform: 1363129950.117 sec old
Buffer length: 4.790 sec
Broadcaster: /robot_state_publisher
Average rate: 40.084 Hz
Most recent transform: 1363129950.117 sec old
Buffer length: 4.790 sec
/base_bellow_link
/base_laser_link
/torso_lift_link
/bl_caster_rotation_link
/br_caster_rotation_link
/fl_caster_rotation_link
/fr_caster_rotation_link
/torso_lift_motor_screw_link
Broadcaster: /robot_state_publisher
Average rate: 40.084 Hz
Most recent transform: 1363129950.117 sec old
Buffer length: 4.790 sec
Broadcaster: /robot_state_publisher
Average rate: 50.206 Hz
Most recent transform: 1363129949.576 sec old
Buffer length: 4.860 sec
Broadcaster: /robot_state_publisher
Average rate: 50.206 Hz
Most recent transform: 1363129949.576 sec old
Buffer length: 4.860 sec
Broadcaster: /robot_state_publisher
Average rate: 40.084 Hz
Most recent transform: 1363129950.117 sec old
Buffer length: 4.790 sec
Broadcaster: /robot_state_publisher
Average rate: 50.206 Hz
Most recent transform: 1363129949.576 sec old
Buffer length: 4.860 sec
Broadcaster: /robot_state_publisher
Average rate: 40.084 Hz
Most recent transform: 1363129950.117 sec old
Buffer length: 4.790 sec
Broadcaster: /robot_state_publisher
Average rate: 40.084 Hz
Most recent transform: 1363129950.117 sec old
Buffer length: 4.790 sec
Broadcaster: /robot_state_publisher
Average rate: 40.084 Hz
Most recent transform: 1363129950.117 sec old
Buffer length: 4.790 sec
Broadcaster: /robot_state_publisher
Average rate: 40.084 Hz
Most recent transform: 1363129950.117 sec old
Buffer length: 4.790 sec
Broadcaster: /robot_state_publisher
Average rate: 40.084 Hz
Most recent transform: 1363129950.117 sec old
Buffer length: 4.790 sec
Broadcaster: /robot_state_publisher
Average rate: 40.084 Hz
Most recent transform: 1363129950.117 sec old
Buffer length: 4.790 sec
Broadcaster: /robot_state_publisher
Average rate: 40.084 Hz
Most recent transform: 1363129950.117 sec old
Buffer length: 4.790 sec
Broadcaster: /robot_state_publisher
Average rate: 40.084 Hz
Most recent transform: 1363129950.117 sec old
Buffer length: 4.790 sec
Broadcaster: /robot_state_publisher
Average rate: 40.084 Hz
Most recent transform: 1363129950.117 sec old
Buffer length: 4.790 sec
Broadcaster: /robot_state_publisher
Average rate: 40.084 Hz
Most recent transform: 1363129950.117 sec old
Buffer length: 4.790 sec
/head_pan_link
/imu_link
/l_torso_lift_side_plate_link
/laser_tilt_mount_link
/r_torso_lift_side_plate_link
/l_shoulder_pan_link
/r_shoulder_pan_link
/bl_caster_l_wheel_link
/bl_caster_r_wheel_link
/br_caster_l_wheel_link
/br_caster_r_wheel_link
/fl_caster_l_wheel_link
/fl_caster_r_wheel_link
/fr_caster_l_wheel_link
/fr_caster_r_wheel_link
Broadcaster: /robot_state_publisher
Average rate: 40.084 Hz
Most recent transform: 1363129950.117 sec old
Buffer length: 4.790 sec
Broadcaster: /robot_state_publisher
Average rate: 50.206 Hz
Most recent transform: 1363129949.576 sec old
Buffer length: 4.860 sec
Broadcaster: /robot_state_publisher
Average rate: 40.084 Hz
Most recent transform: 1363129950.117 sec old
Buffer length: 4.790 sec
Broadcaster: /robot_state_publisher
Average rate: 40.084 Hz
Most recent transform: 1363129950.117 sec old
Buffer length: 4.790 sec
/head_tilt_link
/laser_tilt_link
/l_shoulder_lift_link
/r_shoulder_lift_link
Broadcaster: /robot_state_publisher
Average rate: 50.206 Hz
Most recent transform: 1363129949.576 sec old
Buffer length: 4.860 sec
Broadcaster: /robot_state_publisher
Average rate: 40.084 Hz
Most recent transform: 1363129950.117 sec old
Buffer length: 4.790 sec
Broadcaster: /robot_state_publisher
Average rate: 40.084 Hz
Most recent transform: 1363129950.117 sec old
Buffer length: 4.790 sec
/head_plate_frame
/l_upper_arm_roll_link
/r_upper_arm_roll_link
Broadcaster: /robot_state_publisher
Average rate: 50.206 Hz
Most recent transform: 1363129949.576 sec old
Buffer length: 4.860 sec
Broadcaster: /robot_state_publisher
Average rate: 50.206 Hz
Most recent transform: 1363129949.576 sec old
Buffer length: 4.860 sec
Broadcaster: /robot_state_publisher
Average rate: 50.206 Hz
Most recent transform: 1363129949.576 sec old
Buffer length: 4.860 sec
/sensor_mount_link
/l_upper_arm_link
/r_upper_arm_link
Broadcaster: /robot_state_publisher
Average rate: 50.206 Hz
Most recent transform: 1363129949.576 sec old
Buffer length: 4.860 sec
Broadcaster: /robot_state_publisher
Average rate: 50.206 Hz
Most recent transform: 1363129949.576 sec old
Buffer length: 4.860 sec
Broadcaster: /robot_state_publisher
Average rate: 40.084 Hz
Most recent transform: 1363129950.117 sec old
Buffer length: 4.790 sec
Broadcaster: /robot_state_publisher
Average rate: 40.084 Hz
Most recent transform: 1363129950.117 sec old
Buffer length: 4.790 sec
/double_stereo_link
/high_def_frame
/l_elbow_flex_link
/r_elbow_flex_link
Broadcaster: /robot_state_publisher
Average rate: 50.206 Hz
Most recent transform: 1363129949.576 sec old
Buffer length: 4.860 sec
Broadcaster: /robot_state_publisher
Average rate: 50.206 Hz
Most recent transform: 1363129949.576 sec old
Buffer length: 4.860 sec
Broadcaster: /robot_state_publisher
Average rate: 50.206 Hz
Most recent transform: 1363129949.576 sec old
Buffer length: 4.860 sec
Broadcaster: /robot_state_publisher
Average rate: 40.084 Hz
Most recent transform: 1363129950.117 sec old
Buffer length: 4.790 sec
Broadcaster: /robot_state_publisher
Average rate: 40.084 Hz
Most recent transform: 1363129950.117 sec old
Buffer length: 4.790 sec
/narrow_stereo_link
/wide_stereo_link
/high_def_optical_frame
/l_forearm_roll_link
/r_forearm_roll_link
Broadcaster: /robot_state_publisher
Average rate: 50.206 Hz
Most recent transform: 1363129949.576 sec old
Buffer length: 4.860 sec
Broadcaster: /robot_state_publisher
Average rate: 50.206 Hz
Most recent transform: 1363129949.576 sec old
Buffer length: 4.860 sec
Broadcaster: /robot_state_publisher
Average rate: 50.206 Hz
Most recent transform: 1363129949.576 sec old
Buffer length: 4.860 sec
Broadcaster: /robot_state_publisher
Average rate: 50.206 Hz
Most recent transform: 1363129949.576 sec old
Buffer length: 4.860 sec
Broadcaster: /robot_state_publisher
Average rate: 50.206 Hz
Most recent transform: 1363129949.576 sec old
Buffer length: 4.860 sec
Broadcaster: /robot_state_publisher
Average rate: 50.206 Hz
Most recent transform: 1363129949.576 sec old
Buffer length: 4.860 sec
Broadcaster: /robot_state_publisher
Average rate: 50.206 Hz
Most recent transform: 1363129949.576 sec old
Buffer length: 4.860 sec
Broadcaster: /robot_state_publisher
Average rate: 50.206 Hz
Most recent transform: 1363129949.576 sec old
Buffer length: 4.860 sec
/narrow_stereo_gazebo_l_stereo_camera_frame
/narrow_stereo_optical_frame
/wide_stereo_gazebo_l_stereo_camera_frame
/wide_stereo_optical_frame
/l_forearm_cam_frame
/l_forearm_link
/r_forearm_cam_frame
/r_forearm_link
Broadcaster: /robot_state_publisher
Average rate: 50.206 Hz
Most recent transform: 1363129949.576 sec old
Buffer length: 4.860 sec
Broadcaster: /robot_state_publisher
Average rate: 50.206 Hz
Most recent transform: 1363129949.576 sec old
Buffer length: 4.860 sec
Broadcaster: /robot_state_publisher
Average rate: 50.206 Hz
Most recent transform: 1363129949.576 sec old
Buffer length: 4.860 sec
Broadcaster: /robot_state_publisher
Average rate: 50.206 Hz
Most recent transform: 1363129949.576 sec old
Buffer length: 4.860 sec
Broadcaster: /robot_state_publisher
Average rate: 50.206 Hz
Most recent transform: 1363129949.576 sec old
Buffer length: 4.860 sec
Broadcaster: /robot_state_publisher
Average rate: 40.084 Hz
Most recent transform: 1363129950.117 sec old
Buffer length: 4.790 sec
Broadcaster: /robot_state_publisher
Average rate: 50.206 Hz
Most recent transform: 1363129949.576 sec old
Buffer length: 4.860 sec
Broadcaster: /robot_state_publisher
Average rate: 40.084 Hz
Most recent transform: 1363129950.117 sec old
Buffer length: 4.790 sec
/narrow_stereo_gazebo_l_stereo_camera_optical_frame
/narrow_stereo_gazebo_r_stereo_camera_frame
/wide_stereo_gazebo_l_stereo_camera_optical_frame
/wide_stereo_gazebo_r_stereo_camera_frame
/l_forearm_cam_optical_frame
/l_wrist_flex_link
/r_forearm_cam_optical_frame
/r_wrist_flex_link
Broadcaster: /robot_state_publisher
Average rate: 50.206 Hz
Most recent transform: 1363129949.576 sec old
Buffer length: 4.860 sec
Broadcaster: /robot_state_publisher
Average rate: 50.206 Hz
Most recent transform: 1363129949.576 sec old
Buffer length: 4.860 sec
Broadcaster: /robot_state_publisher
Average rate: 40.084 Hz
Most recent transform: 1363129950.117 sec old
Buffer length: 4.790 sec
Broadcaster: /robot_state_publisher
Average rate: 40.084 Hz
Most recent transform: 1363129950.117 sec old
Buffer length: 4.790 sec
/narrow_stereo_gazebo_r_stereo_camera_optical_frame
/wide_stereo_gazebo_r_stereo_camera_optical_frame
/l_wrist_roll_link
/r_wrist_roll_link
Broadcaster: /robot_state_publisher
Average rate: 50.206 Hz
Most recent transform: 1363129949.576 sec old
Buffer length: 4.860 sec
Broadcaster: /robot_state_publisher
Average rate: 50.206 Hz
Most recent transform: 1363129949.576 sec old
Buffer length: 4.860 sec
/l_gripper_palm_link
/r_gripper_palm_link
Broadcaster: /robot_state_publisher
Average rate: 50.206 Hz
Most recent transform: 1363129949.576 sec old
Buffer length: 4.860 sec
Broadcaster: /robot_state_publisher
Average rate: 50.206 Hz
Most recent transform: 1363129949.576 sec old
Buffer length: 4.860 sec
Broadcaster: /robot_state_publisher
Average rate: 50.206 Hz
Most recent transform: 1363129949.576 sec old
Buffer length: 4.860 sec
Broadcaster: /robot_state_publisher
Average rate: 40.084 Hz
Most recent transform: 1363129950.117 sec old
Buffer length: 4.790 sec
Broadcaster: /robot_state_publisher
Average rate: 40.084 Hz
Most recent transform: 1363129950.117 sec old
Buffer length: 4.790 sec
Broadcaster: /robot_state_publisher
Average rate: 40.084 Hz
Most recent transform: 1363129950.117 sec old
Buffer length: 4.790 sec
Broadcaster: /robot_state_publisher
Average rate: 50.206 Hz
Most recent transform: 1363129949.576 sec old
Buffer length: 4.860 sec
Broadcaster: /robot_state_publisher
Average rate: 50.206 Hz
Most recent transform: 1363129949.576 sec old
Buffer length: 4.860 sec
Broadcaster: /robot_state_publisher
Average rate: 50.206 Hz
Most recent transform: 1363129949.576 sec old
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Broadcaster: /robot_state_publisher
Average rate: 50.206 Hz
Most recent transform: 1363129949.576 sec old
Buffer length: 4.860 sec
Broadcaster: /robot_state_publisher
Average rate: 40.084 Hz
Most recent transform: 1363129950.117 sec old
Buffer length: 4.790 sec
Broadcaster: /robot_state_publisher
Average rate: 40.084 Hz
Most recent transform: 1363129950.117 sec old
Buffer length: 4.790 sec
Broadcaster: /robot_state_publisher
Average rate: 40.084 Hz
Most recent transform: 1363129950.117 sec old
Buffer length: 4.790 sec
/l_gripper_led_frame
/l_gripper_motor_accelerometer_link
/l_gripper_tool_frame
/l_gripper_r_finger_link
/l_gripper_l_finger_link
/l_gripper_motor_slider_link
/lever_stick
/r_gripper_led_frame
/r_gripper_motor_accelerometer_link
/r_gripper_tool_frame
/r_gripper_r_finger_link
/r_gripper_l_finger_link
/r_gripper_motor_slider_link
Broadcaster: /robot_state_publisher
Average rate: 40.084 Hz
Most recent transform: 1363129950.117 sec old
Buffer length: 4.790 sec
Broadcaster: /robot_state_publisher
Average rate: 40.084 Hz
Most recent transform: 1363129950.117 sec old
Buffer length: 4.790 sec
Broadcaster: /robot_state_publisher
Average rate: 40.084 Hz
Most recent transform: 1363129950.117 sec old
Buffer length: 4.790 sec
Broadcaster: /robot_state_publisher
Average rate: 40.084 Hz
Most recent transform: 1363129950.117 sec old
Buffer length: 4.790 sec
Broadcaster: /robot_state_publisher
Average rate: 40.084 Hz
Most recent transform: 1363129950.117 sec old
Buffer length: 4.790 sec
Broadcaster: /robot_state_publisher
Average rate: 40.084 Hz
Most recent transform: 1363129950.117 sec old
Buffer length: 4.790 sec
/l_gripper_r_finger_tip_link
/l_gripper_l_finger_tip_link
/l_gripper_motor_screw_link
/r_gripper_r_finger_tip_link
/r_gripper_l_finger_tip_link
/r_gripper_motor_screw_link
Broadcaster: /robot_state_publisher
Average rate: 40.084 Hz
Most recent transform: 1363129950.117 sec old
Buffer length: 4.790 sec
Broadcaster: /robot_state_publisher
Average rate: 40.084 Hz
Most recent transform: 1363129950.117 sec old
Buffer length: 4.790 sec
/l_gripper_l_finger_tip_frame
/r_gripper_l_finger_tip_frame