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1 Introduction and functional overview

The FrTSyn module handles the distribution of time information over FlexRay buses.

The FlexRay mechanism is much simpler than the mechanism for CAN since it is based on the fact, that FlexRay nodes are synchronized to each other, otherwise no messages can be transmitted on FlexRay.

Both, Time Master and Time Slaves have the same view on the FlexRay global time. It is therefore just necessary to define the same point in (FlexRay) time and to transmit the time information, which will be valid at that point in (FlexRay) time.

Although this same point in (FlexRay) time could be in theory any FlexRay macrotick within a FlexRay cycle, the start of a FlexRay cycle simplifies this mechanism. In addition, the mechanism does not just use any cycle start but uses the cycle start of the subsequent cycle with cycle counter value 0, i.e. the Time Master transmits time information located in the future.

On FlexRay only one Time Synchronization message is needed.
The Time Master uses its current FlexRay time, i.e. macrotick counter and cycle counter, and the current time, which shall be distributed and calculates the resulting time at the start of the next cycle 0. Once this resulting time has been calculated, it is neither very time critical, when exactly the FlexRay frame is transmitted, nor when it is received and processed.

Every Time Slave receiving the transmitted time information will use it in combination with the current FlexRay macrotick counter and cycle counter to determine the actual master time and set its slave time.

The following Figure shows the Time Synchronization mechanism on FlexRay.

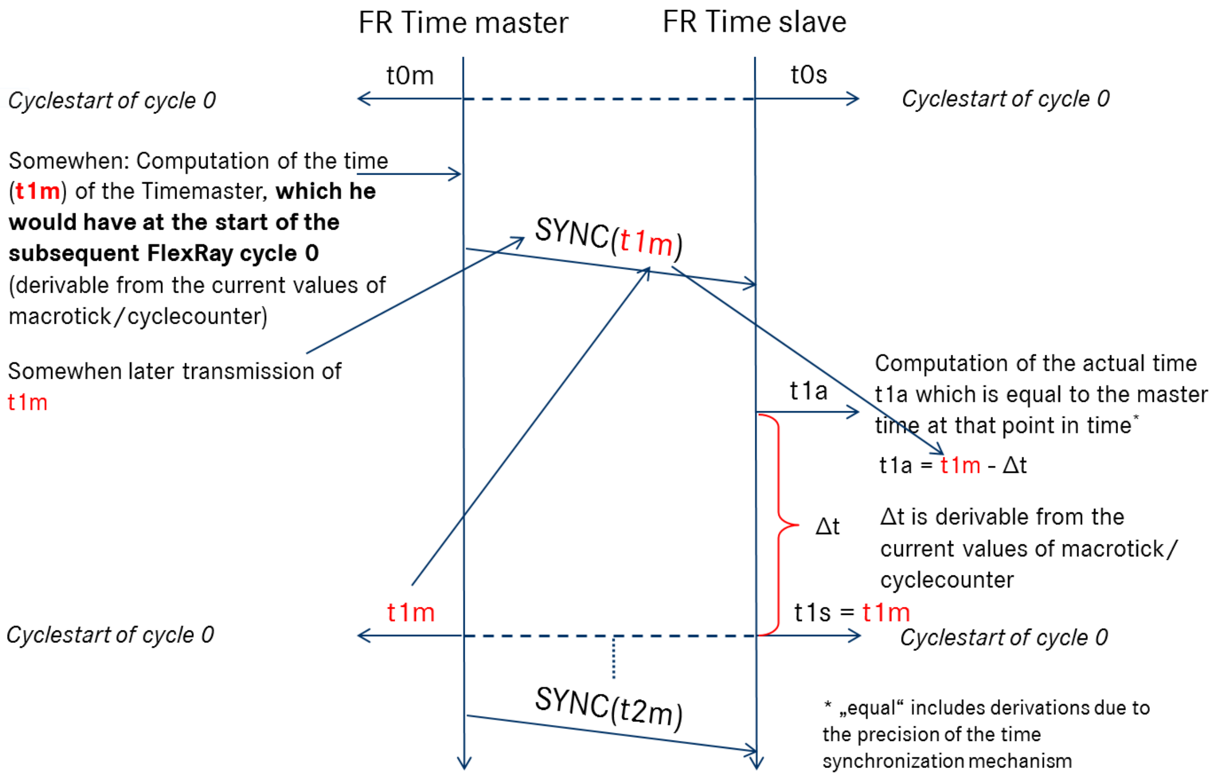

FR Time master
FR Time slave
t0m
t0s
Cyclestart of cycle 0
Cyclestart of cycle 0
Somewhen: Computation of the time (t1m) of the Timemaster, which he would have at the start of the subsequent FlexRay cycle 0 (derivable from the current values of macrotick/cyclecounter)
SYNC(t1m)
Somewhen later transmission of t1m
Computation of the actual time t1a which is equal to the master time at that point in time*
t1a
t1a = t1m - Δt
Δt
Δt is derivable from the current values of macrotick/ cyclecounter
t1m
t1s = t1m
Cyclestart of cycle 0
Cyclestart of cycle 0
SYNC(t2m)
* „equal" includes derivations due to the precision of the time synchronization mechanism

Figure 1: FlexRay Time Synchronization mechanism

2 Acronyms, Abbreviations, and Definitions

This section lists module local Abbreviations and Definitions. For a complete set of Synchronized Time Base related Abbreviations and Definitions refer to the corresponding chapter in [4].

Abbreviation / Acronym:	Description
(G)TD	(Global) Time Domain
(G)TM	(Global) Time Master
<Bus>TSyn	A bus specific Time Synchronization module
CRC	Cyclic Redundancy Checksum
Debounce Time	Minimum gap between two Tx messages with the same PDU
DEM	Diagnostic Event Manager
DET	Default Error Tracer
FR	FlexRay
FUP message	Follow-Up message
OFNS message	Offset adjustment message
OFS message	Offset Synchronization message
StbM	Synchronized Time-Base Manager
SYNC message	Time Synchronization message
TG	Time Gateway
Timesync	Time Synchronization
TS	Time Slave
TSD	Time Sub-domain

3 Related documentation

3.1 Input documents

[1] Requirements on Synchronized Time-Base Manager
AUTOSAR_SRS_SynchronizedTimeBaseManager.pdf

[2] Layered Software Architecture
AUTOSAR_EXP_LayeredSoftwareArchitecture.pdf

[3] General Specification of Basic Software Modules
AUTOSAR_SWS_BSWGeneral.pdf

[4] Specification of Synchronized Time-Base Manager
AUTOSAR_SWS_SynchronizedTimeBaseManager.pdf

[5] Specification of CRC Routines
AUTOSAR_SWS_CRCLibrary.pdf

[6] Specification of FlexRay Interface
AUTOSAR_SWS_FlexRayInterface.pdf

[7] Specification of Default Error Tracer
AUTOSAR_SWS_DefaultErrorTracer.pdf

[8] Specification of Basic Software Mode Manager
AUTOSAR_SWS_BSWModeManager.pdf

3.2 Related specification

AUTOSAR provides a General Specification on Basic Software (SWS BSW General [3]) which is also valid for FrTSyn.

Thus, the General Specification on Basic Software (SWS BSW General) shall be considered additionally and as required specification for FrTSyn.

4 Constraints and assumptions

4.1 Limitations

Time Masters, Time Gateways and Time Slaves shall work with a Time Base reference clock with a worst-case accuracy of 10µs.

The Time Base in the OFS messages is limited to 32 bit, wherefore the maximum supported time value is 4294967295 seconds (2^{32}-1).

4.2 Applicability to car domains

Systems requiring a common Time Base to ECUs independent to which bus system the ECU is connected.

5 Dependencies to other modules

The Time Synchronization over FlexRay (FrTSyn) has interfaces towards the Synchronized Time-Base Manager (StbM), the FlexRay Interface (FrIf) and the Default Error Tracer (DET).

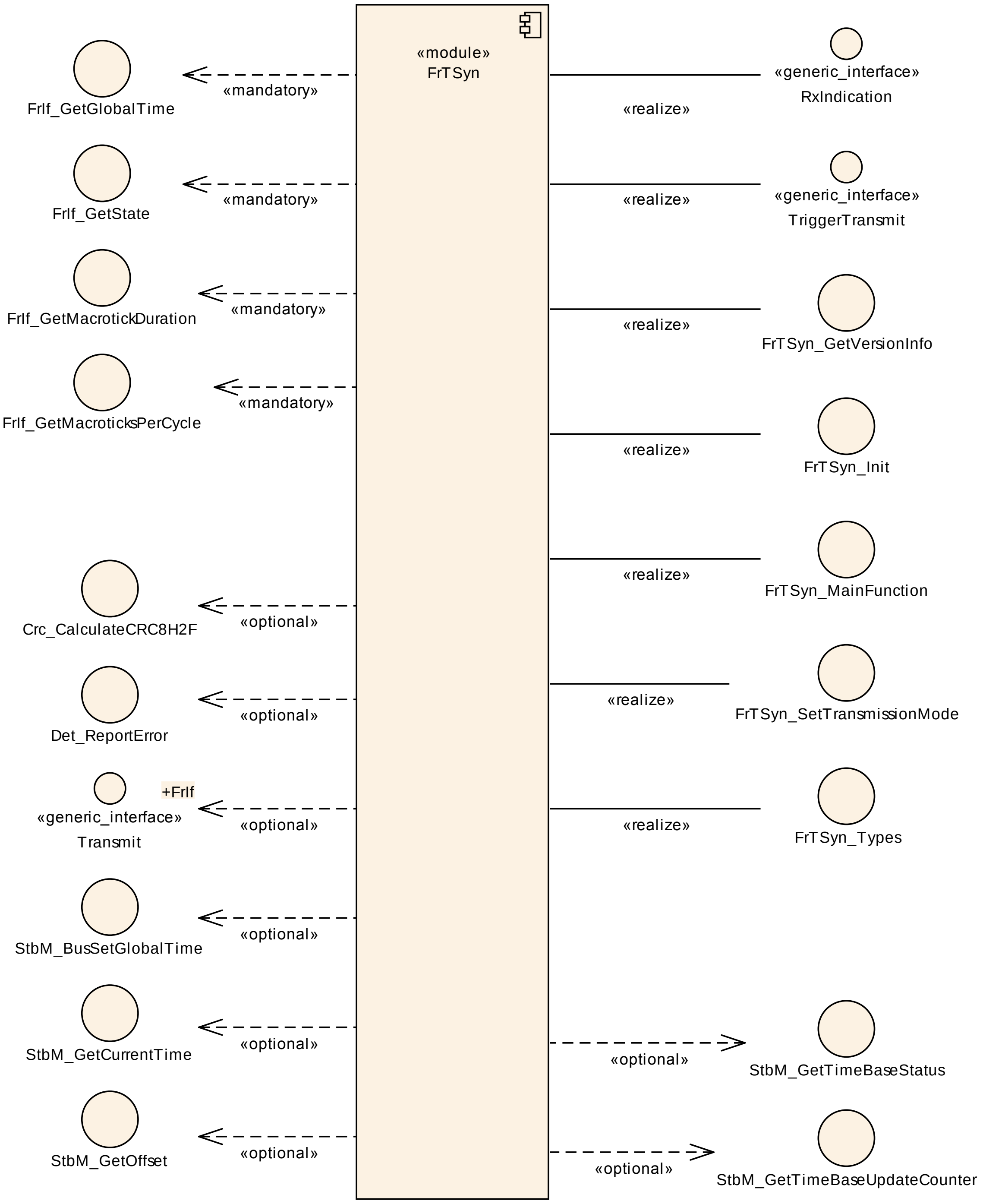


Figure 2: Module dependencies of the FrTSyn module

- StbM – Get and set the current time value

- FrIf – Receiving and transmitting messages
- BswM – Coordination of network access (via `FrTSyn_SetTransmissionMode()`)
- DET – Reporting of development errors

5.1 File structure

5.1.1 Code file structure

For details, refer to the section 5.1.6 "Code file structure" of the SWS BSW General [3].

5.1.2 Header file structure

Besides the files defined in section 5.1.7 “Header file structure” of the SWS BSW General [3], the Time Synchronization over FlexRay needs to include the files defined below.

[SWS_FrTSyn_00002]⌈
The implementation header files shall include *`ComStack_Types.h`*.
⌋(SRS_BSW_00301, SRS_BSW_00456)

The following picture shows the include hierarchy of the Time Synchronization over FlexRay.

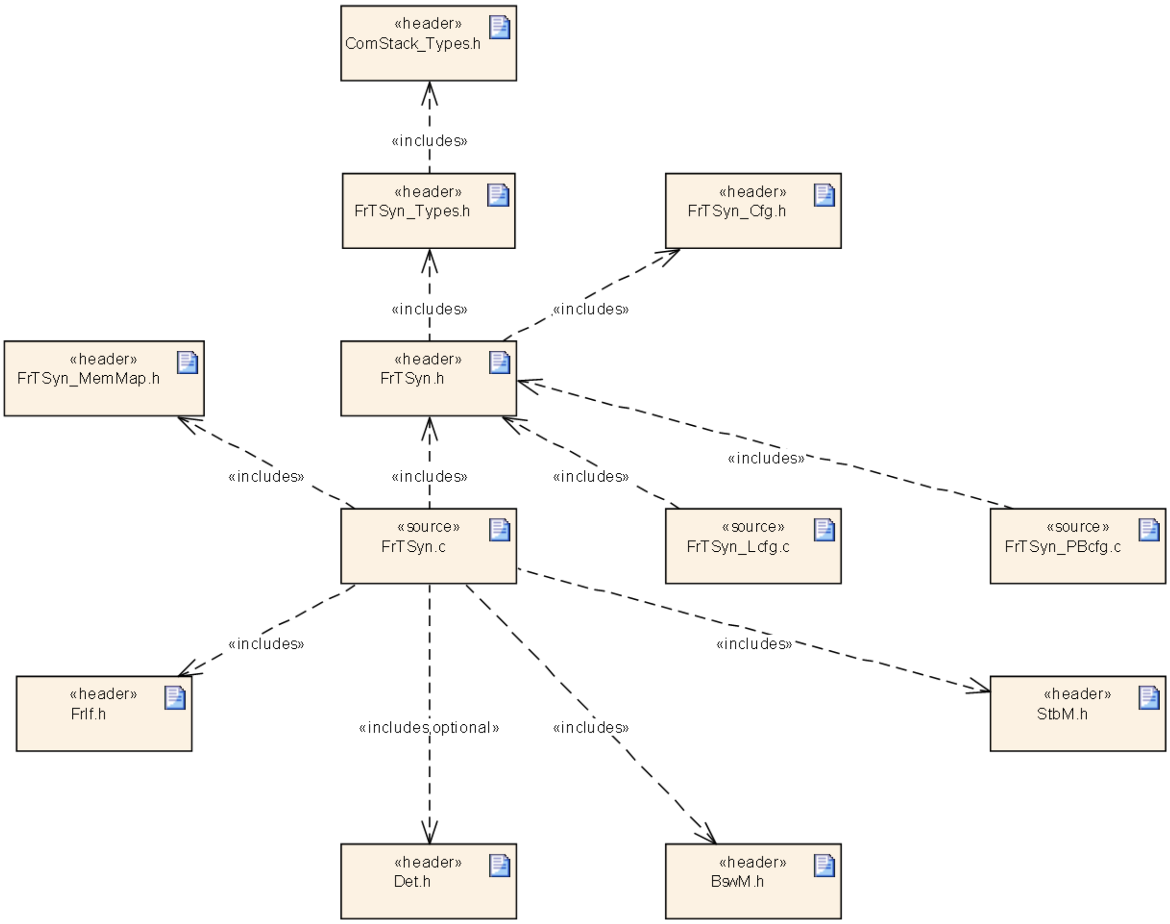


Figure 3: File structure of FrTSyn

6 Requirements traceability

Requirement	Description	Satisfied by
SRS_BSW_00301	All AUTOSAR Basic Software Modules shall only import the necessary information	SWS_FrTSyn_00002
SRS_BSW_00323	All AUTOSAR Basic Software Modules shall check passed API parameters for validity	SWS_FrTSyn_00058, SWS_FrTSyn_00067, SWS_FrTSyn_00070, SWS_FrTSyn_00095
SRS_BSW_00337	Classification of development errors	SWS_FrTSyn_00004, SWS_FrTSyn_00067, SWS_FrTSyn_00070, SWS_FrTSyn_00095
SRS_BSW_00385	List possible error notifications	SWS_FrTSyn_00059
SRS_BSW_00456	- A Header file shall be defined in order to harmonize BSW Modules	SWS_FrTSyn_00002
SRS_StbM_20018	The StbM shall initialize the Local Time Base with 0 at startup if configured as Time Slave	SWS_FrTSyn_00003, SWS_FrTSyn_00005
SRS_StbM_20019	The StbM shall initialize the Global Time Base with a configurable startup value if configured as Time Master	SWS_FrTSyn_00003, SWS_FrTSyn_00005
SRS_StbM_20039	The FlexRay Timesync module shall trigger Time Base Synchronization transmission	SWS_FrTSyn_00019, SWS_FrTSyn_00023, SWS_FrTSyn_00026, SWS_FrTSyn_00027, SWS_FrTSyn_00084, SWS_FrTSyn_00085, SWS_FrTSyn_00086, SWS_FrTSyn_00087, SWS_FrTSyn_00088, SWS_FrTSyn_00089, SWS_FrTSyn_00090, SWS_FrTSyn_00091, SWS_FrTSyn_00093
SRS_StbM_20040	The FlexRay Timesync module shall provide a Time Base after reception of a valid protocol information	SWS_FrTSyn_00041, SWS_FrTSyn_00045, SWS_FrTSyn_00078, SWS_FrTSyn_00094
SRS_StbM_20041	The FlexRay Timesync module shall support means to protect the Time Synchronization protocol	SWS_FrTSyn_00006, SWS_FrTSyn_00014, SWS_FrTSyn_00015, SWS_FrTSyn_00021, SWS_FrTSyn_00025, SWS_FrTSyn_00030, SWS_FrTSyn_00031, SWS_FrTSyn_00035, SWS_FrTSyn_00036, SWS_FrTSyn_00078, SWS_FrTSyn_00079, SWS_FrTSyn_00080
SRS_StbM_20042	The FlexRay Timesync Module shall detect and handle timeout and integrity errors in the Time Synchronization protocol	SWS_FrTSyn_00015, SWS_FrTSyn_00038, SWS_FrTSyn_00041, SWS_FrTSyn_00042, SWS_FrTSyn_00045, SWS_FrTSyn_00048, SWS_FrTSyn_00049, SWS_FrTSyn_00050, SWS_FrTSyn_00054, SWS_FrTSyn_00055, SWS_FrTSyn_00057, SWS_FrTSyn_00058, SWS_FrTSyn_00080, SWS_FrTSyn_00081,

		SWS_FrTSyn_00082, SWS_FrTSyn_00094
SRS_StbM_20043	The FlexRay Timesync module shall support a protocol for precise time measurement and synchronization over FlexRay	SWS_FrTSyn_00007, SWS_FrTSyn_00009, SWS_FrTSyn_00010, SWS_FrTSyn_00014, SWS_FrTSyn_00015, SWS_FrTSyn_00018, SWS_FrTSyn_00019, SWS_FrTSyn_00020, SWS_FrTSyn_00021, SWS_FrTSyn_00026, SWS_FrTSyn_00027, SWS_FrTSyn_00028, SWS_FrTSyn_00030, SWS_FrTSyn_00031, SWS_FrTSyn_00035, SWS_FrTSyn_00036, SWS_FrTSyn_00037, SWS_FrTSyn_00038, SWS_FrTSyn_00039, SWS_FrTSyn_00040, SWS_FrTSyn_00041, SWS_FrTSyn_00046, SWS_FrTSyn_00048, SWS_FrTSyn_00049, SWS_FrTSyn_00050, SWS_FrTSyn_00054, SWS_FrTSyn_00055, SWS_FrTSyn_00056, SWS_FrTSyn_00057, SWS_FrTSyn_00060, SWS_FrTSyn_00061, SWS_FrTSyn_00062, SWS_FrTSyn_00063, SWS_FrTSyn_00064, SWS_FrTSyn_00065, SWS_FrTSyn_00066, SWS_FrTSyn_00069, SWS_FrTSyn_00071, SWS_FrTSyn_00072, SWS_FrTSyn_00074, SWS_FrTSyn_00075, SWS_FrTSyn_00081
SRS_StbM_20044	The FlexRay Timesync module shall use the time measurement and synchronization protocol to transmit and receive an offset value	SWS_FrTSyn_00007, SWS_FrTSyn_00009, SWS_FrTSyn_00010, SWS_FrTSyn_00020, SWS_FrTSyn_00022, SWS_FrTSyn_00023, SWS_FrTSyn_00025, SWS_FrTSyn_00026, SWS_FrTSyn_00027, SWS_FrTSyn_00029, SWS_FrTSyn_00030, SWS_FrTSyn_00031, SWS_FrTSyn_00035, SWS_FrTSyn_00036, SWS_FrTSyn_00037, SWS_FrTSyn_00042, SWS_FrTSyn_00043, SWS_FrTSyn_00044, SWS_FrTSyn_00045, SWS_FrTSyn_00047, SWS_FrTSyn_00048, SWS_FrTSyn_00049, SWS_FrTSyn_00050, SWS_FrTSyn_00054, SWS_FrTSyn_00055, SWS_FrTSyn_00056, SWS_FrTSyn_00057, SWS_FrTSyn_00079, SWS_FrTSyn_00080, SWS_FrTSyn_00082
SRS_StbM_20045	The FlexRay Timesync module shall support user specific data within the time measurement and synchronization protocol	SWS_FrTSyn_00010, SWS_FrTSyn_00011, SWS_FrTSyn_00012, SWS_FrTSyn_00013
SRS_StbM_20046	The FlexRay Timesync configuration shall allow the FrTSyn to support different roles for a Time Base	SWS_FrTSyn_00077
SRS_StbM_20057	The StbM shall provide measurement data to the application	SWS_FrTSyn_00092

7 Functional specification

This chapter defines the behavior of the Time Synchronization over FlexRay. The API of the module is defined in chapter 8, while the configuration is defined in chapter 10.

7.1 Overview

The Time Synchronization over FlexRay is responsible to ensure the collection and distribution of Synchronized Time information across the FlexRay network. It interacts with the StbM and provides all FlexRay specific functions to the StbM. Time Synchronization principles and common wording is described in [4].

7.2 Module Handling

This section contains description of auxiliary functionality of the Time Synchronization over FlexRay.

7.2.1 Initialization

The Time Synchronization over FlexRay is initialized via `FrTSyn_Init()`. Except for `FrTSyn_GetVersionInfo()` and `FrTSyn_Init()`, the API functions of the Time Synchronization over FlexRay may only be called when the module has been properly initialized.

[SWS_FrTSyn_00003]⌈
A call to `FrTSyn_Init()` initializes all internal variables and sets the Time Synchronization over FlexRay to the initialized state.
⌋(SRS_StbM_20018, SRS_StbM_20019)

[SWS_FrTSyn_00004]⌈
When DET reporting is enabled (see `FrTSynDevErrorDetect`), the Time Synchronization over FlexRay shall call `Det_ReportError()` with the error code `FRTSYN_E_NOT_INITIALIZED` when any API other than `FrTSyn_GetVersionInfo()` or `FrTSyn_Init()` is called in uninitialized state.
⌋(SRS_BSW_00337)

[SWS_FrTSyn_00005]⌈
When `FrTSyn_Init()` is called in initialized state, the Time Synchronization over FlexRay shall re-initialize its internal variables.
⌋(SRS_StbM_20018, SRS_StbM_20019)

[SWS_FrTSyn_00006]⌈
The Sequence Counter (*SC*) shall be initialized with 0.
⌋(SRS_StbM_20041)

7.2.2 FlexRay Interface

[SWS_FrTSyn_00078]⌈
The FrTSyn module shall call `FrIf_GetGlobalTime()` only if `FrIf_GetState()` returns `FRIF_STATE_ONLINE`. This is to ensure that `FrIf_GetGlobalTime` returns valid time information, i.e. that the FlexRay communication controller is synchronous to the FlexRay global time.
⌋(SRS_StbM_20040, SRS_StbM_20041)

7.3 Message Format

SYNC and OFS messages are assigned to a dedicated SLOT ID of the Static Segment.

SYNC and OFS messages may share the same FR PDU by using a multiplexed signal group. The multiplexer is located in Byte 0, named "*Type*".

For different Time Domains the same FR PDU may be used if Time Synchronization messages are sent by the same Time Master or Time Gateway.

For different Time Domains different FR PDUs shall be used if Time Synchronization messages are sent by different Time Masters or Time Gateways.

The usage of *CRC* is optional. To ensure a great variability between several time observing units, the configuration decides of how to handle *CRC* secured time synchronization messages if the receiver does not support the *CRC* calculation. Hence it might be possible, that a receiver is just using the given Time Base value, without evaluating the *CRC*.

[SWS_FrTSyn_00007]⌈
The byte order for time values inside Time Synchronization messages is "Big Endian".
⌋(SRS_StbM_20043, SRS_StbM_20044)

[SWS_FrTSyn_00009]⌈
The PayloadLength is 16.
⌋(SRS_StbM_20043, SRS_StbM_20044)

[SWS_FrTSyn_00010]⌈
Time Synchronization messages contain User Data according to the given message format.
⌋(SRS_StbM_20043, SRS_StbM_20044, SRS_StbM_20045)

[SWS_FrTSyn_00011]⌈
User Data shall be read consistently from the incoming Time Synchronization messages.
⌋(SRS_StbM_20045)

[SWS_FrTSyn_00012]⌈

User Data shall be written consistently to outgoing Time Synchronization messages.
⌋(SRS_StbM_20045)

[SWS_FrTSyn_00013]⌈
User Data shall be mapped to the `StbM_UserDataType`, whereas the byte number given in the message and by the `StbM_UserDataType` shall match (User Byte 0 mapped to `StbM_UserDataType.userByte0` etc.). Afterwards `StbM_UserDataType.userDataLength` shall be set accordingly.
⌋(SRS_StbM_20045)

7.3.1 SYNC message

[SWS_FrTSyn_00014]⌈
SYNC not CRC secured message format:

Byte 0:	*Type* = 0x10
Byte 1:	User Byte 2, default: 0
Byte 2:	*D* = Time Domain 0 to 15 (Bit 7 to Bit 4)
	SC = Sequence Counter (Bit 3 to Bit 0)
Byte 3:	*FCNT* = FlexRay Cycle Counter from 0 to 63 (Bit 7 to Bit 2)
	SGW (Bit 1)
	SyncToGTM = 0
	SyncToSubDomain = 1
	reserved (Bit 0), default: 0
Byte 4:	User Byte 0, default: 0
Byte 5:	User Byte 1, default: 0
Byte 6-11:	*SyncTimeSec* = 48 Bit time value in seconds
Byte 12-15:	*SyncTimeNSec* = 32 Bit time value in nanoseconds

⌋(SRS_StbM_20041, SRS_StbM_20043)

[SWS_FrTSyn_00015]⌈
SYNC CRC secured message format:

Byte 0:	Type = 0x20
Byte 1:	*CRC*
Byte 2:	*D* = Time Domain 0 to 15 (Bit 7 to Bit 4)
	SC = Sequence Counter (Bit 3 to Bit 0)
Byte 3:	*FCNT* = FlexRay Cycle Counter from 0 to 63 (Bit 7 to Bit 2)
	SGW (Bit 1)
	SyncToGTM = 0
	SyncToSubDomain = 1
	reserved (Bit 0), default: 0
Byte 4:	User Byte 0, default: 0
Byte 5:	User Byte 1, default: 0
Byte 6-11:	*SyncTimeSec* = 48 Bit time value in seconds
Byte 12-15:	*SyncTimeNSec* = 32 Bit time value in nanoseconds

⌋(SRS_StbM_20041, SRS_StbM_20042, SRS_StbM_20043)

7.3.2 OFS message

Offset messages can be multiplexed with SYNC messages (using the same PDU, etc.).

[SWS_FrTSyn_00079]⌈
OFS not CRC secured message format:
Byte 0: *Type* = 0x34
Byte 1: User Byte 2, default: 0
Byte 2: *D* = Time Domain 16 to 31 (Bit 7 to Bit 4)
SC = Sequence Counter (Bit 3 to Bit 0)
Byte 3: reserved (Bit 7 to Bit 2), default: 0
SGW (Bit 1)
SyncToGTM = 0
SyncToSubDomain = 1
reserved (Bit 0), default: 0
Byte 4: User Byte 0, default: 0
Byte 5: User Byte 1, default: 0
Byte 6: reserved, default: 0
Byte 7: reserved, default: 0
Byte 8-11: *OfsTimeSec* = 32 Bit offset time value in seconds
Byte 12-15: *OfsTimeNSec* = 32 Bit offset time value in nanoseconds
⌋(SRS_StbM_20041, SRS_StbM_20044)

[SWS_FrTSyn_00080]⌈
OFS CRC secured message format:
Byte 0: Type = 0x44
Byte 1: *CRC*
Byte 2: *D* = Time Domain 16 to 31 (Bit 7 to Bit 4)
SC = Sequence Counter (Bit 3 to Bit 0)
Byte 3: reserved (Bit 7 to Bit 2), default: 0
SGW (Bit 1)
SyncToGTM = 0
SyncToSubDomain = 1
reserved (Bit 0), default: 0
Byte 4: User Byte 0, default: 0
Byte 5: User Byte 1, default: 0
Byte 6: reserved, default: 0
Byte 7: reserved, default: 0
Byte 8-11: *OfsTimeSec* = 32 Bit offset time value in seconds
Byte 12-15: *OfsTimeNSec* = 32 Bit offset time value in nanoseconds
⌋(SRS_StbM_20041, SRS_StbM_20042, SRS_StbM_20044)

7.4 Acting as Time Master

A Time Master is an entity which is the master for a certain Time Base and which propagates this Time Base to a set of Time Slaves within a certain segment of a communication network, being a source for this Time Base.

If a Time Master is also the owner of the Global Time Base, the Time Base from which all further Time Bases are derived from, then it is the Global Time Master. A Time Gateway typically consists of one Time Master port which is connected to one or more Time Slaves. When mapping time entities to real ECUs it has to be noted, that an ECU could be Time Master (or even Global Time Master) for one Time Base and Time Slave for another Time Base.

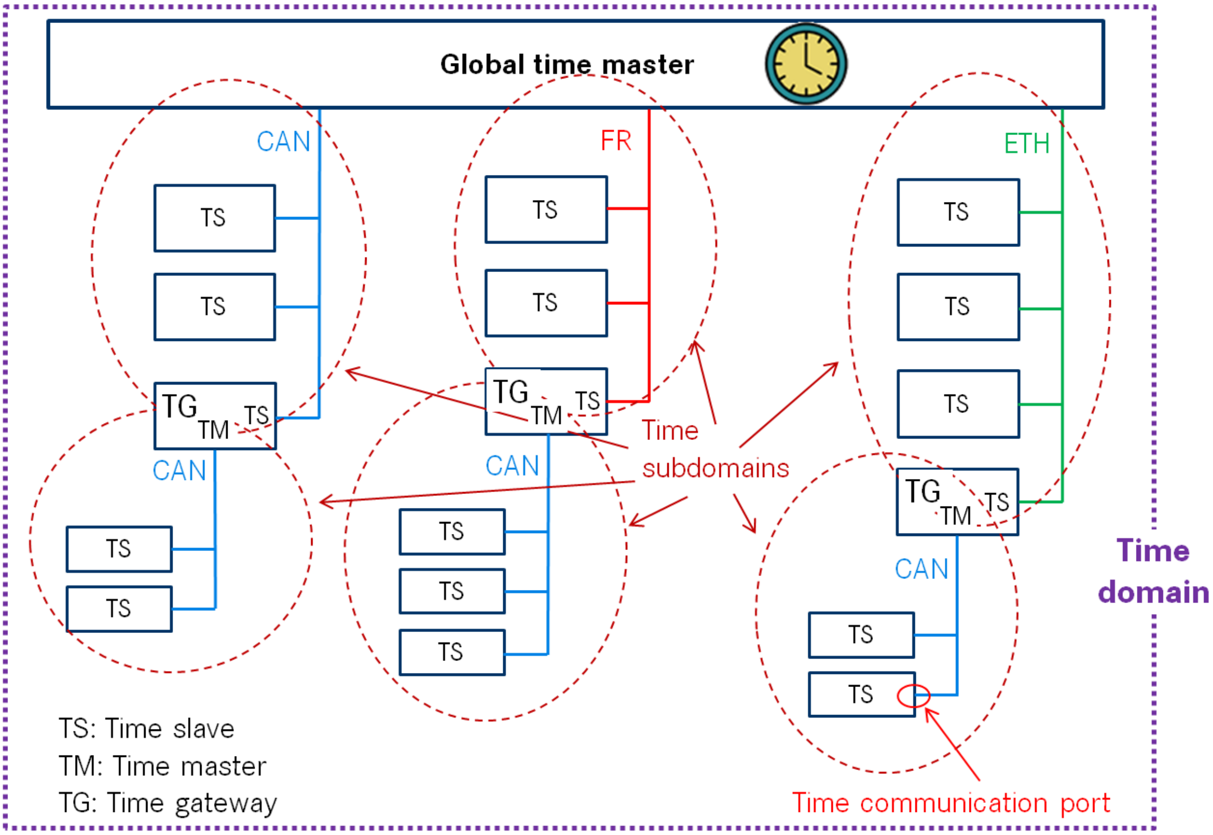


Figure 4: Terminology Example

7.4.1 SYNC message processing

[SWS_FrTSyn_00018]⌈
A Time Synchronization message sequence consists of a SYNC message per Time Domain.
⌋(SRS_StbM_20043)

[SWS_FrTSyn_00019]⌈
For each configured Time Master (`FrTSynGlobalTimeMaster`) the FrTSyn module shall periodically transmit SYNC messages with the cycle `FrTSynGlobalTimeTxPeriod` (**ECUC_FrTSyn_00014 :**) including the time value, which will be valid at the start of the next FlexRay cycle 0 (see Figure 5: Master FR SYNC) and User Data, if the `GLOBAL_TIME_BASE` bit within the `timeBaseStatus`

is set and FrTSynGlobalTimeTxPeriod is unequal to 0 and if the associated cyclicMsgResumeCounter is not running (see 7.4.5).
⌋(SRS_StbM_20039, SRS_StbM_20043)

[SWS_FrTSyn_00021]⌈
Depending on FrTSynGlobalTimeTxCrcSecured (**ECUC_FrTSyn_00013 :**) the SYNC message shall be of type:

FrTSynGlobalTimeTxCrcSecured	SYNC
CRC_NOT_SUPPORTED	0x10 SYNC not CRC secured message
CRC_SUPPORTED	0x20 SYNC CRC secured message

⌋(SRS_StbM_20041, SRS_StbM_20043)

7.4.2 OFS message processing

[SWS_FrTSyn_00022]⌈
An offset message sequence consists of an OFS message per Time Domain.
⌋(SRS_StbM_20044)

[SWS_FrTSyn_00023]⌈
For each configured Time Master (FrTSynGlobalTimeMaster) the FrTSyn module shall periodically transmit OFS messages with the cycle FrTSynGlobalTimeTxPeriod (**ECUC_FrTSyn_00014 :**) including the Offset Time value and User Data, if the GLOBAL_TIME_BASE bit within the timeBaseStatus is set and FrTSynGlobalTimeTxPeriod is unequal to 0 and if the associated cyclicMsgResumeCounter is not running (see 7.4.5).
⌋(SRS_StbM_20039, SRS_StbM_20044)

[SWS_FrTSyn_00025]⌈
Depending on FrTSynGlobalTimeTxCrcSecured (**ECUC_FrTSyn_00013 :**) the OFS message shall be of type:

FrTSynGlobalTimeTxCrcSecured	OFS
CRC_NOT_SUPPORTED	0x34 OFS not CRC secured message
CRC_SUPPORTED	0x44 OFS CRC secured message

⌋(SRS_StbM_20041, SRS_StbM_20044)

7.4.3 Transmission mode

[SWS_FrTSyn_00026]⌈
If FrTSyn_SetTransmissionMode(Controller, Mode) is called and parameter Mode equals FRTSYN_TX_OFF, all transmit requests from FrTSyn shall be omitted on this FlexRay channel.

⌋(SRS_StbM_20039, SRS_StbM_20043, SRS_StbM_20044)

[SWS_FrTSyn_00027]⌈
If FrTSyn_SetTransmissionMode(Controller, Mode) is called and parameter Mode equals FRTSYN_TX_ON, all transmit requests from FrTSyn on this FlexRay channel shall be able to be transmitted.
⌋(SRS_StbM_20039, SRS_StbM_20043, SRS_StbM_20044)

7.4.4 Debounce Time

[SWS_FrTSyn_00084]⌈
If FrTSynGlobalTimeDebounceTime (**ECUC_FrTSyn_00033 :**) is greater than 0 for a Time Base, FrTSyn shall always do debouncing for the corresponding Timesync PDUs as described below, otherwise FrTSyn shall not do any debouncing.
⌋(SRS_StbM_20039)

[SWS_FrTSyn_00085]⌈
FrTSynGlobalTimeDebounceTime (**ECUC_FrTSyn_00033 :**) represents the debounce value of a debounceCounter of a Time Base. FrTSyn shall reload the debounceCounter after a Timesync PDU for the corresponding Time Base (SYNC and OFS) has been sent. FrTSyn shall decrement the debounceCounter value on each invocation of FrTSyn_MainFunction(), if no Timesync PDU is transmitted.
⌋(SRS_StbM_20039)

[SWS_FrTSyn_00086]⌈
A new Timesync PDU shall only be sent if the corresponding debounceCounter has a value equal or less than zero.
⌋(SRS_StbM_20039)

7.4.5 Immediate Time Synchronization

In addition to the cyclic Timesync message transmission, an immediate message transmission might be required.
Depending on configuration, the FrTSyn module checks on each FrTSyn_MainFunction() call the necessity for a Timesync message transmission for each Time Base, where a Master Port belongs to.

[SWS_FrTSyn_00087]⌈
If FrTSynImmediateTimeSync (**ECUC_FrTSyn_00031 :**) is set to TRUE for a Time Base, FrTSyn shall check on each FrTSyn_MainFunction() call by calling StbM_GetTimeBaseUpdateCounter(), if the timeBaseUpdateCounter of the corresponding Time Base has changed.
⌋(SRS_StbM_20039)

[SWS_FrTSyn_00088]⌈
If FrTSynImmediateTimeSync (**ECUC_FrTSyn_00031 :**) is set to TRUE and the timeBaseUpdateCounter of a Time Base has changed and the

GLOBAL_TIME_BASE bit of the timeBaseStatus is set, FrTSyn shall trigger an immediate transmission of Time Synchronization messages for the corresponding Time Base.
⌋(SRS_StbM_20039)

Note: timeBaseStatus can be obtained by StbM_GetTimeBaseStatus() or StbM_GetCurrentTime().

Note: The debounceTimer as described in 7.4.4 shall always be considered.

[SWS_FrTSyn_00089]⌈
If FrTSynImmediateTimeSync (**ECUC_FrTSyn_00031 :**) is set to TRUE, cyclicMsgResumeCounter and FrTSynCyclicMsgResumeTime (**ECUC_FrTSyn_00032 :**) shall be considered.
⌋(SRS_StbM_20039)

[SWS_FrTSyn_00090]⌈
FrTSynCyclicMsgResumeTime (**ECUC_FrTSyn_00032 :**) represents the timeout value of a cyclicMsgResumeCounter that shall be started when either a SYNC or OFS message has been sent immediately, asynchronous to the cyclic Timesync message transmission. FrTSynCyclicMsgResumeTime shall be decremented on each invocation of FrTSyn_MainFunction(), if no Timesync PDU is transmitted asynchronously.
⌋(SRS_StbM_20039)

[SWS_FrTSyn_00091]⌈
If the cyclicMsgResumeCounter has reached a value equal or less than zero, FrTSyn shall resume cyclic Timesync message transmission by sending either a SYNC or OFS message.
⌋(SRS_StbM_20039)

[SWS_FrTSyn_00093]⌈
If the cyclicMsgResumeCounter is started, FrTSyn shall stop cyclic Timesync message transmission.
⌋(SRS_StbM_20039)

7.4.6 Calculation and Assembling of Time Synchronization Messages

This chapter describes the workflow, how the items of a Time Synchronization message will be calculated (1st step) and how the message will be assembled (2nd step).

7.4.6.1 Global Time Calculation

[SWS_FrTSyn_00028]⌈
The transmitter of a Synchronized Time Base (Time Master) shall perform the following steps to distribute the Synchronized Time Base:

1. Get `currentCycle` and `currentMacroticks` from FlexRay driver

2. Retrieve current Synchronized Time Base value as T_{SYNC} via `StbM_GetCurrentTime()`

3. Calculate the (future) time value of the Time Base at the start of the next FlexRay cycle by
   T0 = T_{SYNC} + (`MacroticksPerCycle` * (64 - `currentCycle`) - `currentMacroticks`) * `MacrotickDuration`

4. Calculate *SyncTimeSec* (second portion of T0) and *SyncTimeNSec* (nanosecond portion of T0)

⌋(SRS_StbM_20043)

Note: `MacroticksPerCycle` and `MacrotickDuration` are given statically by configuration.

[SWS_FrTSyn_00029]⌈
The transmitter of an Offset Time Base (Time Master) shall perform the following steps to distribute the Offset Time Base:

1. Retrieve current Offset Time via `StbM_GetOffset()`
2. Write second portion of the Offset Time to *OfsTimeSec*
3. Write nanosecond portion of the Offset Time to *OfsTimeNSec*

⌋(SRS_StbM_20044)

7.4.6.2 SGW Calculation

[SWS_FrTSyn_00020]⌈
The *SGW* value (Time Gateway synchronization status) shall be retrieved from the Time Base synchronization status. If the `SYNC_TO_GATEWAY` bit within `timeBaseStatus` is not set the *SGW* value shall be *SyncToGTM*. Otherwise the *SGW* value shall be set to *SyncToSubDomain*.
⌋(SRS_StbM_20043, SRS_StbM_20044)

7.4.6.3 Sequence Counter Calculation

[SWS_FrTSyn_00030]⌈
A Sequence Counter (*SC*) of 4 bit is representing numbers from 0 to 15 per Time Domain. The Sequence Counter shall be independent between SYNC and OFS messages and shall be incremented by 1 on every transmission request of a SYNC or OFS message. It shall wrap around at 15 to 0 again.
⌋(SRS_StbM_20041, SRS_StbM_20043, SRS_StbM_20044)

7.4.6.4 CRC Calculation

[SWS_FrTSyn_00031]⌈

The function `Crc_CalculateCRC8H2F()` as defined in [5] shall be used to calculate the *CRC,* if configured.
⌋(SRS_StbM_20041, SRS_StbM_20043, SRS_StbM_20044)

[SWS_FrTSyn_00035]⌈
The `DataID` shall be calculated as `DataID = DataIDList[`*SC*`]`, where `DataIDList` (**ECUC_FrTSyn_00023 : ECUC_FrTSyn_00024 :**) is given by configuration for each message *Type*.
⌋(SRS_StbM_20041, SRS_StbM_20043, SRS_StbM_20044)

Note: A specific `DataID` out of a predefined `DataIDList` ensures the identification of data elements of Time Synchronization messages.

[SWS_FrTSyn_00036]⌈
The *CRC* shall be calculated over Time Synchronization message *Byte 2* to *Byte 15* and `DataID`.
⌋(SRS_StbM_20041, SRS_StbM_20043, SRS_StbM_20044)

7.4.6.5 Message Assembling

[SWS_FrTSyn_00037]⌈
For each transmission of a Time Synchronization message the FrTSyn module shall assemble the message as follows:

1. Calculate *SC*
2. Calculate *FCNT* (for SYNC message)
3. Calculate *SGW*
4. Copy all data to the appropriate position within the related message
5. Calculate *CRC* (configuration dependent)

⌋(SRS_StbM_20043, SRS_StbM_20044)

7.5 Acting as Time Slave

A Time Slave is an entity, which is the recipient for a certain Time Base within a certain segment of a communication network, being a consumer for this Time Base.

7.5.1 SYNC message processing

[SWS_FrTSyn_00038]⌈
The FrTSyn shall only accept a SYNC message with *Type* equal to `0x20` and a correct *CRC* value if `FrTSynRxCrcValidated` is configured to `CRC_VALIDATED`.
⌋(SRS_StbM_20042, SRS_StbM_20043)

[SWS_FrTSyn_00039]⌈
The FrTSyn shall only accept a SYNC message with *Type* equal to `0x10` if `FrTSynRxCrcValidated` is configured to `CRC_NOT_VALIDATED`.
⌋(SRS_StbM_20043)

[SWS_FrTSyn_00040]⌈
The FrTSyn shall only accept a SYNC message with *Type* equal to `0x10` or `0x20` if `FrTSynRxCrcValidated` is configured to `CRC_IGNORED`.
⌋(SRS_StbM_20043)

[SWS_FrTSyn_00081]⌈
The FrTSyn shall only accept a SYNC message with *Type* equal to `0x10` or a SYNC message with *Type* equal to `0x20` and a correct *CRC* value if `FrTSynRxCrcValidated` is configured to `CRC_OPTIONAL`.
⌋(SRS_StbM_20042, SRS_StbM_20043)

[SWS_FrTSyn_00041]⌈
For valid SYNC messages a new Global Time value shall be calculated and forwarded to the StbM module via `StbM_BusSetGlobalTime()` (see Figure 6: Slave FR SYNC).
⌋(SRS_StbM_20040, SRS_StbM_20042, SRS_StbM_20043)

7.5.2 OFS message processing

[SWS_FrTSyn_00042]⌈
The FrTSyn shall only accept an OFS message with *Type* equal to `0x44` and a correct *CRC* value if `FrTSynRxCrcValidated` is configured to `CRC_VALIDATED`.
⌋(SRS_StbM_20042, SRS_StbM_20044)

[SWS_FrTSyn_00043]⌈
The FrTSyn shall only accept an OFS message with *Type* equal to `0x34` if `FrTSynRxCrcValidated` is configured to `CRC_NOT_VALIDATED`.
⌋(SRS_StbM_20044)

[SWS_FrTSyn_00044]⌈
The FrTSyn shall only accept an OFS message with *Type* equal to `0x34` or `0x44` if `FrTSynRxCrcValidated` is configured to `CRC_IGNORED`.
⌋(SRS_StbM_20044)

[SWS_FrTSyn_00082]⌈
The FrTSyn shall only accept an OFS message with *Type* equal to `0x34` or an OFS message with *Type* equal to `0x44` and a correct *CRC* value if `FrTSynRxCrcValidated` is configured to `CRC_OPTIONAL`.
⌋(SRS_StbM_20042, SRS_StbM_20044)

[SWS_FrTSyn_00045]⌈
For valid OFS messages a new Offset Time value shall be calculated (according **[SWS_FrTSyn_00047]**) and forwarded to the StbM module via `StbM_BusSetGlobalTime().`
⌋(SRS_StbM_20040, SRS_StbM_20042, SRS_StbM_20044)

7.5.3 Validation and Disassembling of Time Synchronization Messages

This chapter describes the workflow how the items of a Time Synchronization message will be validated (1st step) and how the message will be disassembled (2nd step).

7.5.3.1 Global Time Calculation

[SWS_FrTSyn_00046]⌈
The receiver of a Synchronized Time Base shall perform the following steps to assemble the Synchronized Time Base:

1. On SYNC message RX indication (or in the subsequent `MainFunction` call) store received time value T0 (*SyncTimeSec, SyncTimeNSec*)

2. Get `currentCycle` and `currentMacroticks` from FlexRay driver

3. Calculate T1 to update the Time Slave's Local Time Base as:
   T1 = T0 + (((`MacroticksPerCycle` * `currentCycle`) + `currentMacroticks`) * `MacrotickDuration`)

4. If the `currentCycle` has passed the retrieved *FCNT* from the transmitter side then the previously calculated T1 must be adjusted by the maximum of the cycle counter to:
   T1 = T1 – (`MacroticksPerCycle` * 64 * `MacrotickDuration`)

⌋(SRS_StbM_20043)

Note: `MacroticksPerCycle` and `MacrotickDuration` are given statically by configuration.

[SWS_FrTSyn_00047]⌈
The receiver of an Offset Time Base shall perform the following steps to assemble the Offset Time:

1. Get second portion of the Offset Time out of *OfsTimeSec*
2. Get nanosecond portion of the Offset Time out of *OfsTimeNSec*

⌋(SRS_StbM_20044)

7.5.3.2 SGW Calculation

[SWS_FrTSyn_00094]⌈
If the *SGW* value (FUP and OFS) is set to `SyncToSubDomain`, the `SYNC_TO_GATEWAY` bit within `timeBaseStatus` shall be set to `TRUE`. Otherwise, it shall be set to `FALSE`.
⌋(SRS_StbM_20040, SRS_StbM_20042)

7.5.3.3 Sequence Counter Validation

[SWS_FrTSyn_00048]⌈
The Sequence Counter Jump Width between two consecutive SYNC or two consecutive OFS messages of the same Time Domain shall always be smaller than or equal to `FrTSynGlobalTimeSequenceCounterJumpWidth`. Otherwise a Time Slave shall discard the respective SYNC / OFS message.

The `FrTSynGlobalTimeSequenceCounterJumpWidth` value 0 is not allowed.
⌋(SRS_StbM_20042, SRS_StbM_20043, SRS_StbM_20044)

[SWS_FrTSyn_00049]⌈
At Startup or if a Time Base update timeout has been detected (`TIMEOUT` bit set in Time Base synchronization status `timeBaseStatus`), a Time Slave shall not check the Sequence Counter of the 1st received SYNC (or OFS) message per Time Domain against the defined Sequence Counter Jump Width.
⌋(SRS_StbM_20042, SRS_StbM_20043, SRS_StbM_20044)

Note: There are scenarios where it makes sense to skip the check of the Sequence Counter Jump Width, e.g. at startup (Time Slaves start asynchronously to the Time Master) or after a message timeout to allow for Sequence Counter (re-)synchronization. In case of a timeout the error has been detected already by the timeout monitoring, there is no benefit in generating a subsequent error by the jump width check.

7.5.3.4 CRC Validation

[SWS_FrTSyn_00050]⌈
The function `Crc_CalculateCRC8H2F()` as defined in [5] shall be used to validate the *CRC,* if configured.
⌋(SRS_StbM_20042, SRS_StbM_20043, SRS_StbM_20044)

[SWS_FrTSyn_00054]⌈
The DataID shall be calculated as DataID = DataIDList[*SC*], where DataIDList is given by configuration for each message *Type*.
⌋(SRS_StbM_20042, SRS_StbM_20043, SRS_StbM_20044)

Note: A specific DataID out of a predefined DataIDList ensures the identification of data elements of Time Synchronization messages.

[SWS_FrTSyn_00055]⌈
The *CRC* shall be calculated over Time Synchronization message *Byte 2* to *Byte 15* and DataID.
⌋(SRS_StbM_20042, SRS_StbM_20043, SRS_StbM_20044)

7.5.3.5 Message Disassembling

[SWS_FrTSyn_00056]⌈
For each received Time Synchronization message the FrTSyn shall validate the message as follows (all conditions must match):

1. *Type* matches depending on the FrTSynRxCrcValidated parameter
2. *SC* matches to the expected value
3. *D* matches to the defined Time Domain range for each *Type*
4. *D* matches to one of the configured Time Domains
5. *SyncTimeNSec* (SYNC message) or *OfsTimeNSec* (OFS message) matches the defined range of StbM_TimeStampType.nanoseconds.
6. *CRC* (including DataID) matches depending on the FrTSynRxCrcValidated parameter.

⌋(SRS_StbM_20043, SRS_StbM_20044)

[SWS_FrTSyn_00057]⌈
For each received Time Synchronization message the FrTSyn shall disassemble the message after successful validation **[SWS_FrTSyn_00056]**.
⌋(SRS_StbM_20042, SRS_StbM_20043, SRS_StbM_20044)

7.6 Global Time Measurement Support

[SWS_FrTSyn_00092]⌈
On an invocation of StbM_BusSetGlobalTime() the member PathDelay of the measureDataPtr structure shall be set to 0.
⌋(SRS_StbM_20057)

7.7 Error Classification

This chapter lists and classifies all errors that can be detected by this software module. Each error is classified to relevance (development / production) and the related error code (unique label for the error). For development errors this table also specifies the unique values, which correspond to the error codes.

[SWS_FrTSyn_00058]⌈
On errors and exceptions, the FrTSyn module shall not modify its current module state but shall simply report the error event.
⌋(SRS_StbM_20042, SRS_BSW_00323)

7.7.1 Development Errors

The detection of development errors is configurable (see section 10.2, FrTSynDevErrorDetect).

[SWS_FrTSyn_00059]⌈
FrTSyn shall use following development errors:

Type or error	***Related error code***	***Value [hex]***
API service called with wrong PDU or SDU.	FRTSYN_E_INVALID_PDUID	0x01
API service used in un-initialized state	FRTSYN_E_NOT_INITIALIZED	0x20
A pointer is invalid	FRTSYN_E_NULL_POINTER	0x21
FrTSyn initialization failed	FRTSYN_E_INIT_FAILED	0x22
API called with invalid parameter	FRTSYN_E_PARAM	0x23
Invalid Controller index	FRTSYN_E_INV_CTRL_IDX	0x24

⌋(SRS_BSW_00385)

7.7.2 Runtime Errors

No Runtime Errors defined.

7.7.3 Transient Faults

No Transient Faults defined.

7.7.4 Production Errors

No Production Errors defined.

7.7.5 Extended Production Errors

No Extended Production Errors defined.

8 API specification

8.1 API

8.1.1 Imported types

In this section all types included from the following files are listed:

[SWS_FrTSyn_00060] ⌈

Module	*Imported Type*
ComStack_Types	PduIdType
	PduInfoType
FrIf	FrIf_StateType
StbM	StbM_MeasurementType
	StbM_SynchronizedTimeBaseType
	StbM_TimeBaseStatusType
	StbM_TimeStampType
	StbM_UserDataType
Std_Types	Std_ReturnType
	Std_VersionInfoType

⌋ (SRS_StbM_20043)

8.1.2 Type definitions

8.1.2.1 FrTSyn_ConfigType

[SWS_FrTSyn_00061] ⌈

Name:	FrTSyn_ConfigType		
Type:	Structure		
Element:	void	implementation specific	--
Description:	This is the base type for the configuration of the Time Synchronization over FlexRay. A pointer to an instance of this structure will be used in the initialization of the Time Synchronization over FlexRay. The content of this structure is defined in chapter 10 Configuration specification.		

⌋ (SRS_StbM_20043)

8.1.2.2 FrTSyn_TransmissionModeType

[SWS_FrTSyn_00062] ⌈

Name:	FrTSyn_TransmissionModeType		
Type:	Enumeration		
Range:	FRTSYN_TX_OFF	--	Transmission Disabled

	FRTSYN_TX_ON	--	Transmission Enabled
Description:	Handles the enabling and disabling of the transmission mode		

⌋ (SRS_StbM_20043)

8.1.3 Function definitions

8.1.3.1 FrTSyn_Init

[SWS_FrTSyn_00063] ⌈

Service name:	FrTSyn_Init	

Syntax:	`void FrTSyn_Init(`
	`    const FrTSyn_ConfigType* configPtr`
	`)`	

Service ID[hex]:	0x01	
Sync/Async:	Synchronous	
Reentrancy:	Non Reentrant	
Parameters (in):	configPtr	Pointer to selected configuration structure
Parameters (inout):	None	
Parameters (out):	None	
Return value:	None	
Description:	This function initializes the Time Synchronization over FlexRay.	

⌋ (SRS_StbM_20043)

See section 7.2.1 for details.

8.1.3.2 FrTSyn_GetVersionInfo

[SWS_FrTSyn_00064] ⌈

Service name:	FrTSyn_GetVersionInfo	

Syntax:	`void FrTSyn_GetVersionInfo(`
	`    Std_VersionInfoType* versioninfo`
	`)`	

Service ID[hex]:	0x02	
Sync/Async:	Synchronous	
Reentrancy:	Non Reentrant	
Parameters (in):	versioninfo	Pointer to where to store the version information of this module.
Parameters (inout):	None	
Parameters (out):	None	
Return value:	None	
Description:	Returns the version information of this module.	

⌋ (SRS_StbM_20043)

8.1.3.3 FrTSyn_SetTransmissionMode

[SWS_FrTSyn_00065] ⌈

Service name:	FrTSyn_SetTransmissionMode

Syntax:	`void FrTSyn_SetTransmissionMode(`
	`    uint8 CtrlIdx,`
	`    FrTSyn_TransmissionModeType Mode`
	`)`

Service ID[hex]:	0x03	
Sync/Async:	Synchronous	
Reentrancy:	Non Reentrant	
Parameters (in):	CtrlIdx	Index of the FlexRay channel
	Mode	FRTSYN_TX_OFF FRTSYN_TX_ON
Parameters (inout):	None	
Parameters (out):	None	
Return value:	None	
Description:	This API is used to turn on and off the TX capabilities of the FrTSyn.	

⌋ (SRS_StbM_20043)

[SWS_FrTSyn_00095]⌈
The function `FrTSyn_SetTransmissionMode()` shall inform the DET, if development error detection is enabled (`FrTSynDevErrorDetect` is set to `TRUE`) and if function call has failed because of the following reasons:

- Invalid `CtrlIdx` (`FRTSYN_E_INV_CTRL_IDX`)
- Invalid `Mode` (`FRTSYN_E_PARAM`)

⌋(SRS_BSW_00323, SRS_BSW_00337)

8.1.4 Call-back notifications

This is a list of functions provided for other modules. The function prototypes of the callback functions shall be provided in the file *`FrTSyn_Cbk.h`*.

8.1.4.1 FrTSyn_RxIndication

[SWS_FrTSyn_00066] ⌈

Service name:	FrTSyn_RxIndication	

Syntax:	`void FrTSyn_RxIndication(`
	`    PduIdType RxPduId,`
	`    const PduInfoType* PduInfoPtr`
	`)`	

Service ID[hex]:	0x42	
Sync/Async:	Synchronous	
Reentrancy:	Reentrant for different PduIds. Non reentrant for the same PduId.	
Parameters (in):	RxPduId	ID of the received PDU.
	PduInfoPtr	Contains the length (SduLength) of the received PDU, a pointer to a buffer (SduDataPtr) containing the PDU, and the MetaData related to this PDU.
Parameters (inout):	None	
Parameters (out):	None	
Return value:	None	
Description:	Indication of a received PDU from a lower layer communication interface module.	

⌋ (SRS_StbM_20043)

Note: The callback function `FrTSyn_RxIndication` called by the FR Interface and implemented by the FrTSyn module. It is called in case of a receive indication event of the FR Driver.

[SWS_FrTSyn_00067]⌈
The callback function `FrTSyn_RxIndication()` shall inform the DET, if development error detection is enabled (`FrTSynDevErrorDetect` is set to TRUE) and if function call has failed because of the following reasons:

- Invalid PDU ID (`FRTSYN_E_INVALID_PDUID`)
- `PduInfoPtr` or `SduDataPtr` equals `NULL_PTR` (`FRTSYN_E_NULL_POINTER`)

⌋(SRS_BSW_00323, SRS_BSW_00337)

Caveats of `FrTSyn_RxIndication()`:

- The FrTSyn module is initialized correctly.

8.1.4.2 FrTSyn_TriggerTransmit

[SWS_FrTSyn_00069] ⌈

Service name:	FrTSyn_TriggerTransmit	

Syntax:	`Std_ReturnType FrTSyn_TriggerTransmit(`
	`    PduIdType TxPduId,`
	`    PduInfoType* PduInfoPtr`
	`)`	

Service ID[hex]:	0x41	
Sync/Async:	Synchronous	
Reentrancy:	Reentrant for different PduIds. Non reentrant for the same PduId.	
Parameters (in):	TxPduId	ID of the SDU that is requested to be transmitted.
Parameters (inout):	PduInfoPtr	Contains a pointer to a buffer (SduDataPtr) to where the SDU data shall be copied, and the available buffer size in SduLengh. On return, the service will indicate the length of the copied SDU data in SduLength.
Parameters (out):	None	
Return value:	Std_ReturnType	E_OK: SDU has been copied and SduLength indicates the number of copied bytes. E_NOT_OK: No SDU data has been copied. PduInfoPtr must not be used since it may contain a NULL pointer or point to invalid data.
Description:	Within this API, the upper layer module (called module) shall check whether the available data fits into the buffer size reported by PduInfoPtr->SduLength. If it fits, it shall copy its data into the buffer provided by PduInfoPtr->SduDataPtr and update the length of the actual copied data in PduInfoPtr->SduLength. If not, it returns E_NOT_OK without changing PduInfoPtr.	

⌋ (SRS_StbM_20043)

Note: The function `FrTSyn_TriggerTransmit()` might be called by the FrTSyn module's environment in an interrupt context.

[SWS_FrTSyn_00070]⌈

The callback function `FrTSyn_TriggerTransmit()` shall inform the DET, if development error detection is enabled (`FrTSynDevErrorDetect` is set to `TRUE`) and if function call has failed because of the following reasons:

- Invalid PDU ID (`FRTSYN_E_INVALID_PDUID`)
- `PduInfoPtr` or `SduDataPtr` equals `NULL_PTR` (`FRTSYN_E_NULL_POINTER`)

⌋(SRS_BSW_00323, SRS_BSW_00337)

8.1.5 Scheduled functions

These functions are directly called by the Basic Software Scheduler. The following functions shall have no return value and no parameters. All functions shall be non-reentrant.

8.1.5.1 FrTSyn_MainFunction

[SWS_FrTSyn_00071] ⌈

Service name:	FrTSyn_MainFunction

Syntax:	`void FrTSyn_MainFunction(`
	`    void`
	`)`

Service ID[hex]:	0x04
Sync/Async:	Synchronous
Reentrancy:	Non Reentrant
Parameters (in):	None
Parameters (inout):	None
Parameters (out):	None
Return value:	None
Description:	Main function for cyclic call / resp. Timesync message transmission

⌋ (SRS_StbM_20043)

[SWS_FrTSyn_00072]⌈
The frequency of invocations of `FrTSyn_MainFunction()` is determined by the configuration parameter `FrTSynMainFunctionPeriod` (refer to **ECUC_FrTSyn_00016 :**).
⌋(SRS_StbM_20043)

8.1.6 Expected Interfaces

In this section, all interfaces required by other modules are listed.

8.1.6.1 Mandatory Interfaces

This section defines all interfaces that are required to fulfill a mandatory functionality of the module.

[SWS_FrTSyn_00074] ⌈

API function	***Description***
FrIf_GetGlobalTime	Wraps the FlexRay Driver API function Fr_GetGlobalTime().
FrIf_GetMacrotickDuration	Retrieves the Duration of a Macrotick in ns
FrIf_GetMacroticksPerCycle	Retrieves the amount of Macroticks per Cycle
FrIf_GetState	Get current FrIf state.

⌋ (SRS_StbM_20043)

8.1.6.2 Optional Interfaces

This section defines all interfaces that are required to fulfill an optional functionality of the module.

[SWS_FrTSyn_00075] ⌈

API function	***Description***
Crc_CalculateCRC8H2F	This service makes a CRC8 calculation with the Polynomial 0x2F on Crc_Length
Det_ReportError	Service to report development errors.
FrIf_Transmit	Requests transmission of a PDU.
StbM_BusSetGlobalTime	Allows the Time Base Provider Modules to forward a new Global Time value to the StbM, which has been received from a bus.
StbM_GetCurrentTime	Returns a time value (Local Time Base derived from Global Time Base) in standard format.
StbM_GetOffset	Allows the Timesync Modules to get the current Offset Time and User Data.
StbM_GetTimeBaseStatus	Returns the detailed status of the Time Base. For Offset Time Bases the status of the Offset Time Base itself and the status of the underlying Synchronized Time Base is returned.
StbM_GetTimeBaseUpdateCounter	Allows the Timesync Modules to detect, whether a Time Base should be transmitted immediately in the subsequent <Bus>TSyn_MainFunction() cycle.

⌋ (SRS_StbM_20043)

9 Sequence diagrams

9.1 StbM_GetCurrentTime <Master FR SYNC>

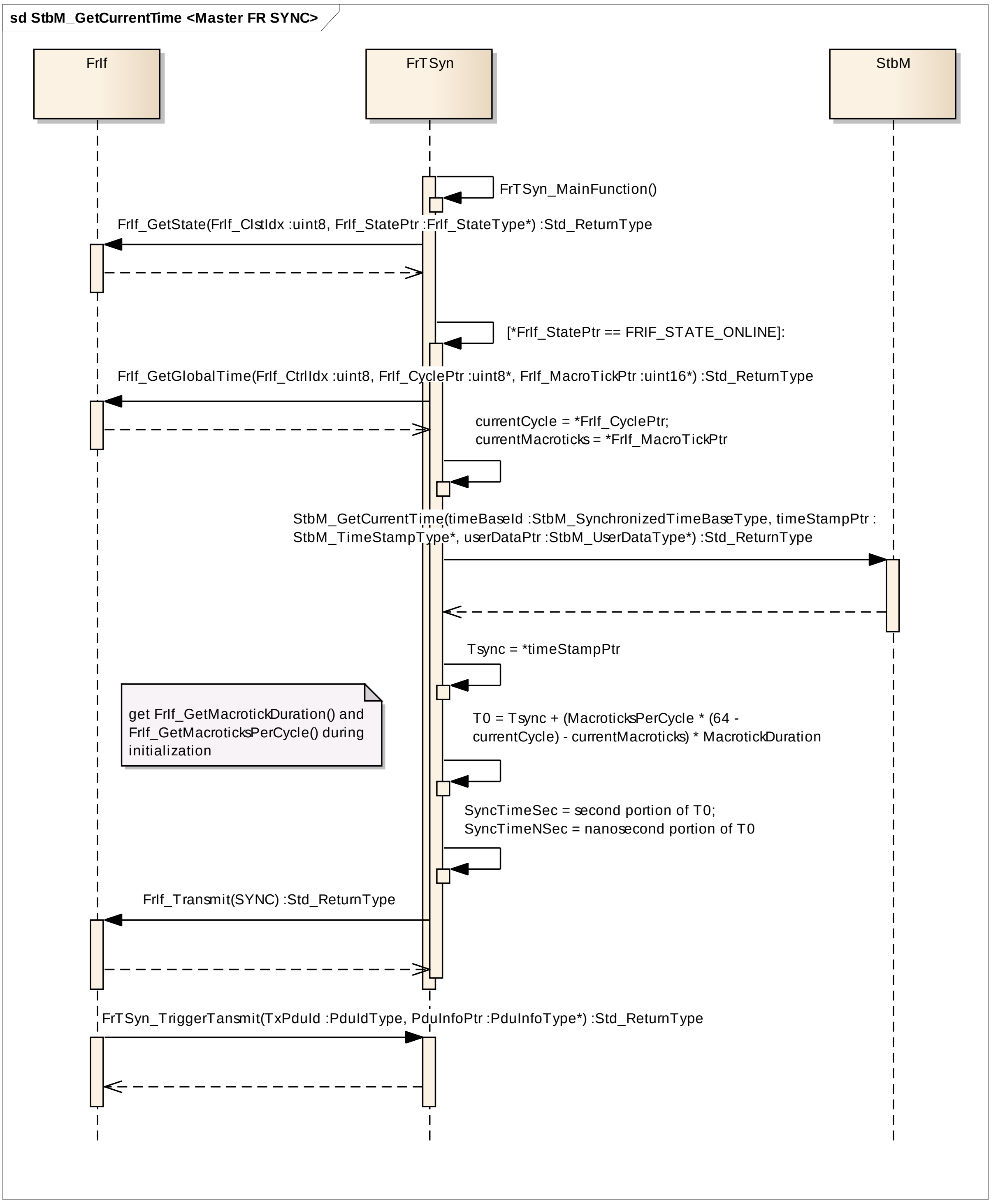

sd StbM_GetCurrentTime <Master FR SYNC>
FrIf
FrTSyn
StbM
FrTSyn_MainFunction()
FrIf_GetState(FrIf_ClstIdx :uint8, FrIf_StatePtr :FrIf_StateType*) :Std_ReturnType
[*FrIf_StatePtr == FRIF_STATE_ONLINE]:
FrIf_GetGlobalTime(FrIf_CtrlIdx :uint8, FrIf_CyclePtr :uint8*, FrIf_MacroTickPtr :uint16*) :Std_ReturnType
currentCycle = *FrIf_CyclePtr;
currentMacroticks = *FrIf_MacroTickPtr
StbM_GetCurrentTime(timeBaseId :StbM_SynchronizedTimeBaseType, timeStampPtr :
StbM_TimeStampType*, userDataPtr :StbM_UserDataType*) :Std_ReturnType
Tsync = *timeStampPtr
get FrIf_GetMacrotickDuration() and
FrIf_GetMacroticksPerCycle() during
initialization
T0 = Tsync + (MacroticksPerCycle * (64 -
currentCycle) - currentMacroticks) * MacrotickDuration
SyncTimeSec = second portion of T0;
SyncTimeNSec = nanosecond portion of T0
FrIf_Transmit(SYNC) :Std_ReturnType
FrTSyn_TriggerTansmit(TxPduId :PduIdType, PduInfoPtr :PduInfoType*) :Std_ReturnType

Figure 5: Master FR SYNC

9.2 StbM_BusSetGlobalTime <Slave FR SYNC>

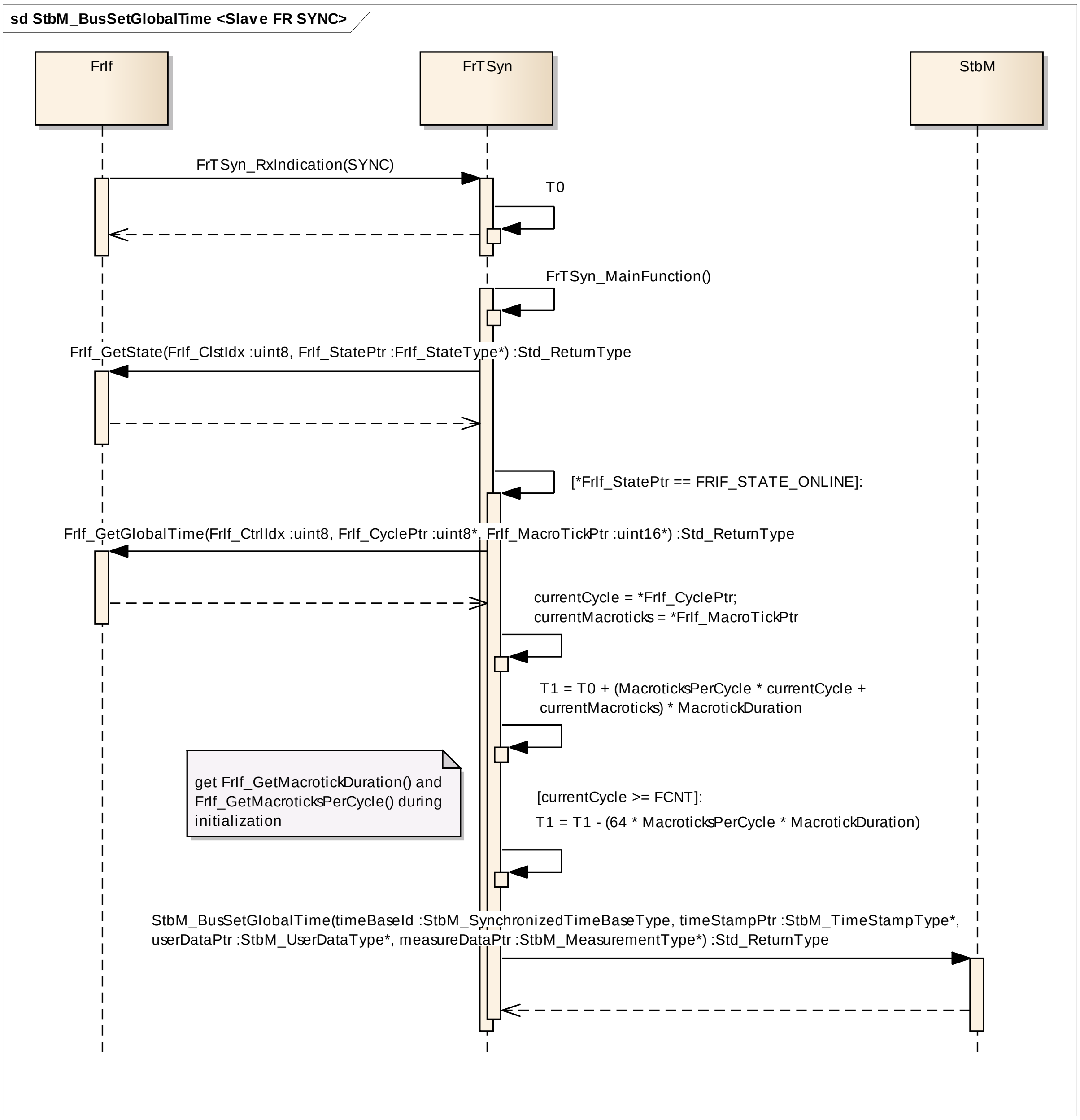

sd StbM_BusSetGlobalTime <Slave FR SYNC>
FrIf
FrTSyn
StbM
FrTSyn_RxIndication(SYNC)
T0
FrTSyn_MainFunction()
FrIf_GetState(FrIf_ClstIdx :uint8, FrIf_StatePtr :FrIf_StateType*) :Std_ReturnType
[*FrIf_StatePtr == FRIF_STATE_ONLINE]:
FrIf_GetGlobalTime(FrIf_CtrlIdx :uint8, FrIf_CyclePtr :uint8*, FrIf_MacroTickPtr :uint16*) :Std_ReturnType
currentCycle = *FrIf_CyclePtr;
currentMacroticks = *FrIf_MacroTickPtr
T1 = T0 + (MacroticksPerCycle * currentCycle + currentMacroticks) * MacrotickDuration
get FrIf_GetMacrotickDuration() and FrIf_GetMacroticksPerCycle() during initialization
[currentCycle >= FCNT]:
T1 = T1 - (64 * MacroticksPerCycle * MacrotickDuration)
StbM_BusSetGlobalTime(timeBaseId :StbM_SynchronizedTimeBaseType, timeStampPtr :StbM_TimeStampType*, userDataPtr :StbM_UserDataType*, measureDataPtr :StbM_MeasurementType*) :Std_ReturnType

Figure 6: Slave FR SYNC

10 Configuration specification

In general, this chapter defines configuration parameters and their clustering into containers. In order to support the specification section 10.1 describes fundamentals. It also specifies a template (table) you shall use for the parameter specification. We intend to leave section 10.1 in the specification to guarantee comprehension.

Section 10.2 specifies the structure (containers) and the parameters of the Time Synchronization over FlexRay.

Section 10.3 specifies published information of the Time Synchronization over FlexRay.

10.1 How to read this chapter

For details, refer to the chapter 10.1 “Introduction to configuration specification” in *SWS_BSWGeneral*.

10.2 Containers and configuration parameters

The following sections summarize all configuration parameters of the Time Synchronization over FlexRay. The detailed meaning of the parameters is described in chapters 7 and 8.

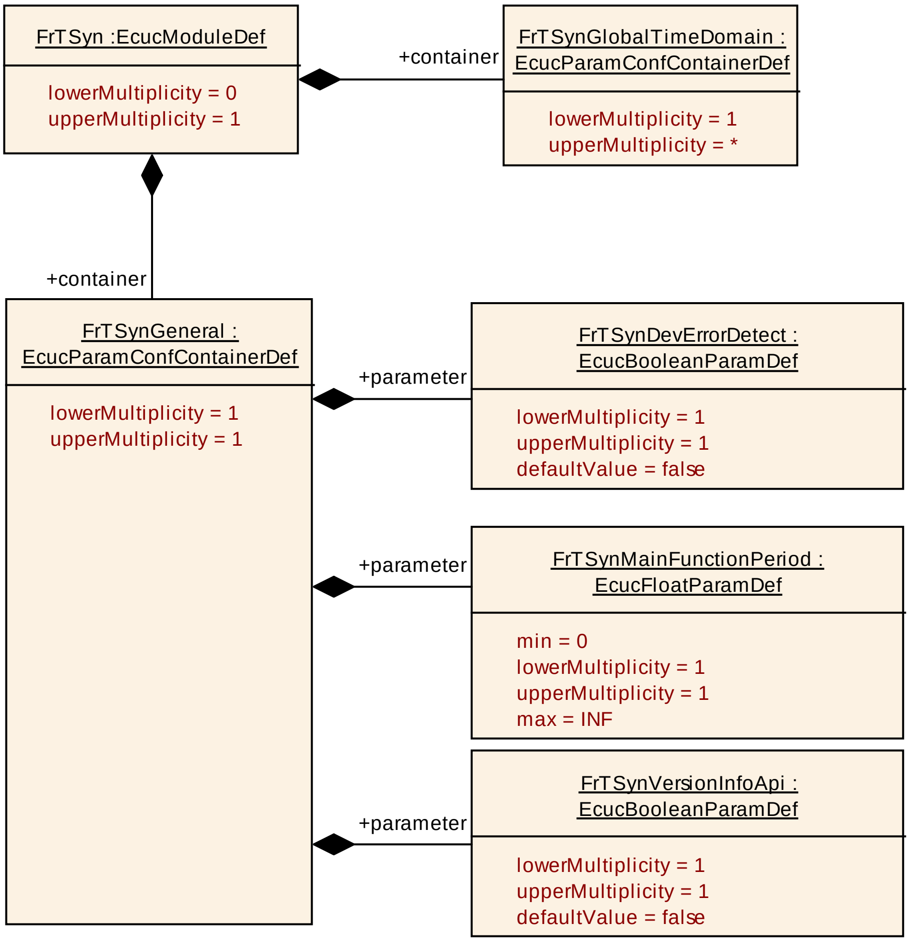
10.2.1 Variants

[SWS_FrTSyn_00077]⌈
The Time Synchronization over FlexRay shall support the configuration for Time Master, Time Slave and Time Gateway.
⌋(SRS_StbM_20046)

10.2.2 FrTSyn

SWS Item	**ECUC_FrTSyn_00001 :**
Module Name	*FrTSyn*
Module Description	This represents the specific configuration variant for the TSyn on Flexray.
Post-Build Variant Support	true
Supported Config Variants	VARIANT-POST-BUILD, VARIANT-PRE-COMPILE

Included Containers		
Container Name	***Multiplicity***	***Scope / Dependency***
FrTSynGeneral	1	This container holds the general parameters of the Flexray-specific Synchronized Time-base Manager
FrTSynGlobalTimeDomain	1..*	This represents the existence of a global time domain on Flexray. The FrTSyn module can administrate several global time domains at the same time that in itself form a hierarchy of domains and sub-domains. If the FrTSyn exists it is assumed that at least one global time domain exists.



10.2.3 FrTSynGeneral

SWS Item	**ECUC_FrTSyn_00003 :**
Container Name	FrTSynGeneral
Description	This container holds the general parameters of the Flexray-specific Synchronized Time-base Manager
Configuration Parameters	

SWS Item	**ECUC_FrTSyn_00002 :**		
Name	FrTSynDevErrorDetect		
Description	Switches the development error detection and notification on or off. • true: detection and notification is enabled. • false: detection and notification is disabled.		
Multiplicity	1		
Type	EcucBooleanParamDef		
Default value	false		
Post-Build Variant Value	false		
Value Configuration Class	***Pre-compile time***	X	All Variants
	Link time	--	
	Post-build time	--	
Scope / Dependency	scope: local		

SWS Item	**ECUC_FrTSyn_00016 :**		
Name	FrTSynMainFunctionPeriod		
Description	Schedule period of the main function FrTSyn_MainFunction. Unit: [s].		
Multiplicity	1		
Type	EcucFloatParamDef		
Range	]0 .. INF[		
Default value	--		
Post-Build Variant Value	false		
Value Configuration Class	***Pre-compile time***	X	All Variants
	Link time	--	
	Post-build time	--	
Scope / Dependency	scope: local		

SWS Item	**ECUC_FrTSyn_00019 :**		
Name	FrTSynVersionInfoApi		
Description	Activate/Deactivate the version information API (FrTSyn_GetVersionInfo). True: version information API activated False: version information API deactivated.		
Multiplicity	1		
Type	EcucBooleanParamDef		
Default value	false		
Post-Build Variant Value	false		
Value Configuration Class	***Pre-compile time***	X	All Variants
	Link time	--	
	Post-build time	--	
Scope / Dependency	scope: local		

No Included Containers

10.2.4 FrTSynGlobalTimeDomain

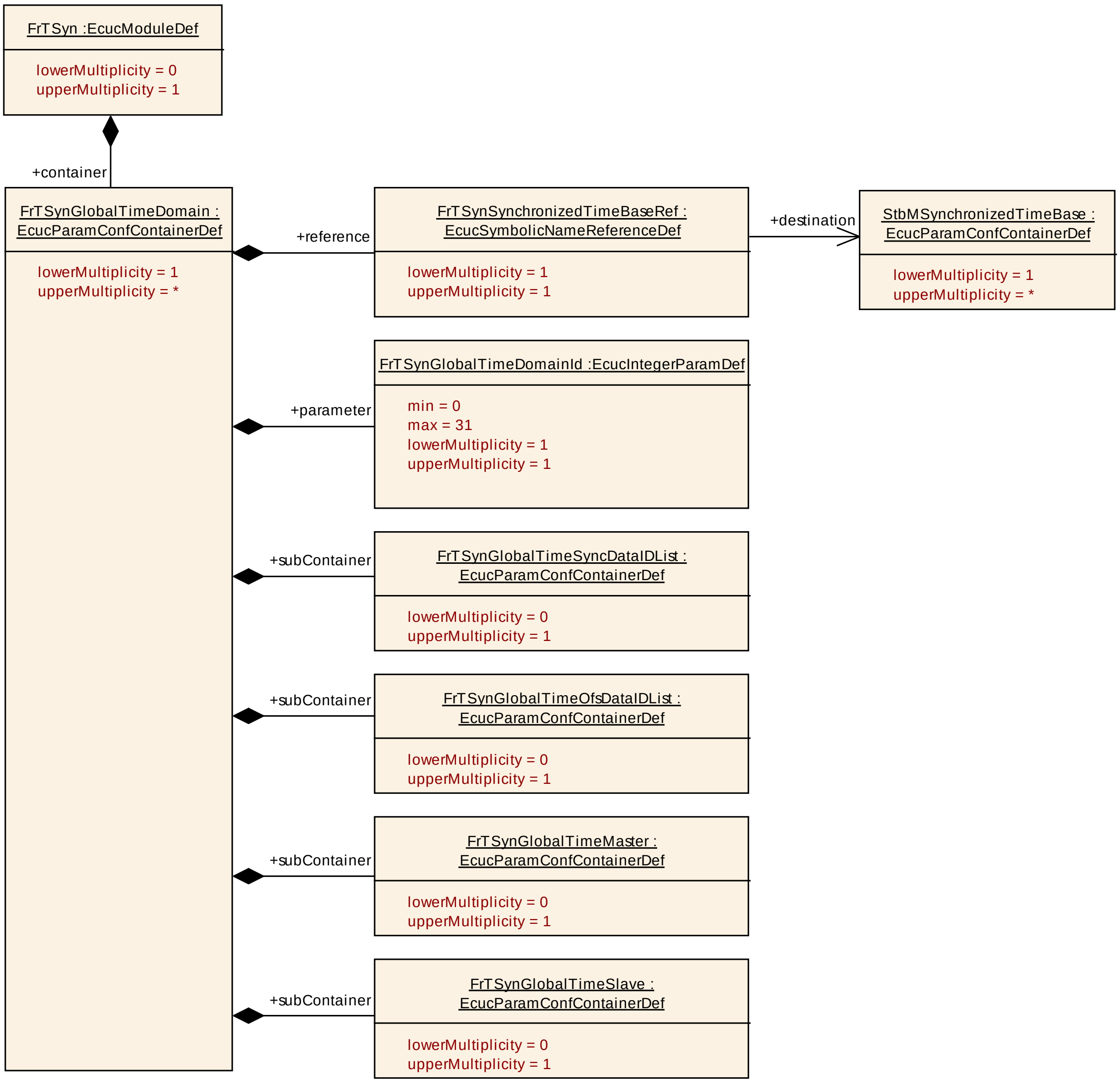
SWS Item	**ECUC_FrTSyn_00004 :**
Container Name	FrTSynGlobalTimeDomain
Description	This represents the existence of a global time domain on Flexray. The FrTSyn module can administrate several global time domains at the same time that in itself form a hierarchy of domains and sub-domains. If the FrTSyn exists it is assumed that at least one global time domain exists.
Configuration Parameters	

SWS Item	**ECUC_FrTSyn_00005 :**		
Name	FrTSynGlobalTimeDomainId		
Description	The global time domain ID.		
Multiplicity	1		
Type	EcucIntegerParamDef		
Range	0 .. 31		
Default value	--		
Post-Build Variant Value	false		
Value Configuration Class	***Pre-compile time***	X	All Variants
	Link time	--	
	Post-build time	--	

Scope / Dependency	scope: local

SWS Item	**ECUC_FrTSyn_00018 :**		
Name	FrTSynSynchronizedTimeBaseRef		
Description	Mandatory reference to the required synchronized time-base.		
Multiplicity	1		
Type	Symbolic name reference to [StbMSynchronizedTimeBase]		
Post-Build Variant Value	false		
Value Configuration Class	***Pre-compile time***	X	All Variants
	Link time	--	
	Post-build time	--	
Scope / Dependency	scope: local		

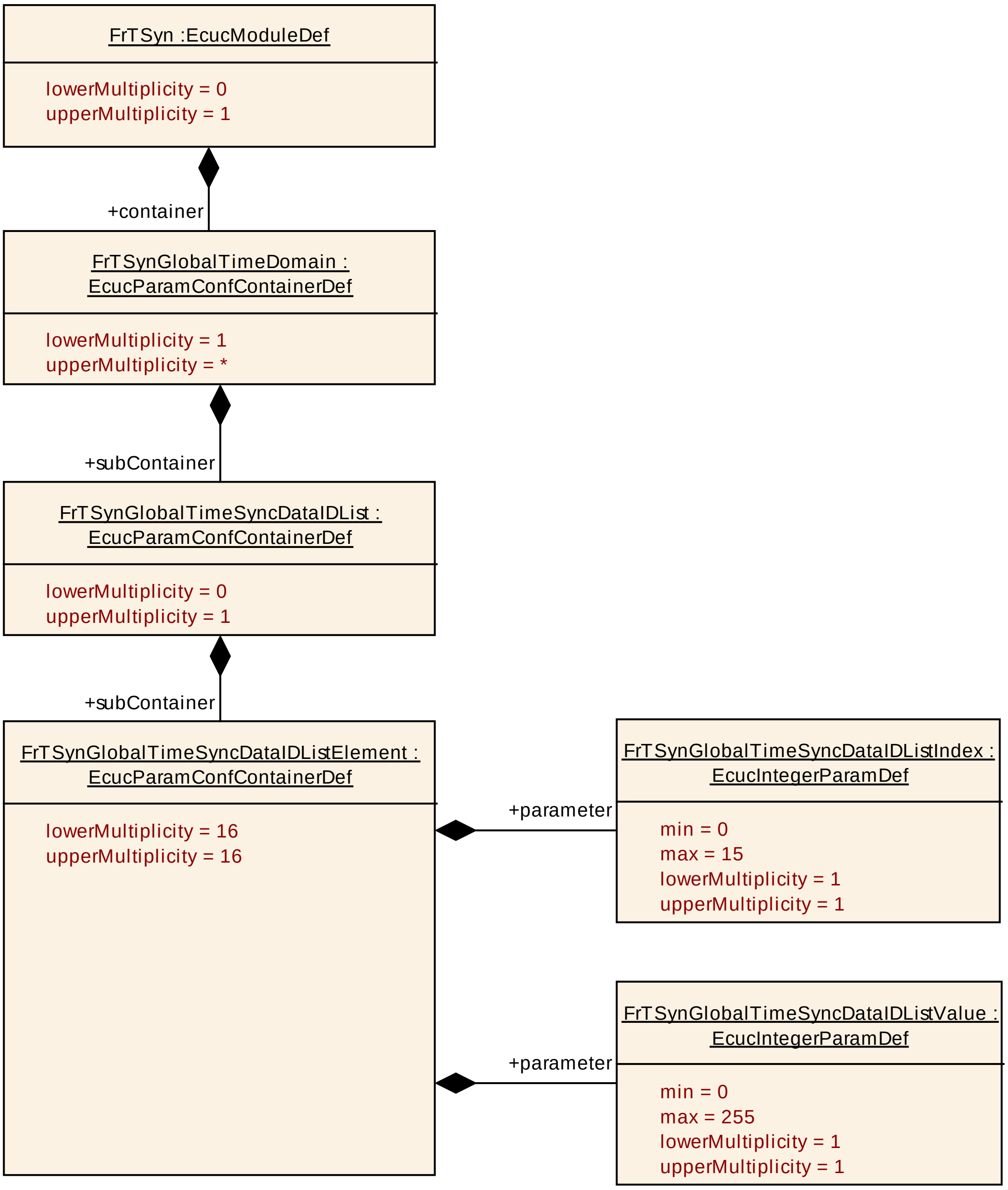
Included Containers		
Container Name	***Multiplicity***	***Scope / Dependency***
FrTSynGlobalTimeMaster	0..1	Configuration of the global time master. Each global time domain is required to have exactly one global time master. This master may or may not exist on the configured ECU.
FrTSynGlobalTimeOfsDataIDList	0..1	The DataIDList for OFS messages ensures the identification of data elements due to CRC calculation process.
FrTSynGlobalTimeSlave	0..1	This represents the time slave for the enclosing global time domain.
FrTSynGlobalTimeSyncDataIDList	0..1	The DataIDList for SYNC messages ensures the identification of data elements due to CRC calculation process.



10.2.5 FrTSynGlobalTimeSyncDataIDList

SWS Item	**ECUC_FrTSyn_00023 :**		
Container Name	FrTSynGlobalTimeSyncDataIDList		
Description	The DataIDList for SYNC messages ensures the identification of data elements due to CRC calculation process.		
Post-Build Variant Multiplicity	true		
Multiplicity Configuration Class	***Pre-compile time***	X	All Variants
	Link time	--	
	Post-build time	--	
Configuration Parameters			

Included Containers		
Container Name	***Multiplicity***	***Scope / Dependency***
FrTSynGlobalTimeSyncDataIDListElement	16	Element of the DataIDList for SYNC messages ensures the identification of data elements due to CRC calculation process.



10.2.6 FrTSynGlobalTimeSyncDataIDListElement

SWS Item	**ECUC_FrTSyn_00025 :**
Container Name	FrTSynGlobalTimeSyncDataIDListElement
Description	Element of the DataIDList for SYNC messages ensures the identification of data elements due to CRC calculation process.
Configuration Parameters	

SWS Item	**ECUC_FrTSyn_00026 :**
Name	FrTSynGlobalTimeSyncDataIDListIndex

Description	Index of the DataIDList for SYNC messages ensures the identification of data elements due to CRC calculation process.		
Multiplicity	1		
Type	EcucIntegerParamDef		
Range	0 .. 15		
Default value	--		
Post-Build Variant Value	true		
Value Configuration Class	***Pre-compile time***	X	All Variants
	Link time	--	
	Post-build time	--	
Scope / Dependency	scope: local		

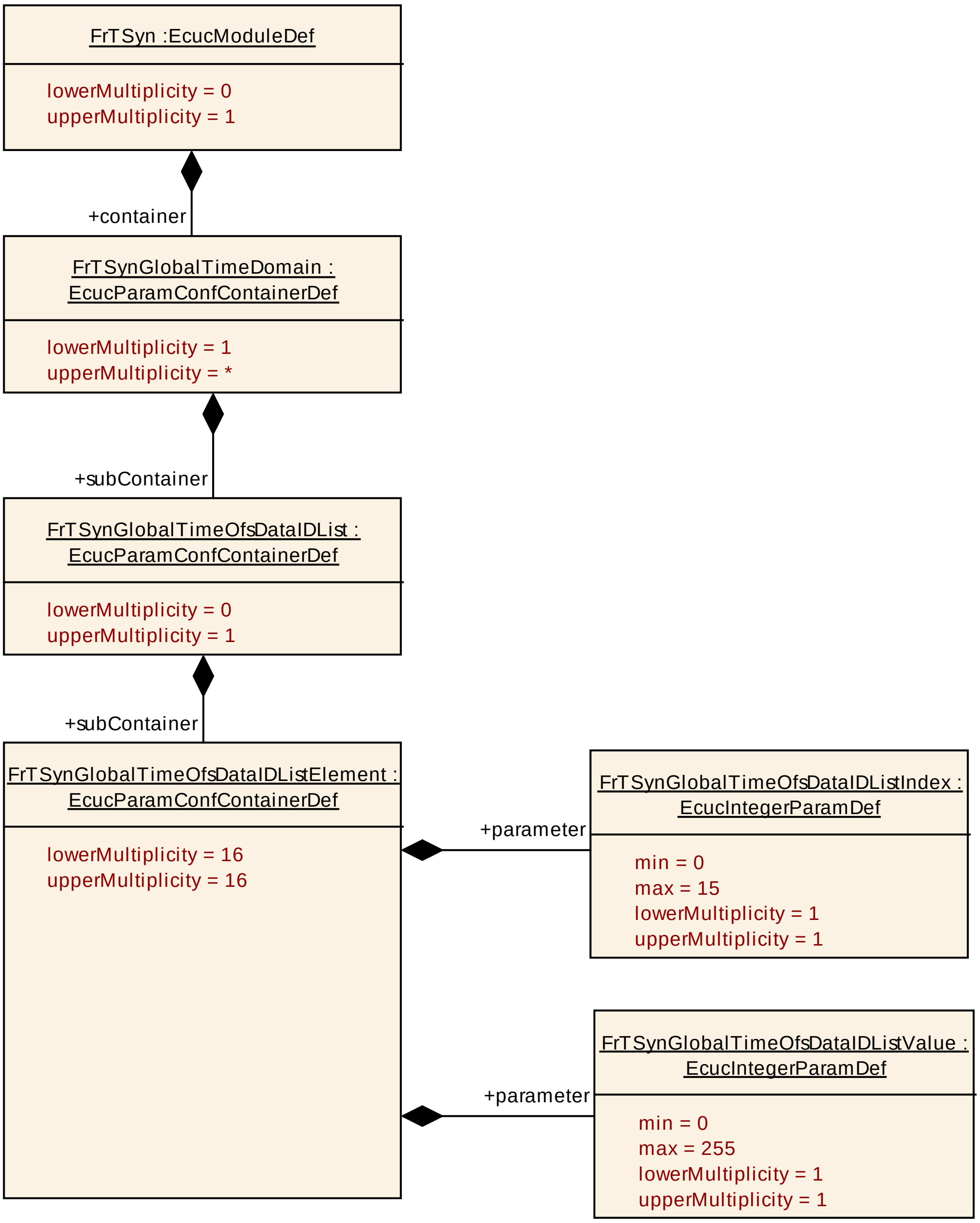
SWS Item	**ECUC_FrTSyn_00027 :**		
Name	FrTSynGlobalTimeSyncDataIDListValue		
Description	Value of the DataIDList for SYNC messages ensures the identification of data elements due to CRC calculation process.		
Multiplicity	1		
Type	EcucIntegerParamDef		
Range	0 .. 255		
Default value	--		
Post-Build Variant Value	true		
Value Configuration Class	***Pre-compile time***	X	All Variants
	Link time	--	
	Post-build time	--	
Scope / Dependency	scope: local		

No Included Containers

10.2.7 FrTSynGlobalTimeOfsDataIDList

SWS Item	**ECUC_FrTSyn_00024 :**		
Container Name	FrTSynGlobalTimeOfsDataIDList		
Description	The DataIDList for OFS messages ensures the identification of data elements due to CRC calculation process.		
Post-Build Variant Multiplicity	true		
Multiplicity Configuration Class	***Pre-compile time***	X	All Variants
	Link time	--	
	Post-build time	--	
Configuration Parameters			

Included Containers		
Container Name	***Multiplicity***	***Scope / Dependency***
FrTSynGlobalTimeOfsDataIDListElement	16	Element of the DataIDList for OFS messages ensures the identification of data elements due to CRC calculation process.



10.2.8 FrTSynGlobalTimeOfsDataIDListElement

SWS Item	**ECUC_FrTSyn_00028 :**
Container Name	FrTSynGlobalTimeOfsDataIDListElement
Description	Element of the DataIDList for OFS messages ensures the identification of data elements due to CRC calculation process.
Configuration Parameters	

SWS Item	**ECUC_FrTSyn_00029 :**
Name	FrTSynGlobalTimeOfsDataIDListIndex
Description	Index of the DataIDList for OFS messages ensures the identification of data elements due to CRC calculation process.

Multiplicity	1		
Type	EcucIntegerParamDef		
Range	0 .. 15		
Default value	--		
Post-Build Variant Value	true		
Value Configuration Class	***Pre-compile time***	X	All Variants
	Link time	--	
	Post-build time	--	
Scope / Dependency	scope: local		

SWS Item	**ECUC_FrTSyn_00030 :**		
Name	FrTSynGlobalTimeOfsDataIDListValue		
Description	Value of the DataIDList for OFS messages ensures the identification of data elements due to CRC calculation process.		
Multiplicity	1		
Type	EcucIntegerParamDef		
Range	0 .. 255		
Default value	--		
Post-Build Variant Value	true		
Value Configuration Class	***Pre-compile time***	X	All Variants
	Link time	--	
	Post-build time	--	
Scope / Dependency	scope: local		

No Included Containers

10.2.9 FrTSynGlobalTimeMaster

SWS Item	**ECUC_FrTSyn_00006 :**		
Container Name	FrTSynGlobalTimeMaster		
Description	Configuration of the global time master. Each global time domain is required to have exactly one global time master. This master may or may not exist on the configured ECU.		
Post-Build Variant Multiplicity	true		
Multiplicity Configuration Class	***Pre-compile time***	X	All Variants
	Link time	--	
	Post-build time	--	
Configuration Parameters			

SWS Item	**ECUC_FrTSyn_00032 :**		
Name	FrTSynCyclicMsgResumeTime		
Description	Defines the time where the 1st regular cycle time based message transmission takes place, after an immediate transmission before. Unit: seconds		
Multiplicity	1		
Type	EcucFloatParamDef		
Range	[0 .. INF]		
Default value	--		
Post-Build Variant Value	true		
Value Configuration Class	***Pre-compile time***	X	All Variants
	Link time	--	

	Post-build time	--	
Scope / Dependency	scope: local		

SWS Item	**ECUC_FrTSyn_00033 :**		
Name	FrTSynGlobalTimeDebounceTime		
Description	This represents the configuration of a TX debounce time for SYNC and OFS messages compared to a message before with the same PDU. Unit: seconds		
Multiplicity	1		
Type	EcucFloatParamDef		
Range	[0 .. INF[		
Default value	--		
Post-Build Variant Value	true		
Value Configuration Class	***Pre-compile time***	X	All Variants
	Link time	--	
	Post-build time	--	
Scope / Dependency	scope: local		

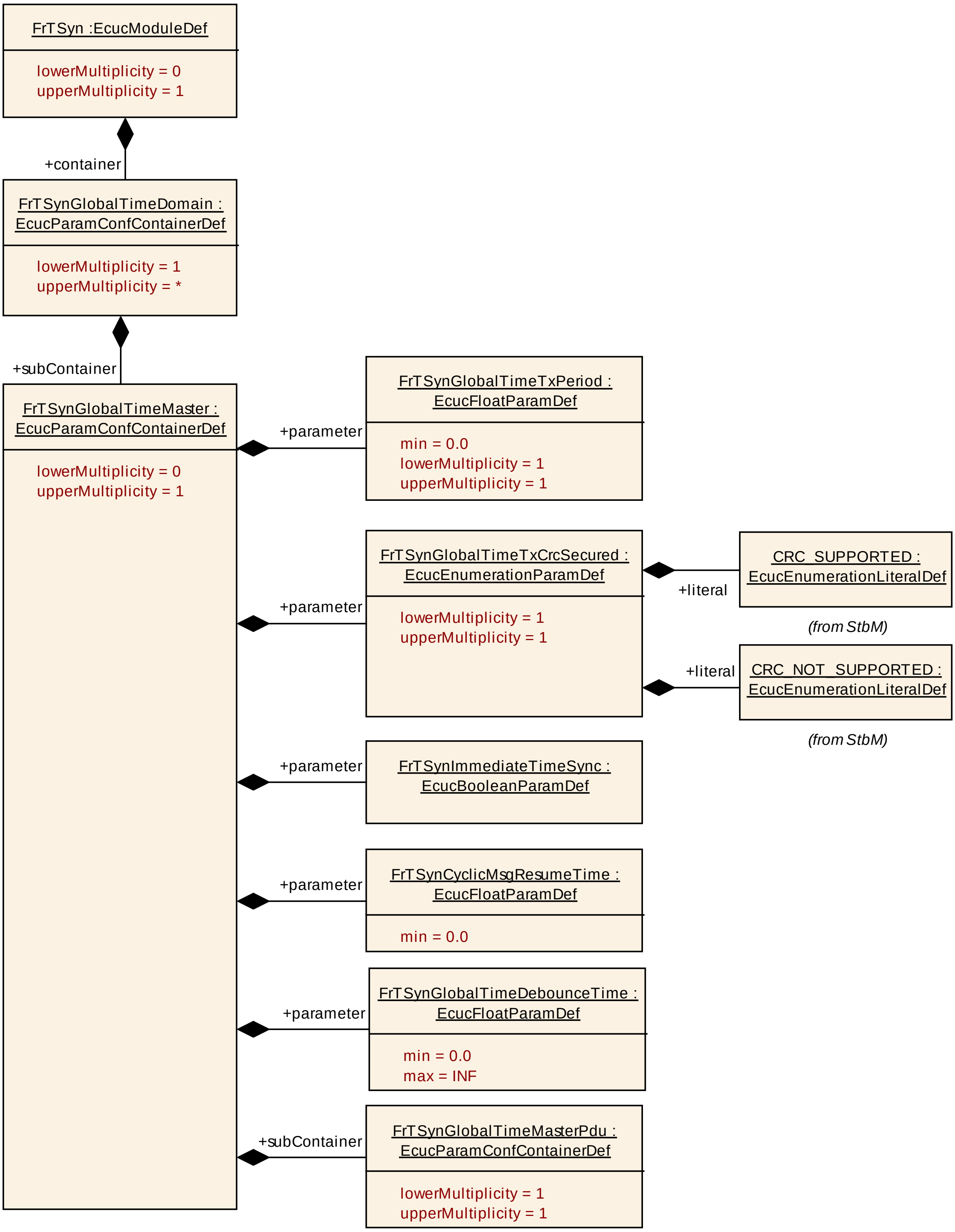
SWS Item	**ECUC_FrTSyn_00013 :**		
Name	FrTSynGlobalTimeTxCrcSecured		
Description	This represents the configuration of whether or not CRC is supported.		
Multiplicity	1		
Type	EcucEnumerationParamDef		
Range	CRC_NOT_SUPPORTED	This represents a configuration where CRC is not supported.	
	CRC_SUPPORTED	This represents a configuration where CRC is supported.	
Post-Build Variant Value	true		
Value Configuration Class	***Pre-compile time***	X	All Variants
	Link time	--	
	Post-build time	--	
Scope / Dependency	scope: local		

SWS Item	**ECUC_FrTSyn_00014 :**		
Name	FrTSynGlobalTimeTxPeriod		
Description	This represents the TX period. Unit: seconds		
Multiplicity	1		
Type	EcucFloatParamDef		
Range	[0 .. INF]		
Default value	--		
Post-Build Variant Value	true		
Value Configuration Class	***Pre-compile time***	X	All Variants
	Link time	--	
	Post-build time	--	
Scope / Dependency	scope: local		

SWS Item	**ECUC_FrTSyn_00031 :**
Name	FrTSynImmediateTimeSync
Description	Enables/Disables the cyclic polling of StbM_GetTimeBaseUpdateCounter() within FrTSyn_MainFunction().
Multiplicity	1
Type	EcucBooleanParamDef
Default value	--

Post-Build Variant Value	true		
Value Configuration Class	***Pre-compile time***	X	All Variants
	Link time	--	
	Post-build time	--	
Scope / Dependency	scope: local		

Included Containers		
Container Name	***Multiplicity***	***Scope / Dependency***
FrTSynGlobalTimeMasterPdu	1	This container carries all properties required to configure the PDU sent by the global time master for the given global time domain.


FrTSyn :EcucModuleDef
lowerMultiplicity = 0
upperMultiplicity = 1
+container
FrTSynGlobalTimeDomain : EcucParamConfContainerDef
lowerMultiplicity = 1
upperMultiplicity = *
+subContainer
FrTSynGlobalTimeMaster : EcucParamConfContainerDef
lowerMultiplicity = 0
upperMultiplicity = 1
+parameter
FrTSynGlobalTimeTxPeriod : EcucFloatParamDef
min = 0.0
lowerMultiplicity = 1
upperMultiplicity = 1
+parameter
FrTSynGlobalTimeTxCrcSecured : EcucEnumerationParamDef
lowerMultiplicity = 1
upperMultiplicity = 1
+literal
CRC_SUPPORTED : EcucEnumerationLiteralDef
(from StbM)
+literal
CRC_NOT_SUPPORTED : EcucEnumerationLiteralDef
(from StbM)
+parameter
FrTSynImmediateTimeSync : EcucBooleanParamDef
+parameter
FrTSynCyclicMsgResumeTime : EcucFloatParamDef
min = 0.0
+parameter
FrTSynGlobalTimeDebounceTime : EcucFloatParamDef
min = 0.0
max = INF
+subContainer
FrTSynGlobalTimeMasterPdu : EcucParamConfContainerDef
lowerMultiplicity = 1
upperMultiplicity = 1

10.2.10 FrTSynGlobalTimeMasterPdu

SWS Item	**ECUC_FrTSyn_00008 :**
Container Name	FrTSynGlobalTimeMasterPdu
Description	This container carries all properties required to configure the PDU sent by the global time master for the given global time domain.
Configuration Parameters	

SWS Item	**ECUC_FrTSyn_00007 :**		
Name	FrTSynGlobalTimeMasterHandleId		
Description	This represents the handle ID of the PDU that contains the global time information.		
Multiplicity	1		
Type	EcucIntegerParamDef (Symbolic Name generated for this parameter)		
Range	0 .. 65535		
Default value	--		
Post-Build Variant Value	true		
Value Configuration Class	***Pre-compile time***	X	All Variants
	Link time	--	
	Post-build time	--	
Scope / Dependency	scope: local		

SWS Item	**ECUC_FrTSyn_00020 :**		
Name	FrTSynGlobalTimePduRef		
Description	This represents the reference to the Pdu taken to transmit the global time information. The global time master of a global time domain acts as the sender of the Pdu while all the time slaves are supposed to receive the Pdu.		
Multiplicity	1		
Type	Reference to [Pdu]		
Post-Build Variant Value	true		
Value Configuration Class	***Pre-compile time***	X	All Variants
	Link time	--	
	Post-build time	--	
Scope / Dependency	scope: local		

No Included Containers

10.2.11 FrTSynGlobalTimeSlave

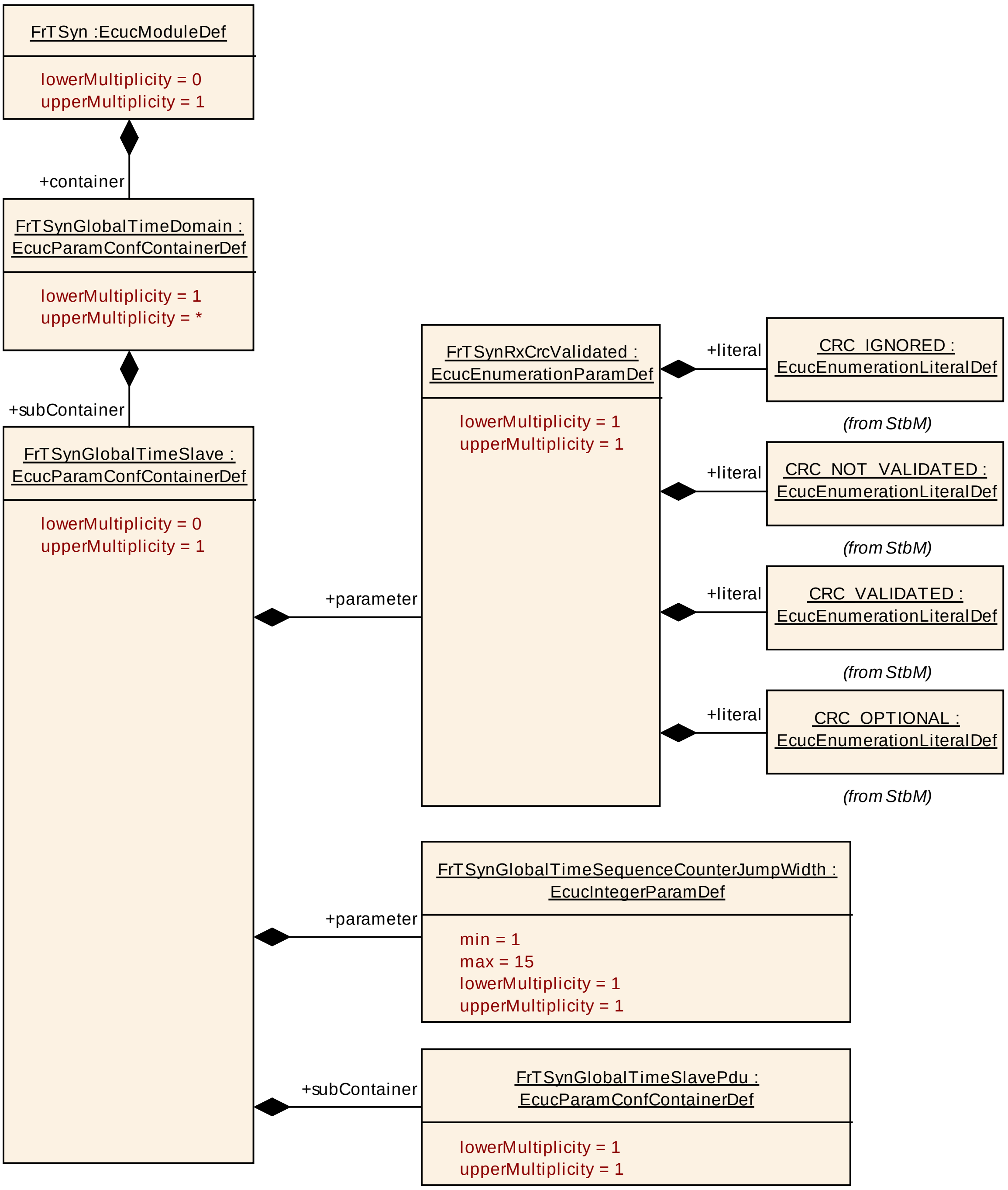
SWS Item	**ECUC_FrTSyn_00010 :**		
Container Name	FrTSynGlobalTimeSlave		
Description	This represents the time slave for the enclosing global time domain.		
Post-Build Variant Multiplicity	true		
Multiplicity Configuration Class	***Pre-compile time***	X	All Variants
	Link time	--	
	Post-build time	--	
Configuration Parameters			

SWS Item	**ECUC_FrTSyn_00022 :**	
Name	FrTSynGlobalTimeSequenceCounterJumpWidth	
Description	The SequenceCounterJumpWidth specifies the maximum allowed gap of the Sequence Counter between two SYNC resp. two OFS messages.	
Multiplicity	1	
Type	EcucIntegerParamDef	
Range	1 .. 15	
Default value	--	

Post-Build Variant Value	true		
Value Configuration Class	***Pre-compile time***	X	All Variants
	Link time	--	
	Post-build time	--	
Scope / Dependency	scope: local		

SWS Item	**ECUC_FrTSyn_00017 :**		
Name	FrTSynRxCrcValidated		
Description	This parameter controls whether or not CRC validation shall be supported.		
Multiplicity	1		
Type	EcucEnumerationParamDef		
Range	CRC_IGNORED	The Timesync module accepts Time Synchronization messages, which are CRC secured (without actually validating the CRC) and those, which are not CRC secured. That means, the Timesync module ignores the CRC.	
	CRC_NOT_VALIDATED	The Timesync module accepts only Time Synchronization messages, which are not CRC secured. All other Time Synchronization messages are ignored.	
	CRC_OPTIONAL	The Timesync module accepts only Time Synchronization messages which are not CRC secured and Time Synchronization messages which are CRC secured and have the correct CRC. All other Time Synchronization messages are ignored.	
	CRC_VALIDATED	The Timesync module accepts only Time Synchronization messages, which are CRC secured and have the correct CRC. All other Time Synchronization messages are ignored.	
Post-Build Variant Value	true		
Value Configuration Class	***Pre-compile time***	X	All Variants
	Link time	--	
	Post-build time	--	
Scope / Dependency	scope: local		

Included Containers		
Container Name	***Multiplicity***	***Scope / Dependency***
FrTSynGlobalTimeSlavePdu	1	This container carries all properties required to configure the PDU received by the time slave for the given global time domain.


FrTSyn :EcucModuleDef
lowerMultiplicity = 0
upperMultiplicity = 1
+container
FrTSynGlobalTimeDomain : EcucParamConfContainerDef
lowerMultiplicity = 1
upperMultiplicity = *
+subContainer
FrTSynGlobalTimeSlave : EcucParamConfContainerDef
lowerMultiplicity = 0
upperMultiplicity = 1
+parameter
FrTSynRxCrcValidated : EcucEnumerationParamDef
lowerMultiplicity = 1
upperMultiplicity = 1
+literal
CRC_IGNORED : EcucEnumerationLiteralDef
(from StbM)
+literal
CRC_NOT_VALIDATED : EcucEnumerationLiteralDef
(from StbM)
+literal
CRC_VALIDATED : EcucEnumerationLiteralDef
(from StbM)
+literal
CRC_OPTIONAL : EcucEnumerationLiteralDef
(from StbM)
+parameter
FrTSynGlobalTimeSequenceCounterJumpWidth : EcucIntegerParamDef
min = 1
max = 15
lowerMultiplicity = 1
upperMultiplicity = 1
+subContainer
FrTSynGlobalTimeSlavePdu : EcucParamConfContainerDef
lowerMultiplicity = 1
upperMultiplicity = 1

10.2.12 FrTSynGlobalTimeSlavePdu

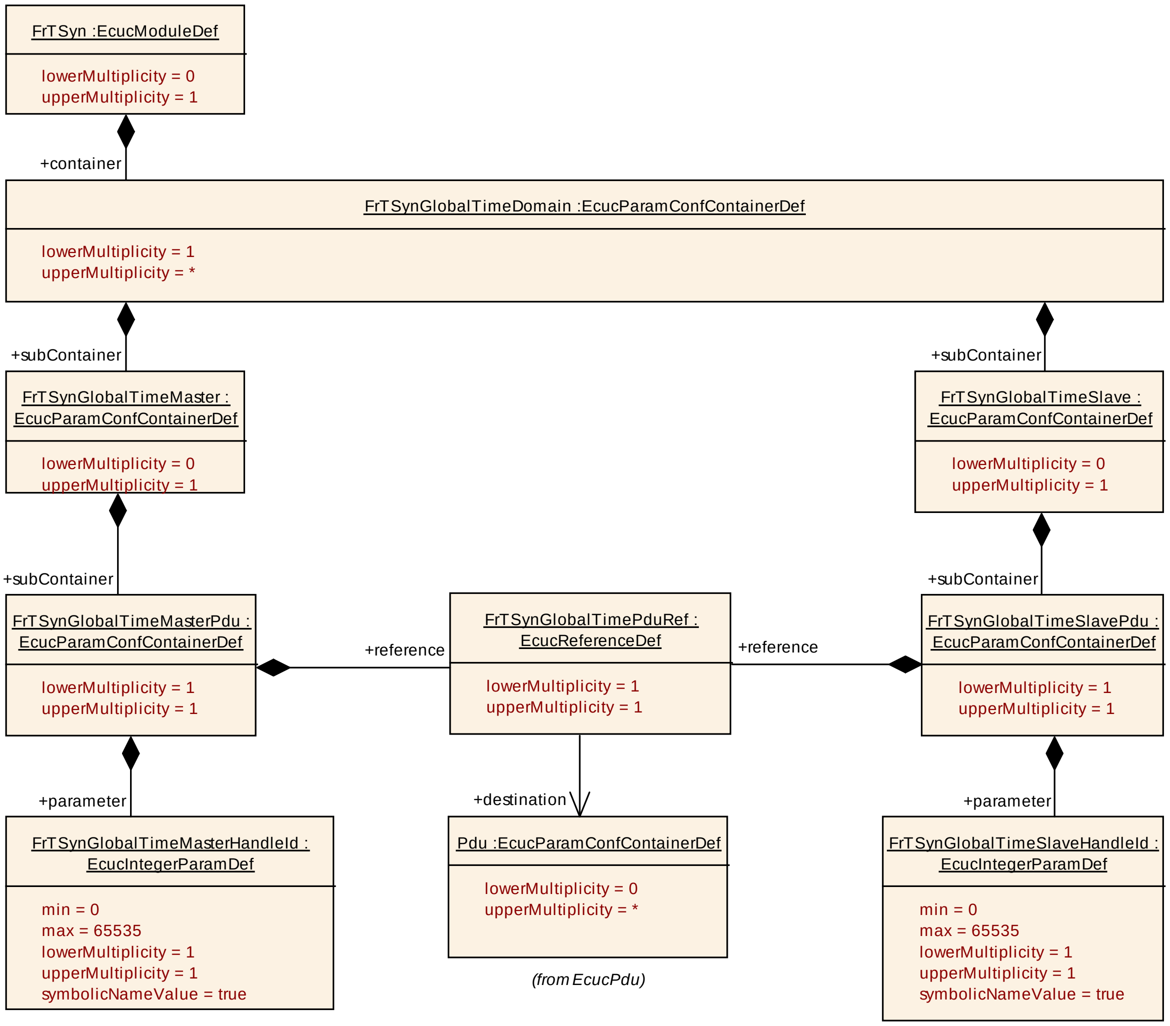
SWS Item	**ECUC_FrTSyn_00012 :**
Container Name	FrTSynGlobalTimeSlavePdu
Description	This container carries all properties required to configure the PDU received by the time slave for the given global time domain.
Configuration Parameters	

SWS Item	**ECUC_FrTSyn_00011 :**
Name	FrTSynGlobalTimeSlaveHandleId

Description	This represents the handle ID of the PDU that contains the global time information.		
Multiplicity	1		
Type	EcucIntegerParamDef (Symbolic Name generated for this parameter)		
Range	0 .. 65535		
Default value	--		
Post-Build Variant Value	true		
Value Configuration Class	***Pre-compile time***	X	All Variants
	Link time	--	
	Post-build time	--	
Scope / Dependency	scope: local		

SWS Item	**ECUC_FrTSyn_00021 :**		
Name	FrTSynGlobalTimePduRef		
Description	This represents the reference to the Pdu taken to transmit the global time information. The global time master of a global time domain acts as the sender of the Pdu while all the time slaves are supposed to receive the Pdu.		
Multiplicity	1		
Type	Reference to [Pdu]		
Post-Build Variant Value	true		
Value Configuration Class	***Pre-compile time***	X	All Variants
	Link time	--	
	Post-build time	--	
Scope / Dependency	scope: local		

No Included Containers



10.3 Published Information

For details, refer to the chapter 10.3 “Published Information” in *SWS_BSWGeneral*.