

Machine Learning Bootcamp

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August 19, 2021

Overview

- Paper name: VERY DEEP CONVOLUTIONAL NEURAL NETWORKS FOR RAW WAVEFORMS.
- Authors: Wei Dai, Chia Dai, Shuhui Qu, Juncheng Li, Samarjit Das.
- Released: 1 Oct 2016

Understanding the problem

Item 1

Challenging and time intensive to find the right feature representation of the speech.

Might not be optimal for the predictive task.

Discuss the use of waveform directly.

Item 2

Learning acoustic models directly from the raw waveform is computational intensive.

Simpler representation allows the model to jointly learn the features and do the classification.

Item 3

Fully convolutional net reduces the number of parameters.

Forces learn of good representation in the convolutional layer.

Deep network to deal with the long audio sequences.

Proposed Solution

Input

- Waveform representation.

Models

- Deep fully convolutional network.

Additional layers

- Batch normalisation layers.
- Residual blocks.

Task

- Environmental sound recognition

They did the following to allow very deep network

Batch normalisation

Fights exploding and vanishing gradients

Residual connection

Allows the selection of more simpler models

Glorot initialisation

Fights exploding and vanishing gradients

Small filter size

Provides larger receptive field with less number of parameters.

Dataset

- URBANSOUND8K DATASET.
- 8732 labeled sound excerpts (≤ 4 s).
- 10 classes: air_conditioner, car_horn, children_playing, dog_bark, drilling, engine_idling, gun_shot, jackhammer, siren, and street_music.
- Divided into 10 folds.
- Warning: don't reshuffle the folds; will be incorrectly placing related samples in both the train and test sets; and hence it will provide wrong results.

Experiments

Models

M3 (0.2M)	M5 (0.5M)	M11 (1.8M)	M18 (3.7M)	M34-res (4M)
Input: 32000x1 time-domain waveform				
[80/4, 256]	[80/4, 128]	[80/4, 64]	[80/4, 64]	[80/4, 48]
Maxpool: 4x1 (output: $2000 \times n$)				
[3, 256]	[3, 128]	[3, 64] \times 2	[3, 64] \times 4	$\begin{bmatrix} 3, 48 \\ 3, 48 \end{bmatrix} \times 3$
Maxpool: 4x1 (output: $500 \times n$)				
	[3, 256]	[3, 128] \times 2	[3, 128] \times 4	$\begin{bmatrix} 3, 96 \\ 3, 96 \end{bmatrix} \times 4$
	Maxpool: 4x1 (output: $125 \times n$)			
	[3, 512]	[3, 256] \times 3	[3, 256] \times 4	$\begin{bmatrix} 3, 192 \\ 3, 192 \end{bmatrix} \times 6$
	Maxpool: 4x1 (output: $32 \times n$)			
		[3, 512] \times 2	[3, 512] \times 4	$\begin{bmatrix} 3, 384 \\ 3, 384 \end{bmatrix} \times 3$
Global average pooling (output: $1 \times n$)				
Softmax				

Table 1: Architectures of proposed fully convolutional network for time-domain waveform inputs. M3 (0.2M) denotes 3 weight layers and 0.2M parameters. [80/4, 256] denotes a convolutional layer with receptive field 80 and 256 filters, with stride 4. Stride is omitted for stride 1 (e.g., [3, 256] has stride 1). [...] $\times k$ denotes k stacked layers. Double layers in a bracket denotes a residual block and only occur in M34-res. Output size after each pooling is written as $m \times n$ where m is the size in time-domain and n is the number of feature maps and can vary across architectures. All convolutional layers are followed by batch normalization layers, which are omitted to avoid clutter. Without fully connected layers, we do not use dropout [14] in these architectures.

What I did so far

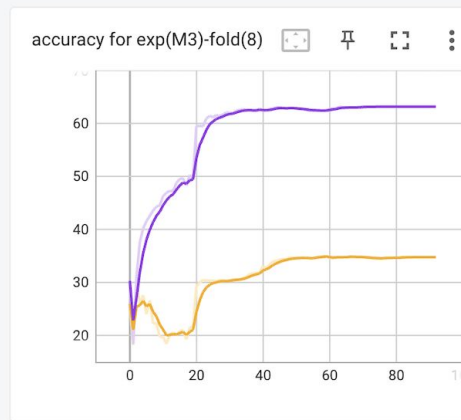
Model implementation

I implemented all the aforementioned architectures and test all the architectures with 10 epochs. For experiment M3 I tested it with 100 epochs and achieved accuracy of 32% compared the paper's accuracy of 51% achieved after 400 epochs.

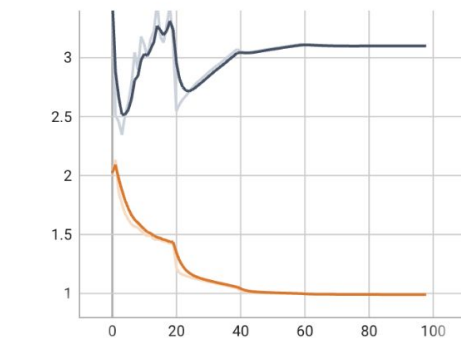
Remarks:

- I cannot guarantee that I will get the same results but the first results is promising.

accuracy for exp(M3)-fold(8)



loss for exp(M3)-fold(2)

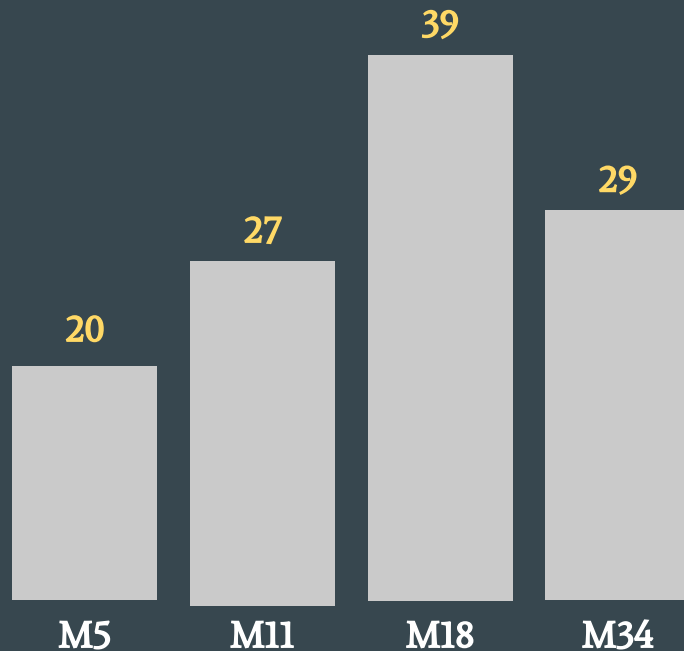


Results

The test accuracy of the different models after 10 epochs of training with 8 folds and test on fold 10.

Remarks:

- This doesn't describe the performance of the models. It just a sanity check to make sure the modes are working and no problem is occurring.



Future Work

- Repeat the experiments with 400 epochs to compare the results.
- Change the number of the filters and/or the number of the layers and see the results.
- Compare the results with FC network.
- Test the same models with feature representation.

Thank you for your time !

Questions ?