

*"A C program is like a fast dance on a newly waxed dance floor by people carrying razors."*

- W. Ravens

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# CSE341

## Programming Languages

Lecture 4 – October 2019

Variables

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Largely adapted from V. Shmatikov, J. Mitchell and R.W. Sebesta

## Variables, Bindings and Scopes

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- Variables
- Initialization
- Constants
- Binding
- Type Checking
- Scope

## Variables

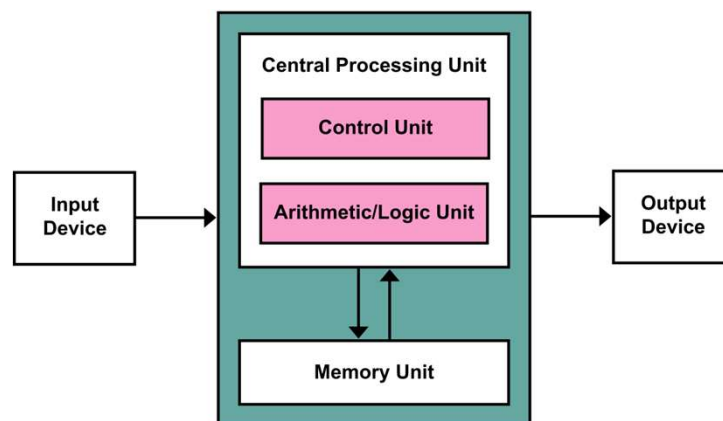
- Imperative languages are abstractions of von Neumann architecture
  - Memory / Storage
  - Processor / CPU
- Variable: an abstraction of a computer memory cell or collection of cells
- Variables are characterized by attributes
- Their design must consider
  - Location
  - Referencing
  - Scope
  - Lifetime
  - Type checking
  - Initialization
  - Type compatibility

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## Von Neumann Architecture



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## Turing Machine

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- Von Neumann computer implements a universal Turing machine
- It specifies sequential architectures...

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## Turing Machine

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- A mathematical tool equivalent to a digital computer
- Suggested by Turing in 1936
- The most widely used model of computation in computability and complexity theory
- Although simple, the machine can simulate any computer algorithm, no matter how complicated it is

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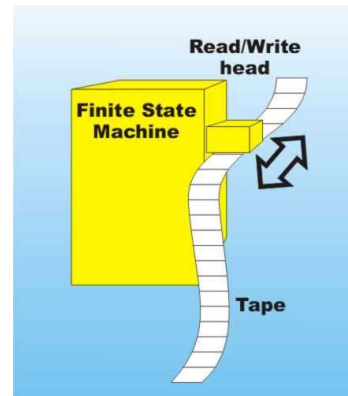
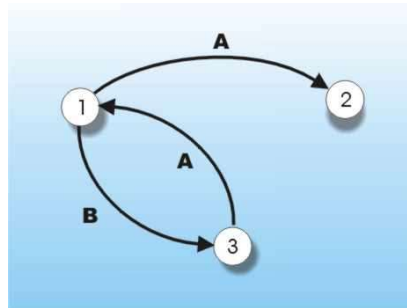
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## Turing Machine

Actions:

- Print something on the tape
- Move the tape right or left by one cell
- Change to a new state



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## Variables

- Imperative languages are abstractions of von Neumann architecture
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## Variable Attributes

- Variable is an abstraction of memory cell(s)
- Characterized by six attributes:
  - Name (usually)
  - Address (in memory)
  - Value (if initialized)
  - Type (range of values, interpretation, operations)
  - Lifetime
  - Scope
- Name - not all variables have them!

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## Characters

- Character Sets
  - 40 character BCD
  - 48 Fortran II
  - 128 ASCII characters
  - Unicode
  - Some Character Categories
    - <digit> -> 0|1|2|3|4|5|6|7|8|9
    - <lcletter> ->  
a|b|c|d|e|f|g|h|i|j|k|l|m|n|o|p|q|r|s|t|u|v|w|x|y|z
    - <ucletter> ->  
A|B|C|D|E|F|G|H|I|J|K|L|M|N|O|P|Q|R|S|T|U|V|W|X|Y|Z
    - <underscore> -> \_

American Standard Code for Information  
Interchange

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## Names

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- Set of characters
- Names, or identifiers, are used for variables, subprograms (or methods), types, classes, etc.
- Not names
  - Comments, line boundaries, white spaces
- Tokens
  - Punctuations, operators, numbers and other literals
  - Names (identifiers)
  - Keywords, reserved words

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## Variable Names

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- User-defined names
- Design issues for names:
  - Maximum length?
  - Are connector characters allowed?
  - Are names case sensitive?
  - Are some words reserved words or keywords?
  - ONLY UPPERCASE LETTERS ALLOWED?

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## Name Length

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- If too short, they can't explain the meaning
  - Readability, writability
- If too long
  - ?
- Language examples:
  - FORTRAN I: maximum 6
  - COBOL: maximum 30
  - FORTRAN 90 and ANSI C: maximum 31
  - Ada and Java: no limit, all are significant
  - C++: no limit, but implementers often impose one
- What is a good maximum length?

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## Connectors / Non-Letter Characters

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- Pascal `_`
  - underscore only
- Modula-2, and FORTRAN 77
  - none allowed
- Java
  - `$, _` (but `$` is by the system used for inner classes)
- Common Lisp
  - many, including `*, +, -, _` ...
- Advantages of having connectors?
- Disadvantages of having connectors?

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## Case Sensitivity in Variable Names

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- Many languages **are not** case sensitive
- C, C++, and Java names are case sensitive
- Common Lisp: case sensitive (default)
- Prolog: case of first character determines whether it's constant or variable!
- Disadvantage: readability
  - names that look alike are different
- C++ and Java: predefined names are mixed case
  - e.g. `IndexOutOfBoundsException`)
- Effects on writability?

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## Named Constants

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- **Named constant**
  - variable bound to a value only when it is bound to storage
- Advantages:
  - readability and modifiability
- Used to parameterize programs
- The binding of values to constants can be either static (called **manifest constants**) or dynamic
  - Pascal: literals only
  - FORTRAN 90: constant-valued expressions
  - Ada, C++, and Java: expressions of any kind

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## Variable Addresses

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- **Memory address** associated with variable
  - also called l-value
- Location may change during execution
  - i.e. may have different addresses at different times
- **Aliases**
  - variable names that refer to the same memory location
- Aliases often reduce readability
  - program readers must remember that changing value of one variable means a change of all others

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## Variable Aliases

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- Created by
  - pointers
  - reference variables
  - C and C++ unions
  - Pascal **variant-records**
  - and by parameters!
- Original reasons for aliases are no longer valid
  - memory limits forced re-use of space in FORTRAN
- Instead, use **dynamic allocation**

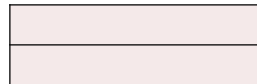
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## Variable Types and Values

- **Type** - determines the
  - range of values
  - set of operations that are defined for the variable
  - interpretation of bit patterns
  - for floating point, determines the precision
- **Value** - contents of the memory location associated with the variable
  - r-value (when appearing on right side of assignment)
- **Abstract memory cell** – (graphical) representation of collection of cells associated with a variable



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## The Concept of Binding

- The **l-value** = address
- The **r-value** = value
- **Binding** = association
  - for a variable, the association of l-value to r-value
- **Binding time**
  - time (during execution) when l-value is associated with r-value

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## Variable Initialization

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- **Initialization**
  - the initial binding of a variable to a value
- Often done with the **declaration statement**
  - e.g., in Java
    - `int sum = 0;`
  - e.g., in Lisp
    - `(defvar sum 0)`
  - e.g., in Clojure
    - ?

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## Possible Binding Times

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- Language design time
  - e.g., bind operator symbols to operations
- Language implementation time
  - e.g., bind floating point type to a representation
- Compile time
  - e.g., bind a variable to a type in C or Java
- Load time
  - e.g., bind a FORTRAN 77 variable to a memory cell, or
  - bind static variable in C or Java
- Runtime
  - e.g., bind a non-static local variable to a memory cell

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## Static vs. Dynamic Binding

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- Static
  - first occurs before run time and
  - remains unchanged throughout program execution
- Dynamic
  - first occurs during execution, or
  - can change during execution of the program.

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## Type Bindings

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- How is a variable's type specified?
- When does the binding take place?
- If static, type specified by either
  - explicit declaration or
  - implicitly

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## Implicit vs. Explicit Declaration

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- Explicit type declaration
  - as program statement
- Implicit type declaration
  - default mechanism - at the first appearance in the program
  - e.g., in FORTRAN, BASIC, and Perl
- Type Inferencing (ML, Miranda, and Haskell)
  - Type is determined from the context of the reference
- Unification (Prolog)
  - Variables are unified with other variables or constants during the resolution process
- Advantage of implicit declaration: writability
- Disadvantage: reliability

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## Dynamic Binding

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- JavaScript, PHP, Common Lisp
- Specified through an assignment statement e.g., JavaScript
  - `list = [2, 4.33, 6, 8];`
  - `list = 17.3;`
- Advantage: flexibility (generic program units)
- Disadvantages:
  - Speed penalty for type checking and interpretation
  - Type error detection by the compiler is more difficult

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## Variable Lifetime

- **Lifetime**
  - the time during which it is bound to a particular memory cell
- **Allocation**
  - getting a cell from a pool of available cells
- **De-allocation**
  - returning a cell back into the pool

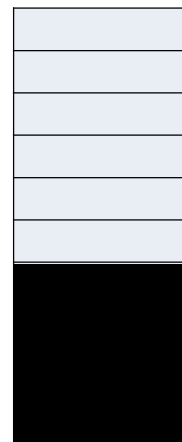
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## Static Variables

- **Static variables**
  - bound to memory cells before program execution begins
  - remain bound to same memory cells until program execution terminates
- **Example**
  - all FORTRAN 77 variables
  - C static variables
- **Advantages:**
  - efficiency (direct addressing)
  - history-sensitive subprogram support
- **Disadvantage:**
  - less flexible (no recursion)



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## Stack Dynamic Variables

- Storage bindings are created for variables when their declaration statements are elaborated (storage allocation and binding)
  - Allocated from the run-time stack
  - De-allocate after execution (garbage collection)
  - Can happen at the beginning of block or anywhere
- Advantage:
  - allows recursion
  - conserves storage – allocate when and where needed
- Disadvantages (compared to static vars):
  - Overhead of allocation and de-allocation
  - Subprograms cannot be history sensitive
  - Indirect addressing (longer time)

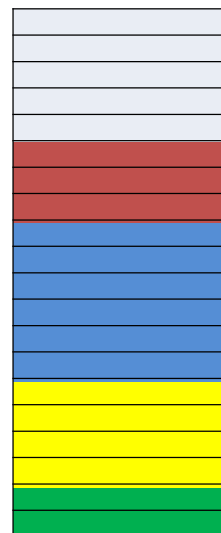
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## Runtime Stack (Dynamic)

- Stack-dynamic
  - allocation during execution at declaration elaboration time



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## Stack Dynamic Variables

- If scalar, all attributes except address are statically bound
  - e.g. local variables in C subprograms and Java methods
- Examples
  - Variables defined in methods in Java, C, C#

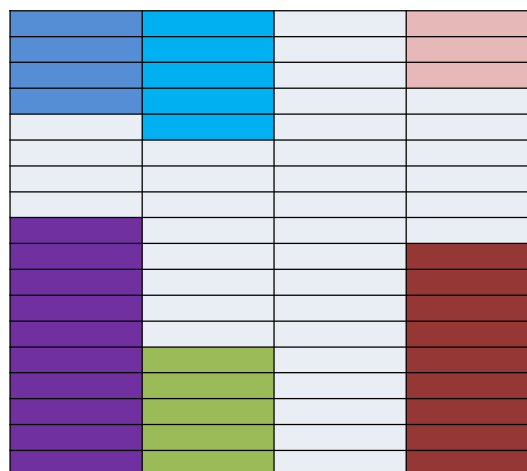
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## Heap Variables (Dynamic)

- Implicit
  - Automatic
- Explicit
  - programmer's instruction



The heap is a collection of highly disorganized storage cells for unpredictable use...

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## Explicit Heap-Dynamic Variables

- Nameless abstract memory cells (heap)
  - Allocated and de-allocated by explicit directives
  - Specified by the programmer
  - Takes effect during execution
  - Referenced only through pointers or references
    - e.g. dynamic objects in C++ (via new and delete)
 

```
int * i;
i = new int;
...
delete i;
```
    - all objects in Java
- Advantage:
  - provides for dynamic storage management (flexibility)
- Disadvantage:
  - inefficient by comparison (cost of reference)
  - reliability must be shown

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## Implicit Heap-Dynamic Variables

- Bound to heap storage automatically
  - Only when they are assigned values
  - All attributes are bound every time they are assigned
- Allocation and de-allocation caused by assignments
  - e.g. all variables in APL
  - all strings and arrays in Perl and JavaScript
- Example: Java statement “highs = [74, 84, 490, 44, 45];”
  - “highs” is now an array ...
- Advantage:
  - Flexibility
  - Writability
- Disadvantages:
  - Inefficient, because all attributes are dynamic
  - More work to do error detection

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## Variable Bindings

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- Static
  - E.g., C static variables
- Stack dynamic
  - E.g., C method variables
- Heap dynamic variables
  - Explicit Heap-Dynamic Variables
    - E.g., dynamic objects in C++ (new and delete)
  - Implicit Heap-Dynamic Variables
    - E.g., arrays in JavaScript

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## Variables

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- Six attributes
  - Name (usually)
  - Address (in memory)
  - Value (if initialized)
  - Type (range of values, interpretation, operations)
  - Lifetime
  - Scope

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## Type Checking

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- Type checking ensures that the operands and the operator are of compatible types
- Generalized to include subprograms and assignments
- Compatible type is either
  - legal for the operator, or
  - language rules allow it to be converted to a legal type
- Coercion
  - Automatic (implicit) conversion
- Type error
  - Application of an operator to an operand of incorrect type
- Nearly all type checking can be static for static type bindings
- Type checking must be dynamic for dynamic type bindings

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## Strong Typing

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- Strongly typed programming language
  - PL where type errors are always detected
- Advantages:
  - Reliability
  - Detection of the misuses of variables that result in type errors
- Disadvantages:
  - Increased size of code
  - Slower development - declarations
  - Reduced writability
  - Exception handling may be more complicated

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## Strong Typing in PLs

- Examples:
  - FORTRAN 77 is not: parameters, EQUIVALENCE
  - Pascal is not: variant records
  - C and C++ are not: parameter type checking can be avoided; unions are not type checked
  - Ada is, almost (UNCHECKED CONVERSION is loophole)
  - Java is similar to Ada
- Coercion rules affect strong typing
  - can weaken it considerably (C++ versus Ada)
  - C++ is less reliable than Ada (less coercion)
- Java has just half the assignment coercions of C++
- Java's strong typing is still less effective than in Ada

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## Coercion in Java

```
short x = 2;
x += 2.2;
```

```
short x = 3;
x = (short)(x + 4.6);
```

```
void mymethod() {
    int a, b, c;
    float d;
    ...
    a = b * d;
    ...
}
```

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## Type Compatibility

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- The result of two variables being of compatible types is that either one can have its value assigned to the other
- Two different type compatibility methods:
  - Name compatibility
  - Structure type compatibility
- Most languages use combinations of the different techniques
- There are some variations of these two methods

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## Name Type Compatibility

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- Variables have compatible types if they are either
  - in the same declaration
  - or in declarations that use the same type name
- Easy to implement but highly restrictive
  - Sub-ranges of integer are not compatible with integer (as in Pascal)
  - Formal parameters must be the same type as their corresponding actual parameters (Pascal)

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## Structure Type Compatibility

- Variables have compatible types if their types have identical structures
  - More flexible
  - But harder to implement
    - Because of structured types (comparison of whole structures instead of names)
    - Others are much simpler
- Questions:
  - Structurally the same record types with different field names?
  - Array types with the same base type but different subscripts? E.g. [1..10] vs. [0..9]
  - Enumeration types whose components are spelled differently?
- With structural type compatibility, you can not differentiate between types of the same structure
  - E.g. different units of speed, when both are floating point

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## Type Compatibility Examples

- Pascal: usually structure, but in some cases name is used (formal parameters)
- C: structure, except for records
- Ada: restricted form of name
  - Derived types allow types with the same structure to be different
  - Anonymous types are all unique, even in:
 

A, B : array (1..10) of INTEGER

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## C# and Implicit Typed Local Variables

Local variables can be given an inferred "type" of **var** instead of an explicit type. The **var** keyword instructs the compiler to infer the type of the variable from the expression on the right side of the initialization statement.

```
// i is compiled as an int
var i = 5;
// s is compiled as a string
var s = "Hello";
// a is compiled as int[]
var a = new[] { 0, 1, 2 };
// expr is compiled as IEnumerable<Customer>
// or perhaps IQueryable<Customer>
var expr =
    from c in customers
    where c.City == "London"
    select c;
// anon is compiled as an anonymous type
var anon = new { Name = "Terry", Age = 34 };
// list is compiled as List<int>
var list = new List<int>();
```

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## Any Advantage

There's no problem with declaring types for locals, but the compiler can work it out, so it's redundant information to add types...

Using **var** does not change the meaning of a program, only its textual representation....

```
public static IMyType GetGatewayManager() {
    var container = GetContainer();
    var gatewayManager = container.Resolve<IMyType>();
    return gatewayManager;
}
```

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## Choice

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Summing up, my advice is:

- Use var when you have to; when you are using anonymous types.
- Use var when the type of the declaration is obvious from the initializer, especially if it is an object creation. This eliminates redundancy.
- Consider using var if the code emphasizes the semantic "business purpose" of the variable and downplays the "mechanical" details of its storage.
- Use explicit types if doing so is *necessary* for the code to be correctly understood and maintained.
- Use descriptive variable names regardless of whether you use "var". Variable names should represent the semantics of the variable, not details of its storage; "decimalRate" is bad; "interestRate" is good.

<http://blogs.msdn.com/b/ericlippert/archive/2011/04/20/uses-and-misuses-of-implicit-typing.aspx>