

*"If it looks like a duck, quacks like a duck, but needs batteries – you probably have the wrong abstraction."*  
 - The Internets on the Liskov Substitution Principle

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# CSE341

## Programming Languages

Lecture 8 – November 2019

ADT

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Slides are taken from C. Li & W. He

## Voldemort Type

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```
int main()
{
    auto createVoldemortType = []           // use lambda auto return type
    {
        struct Voldemort                   // locally defined type
        {
            int getValue() { return 21; }
        };
        return Voldemort{};
    };
    createVoldemortType::Voldemort c = createVoldemortType();
    createVoldemortType::Voldemort c = createVoldemortType();
    Voldemort c = createVoldemortType();
}
```

Source: <http://videocortex.io/2017/Bestiary/>

## Voldemort Type

---

```

int main()
{
    auto createVoldemortType = []           // use lambda auto return type
    {
        struct Voldemort                   // locally defined type
        {
            int getValue() { return 21; }
        };
        return Voldemort{};
    };
    // createVoldemortType().Voldemort c = createVoldemortType(); // no, error
    // createVoldemortType::Voldemort c = createVoldemortType(); // nope
    // Voldemort c = createVoldemortType(); // also nope
    auto unnameable = createVoldemortType(); // works!
    decltype(unnameable) unnameable2;        // but, can be used with decltype
    return unnameable.getValue() +          // can use unnameable API
           unnameable2.getValue();
}

```

Source: <http://videocortex.io/2017/Bestiary/>

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## Abstract Data Types

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## Data Types

- Predefined
- Type constructors: build new data types
- How to provide “queue”?
  - What should be the data values?
  - What should be the operations?
  - How to implement (data representation, operations)?

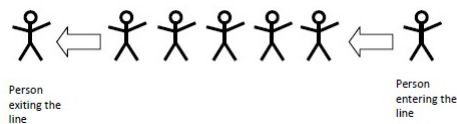
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## Queue

- A common abstract data type is a queue.



- A queue is a first in, first out (FIFO) structure or in the other sense, a last in, last out (LILO) structure. A queue is sometimes generalized as a structure where insertion (enqueue) occur at one end and removal (dequeue) occurs at the other end.

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## Queue Implementation

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## What are inadequate here?

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- **The operations are not associated with the data type**
  - You can use the operation on an invalid value
- **Users see all the details: direct access to data elements, implementations**
  - Implementation dependent
  - Users can even mess up with things

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## What do we want?

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- For basic types:
  - 4 bytes or 2 bytes, users don't need to know.
  - Can only use predefined operations.
- Similarly, for the "Queue" data type:  
?

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## Abstract Data Types

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- Built-in types have important properties that "abstract" away the implementation: use of int and its operations (+, \*, etc.) normally do not require knowledge of bit patterns (2's complement? 4 bytes?)
- User-defined types do not in general have this property: internal structure is visible to all code
- Use of internal structure makes it difficult to change later
- Operations on data (except the most basic) not specified and often hard to find

Kenneth C. Loudon, 2005

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## Abstract Data Types

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- A mechanism of a programming language designed to imitate the abstract properties of a built-in type as much as possible
- Must include a specification of the operations that can be applied to the data
- Must hide the implementation details from client code
- These properties are sometimes called encapsulation & information hiding (with different emphases)

Kenneth C. Loudon, 2005

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## Abstract Data Type

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- **Encapsulation:**  
All definitions of allowed operations for a data type in one place.
- **Information Hiding:**  
Separation of implementation details from definitions. Hide the details .

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## Algebraic Specification of ADT

- **Syntactic specification (signature, interface):**  
the name of the type, the prototype of the operations
- **Semantic specification (axioms, implementation):**  
guide for required properties in implementation  
mathematical properties of the operations

They don't specify:

- data representation
- implementation details

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## Syntactic Specification

```
type queue(element) imports boolean
operations:
  createq:    queue
  enqueue:    queue × element → queue
  dequeue:    queue → queue
  frontq:     queue → element
  emptyq:     queue → boolean
```

- **imports:** the definition queue needs boolean
- **Parameterized data type** (element)
- **createq:** not a function, or viewed as a function with no parameter

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## Syntactic Specification

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```

type xue(element) imports boolean
operations:
  createq:    xue
  enqueue:    xue × element → queue
  dequeue:    xue → queue
  frontq:     xue → element
  emptyq:     xue → boolean

```

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## Algebraic Specification

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```

variables: q: queue; x: element
axioms:
  emptyq(createq)      = true
  emptyq(enqueue(q,x)) = false
  frontq(createq)       = error
  frontq(enqueue(q,x)) = if emptyq(q) then x
                           else frontq(q)
  dequeue(createq)      = error
  dequeue(enqueue(q,x)) = if emptyq(q) then q
                           else enqueue(dequeue(q), x)

```

- error axiom (exceptions)

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## Stack

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```

type stack(element) imports boolean
operations:
  createstk : stack
  push      : stack × element → stack
  pop       : stack → stack
  top       : stack → element
  emptystk  : stack → boolean

variables: s: stack; x: element
axioms:
  emptystk(createstk)    = true
  emptystk(push(s,x))    = false
  top(createstk)         = error
  top(push(s,x))         = x
  pop(createstk)         = error
  pop(push(s,x))         = s

```

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## Axioms

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- How many axioms are sufficient for proving all necessary properties?

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## Some Heuristics

```

type stack(element) imports boolean
operations:
  createstk : stack
  push      : stack × element → stack
  pop       : stack → stack
  top       : stack → element
  emptystk  : stack → boolean

variables: s: stack; x: element
axioms:
  emptystk(createstk)      = true
  emptystk(push(s,x))      = false
  top(createstk)           = error
  top(push(s,x))           = x
  pop(createstk)           = error
  pop(push(s,x))           = s

```

**Constructor:**  
createstk  
push

**Inspector:**  
pop  
top  
emptystk

$2 * 3 = 6$  rules

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## Binary Search Tree

```

type BST(element) imports boolean, int
operations:
  createbst : BST
  emptybst  : BST → boolean
  insert    : BST × element → BST
  delete    : BST × element → BST
  getRoot   : BST → element
  getHeight : BST → int
  max       : BST → element
  search    : BST × element → boolean

variables: t: bst; x: element
axioms:
  emptystk(createbst) = true
  ...

```

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## Other Examples of ADT

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- Stack
- Queue
- Tree
- Set
- Map
- Vector
- List
- Priority Queue
- Graph
- ...

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## Algebraic Specification Notes

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- Specifications are usually written in functional form with no side effects or assignment. So no "void" functions
- Specifications are often simplified to make axiom writing easier
  - E.g., in the stack example, pop does not return the top, only the (previously created) stack below the current top.
  - We could have written pop as “pop: stack  $\rightarrow$  element x stack”, but the axioms are more complex

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## ADT Language Mechanisms

- Most languages do not have a specific ADT mechanism – instead they have a more general module mechanism
- Specific ADT mechanisms
  - ML abstype – but newer module mechanism is more useful...
- General module mechanism: not just about a single data type and its operations
  - Separate compilation and name control: C, C++, Java
  - Ada, ML
- Class in OO languages (which has many of the properties needed by an ADT mechanism)

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## Modules

- **Module:** A program unit with a public interface and a private implementation; all services that are available from a module are described in its public interface and are exported to other modules, and all services that are needed by a module must be imported from other modules.
- A module offers general services, which may include types and operations on those types, but are not restricted to these.
- Modules have nice properties:
  - A module can be (re)used in any way that its public interface allows.
  - A module implementation can change without affecting the behavior of other modules.
- In addition to ADT, module supports structuring of large programs: Separate compilation and name control

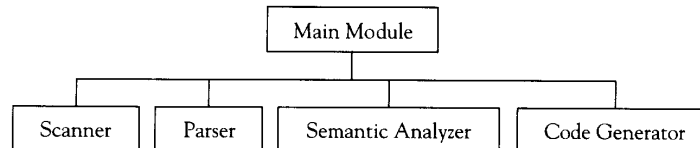
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## Modules

- Modules are the principle mechanism used to decompose large programs
- Example – a compiler:



- Modules usually offer an additional benefit: names within one module do not clash with names in other modules
- Modules usually have a close relationship to separate compilation

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## Modules

- Languages that have comprehensive module mechanisms:
  - Ada, where they are called packages (not to be confused with Java packages)
  - ML, where they are called structures
- Languages that have weak mechanisms with some module-like properties:
  - C++, where they are called namespaces
  - Java, where they are called packages
- Languages with no module mechanism:
  - C (but modules can be imitated using separate compilation)
  - Pascal

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## C++ Namespaces & Java Packages

- C++ and Java do not have modules in the sense of Ada and ML: classes are used instead
- C++ and Java do have mechanisms for controlling name clashes and organizing code into groups: namespaces in C++, packages in Java.
- Clients must use similar dot notation as in Ada and ML to reference names in namespaces/packages.
- Each of these languages has a mechanism for automatically dereferencing names:
  - Ada: use
  - ML: open
  - C++: using [namespace]
  - Java: import
- Only Ada has explicit dependency syntax (keyword with). Java class loader automatically searches for code. C++ requires textual inclusions for declarations, linker must search for code. ML "compilation manager" does this too (not in ML specification).

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## C: Separate Compilation

- queue.h : header file

```

#ifndef QUEUE_H
#define QUEUE_H

struct Queuerep;
typedef struct Queuerep * Queue;
Queue createq(void);
Queue enqueue(Queue q, void* elem);
void* frontq(Queue q);
Queue dequeue(Queue q);
int emptyq(Queue q);

#endif

```

Incomplete type:  
Separate implementation

Simulate  
Parameteric polymorphism

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## C: Separate Compilation

- queue.c: queue implementation

```
#include "queue.h"

struct QueueRep
{ void* data;
  Queue next;
};

Queue createq(void)
{ return 0;
}

void* frontq(Queue q)
{ return q->next->data;
}

...
```

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## C: Separate Compilation

- q\_user.C: client code

```
#include "queue.h"

int *x = malloc(sizeof(int));
int *y = malloc(sizeof(int));
int *z;
*x = 2;
*y = 3;

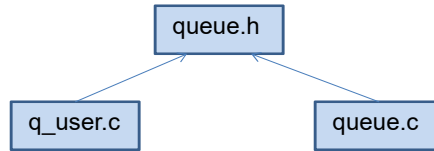
Queue q = createq();
q = enqueue(q, x);
q = enqueue(q, y);
q = dequeue(q);
z = (int*) frontq(q);
```

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## C: Separate Compilation



- Not real ADT

- casting, allocation: for parametric polymorphism
- header file directly incorporated into q\_user.c: definition / usage consistent
- data not protected: user may manipulate the type value in arbitrary ways
- The language itself doesn't help in tracking changes and managing compilation/linking: thus tools like `make`

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## C++: Namespaces

- queue.h:

```

#ifndef QUEUE_H
#define QUEUE_H
namespace MyQueue
{
    struct Queuerep;
    typedef struct Queuerep * Queue;
    Queue createq(void);
    ...
}
#endif
  
```

- queue.c:

```

#include "queue.h"

struct MyQueue::Queuerep
{ void* data;
  Queue next;
};
...
  
```

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## C++: Namespaces

- `q_user.cpp`:

```
#include "queue.h"

using std::endl;
using namespace MyQueue;

main() {
    int *x = malloc(sizeof(int));
    int *y = malloc(sizeof(int));
    int *z;
    *x = 2;
    *y = 3;
    Queue q = MyQueue::createq();
    q = enqueue(q, x);
    q = enqueue(q, y);
    q = dequeue(q);
    z = (int*) frontq(q);
    ...
}
```

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## Java: Packages

`Queue.java`:

```
package queues.myqueue;
...
```

`PQueue.java`:

```
package queues.myqueue;
...
```

`Q_user.java`:

```
import queues.myqueue.Queue;
import queues.myqueue.*;
queues.myqueue.Queue;
```

directory:  
queues/myqueue

class files:  
Queue.class, PQueue.class

queues/myqueue in  
CLASSPATH

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## Example

- Package java.util  
<http://java.sun.com/j2se/1.5.0/docs/api/java/util/package-summary.html>
- Interface Collection  
<http://java.sun.com/j2se/1.5.0/docs/api/java/util/Collection.html>
- Class PriorityQueue  
<http://java.sun.com/j2se/1.5.0/docs/api/java/util/PriorityQueue.html>
- boost: providing free peer-reviewed portable C++ source libraries  
<http://www.boost.org/>

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## boost

```
#include <boost/lambda/lambda.hpp>
#include <iostream>
#include <iterator>
#include <algorithm>

int main(){
    using namespace boost::lambda;
    typedef std::istream_iterator<int> in;

    std::for_each(
        in(std::cin), in(), std::cout << (_1 * 3) << " " );
    }

    for_each( InputIt first, InputIt last, UnaryFunction f )
```

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## boost lambda

The Boost Lambda Library (BLL) is a C++ template library, which implements a form of lambda abstractions for C++. The term originates from functional programming and lambda calculus, where a lambda abstraction defines an unnamed function. The primary motivation for the BLL is to provide flexible and convenient means to define unnamed function objects for STL algorithms.

Example:

```
for_each(a.begin(), a.end(), std::cout << _1 << ' ');
```

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## boost queue

```
// In header: <boost/lockfree/queue.hpp>

template<typename T, ... Options>
class queue {
public:
    // types
    typedef T value_type;
    typedef implementation_defined::allocator allocator;
    typedef implementation_defined::size_type size_type;

    // construct/copy/destruct
    queue(void);
    template<typename U>
        explicit queue(typename node_allocator::template rebind< U >::other const &);
    explicit queue(allocator const &);
    explicit queue(size_type);
    template<typename U>
        queue(size_type,
            typename node_allocator::template rebind< U >::other const &);
    ~queue(void);

    // public member functions
    bool is_lock_free(void) const;
    void reserve(size_type);
    void reserve_unsafe(size_type);
    bool empty(void);
    bool push(T const &);
    bool bounded_push(T const &);
    bool unsynchronized_push(T const &);
    bool pop(T &);
    template<typename U> bool pop(U &);
    bool unsynchronized_pop(T &);
    template<typename U> bool unsynchronized_pop(U &);
};
```

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## Problems with Modules

- Modules are not types
  - Modules sometimes used to imitate OO classes
  - Module interface usually contains types, whose representations may be exposed
- Modules are static
  - Modules are primarily compile-time artifacts
  - Use of a module to imitate a class (without exporting a type) results in only one available object
- Modules do not control values of exported types
  - Assignment can cause undesirable aliasing
  - Equality tests may not be appropriate
  - ML and Ada have some ability to control these (with effort)

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## Problems with Modules

- These problems can be (mostly) overcome by using OO classes, with modules relegated to code organization status (C++, Java)
- Significant problems still exist, even with OO :
  - Modules do not expose dependencies
    - Only Ada documents compilation dependencies in code (keyword with)
    - Hidden implementation dependencies can be worse: order relation is a common one
    - C++ does a particularly good job of hiding these
    - Ada uses constrained polymorphism
    - Java uses interfaces such as Comparable, Comparator
  - Modules do not express semantics
    - Universally ignored in today's languages
    - Useful for proving code correctness

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