# Shrikant Arvavasu

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# **Experience**

#### University of Michigan, Laboratory of Dr. Hun-Seok Kim

Ann Arbor, MI

**Research Assistant** (Computer Vision and LiDAR Perception)

May 2023 - Present

- Developed a temporal-sensor-fusion pipeline using a transformer backbone to process NuScenes LiDAR scans and camera frames. combining past detected boxes with LiDAR points, simulating real-time constraints in autonomous vehicle setups.
- Finetuned the state of the art BEVFusion for 3D bounding box detection by only utilizing 50% of the lidar beams, achieving a mAP of 0.601 and NDS of 0.63 on **NuScenes dataset** using subsampled point clouds.
- Developed novel diffusion sampling algorithms for inverse imaging problems, enhancing the quality and fidelity of the samples of latent diffusion models, achieving an FID score of 37.2, an improvement of 17.2% over the baseline model.

Skylark Labs Dover, DE

Machine Learning Intern (Representation Learning and Computer Vision)

June 2023 - August 2023

- Designed a caching mechanism using a pre-trained RegNet model to achieve a recall of 65% in self-learning new categories by storing multi-scale quantized features to recognize pre-trained classes.
- Improved the accuracy of the detector by 12% on detecting novel classes by training a detector with vector-quantized features.

SixSense Corporation Jalan Besar, Singapore

Computer Vision Intern (Automatic Augmentation and Multiclass Classification)

January 2022 - April 2022

- Trained a stochastic automatic augmentation framework based on Fast AutoAugment on a ResNet50 model to techniques for CIFAR-100 and ImageNet.
- Improved the average accuracy of the detector model by 2.3% by integrating the AutoAugment as a plugin-augumentation module for the company's defect detection dataset.

# **Independent Projects**

#### Autolabelling Driving Scenes in Cityscapes using DiNO and Segment Anything

November 2024

- Developed an ML pipeline to auto-label the Cityscapes dataset by combining Grounding-DINO (for 2D Rol extraction) with Grounding-SAM for semantic labels of road markings.
- Trained a YOLOv11-seg model for semantic segmentation of road markings, achieving robust performance with minimal manual annotation.
- · Exported the trained model to .engine format and integrated it into a TensorRT real-time inference pipeline for road marking detection, suitable for deployment on Jetson Devices.

#### Translating Cartoon to Natural Images using Stable Diffusion

November 2023

- Implemented an image-to-image translation system from cartoon Tom and Jerry images to real cat and mouse images using diffusion models.
- Implemented a Stable Diffusion utilizing BLIP-based text guidance to translate cartoon images to real-like images, achieving an FID score of 46.32 comparing the real-ness of the images generated.

#### **Block-Based Compressed Sensing for Natural Images and Videos**

January 2023

- Innovated a block-based compressed sensing approach for natural images and videos, leveraging deep learning inspired by the insights from the paper "Video Compressed Sensing Using a Convolutional Neural Network."
- Trained the model and achieved a compression factor of 0.1 on non-keyframes of videos of KITTI Dataset.

### **Technical Skills**

Languages/OS: Python, C, C++, Cuda, MATLAB, Shell Scripting, Linux, ROS

Developer Tools: OpenCV, SLURM, Git, Open3D, Docker

Machine Learning Tools: Pytorch, Pytorch-Lightning, MMDetection3D, Pandas, TensorRT

Technologies/Concepts: Deep Learning, Image Processing, Point Cloud Processing, 3D Computer Vision, Lidar-Voxel Algorithms, Sensor Fusion in AV systems, Generative AI, Diffusion Models

# **Education**

**University of Michigan** Ann Arbor, Michigan

Master of Science in Electrical and Computer Engineering Specialization: Signal & Image Processing and Machine Learning

National Institute of Technology Karnataka

2022 - 2024

GPA: 3.97/4.0

GPA: 3.87/4.0

Karnataka, India

Bachelor of Technology in Electronics and Communication Engineering

Honors: Machine Learning and Signal Processing

2018 - 2022