

Shrikant Arvasu

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Interests: 3D Object Detection, Lidar-based Object Detection, Deep Learning, Generative Vision, Diffusion Models, Image Segmentation,

Education

University of Michigan

Master of Science in Electrical and Computer Engineering
Specialization: Signal & Image Processing and Machine Learning

Aug 2022 – May 2024

Ann Arbor, Michigan
GPA: 3.97/4.0

National Institute of Technology Karnataka

Bachelor of Technology in Electronics and Communication Engineering
Honors: Machine Learning and Signal Processing

Aug 2018 – April 2022

Karnataka, India
GPA: 3.87/4.0

Experience

Kim's Lab, University of Michigan

Research Assistant (Computer Vision and GenAI)

Ann Arbor, Michigan

May 2023 – Present

- Currently working on a bounding box-based late temporal fusion method using a sparse-voxel transformer model to process NuScenes LiDAR input at 20 Hz.
- Finetuned the state of the art BEVFusion for 3D bounding box detection by only utilizing **50%** of the lidar beams, achieving a mAP of 0.601 and NDS of 0.63 on **NuScenes dataset** using subsampled point clouds.
- Developed novel diffusion sampling algorithms for inverse imaging problems, enhancing the quality and fidelity of the samples of **latent diffusion models**, achieving an FID score of 37.2, **an improvement of 17.2%** over the baseline model.

Skylark Labs

Machine Learning Intern (Representation Learning and Computer Vision)

Dover, Delaware

June 2023 – August 2023

- Designed a framework using a pre-trained RegNet model to achieve a **recall of 65% in self-learning** new categories by storing **multi-scale quantized features** to recognize pre-trained classes.
- Trained the neural network with a vector-quantized feature extractor to learn efficient multi-scale features of objects in natural scenes, enhancing the accuracy of the model by **12%** to detect objects from newly learned classes.
- Implemented the system to work on a **single core of a CPU** to run at about **3 fps** while storing features of new classes encountered.

Burris Lab, University of Michigan

Research Assistant (Computer Vision and Medical Imaging)

Ann Arbor, Michigan

August 2022 – April 2023

- Trained an **attention-UNET**-based model for aortic segmentation, enhancing the accuracy and efficiency of the Vascular Deformation Mapping pipeline, resulting in an **improvement of 3%** in the F1-score, particularly around aortic walls.
- Implemented corrections to an Elastix-based CT **Registration Pipeline**, improving the elastic registration performance of the pipeline for large deformations in the aortic walls. The corrections resulted in the detection of tissue growth by an improved **recall of 8%**.

SixSense Corporation

Computer Vision Intern (Automatic Augmentation and Multiclass Classification)

Jalan Besar, Singapore

January 2022 – April 2022

- Worked on detecting and classifying defects in semiconductor chips using Faster RCNN.
- Trained a stochastic **automatic augmentation** framework based on **Fast AutoAugment** on a ResNet50 model to techniques for several public datasets like CIFAR-100 and in-house datasets which improved the average accuracy by 2.3%. Integrated the automatic augmentation to the defect detection pipeline, improving the **accuracy by 1.4%**.

Projects

Translating Cartoon to Natural Images using Stable Diffusion

November 2023

- Implemented an image-to-image translation system from cartoon Tom and Jerry images to real cat and mouse images using diffusion models.
- Implemented a Stable Diffusion utilizing BLIP-based text guidance to translate cartoon images to real-like images, achieving an FID score of 46.32 comparing the real-ness of the images generated.

Block-Based Compressed Sensing for Natural Images and Videos

January 2023

- Innovated a block-based compressed sensing approach for natural images and videos, leveraging deep learning inspired by the insights from the paper "Video Compressed Sensing Using a Convolutional Neural Network."
- Trained the model and achieved a compression factor of 0.1 on non-keyframes of videos of KITTI Dataset.

Automatic Stroke Lesion Identification

November 2021

- Developed a method for segmenting stroke lesions in brain MRI volumes, utilizing deep 3-D convolutional networks (Residual-UNETs). This approach aimed to enhance the accuracy of stroke risk assessment in patients.
- Improved the lesion segmentation F1-score from 51.7% to 56.3% by incorporating brain parcellations into Grey Matter (GM) and White Matter (WM), improving the precision of diagnosis.

Technical Skills

Languages/OS: Python, C, C++, Cuda, MATLAB, Shell Scripting, Linux

Developer Tools: OpenCV, SLURM, Git, Open3D, ROS, Docker

Machine Learning Tools: Pytorch, Pytorch-Lightning, MMDetection3D, Pandas

Technologies/Concepts: Deep Learning, Image Processing, Computer Vision, Generative AI, Diffusion Models, Lidar Processing

Soft Skills: Professional Communication, Collaborative Working, Interpersonal Communication, Team Oriented, Fast Paced Learner

Publications

- A Chanchal, S Lal, D Barnwal, P Sinha, **S Arvasu**, and J Kini. *Evolution of LiverNet 2.x: Architectures for automated liver cancer grade classification from H&E stained liver histopathological images*. Multimedia Tools and Applications (2024), 83(1), 2791-2821.