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In [5]: #The optimal values of m and b can be actually calculated with way less effort
#than doing a linear regression.
#this is just to demonstrate gradient descent

from numpy import *

# y = mx + b
# m is slope, b is y-intercept
def compute_error_for_line_given_points(b, m, points):
    totalError = 0
    for i in range(0, len(points)):
        x = points[i, 0]
        y = points[i, 1]
        totalError += (y - (m * x + b)) ** 2
    return totalError / float(len(points))

def step_gradient(b_current, m_current, points, learningRate):
    b_gradient = 0
    m_gradient = 0
    N = float(len(points))
    for i in range(0, len(points)):
        x = points[i, 0]
        y = points[i, 1]
        b_gradient += -(2/N) * (y - ((m_current * x) + b_current))
        m_gradient += -(2/N) * x * (y - ((m_current * x) + b_current))
    new_b = b_current - (learningRate * b_gradient)
    new_m = m_current - (learningRate * m_gradient)
    return [new_b, new_m]

def gradient_descent_runner(points, starting_b, starting_m, learning_rate, num_itera
    b = starting_b
    m = starting_m
    for i in range(num_iterations):
        b, m = step_gradient(b, m, array(points), learning_rate)
    return [b, m]

def run():
    points = genfromtxt('C:/Users/USER/Desktop/MLCODE-21SEP2021/data.csv', delimiter
    learning_rate = 0.0001
    initial_b = 0 # initial y-intercept guess
    initial_m = 0 # initial slope guess
    num_iterations = 1000
    print("Starting gradient descent at b = {0}, m = {1}, error = {2}".format(initi
    print("Running...")
    [b, m] = gradient_descent_runner(points, initial_b, initial_m, learning_rate, nu
    print("After {0} iterations b = {1}, m = {2}, error = {3}".format(num_iteration

```