

LC Classical Mechanics and Relativity 1 Lecture Notes

Year 1 Semester 1
MSci Physics with Particle Physics and Cosmology

Ash Stewart
University of Birmingham

Lectures Index

Lecture 1: Orders of Magnitude and Dimensional Analysis	1
Lecture 2: Dimensional Analysis (contd.) and Vectors	2
Lecture 3: Kinematics Introduction	5
Lecture 4: Projectile Motion	7
Lecture 6: The End of Special Relativity	9
Lecture 8	10
Lecture 17: Gravitation	11

Tue 30 Sep 2025 12:00

Lecture 1 - Orders of Magnitude and Dimensional Analysis

Given some equation, for example $E = mv^2$, we can decompose it into the basic physical quantities that make it up, for example in terms of Mass, Time and Length. We can denote the dimensions of some quantity by wrapping it in square brackets.

$$E = \frac{1}{2}mv^2$$

$$[E] = ML^2T^{-2}$$

Example:

$$\text{Pressure} \equiv \frac{\text{Force}}{\text{Area}}$$

Suppose we want to test whether pressure and linear momentum flux (amount of linear momentum per unit time, per unit surface) were equivalent quantities, we could do this using dimensional analysis:

$$[P] = \frac{[F]}{[A]}$$

$$[P] = \frac{M \times LT^{-2}}{L^2}$$

$$= M/LT^2$$

And for linear momentum flux ($\Phi(p)$ where lowercase p is momentum):

$$\Phi(p) = \frac{[p]}{[A][\text{time}]}$$

$$= \frac{MLT^{-1}}{L^2T}$$

$$= \frac{M}{LT^2}$$

So yes, they seem to be (at least dimensionally) equivalent.

0.1 Challenging the LHC

We want to use orders of magnitude calculations to challenge the idea that the LHC is the “Big Bang Machine”.

The LHC operates on the order of magnitude of approx 10TeV. The age of the universe is approx 13.7Bn Years, or (in orders of magnitude) 10^{10} yrs.

What time was the big bang? The Big Bang started the universe, but we can't really say it happened at 0s, because that doesn't really make sense. What about 1sec? or 1ms? Well it's clearly less than both of those, so we want to find the smallest possible increment of time “Plank Second” and say it happened after one of them.

Thu 02 Oct 2025 15:00

Lecture 2 - Dimensional Analysis (contd.) and Vectors

0.1 Continuation of Dimensional Analysis

What if, in theory, we could build a system of units entirely from c , the speed of light, G , Newton's constant and h , the Plank Constant?

Cont. from Lec01, we can try to use this to work out the earliest possible cosmic time.

$$\begin{aligned}h &= 6.6 \times 10^{-34} Js \\ G &= 6.67 \times 10^{-11} Nm^2/kg^2 \\ c &= 3 \times 10^8 m/s\end{aligned}$$

Dimensionally:

$$\begin{aligned}[h] &= \frac{ML^2}{T} \\ [G] &= \frac{L^3}{T^2 M} \\ [c] &= \frac{L}{T}\end{aligned}$$

We want to use these to build out a time unit, so:

$$\begin{aligned}[h^u G^v c^z] &= T \\ \left(\frac{ML^2}{T}\right)^u \left(\frac{L^3}{T^2 M}\right)^v \left(\frac{L}{T}\right)^z &= T \\ M^{u-v} L^{2u+3v+z} T^{-u-2v-z} &= T\end{aligned}$$

Solving for:

$$u - v = 0$$

$$2u + 3v + z = 0$$

$$-u - 2v - z = 1$$

Gives us:

$$u = \frac{1}{2} \tag{2.1}$$

$$v = \frac{1}{2} \tag{2.2}$$

$$z = \frac{-5}{2} \tag{2.3}$$

$t_p = \sqrt{\frac{Gh}{c^5}}$ and plugging in the values for G , h , c gives us a value of time, which the earliest possible cosmic time equal to about $10^{-43}s$

0.2 Plank Energy

Doing the same process for energy gives us (this time, the plank energy is the energy at which traditional theories of physics break down):

$$E_p = \frac{hc^5}{G} \approx 10^9 J$$

On the other hand, the LHC manages about 10TeV, which is orders of magnitude smaller than this, so the LHC cannot accurately simulate energies of this magnitude.

0.3 More Vectors

Again, vector notation will be \vec{a} . We define the x, y, z unit vectors as $\hat{e}_x, \hat{e}_y, \hat{e}_z$.

We can therefore define any vector as:

$$\vec{a} = a_x \hat{e}_x + a_y \hat{e}_y + a_z \hat{e}_z.$$

The length of a vector is again $|\vec{a}|$.

0.4 Vector Multiplication

Given \vec{a} and \vec{b} we can define the dot (scalar) product and the cross (vector) product

$$\vec{a} \cdot \vec{b} = |\vec{a}||\vec{b}| \cos \theta$$

Say we want to know the component of a vector along an axis, we can do the following (eg for x):

$$\vec{a} \cdot \hat{e}_x = a_x$$

For the vector product, we can define:

$$\vec{a} \times \vec{b} = |\vec{a}||\vec{b}| \sin(\theta) \hat{j}$$

As the vector perpendicular to the plane containing a and b. It is in the direction given by the *right hand rule*, where curling four fingers into a fist, and orienting your fist so these fingers sweep from \vec{a} to \vec{b} , the new vector will point in the direction of an extended thumb. Theta is the angle between a and b, while j is the unit vector in the direction the new vector will point.

0.5 Solar Energy Example

The world yearly energy usage is about 180,000TWh, which is about $5 \times 10^{20} J$ total. Is it (theoretically) possible to get this all from solar energy? We can check using an approximate order of magnitude calculation.

The Sun's total luminosity is $L_\odot = 3.8 \times 10^{26}$. This energy is radiated in a spherically symmetric way (we assume). Therefore the energy per time, per unit surface is (using 1AU for distance):

$$\frac{L_\odot}{4\pi \times (1.5 \times 10^6)^2}$$

Which is approximately (using order of magnitude):

$$\frac{3.8 \times 10^{26} W}{10 \times 10^{22} m^2} \approx \frac{1 kW}{m^2}$$

This is true in ideal conditions, and real energy supply is lower (due to clouds, atmosphere etc).

If we totally covered the earth's surface area ($A_{\text{surface}} \approx \pi R_\oplus^2$) which is approximately:

$$A_{\text{surface}} \approx \pi \times (6 \times 10^3 \times 10^3 m)^2 \approx 10^{14} m^2$$

Therefore total energy received is approximately:

$$P = \frac{1kW}{m^2} \times 10^{14}m^2 \approx 10^{17}W$$

And to power the world:

$$E = \frac{5 \times 10^{20}J}{3 \times 10^7s} \approx 10^{13}W$$

So, it's theoretically possible, if we could cover enough of the world in solar panels and if we could perfectly capture the sun's energy without losing some to sources such as clouds, atmosphere, areas of the ocean we cannot cover in solar panels etc.

Thu 04 Sep 2025 12:00

Lecture 3 - Kinematics Introduction

For kinematics, we'll treat all objects as points and disregard aspects like rotation/the physical size of the body etc.

Given some point, we can define its position as a function of time $\vec{r}(t)$, and velocity as the derivative wrt time of this:

$$\vec{v}(t) = \frac{d\vec{r}}{dt}$$

And acceleration:

$$\vec{a}(t) = \frac{d\vec{v}}{dt} = \frac{d^2\vec{r}}{dt^2}$$

0.1 Position from Unit Vectors

We can define:

$$\vec{r}(t) = r_x(t)\hat{e}_x + r_y(t)\hat{e}_y + r_z(t)\hat{e}_z = \sum_{j=1}^3 r_j(t)\hat{e}_j$$

So:

$$\begin{aligned} \frac{d\vec{r}}{dt} &= \frac{d}{dt} \left(\sum_{j=1}^3 r_j \hat{e}_j \right) \\ &= \sum_j \frac{d}{dt} (r_j \hat{e}_j) \\ &= \sum_j \frac{dr_j}{dt} \hat{e}_j \\ \vec{v} &= \sum_j v_j \hat{e}_j \end{aligned}$$

And:

$$\vec{a} = \frac{d\vec{v}}{dt} = \sum_{j=1}^3 a_j \hat{e}_j$$

' Note: Taking the derivative of a vector wrt time is looking at how the variable changes in some infinitesimal time. This can be a change in direction, and/or a change in magnitude. To differentiate a vector we can differentiate it component-wise.

0.2 Cartesian and Polar

Instead of representing a point as x and y components (in 2D), we can instead define it as a distance from the origin r and the angle this distance line forms with the positive x-axis θ .

Therefore (by basic right angle trig) $x = r\cos\theta$, $y = r\sin\theta$, and hence:

$$\vec{r} = r \cos \theta \hat{e}_x + r \sin \theta \hat{e}_y$$

So:

$$\begin{aligned}
 \vec{u}(t) &= \frac{d\vec{r}}{dt} = \frac{d}{dt}(r \cos \theta) \hat{e}_x + \frac{d}{dt}(r \sin \theta) \hat{e}_y \\
 &= (\dot{r} \cos \theta + r(-\sin \theta) \dot{\theta}) \hat{e}_x + (\dot{r} \sin \theta + r(\cos \theta) \dot{\theta}) \hat{e}_y \\
 &= r(\cos \theta \hat{e}_x + \sin \theta \hat{e}_y) + r \dot{\theta}(-\sin \theta \hat{e}_x + \cos \theta \hat{e}_y)
 \end{aligned}$$

0.3 Example

Lets model a particle, in a single dimension moving with constant acceleration (a_0) along a line. What is $x(t)$?

$$\begin{aligned}
 a &= \text{constant} = a_0 \\
 a &= a_0 = \frac{dv}{dt} \\
 \int_{v_0}^v dv &= \int_{t_0}^t a_0 dt = a_0 \int_{t_0}^t dt \\
 v - v_0 &= a_0(t - t_0) \\
 v &= v_0 + a_0(t - t_0)
 \end{aligned}$$

And now the position function:

$$\begin{aligned}
 v &= \frac{dx}{dt} \\
 \int_{x_0}^x v dt &= \int_{t_0}^t v_0 + a_0(t - t_0) dt \\
 x - x_0 &= v_0(t - t_0) + \frac{1}{2}a_0(t - t_0)^2
 \end{aligned}$$

Thu 09 Oct 2025 15:00

Lecture 4 - Projectile Motion

Projectile Motion: The motion of a particle subject to gravitational acceleration, $g \approx 9.81\text{m/s}^2$

1 Projectile Motion

For this to hold, the height of the particle above the ground must be $m \ll R_e \cong 6 \times 10^3\text{km}$.

$$x(t) = x_0 + v_0(t - t_0) + \frac{1}{2}a_0(t - t_0)^2$$

Lets begin solely by considering motion in the vertical axis (called z here, for some strange reason). This particle is falling from height $h\text{m}$, to the ground at $h = 0$, with constant acceleration $g\text{m/s}^2$. It has been dropped at time $t = t_0$

At time t_0 , $v = 0$, $z = h$

$$\begin{aligned} z(t) &= h + 0 - \frac{1}{2}gt^2 \\ \frac{1}{2}gt^2 &= h \\ \Rightarrow t &= \sqrt{\frac{2h}{g}} \end{aligned}$$

1.1 What about 2D?

Now we can expand our example to (rather than drop the particle from rest) give the particle some initial velocity $v_0\text{m/s}$ parallel to the ground. We now want two position functions, $x(t)$ and $z(t)$. As previously calculated:

$$z(t) = h + 0 + \frac{1}{2}(-g)t^2$$

And horizontally:

$$x(t) = 0 + v_0(t) + 0$$

So:

$$\begin{cases} z = h - \frac{1}{2}gt^2 \\ x = v_0t \end{cases}$$

Rearranging:

$$\begin{aligned} t &= \frac{x}{v_0} \\ z &= h - \frac{1}{2}g\left(\frac{x}{v_0}\right)^2 \end{aligned}$$

Since h, g, v_0 are all constants, this is an x^2 parabola.

1.2 Interplanetary Example

Lets consider some planet, with $g_{\text{planet}} = 5m/s^2$. You (denoted Y) fall into the atmosphere at some distance h from the ground, and some horizontal distance d from $O(x = 0)$. There is an alien who wants to kill you, by shooting you down. This “gun” can throw pebbles at some constant speed v_0 . The only degree of freedom the alien has to target you is change the shooting angle wrt the horizontal, θ . From the alien's perspective, what is the required θ to hit the incoming spacecraft?

To hit you, there is some time t , when the position of the bullet B , with initial velocity v where B is in the same position as Y

Consider B

$$x_B(t) = v_0 \cos(\theta)t$$

$$z_B(t) = v_0 \sin(\theta)t - \frac{1}{2}g_p t^2$$

Consider Y

$$x_Y(t) = d$$

$$z_Y(t) = h - \frac{1}{2}g_p t^2$$

We want to find a θ where $x_B = x_Y$ and $z_B = z_Y$ at the same t :

$$v_0 \cos(\theta)t = d \tag{4.1}$$

$$v_0 \sin(\theta)t - \frac{1}{2}g_p t^2 = h - \frac{1}{2}g_p t^2 \tag{4.2}$$

From 2:

$$v_0 \sin(\theta)t = h$$

$$\implies t = \frac{h}{v_0 \sin \theta}$$

And substituting:

$$v_0 \cos(\theta) \left(\frac{h}{v_0 \sin \theta} \right) = d$$

$$\frac{\cos(\theta)h}{\sin(\theta)} = d$$

$$\frac{\cos \theta}{\sin \theta} = \frac{d}{h}$$

$$\tan \theta = \frac{h}{d}$$

Since we have the value of θ in terms of two constants, yes, the alien can always hit the spaceship provided it correctly selects the angle corresponding to the value of these two constants. This means that the required angle does not depend on velocity, in this example.

2 Frames of Reference

“Observer” represents a frame of reference.

Thu 23 Oct 2025 15:00

Lecture 6 - The End of Special Relativity

Doppler Effect of Photons / EM Waves

Rather than considering sound waves, we consider the doppler effect for photons travelling at the speed of light.

$$f_{\text{emission}} \neq f_{\text{observer}}, \quad \text{if observer is moving relative to the source.}$$

In this context, frequency is often denoted ν not f . λ keeps its original meaning of wavelength.

Thu 30 Oct 2025 15:00

Lecture 8

Tue 25 Nov 2025 12:00

Lecture 17 - Gravitation

1 Gravitation

Consider two particles, with masses m_1 and m_2 at distance \vec{r} . We know there is an attractive force between the two masses:

$$\vec{F} = -G \frac{m_1 m_2}{r^2} \hat{e}_r \quad (7.1)$$

$$G = 6.67 \times 10^{-11} \text{m}^3/\text{kg}/\text{s}^2$$

1.1 Key Properties

- “Long Range” force. A force will exist between any two masses anywhere in the universe, regardless of distance and cannot be cancelled. Negligible at large distances, as force quickly tends to zero as distance increases - but never zero.
- Weak.
- $\vec{F} \propto \frac{1}{r^2}$

1.2 Mass Caveats

While we don't practically make a distinction between them, m in gravity refers to ‘gravitational mass’, m_g , while mass in Newton's Second Law $\vec{F} = m\vec{a}$ is ‘inertial mass’, m_i .

Einstein's Equivalence Principle says that they're equal, i.e:

$$\frac{dm_g}{dm_i} = 1$$

Why ‘they could be different but they fundamentally are not’ is important is beyond me.

2 Freefall

Consider an object of mass m at height h from the ground. It has force:

$$F = mg$$

And potential energy:

$$\Delta U(h) = mgh$$

However this first expression looks quite different to our definition of force.

2.1 Derivation

Gravitational force is conservative, and there is a potential energy at all points in the gravitational field, associated with this force.

Give two bodies, M and m . m is moved away from M from r_1 to r_2 along the radial direction (preserving angle, i.e. moving only in \hat{e}_r).

$$\vec{F} = -G \frac{Mm}{r^2} \hat{e}_r$$

This is the negative gradient of the potential (as potential is area under a force curve):

$$\vec{F} = -\nabla U = -\frac{dU}{dr}\hat{e}_r$$

$$\vec{F}dr = -dU\hat{e}_r$$

The work done from r_1 to r_2 is:

$$w_{1\rightarrow 2} = \int_{r_1}^{r_2} \vec{F} \cdot \hat{e}_r dx$$