

Biostat 602 Winter 2017

Lecture Set 4

Principles of Data Reduction

Ancillary Statistics, Completeness

Ancillary Statistic

Reading: CB 6.2

- Sufficient statistics contain all information about θ .
- At the other extreme is a statistic which does not contain any information on θ .

Definition 6.2.11

A statistic $S(\mathbf{X})$ is an *ancillary statistic* if its distribution does not depend on θ .

Question: Why then bother about an ancillary statistic when making an inference on θ ?

Examples

1. X_1, \dots, X_n iid $\mathcal{N}(\mu, \sigma^2)$ where σ^2 is known.
 - $X_1 - X_2 \sim \mathcal{N}(0, 2\sigma^2)$ is ancillary.
 - $(X_1 + X_2)/2 - X_3 \sim \mathcal{N}(0, 1.5\sigma^2)$ is ancillary.
 - $s_{\mathbf{X}}^2 = \frac{1}{n-1} \sum_{i=1}^n (X_i - \bar{X})^2$ is ancillary.
 - $\frac{(n-1)s_{\mathbf{X}}^2}{\sigma^2} \sim \chi_{n-1}^2$ is ancillary.

2. X_1, \dots, X_n iid $\mathcal{N}(0, \sigma^2)$ where σ^2 is unknown.

- X_1/X_2 is ancillary.

- $\bar{X}/S_{\mathbf{X}}$ is ancillary.

- Is \bar{X}/σ ancillary?

3. Let X_1, \dots, X_n iid $Uniform(\theta, \theta + 1)$. Show that the range statistic

$$R = X_{(n)} - X_{(1)}$$

is ancillary. What is its distribution?

Location-Scale Family of Distributions

Let $f(x)$ be any pdf *free of any parameter* and let $-\infty < \mu < \infty$ and $\sigma > 0$ be unknown constants. Then

$$g(x|\mu, \sigma) = \frac{1}{\sigma} f\left(\frac{x - \mu}{\sigma}\right)$$

is a pdf.

Proof: Because $f(x)$ is a pdf, then $f(x) \geq 0$, and $g(x|\mu, \sigma) \geq 0$ for all x . Let $y = (x - \mu)/\sigma$, then $x = \sigma y + \mu$, and $dx/dy = \sigma$.

$$\int_{-\infty}^{\infty} \frac{1}{\sigma} f\left(\frac{x - \mu}{\sigma}\right) dx = \int_{-\infty}^{\infty} \frac{1}{\sigma} f(y) \sigma dy = \int_{-\infty}^{\infty} f(y) dy = 1$$

Therefore, $g(x|\mu, \sigma)$ is also a pdf.

- The pdf g corresponds to a **location-scale** family of distribution with location = μ and scale = σ .
- When $\mu = 0$, g is the pdf of a scale family with **scale** parameter σ .
- When $\sigma = 1$, g is the pdf of a **location** family with location parameter μ .

How do you show a pdf belongs to a location-scale family?

Use the transformation $Y = (X - \mu)/\sigma$. If Y has a **parameter-free** pdf, then the original pdf belongs to a location-scale family.

Examples

1. $X \sim N(\mu, \sigma^2)$

2. $X \sim \text{Exp}(\theta)$

3. $X \sim \text{Cauchy}(\theta, 1)$

4. $X \sim \text{Uniform}(0, \theta)$

5. $X \sim \text{Uniform}(\theta, 2\theta)$

Ancillary Statistic for Location Family

Let X_1, \dots, X_n be iid from a location family with pdf $f(x - \mu)$ where $-\infty < \mu < \infty$. Show that the range $R = X_{(n)} - X_{(1)}$ is an ancillary statistic.

Solution: Since the original population distribution belongs to a location family, $Z_1 = X_1 - \mu, \dots, Z_n = X_n - \mu$ are iid observations from pdf $f(x)$ and cdf $F(x)$, which are free of the parameter μ . Then the cdf of the range statistic R becomes

$$\begin{aligned} F_R(r|\mu) &= \Pr(R \leq r|\mu) = \Pr(X_{(n)} - X_{(1)} \leq r|\mu) \\ &= \Pr(Z_{(n)} + \mu - Z_{(1)} - \mu \leq r|\mu) = \Pr(Z_{(n)} - Z_{(1)} \leq r|\mu) \end{aligned}$$

which does not depend on μ because Z_1, \dots, Z_n does not depend on μ . Therefore, R is an ancillary statistic.

Ancillary Statistic for Scale Family

Let X_1, \dots, X_n be iid from a scale family with pdf $f(x/\sigma)/\sigma$ where $\sigma > 0$. Show that the statistic

$$\mathbf{T}(\mathbf{X}) = (X_1/X_n, \dots, X_{n-1}/X_n) \quad \text{is ancillary.}$$

Solution: Let $Z_1 = X_1/\sigma, \dots, Z_n = X_n/\sigma$ be iid observations from pdf $f(x)$. Then the joint cdf of $\mathbf{T}(\mathbf{X})$ is

$$\begin{aligned} F_{\mathbf{T}}(t_1, \dots, t_{n-1}|\sigma) &= \Pr(X_1/X_n \leq t_1, \dots, X_{n-1}/X_n \leq t_{n-1}|\sigma) \\ &= \Pr(\sigma Z_1/\sigma Z_n \leq t_1, \dots, \sigma Z_{n-1}/\sigma Z_n \leq t_{n-1}|\sigma) \\ &= \Pr(Z_1/Z_n \leq t_1, \dots, Z_{n-1}/Z_n \leq t_{n-1}|\sigma) \end{aligned}$$

Because Z_1, \dots, Z_n does not depend on σ , $\mathbf{T}(\mathbf{X})$ is an ancillary statistic.

Ancillary vs Minimal Sufficient Statistic

- Ancillary statistic is free of θ .
- Minimal sufficient statistic contains minimal information related to θ .
- Are ancillary statistics independent of minimal sufficient statistics?

Example: For $X_1, \dots, X_n \sim \text{Uniform}(\theta, \theta + 1)$, $R = X_{(n)} - X_{(1)}$ and $M = (X_{(n)} + X_{(1)})/2$ are jointly minimal sufficient statistic (why?)

But R is ancillary statistic, so ancillary statistics are not always independent of minimal sufficient statistic.

However, how does R give any information about θ ?

- If $M = 1$, then $0 < \theta < 1$ (why?).
- Suppose now $R = 0.8$. By itself, it does not provide any information about θ .
- In combination with the fact that $M = 1$, it yields that $X_{(1)} = 0.6$ and $X_{(n)} = 1.4$, and so the possible range of θ is narrowed down to $0.4 < \theta < 0.6$.
- Combination of ancillary statistic and another statistic can be more informative jointly than the other statistic alone.
- Thus, an ancillary statistic can provide additional precision about the parameter when combined with another statistic.

Completeness

In statistical inference, the ulterior objective is to identify a statistic that is a *good* estimator for the parameter. **Sufficiency** helps us identify statistics that contain information on the parameter. While somewhat counter-intuitive, **Ancillary** statistics enhance that information, while working in conjunction with a sufficient statistics. The final piece of the puzzle is the concept of **completeness**. Together, these three principles provide enough structure for us to pursue our quest for an efficient estimator in a systematic way.

Definition: Let $\{f_T(t|\theta), \theta \in \Omega\}$ be a family of pdfs or pmfs for a statistic $T(\mathbf{X})$. This family of probability distributions is called *complete* if

$$E[g(T)|\theta] = 0 \text{ for all } \theta \text{ implies } \Pr[g(T) = 0|\theta] = 1 \text{ for all } \theta.$$

Remarks

- In other words, $g(T) = 0$ almost surely, i.e. only the zero function of T can have a mean of zero for all parameter values.
- Loosely $T(\mathbf{X})$ is called a *complete statistic*. However, as we shall see soon, completeness is the property of the family of distributions induced by T , and not that of T itself.
- Completeness implies 'no unnecessary part' conceptually. There is no non-trivial $g(T)$ whose expectation (or distribution) does not depend on θ .
- If an ancillary statistic could be made out of $T(\mathbf{X})$, it is NOT complete.
- This is a more stringent requirement than that is needed for minimal sufficient statistics.

Example 1: Let X_1, \dots, X_n be a random sample from a $Bern(p)$ population. Show that $T = \sum_{i=1}^n X_i$ is complete.

Example 2: Let X_1, \dots, X_n be a random sample from a $Uniform(0, \theta)$ population. Show that $T = \max_i X_i$ is complete.

Example 3: Let X_1, \dots, X_n be a random sample from a $Uniform(\theta, \theta + 1)$ population. We know $\mathbf{T} = (X_{(1)}, X_{(n)})$ is minimal sufficient. Is \mathbf{T} complete?

Example 4: Let X_1, \dots, X_n be a random sample from a $Pois(\lambda)$. Show that $T = \sum_{i=1}^n X_i$ is complete.

Example 5: Let $T \sim Pois(\lambda)$, where the parameter space of λ is given by

$$\Omega = \{\lambda : \lambda = \{1, 2\}\}.$$

Show that the family of distributions induced by T is NOT complete.

Proof: We need to find a counter example which is a function g such that $E[g(T)|\lambda] = 0$ for $\lambda = 1, 2$ but $g(T) \neq 0$. The function g must satisfy

$$E[g(T)|\lambda] = \sum_{t=0}^{\infty} g(t) \frac{\lambda^t e^{-\lambda}}{t!} = 0$$

for $\lambda \in \{1, 2\}$. Thus,

$$\begin{cases} E[g(T)|\lambda = 1] = \sum_{t=0}^{\infty} g(t) \frac{1^t e^{-1}}{t!} = 0 \\ E[g(T)|\lambda = 2] = \sum_{t=0}^{\infty} g(t) \frac{2^t e^{-2}}{t!} = 0 \end{cases}$$

The above equation can be rewritten as

$$\begin{cases} \sum_{t=0}^{\infty} g(t)/t! = 0 \\ \sum_{t=0}^{\infty} 2^t g(t)/t! = 0 \end{cases}$$

Define $g(t)$ as

$$g(t) = \begin{cases} 2 & t = 0 \text{ and } t = 2 \\ -3 & t = 1 \\ 0 & \text{otherwise} \end{cases}$$

Then

$$\begin{aligned} \sum_{t=0}^{\infty} g(t)/t! &= g(0)/0! + g(1)/1! + g(2)/2! = 2 - 3 + 2/2 = 0 \\ \sum_{t=0}^{\infty} 2^t g(t)/t! &= g(0)/0! + 2g(1)/1! + 2^2 g(2)/2! = 2 - 6 + 8/2 = 0 \end{aligned}$$

There exists a non-zero function g that satisfies $E[g(T)|\lambda] = 0$ for all $\lambda \in \Omega$. Therefore this family is NOT complete.

Question: Why is a complete statistic called ‘complete’?

Note that requiring $g(T)$ to satisfy the definition of completeness puts a restriction on g . The larger the family of pdfs/pmfs, the greater is the restriction on g . When the family of pdfs/pmfs is augmented to the point that $E[g(T)] = 0$ for all θ rules out all g except for the trivial $g(T) = 0$, then the family is said to be complete. A common verbalization of this definition is that the family of distributions is complete if there is no *unbiased estimator* of zero except for the trivial estimator $g \equiv 0$.

As the Poisson example shows, ‘completeness’ is a property of the family of distributions rather than the random variable or its parametric form.

Ancillary and Complete Statistics

Fact 1: For a statistic $T(\mathbf{X})$, if a non-constant function of T , say $r(T)$ is ancillary, then $T(\mathbf{X})$ cannot be complete.

Proof: Define $g(T) = r(T) - E[r(T)]$, which does not depend on the parameter θ because $r(T)$ is ancillary. Then $E[g(T)|\theta] = 0$ for a non-zero function $g(T)$, and $T(\mathbf{X})$ is not a complete statistic.

Arbitrary Functions of Complete Statistics

Fact 2: If $T(\mathbf{X})$ is a complete statistic, then a non-constant function of T , say $T^* = r(T)$ is also complete.

Proof: We can write

$$E[g(T^*)|\theta] = E[g \circ r(T)|\theta]$$

Now assume that $E[g(T^*)|\theta] = 0$ for all θ . Then

$$E[g \circ r(T)|\theta] = 0$$

holds for all θ too. Since $T(\mathbf{X})$ is a complete statistic,

$$\Pr[g \circ r(T) = 0] = 1, \quad \forall \theta \in \Omega.$$

Therefore $\Pr[g(T^*) = 0] = 1$, and T^* is a complete statistic.

Completeness and sufficiency

Theorem 6.2.28: If a minimal sufficient statistic exists, then any complete sufficient statistic is also a minimal sufficient statistic.

Proof: Known as *Bahadur's Theorem*, beyond the scope of the course.
Book statement is inaccurate.

Remarks:

- With the exception of very unusual cases, under a mild assumption, minimal sufficient statistics always exist.
- The converse is NOT true. A minimal sufficient statistic is not necessarily complete. Recall the example of $\text{Uniform}(\theta, \theta + 1)$.

Basu's Theorem

If $T(\mathbf{X})$ is a complete sufficient statistic, then $T(\mathbf{X})$ is independent of every ancillary statistic.

Proof – for discrete case

Suppose that $S(\mathbf{X})$ is an ancillary statistic. We want to show that

$$\Pr(S(\mathbf{X}) = s | T(\mathbf{X}) = t) = \Pr(S(\mathbf{X}) = s), \quad \forall t \in \mathcal{T} \quad (*)$$

Now we have, using *law of total probability*,

$$\Pr(S(\mathbf{X}) = s | \theta) = \sum_{t \in \mathcal{T}} \Pr(S(\mathbf{X}) = s | T(\mathbf{X}) = t) \Pr(T(\mathbf{X}) = t | \theta) \quad (1)$$

Since, $\sum_{t \in \mathcal{T}} \Pr(T(\mathbf{X}) = t | \theta) = 1$, we can write

$$\begin{aligned} \Pr(S(\mathbf{X}) = s | \theta) &= \Pr(S(\mathbf{X}) = s) \sum_{t \in \mathcal{T}} \Pr(T(\mathbf{X}) = t | \theta) \\ &= \sum_{t \in \mathcal{T}} \Pr(S(\mathbf{X}) = s) \Pr(T(\mathbf{X}) = t | \theta) \end{aligned} \quad (2)$$

Define $g(t) = \Pr(S(\mathbf{X}) = s | T(\mathbf{X}) = t) - \Pr(S(\mathbf{X}) = s)$. Using (1) and (2),

$$\sum_{t \in \mathcal{T}} [\Pr(S(\mathbf{X}) = s | T(\mathbf{X}) = t) - \Pr(S(\mathbf{X}) = s)] \Pr(T(\mathbf{X}) = t | \theta) = 0$$

This implies

$$\sum_{t \in \mathcal{T}} g(t) \Pr(T(\mathbf{X}) = t | \theta) = E[g(T(\mathbf{X})) | \theta] = 0$$

$T(\mathbf{X})$ is complete, so $g(t) = 0$ almost surely for all possible $t \in \mathcal{T}$.

Therefore, $(*)$ is established and $S(\mathbf{X})$ is independent of $T(\mathbf{X})$.

Example 6: Let X_1, X_2, \dots, X_n be a random sample from a $Uniform(0, \theta)$ distribution. Let $X_{(1)} < X_{(2)} < \dots < X_{(n)}$ be the corresponding order statistics.

(a) Show that $X_{(n)}$ and $X_{(1)}/X_{(n)}$ are independent random variables.

(b) Establish that

$$E \left[\frac{X_{(1)}}{X_{(n)}} \right] = \frac{E(X_{(1)})}{E(X_{(n)})} = \frac{1}{n}.$$

Example 7: Let X_1, X_2, \dots, X_n be a random sample from a $\mathcal{N}(\mu, \sigma^2)$ distribution. Conclude that \bar{X} and S^2 are independent.

Example 8: *Exercise 6.19 CB* The random variable X takes the values 0, 1, 2, according to one of the following distributions:

	$\Pr(X = 0)$	$\Pr(X = 1)$	$\Pr(X = 2)$	
Distribution 1	p	$3p$	$1 - 4p$	$0 < p < \frac{1}{4}$
Distribution 2	p	p^2	$1 - p - p^2$	$0 < p < \frac{1}{2}$

In each case, determine whether the family of distribution of X is complete.

Solution - Distribution 1

Suppose that there exist $g(\cdot)$ such that $E[g(X)|p] = 0$ for all $0 < p < \frac{1}{4}$.

$$\begin{aligned}
 f_X(x|p) &= p^{I(x=0)}(3p)^{I(x=1)}(1-4p)^{I(x=2)} \\
 E[g(X)|p] &= \sum_{x \in \{0,1,2\}} g(x)f_X(x|p) \\
 &= g(0) \cdot p + g(1) \cdot (3p) + g(2) \cdot (1-4p) \\
 &= p[g(0) + 3g(1) - 4g(2)] + g(2) = 0
 \end{aligned}$$

Therefore, $g(2) = 0$, $g(0) + 3g(1) = 0$ must hold, and it is possible that g is a nonzero function that makes $\Pr[g(X) = 0] < 1$. For example, $g(0) = 3, g(1) = -1, g(2) = 0$. Therefore the family of distributions of X is not complete.

Solution - Distribution 2

Suppose that there exist $g(\cdot)$ such that $E[g(X)|p] = 0$ for all $0 < p < \frac{1}{4}$.

$$f_X(x|p) = p^{I(x=0)}(p^2)^{I(x=1)}(1-p-p^2)^{I(x=2)}$$

$$\begin{aligned} E[g(X)|p] &= \sum_{x \in \{0,1,2\}} g(x)f_X(x|p) \\ &= g(0) \cdot p + g(1) \cdot p^2 + g(2) \cdot (1-p-p^2) \\ &= p^2[g(1) - g(2)] + p[g(0) - g(2)] + g(2) = 0 \end{aligned}$$

$g(0) = g(1) = g(2) = 0$ must hold in order to $E[g(X)|p] = 0$ for all p .
Therefore the family of distributions of X is complete.

Example 9: Let X_1, \dots, X_n *i.i.d.* $Pois(\lambda)$, where $\lambda > 0$ is unknown. Let \bar{X} , S^2 denote the sample mean and variance, respectively. Show that

$$E[S^2 | \bar{X}] = \bar{X} \text{ almost surely.}$$