

Stochastic Methods

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Assignment 4 - Solution

[Ashutosh Singh]

Exercise 1: Inconsistent Systems of Equations

(a)

$$A_1 x = b_1 \tag{1}$$

$$\begin{bmatrix} 1 & 0 \\ 1 & 0 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 5 \\ 2 \\ 4 \end{bmatrix}$$

$$A_1^T A_1 x = A_1^T b_1 (2)$$

$$\begin{bmatrix} 1 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 1 & 0 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} 5 \\ 2 \\ 4 \end{bmatrix}$$

$$\begin{bmatrix} 3 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 11 \\ 0 \end{bmatrix}$$

$$\Rightarrow x_1^* = \frac{11}{3}; \Rightarrow x_2^* = k \tag{3}$$

Residual

$$r = b_1 - A_1 x^* \tag{4}$$

$$r = \begin{bmatrix} 5 \\ 2 \\ 4 \end{bmatrix} - \begin{bmatrix} \frac{11}{3} \\ \frac{11}{3} \\ \frac{11}{3} \end{bmatrix}$$

$$r = \begin{bmatrix} \frac{4}{3} \\ -\frac{5}{3} \\ \frac{1}{3} \end{bmatrix}$$

Euclidean norm of Residual

$$||r||_2 = \sqrt{(\frac{4}{3})^2 + (-\frac{5}{3})^2 + (\frac{1}{3})^2}$$
 (5)

$$||r||_2 = 2.16 \tag{6}$$

SE of Residual

$$SE = ||r||_2^2 \tag{7}$$

$$SE = 4.67 \tag{8}$$

RMSE of Residual

$$RMSE = \sqrt{\left(\frac{SE}{m}\right)} \tag{9}$$

$$RMSE = \sqrt{(\frac{4.67}{3})} = 1.247 \tag{10}$$

$$A_{2}x = b_{2}$$

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 1 \\ 1 & 2 & 1 \\ 1 & 0 & 1 \end{bmatrix} \begin{bmatrix} x_{1} \\ x_{2} \\ x_{3} \end{bmatrix} = \begin{bmatrix} 2 \\ 2 \\ 3 \\ 4 \end{bmatrix}$$

$$(11)$$

$$A_{2}^{T}A_{2}x = A_{2}^{T}b_{2}$$

$$\begin{bmatrix} 1 & 0 & 1 & 1 \\ 0 & 1 & 2 & 0 \\ 0 & 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 1 \\ 1 & 2 & 1 \\ 1 & 0 & 1 \end{bmatrix} \begin{bmatrix} x_{1} \\ x_{2} \\ x_{3} \end{bmatrix} = \begin{bmatrix} 1 & 0 & 1 & 1 \\ 0 & 1 & 2 & 0 \\ 0 & 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} 2 \\ 2 \\ 3 \\ 4 \end{bmatrix}$$

$$\begin{bmatrix} 3 & 3 & 2 \\ 3 & 6 & 3 \\ 2 & 3 & 3 \end{bmatrix} \begin{bmatrix} x_{1} \\ x_{2} \\ x_{3} \end{bmatrix} = \begin{bmatrix} 9 \\ 10 \\ 9 \end{bmatrix}$$

$$(12)$$

After gaussian elimination

$$\begin{bmatrix} 3 & 3 & 2 \\ 0 & 3 & 1 \\ 0 & 0 & \frac{4}{3} \end{bmatrix} \begin{bmatrix} x_1^* \\ x_2^* \\ x_3^* \end{bmatrix} = \begin{bmatrix} 9 \\ 1 \\ \frac{8}{3} \end{bmatrix}$$

$$\Rightarrow x_1^* = 2; \Rightarrow x_2^* = -\frac{1}{3}; \Rightarrow x_3^* = 2$$
(13)

Residual

$$r = b_2 - A_2 x^* (14)$$

$$r = \begin{bmatrix} 2 \\ 2 \\ 3 \\ 4 \end{bmatrix} - \begin{bmatrix} \frac{5}{3} \\ \frac{5}{3} \\ \frac{10}{3} \\ 4 \end{bmatrix}$$

$$r = \begin{bmatrix} \frac{1}{3} \\ \frac{1}{3} \\ -\frac{1}{3} \\ 0 \end{bmatrix}$$

Euclidean norm of Residual

$$||r||_2 = \sqrt{(\frac{1}{3})^2 + (\frac{1}{3})^2 + (-\frac{1}{3})^2 + 0}$$
(15)

$$||r||_2 = 0.577 \tag{16}$$

SE of Residual

$$SE = ||r||_2^2$$
 (17)

$$SE = \frac{1}{3} \tag{18}$$

RMSE of Residual

$$RMSE = \sqrt{\left(\frac{SE}{m}\right)} \tag{19}$$

$$RMSE = \sqrt{(\frac{\frac{1}{3}}{4})} = \sqrt{\frac{1}{12}}$$
 (20)

Exercise 2: Comparison of Polynomials Models for Least Squares

(a) 1a

${ m Method/metric}$	norm of residual	SE	RMSE
hand	2.16	4.67	1.247
leastSquares method	2.1602	4.6667	1.2472

1b

Method/metric	norm of residual	SE	RMSE
hand	0.577	0.33	0.288
leastSquares method	0.5774	0.3333	0.2887

- (b) Figures in figures folder under exercise-2b folder
- (c) Figures in figures folder under exercise-2c folder
- (d) Figures in figures folder under exercise-2d folder
- (e) Comparision of linear, quadratic and cubic polynomial models

Kerosene Dataset

model/metric	norm of residual	SE	RMSE	predicted 2012	$true\ 2012$
linear	2.11	4.46	0.37	208.476	267.89
quadratic	2.04	4.19	0.367	224.916	267.89
cubic	2.66	7.12	0.4793	329.728	267.89

For both the datasets we clearly see that All metrics are better for quadratic model and prediction on unseen data is closest as well. I would chose quadratic model

Crude Oil Dataset

$\mathrm{model/metric}$	norm of residual	SE	RMSE	predicted 2012	true 2012
linear	1.96	3.85	0.35	$1.707\mathrm{e}{+04}$	$1.311\mathrm{e}{+04}$
quadratic	1.57	2.49	0.28	$1.40\mathrm{e}{+04}$	$1.311\mathrm{e}{+04}$
cubic	2.51	6.32	0.4517	$4.190\mathrm{e}{+03}$	$1.311\mathrm{e}{+04}$

For crude-oil dataset we can see that all error metrics improve as we increase the degree of the polynomial. But our prediction on unseen values keeps getting worse. Given these conditions without any more test data I would select linear model

Exercise 3: Analysis of Periodic Data

(a) periodicA

${\rm model/metric}$	norm of residual	SE	RMSE
1960-63	10.08	101.68	1.68
1960-70	18.001	324.04	1.64

(b) periodicB

model/metric	norm of residual	SE	RMSE
1960-63	9.49	90.17	1.58
1960-70	17.50	306.29	1.59

(c) After running predictions on entire dataset I could comeup with the result that adding more data has made the model the better.

Lack of time and upcoming project presentations I was not able to include more details in the report

Exercise 4: Linearization and Levenberg-Marquardt Method for Exponential Model

 $y_i = \alpha_1 x_{i2}^{\alpha} \tag{21}$

Applying log on bot sides

$$log(y) = log(\alpha_1) + \alpha_2 log(x) log(y) = k_1 + \alpha_2 log(x)$$
(22)

From nuclear dataset

$$years = \begin{bmatrix} 1999 \\ 2000 \\ 2001 \\ 2002 \\ 2003 \\ 2004 \\ 2005 \\ 2006 \end{bmatrix}$$

$$consumption = \begin{bmatrix} 14.09\\ 15.90\\ 16.60\\ 25.17\\ 41.66\\ 47.95\\ 50.33\\ 54.85 \end{bmatrix}$$

$$change = \begin{bmatrix} 4.68\\12.85\\4.40\\51.63\\65.51\\15.10\\4.96\\8.98 \end{bmatrix}$$

Scaling years by diving them minimum value Writing system in form Ax=b

$$\begin{bmatrix} 1 & ln(\frac{1999}{1999}) \\ 1 & ln(\frac{2000}{1999}) \\ 1 & ln(\frac{2001}{1999}) \\ 1 & ln(\frac{2002}{1999}) \\ 1 & ln(\frac{2003}{1999}) \\ 1 & ln(\frac{2003}{1999}) \\ 1 & ln(\frac{2005}{1999}) \\ 1 & ln(\frac{2006}{1999}) \\ 1 & ln(\frac{2006}{1999}) \end{bmatrix} \begin{bmatrix} k_1 \\ \alpha_2 \end{bmatrix} = \begin{bmatrix} ln(14.09) \\ ln(15.90) \\ ln(41.66) \\ ln(47.95) \\ ln(50.33) \\ ln(54.85) \end{bmatrix}$$

Solving this system by leastSqaures we get

$$RMSE_{log} = 0.1446 \tag{23}$$

$$RMSE_{exp} = 10.9191 \tag{24}$$

(b) Steps

- A function to calculate residual vector at given paramater values
- A function to calculate Jacobian. Precaculated partial derivatives. This function just returns Jacobian Matrix at particular parameter values.
- Run Levenberg-Marquardt algorithm for 10000 steps. to obtain the RMSE.

$$RMSE_{LM} = 0.6205$$
 (25)

NOTE: This RMSE is by using year column as index rather that values. Example

$$years = egin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \\ 5 \\ 6 \\ 7 \\ 8 \end{bmatrix}$$

And I scaled consumption values using min-max scalar.

With original settings i.e. min scaled years vector and no scaling on consumption

$$RMSE_{LM} = 4.989 \tag{26}$$

(c) I would chose LM model because it has lower RMSE than log linearized model

Exercise 5: Tikhonov Regularization

(a) Linear least squares with Tikhonov regularization

$$\min_{x} ||Ax - b||^2 + \alpha ||x||^2 \tag{27}$$

$$J = (Ax - b)^T (Ax - b) + \alpha (x^T x)$$
(28)

Differentiating w.r.t x for finding the optimal point

$$\frac{\partial J}{\partial x} = \frac{\partial}{\partial x} ((Ax - b)^T (Ax - b) + \alpha (x^T x))$$

(29)

$$\frac{\partial J}{\partial x} = \frac{\partial}{\partial x} (x^T A^T A x - 2(Ax)^T b - b^T b + \alpha(x^T x))$$

(30)

Putting

$$\frac{\partial J}{\partial x} = 0 \tag{31}$$

$$2A^T A x - 2A^T b + 2\alpha x = 0 (32)$$

$$x^* = (A^T A + \alpha)^{-1} A^T b (33)$$

Purpose of the regularization parameter alpha is that it forces the weights towards zero (but not exactly zero in this case)

Reasonable values of alpha lie between 0 and 0.1

- (b) Figures are under figures/exercise-5b
- (c) Figures are under figures/exercise-5c

I chose values of alpha between 0 and 0.1