Table1: List of Searching Techniques used in AI towards problem solving

| Name of the<br>Algorithm | Type of the<br>Algorithm | Advantage   | Description  | Limitation  | Application  |
|--------------------------|--------------------------|---|--|---|--|
| BFS                      | Uninformed<br>Search     | 1.BFS will provide the solution with low cost. 2.BFS has the potential to find the goal.  | BFS is a general-graph or tree searching algorithm, which searches in breadth wise starting from the root (HEAD) to following nodes.   | 1.Not memory efficient because BFS will store states (current) to expand through that. 2.Need more computationa I power | 1.To find nodes(USERS) with-in the range.  2.Broadcasting in Network-to reach all nodes                  |
| DFS                      | Uninformed<br>Search     | 1.We know BFS stores the states, but DFS no need to, as it follows a linear path(depth). less time complexity 2.Less time-complexit y | DFS searching algorithm Will start searching from the root and traverse through the depth to find the solution   | 1. Unlike BFS DFS will not guarantee a solution. 2.If the depth of a larger, time complexity will be high.              | 1.Topological sorting. 2.Finding Connected components.   |
| UCS                      | Uninformed<br>Search     | 1.UCS chooses<br>the optimal<br>path in each<br>state.<br>2.UCS is<br>optimal<br>compared   | UCS traverse<br>through the<br>tree or graph,<br>Here cost wise<br>searching<br>happens, so<br>unlike BFS,DFS<br>.UCS will focus<br>on cost for<br>searching and<br>reaching the<br>goal | 1.No information on goal location. 2.Explores different paths in each and every state.                                  | 1.Delivery<br>software-(they<br>can calibrate in<br>every delivery<br>)<br>2.Plane air<br>route planner. |
| Best First<br>Search     | Informed<br>Search       | 1.Best first search can switch between BFS and DFS by gaining the advantages of both the algorithms.                                  | BFS always<br>chooses the<br>best path at<br>that moment.  | 1.As it takes decision on each and every state, it may end up in a loop.  | 1.GPS Navigation systems. 2.Web Crawlers   |

| - 4           |                    |  |   | 4  | 4.0                   |
|---------------|--------------------|--|---|--|-----------------------|
| A*            | Informed<br>Search | A* is the best<br>algorithm and<br>the smartest<br>1.Best<br>Algorithm<br>2.less Time and<br>memory .    | A* is essentially a best-first search algorithm and popular techniques used for pathfinding and graph traversals.   | 1.cost is fixed 2.the speed is dependent on heuristic function.      | 1.Games 2.Web maps    |
| AO*           | Informed<br>Search | 1.It is an optimal algorithm than others. 2.And it can use OR and AND.                                   | AO* algorithm is nothing but A* with AND-OR tree, which gives advantages, the main difference lies in the way termination conditions are determined, since all goals following an AND nodes must be realized; where as a single goal node following an OR node will do. | 1.If the it gets<br>unsolved<br>goal,complexi<br>ty will be high     | 1.Fintech<br>2.E-comm |
| Hill Climbing | Informed           | 1.Hill climbing  | Hill Climbing is  | 1.Local  | 1.Automation          |
|               | Search             | is good if the value is continuous (Node). 2.If goal is in first maxima then high performance we can get | a heuristic search used for mathematical optimization problems in the field of Artificial Intelligence.   | maxima 2.If it get same values , not possible to get best goal state | 2.Map routing         |
|               |                    |  |   |  |                       |
|               |                    |  |   |  |                       |

Table2: performance of Searching Techniques used in AI towards problem solving

| Parameters   | BFA    | DFS      | UCS      |  | Best   | <b>A*</b> | AO*   | Hill     |
|--------------|--------|----------|----------|--|--------|-----------|-------|----------|
|              |        |          |          |  | First  |           |       | Climbing |
|              |        |          |          |  | Search |           |       |          |
| Completeness | Yes    | No       | Yes      |  | No     | Yes       | No    | No       |
| optimal      | Yes    | No       | Yes      |  | No     | Yes       | Yes   | No       |
| Heuristic    | No     | No       | No       |  | Yes    | Yes       | Yes   | Yes      |
| Time         | O(b^s) | O(hd)    | O(b^(1   |  | O(b^m  | O(b^d     | O(b^d | O(b^d)   |
| Complexity   |        | $O(b^d)$ | + C*/ε)) |  | )      | )         | )     |          |
| Space        | O(b^s) | O(bm)    | O(b^(1   |  | O(b^m  | O(b^d     | O(bm) | O(b^d)   |
| Complexity   |        | O(DIII)  | + C*/ε)) |  | )      | )         |       |          |

Table 3: Different heuristic Functions and its properties

| Heuristic Function | Properties of heuristic function | strength         | Limitation        | Application         |
|--------------------|----------------------------------|------------------|-------------------|---------------------|
| f(n) = g(n) + h(n) | Admissible                       | $h(n) \leq g(n)$ | $h_1(n) < h_2(n)$ | 8 Puzzle<br>problem |
|                    | Combining heuristics             |                  | h(s) ≤ h*(s)      |                     |
|                    | Precomputing                     |                  |                   |                     |
|                    |                                  |                  |                   |                     |
|                    |                                  |                  |                   |                     |
|                    |                                  |                  |                   |                     |