Complexities of Algorithms

O(1) complexity: One of the simplest algorithms with O(1) time complexity is accessing a specific element in an array or list by its index.

Algorithm: accessing element using index in array

- 1. Given an array or list of elements and an index i:
- 2. Access the element at index i directly by using the indexing operator or equivalent syntax provided by the programming language.

This algorithm has a constant time complexity of O(1) because the time required to access an element in an array or list is independent of the size of the collection. Whether the collection has 10 elements or 10,000 elements, accessing a specific element by index takes the same amount of time.

It's important to note that this algorithm assumes that the index is within the valid range of the collection. If the index is out of bounds, additional checks or exception handling may be necessary.

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 $O(log\ n)$ complexity: One of the simplest algorithms with $O(log\ n)$ time complexity is the Binary Search algorithm.

Algorithm: Binary search

- 1. Given a sorted array and a target value:
- 2. Set two pointers, left and right, initially pointing to the first and last elements of the array, respectively.
- 3. Repeat the following steps until left is less than or equal to right:
 - a. Calculate the middle index as mid = (left + right) / 2.
 - b. Compare the value at the middle index with the target value.
 - i. If they are equal, return the middle index as the location of the target.
 - ii. If the value at the middle index is greater than the target, update right to mid 1.
 - iii. If the value at the middle index is less than the target, update left to mid + 1.
- 4. If the loop exits without finding the target, it means the target is not present in the array.

The Binary Search algorithm reduces the search space by half at each step, making it more efficient than linear search algorithms. As a result, it achieves a time complexity of O(log n), where n is the number of elements in the array.

It's important to note that the Binary Search algorithm requires the input array to be sorted. If the array is unsorted, a sorting step may be required before applying the Binary Search algorithm.

O(n) complexity: One of the simplest algorithms with O(n) time complexity is a linear search algorithm.

algorithm:

- 1. Given an array or list of elements and a target value:
- 2. Start at the first element of the array and compare it with the target value.
- 3. Move to the next element in the array and repeat the comparison until either the target value is found or the end of the array is reached.
- 4. If the target value is found, return the index or position of the element in the array.
- 5. If the end of the array is reached without finding the target value, indicate that the target is not present.

The linear search algorithm iterates through each element of the array or list until it finds the target or reaches the end. In the worst-case scenario, when the target is at the last position or not present in the array, the algorithm will perform n comparisons, where n is the number of elements in the array.

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The linear search algorithm has a time complexity of O(n), as the number of operations scales linearly with the input size.

While linear search is not the most efficient algorithm for large datasets, it is simple to implement and suitable for small arrays or unsorted collections.

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O(n log n) complexity: One of the simplest algorithms with O(n log n) time complexity is the Merge Sort algorithm. algorithm:

- 1. Given an array of elements:
- 2. Divide the array into two halves recursively until each subarray contains only one element.
- 3. Merge the subarrays back together in sorted order:
 - a. Compare the first element of each subarray.
 - b. Take the smaller element and place it in a temporary array or a separate portion of the original array.
 - c. Move to the next element in the subarray from which the smaller element was
 - d. Repeat the comparison and placement process until all elements are merged.
- 4. Repeat the merging process for larger subarrays until the entire array is sorted.

The Merge Sort algorithm achieves a time complexity of $O(n \log n)$ because it divides the array into halves and merges them back together in sorted order. The divide step takes $O(\log n)$ time, as it recursively splits the array in half, and the merge step takes O(n) time since it compares and combines the elements. Overall, the algorithm performs $O(n \log n)$ operations.

Merge Sort is a widely-used and efficient sorting algorithm. While it may not be the simplest algorithm to implement from scratch, its time complexity makes it suitable for sorting larger datasets.

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 $O(n^2)$ complexity: One of the simplest algorithms with $O(n^2)$ time complexity is the Bubble Sort algorithm. Here's the algorithm:

- 1. Given an array of elements:
- 2. Iterate over the array and compare adjacent elements:
 - a. Compare the first element with the second element.
 - b. If the first element is greater than the second element, swap their positions.
 - c. Move to the next pair of adjacent elements and repeat the comparison and swap process.
- 3. Repeat the iteration process for the remaining elements until the entire array is sorted:
 - a. In each iteration, one pass through the array places the largest unsorted element in its correct position at the end of the array.

The Bubble Sort algorithm has a time complexity of $O(n^2)$ because it involves nested iterations. In the worst-case scenario, where the array is in reverse order, each element needs to be compared and potentially swapped with every other element. This leads to n comparisons for the first pass, n-1 comparisons for the second pass, and so on, resulting in a total of approximately (n * (n-1))/2 comparisons.

While Bubble Sort is simple to understand and implement, it is not the most efficient sorting algorithm for large datasets. However, it can be suitable for small arrays or partially sorted arrays.

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 $O(2^n)$ complexity: An algorithm with $O(2^n)$ time complexity is the exponential search algorithm. Here's a high-level description of the algorithm:

Given an input size n:

Start with a base case, typically when n is a small constant. Solve this base case directly. If the input size is larger than the base case, split the problem into two or more subproblems of roughly equal size.

Recursively solve each subproblem independently.

Combine the solutions of the subproblems to obtain the final solution for the larger problem.

The time complexity of this algorithm is O(2ⁿ) because the problem size doubles with each recursion, resulting in an exponential number of recursive calls. As a result, the runtime grows exponentially as the input size increases.

It's important to note that exponential time complexity is generally considered inefficient and impractical for large input sizes. However, in some cases, exponential algorithms may be applicable for small or specific problem instances.

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O(n!) complexity: An algorithm with O(n!) time complexity is the brute-force approach to solve the permutation problem. algorithm:

- 1. Given a set of n elements:
- 2. Generate all possible permutations of the elements:
 - a. Start with the first element and recursively generate all permutations of the remaining (n-1) elements.
 - b. For each generated permutation, insert the first element in all possible positions to create new permutations.
 - c. Continue this process recursively until all possible permutations are generated.
- 3. Perform the desired operations on each generated permutation.

The time complexity of this algorithm is O(n!) because the number of possible permutations for n elements is n!. Each element has n choices for the first position, (n-1) choices for the second position, (n-2) choices for the third position, and so on until 1 choice for the last position. This results in a total of n * (n-1) * (n-2) * ... * 1 = n! possible permutations.

It's important to note that the factorial time complexity (O(n!)) is extremely high and grows rapidly with the input size. Brute-force algorithms with factorial complexity are generally impractical for even moderately sized inputs.

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