#### **Scalar Visualization**

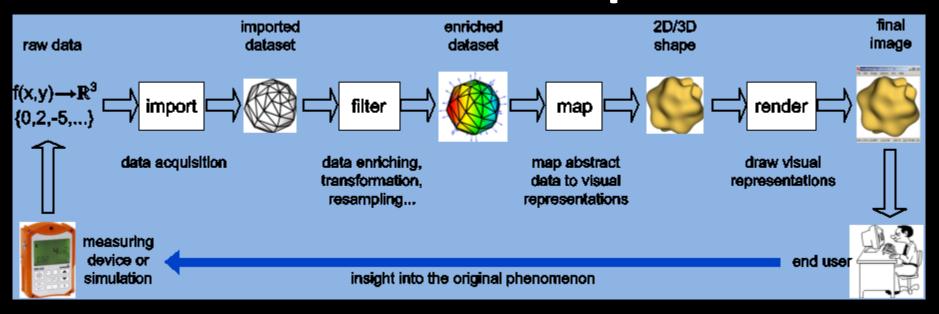
## Visualizing scalar data Popular scalar visualization techniques

- Color mapping
- Contouring
- Height plots





### Recap of Chap 4: Visualization Pipeline



- 1. Data Importing
- 2. Data Filtering
- 3. Data Mapping
- 4. Date Rendering



#### **Scalar Function**

$$f: R \rightarrow R$$
  
1-D, histogram

$$f: \mathbb{R}^2 \to \mathbb{R}$$

2-D, color mapping, contouring, height plot

$$f: \mathbb{R}^3 \to \mathbb{R}$$

3-D, isosurface, slicing, volume visualization

## Visualizing scalar data Popular scalar visualization techniques

- Color mapping
- Contouring
- Height plots



#### Color Mapping

- Color mapping maps scalar data to colors. The scalar mapping is implemented by indexing into a color lookup table. Scalar values then serve as indices into this lookup table
- Color look-up table

Associate a specific color with every scalar value The geometry of **Dv** is the same as **D** 

$$C = \{c_i\}_{i=1,2,...N}$$
where
$$c_i = c(\frac{(N-i)f_{\min} + if_{\max}}{N})$$

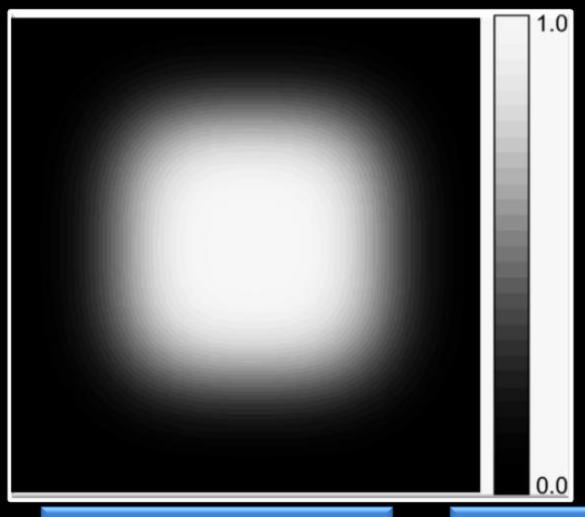


#### **Luminance Colormap**

•Use grayscale to represent scalar value

$$f = e^{-10(x^4 + y^4)}$$

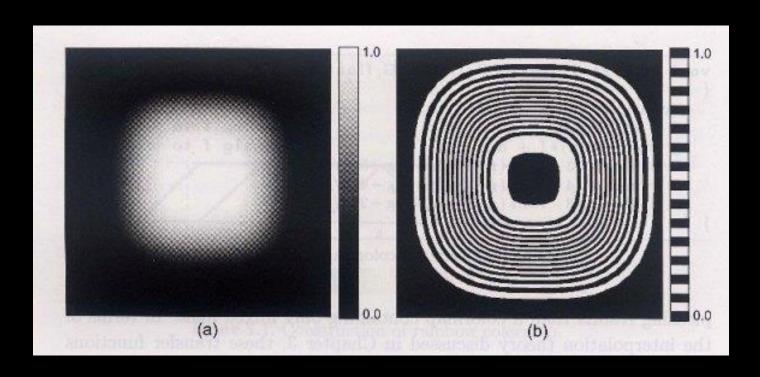
• Most scientific data (through measurement, observation, or simulation) are intrinsically grayscale, not color



**Luminance Colormap** 

Legend



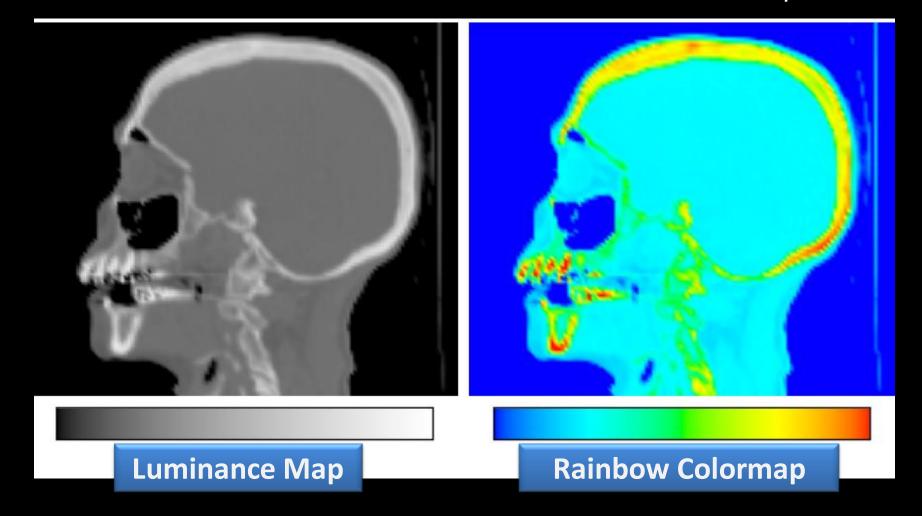


- (a) a luminance colormap and (b) a zebra colormap
- (b) The luminance colormap shows absolute values, whereas the zebra colormap emphasizes rapid value variations.



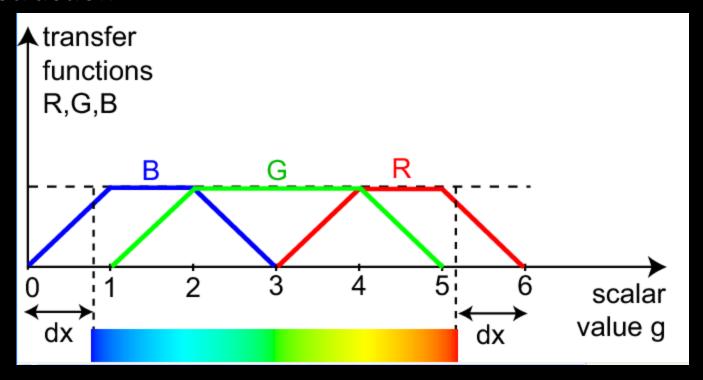
#### Rainbow Colormap

- •Red: high value; Blue: low value
- Medical visualization with luminance and rainbow colormaps



#### Rainbow Colormap

#### Construction



```
• f < dx: R=0, G=0, B=1
```

• 
$$f = 2$$
: R=0, G=1, B=1

• 
$$f = 3$$
: R=0, G=1, B=0

• 
$$f = 4$$
: R=1, G=1, B=0

• 
$$f > 6 - dx$$
: R=1, G=0, B=0

### Colormap: Designing Issues

- Choose right color map for correct perception
  - Grayscale: good in most cases
  - •Rainbow: e.g., temperature map
  - Rainbow + white: e.g., landscape
    - •Blue: sea, lowest
    - •Green: fields
    - Brown: mountains
    - White: mountain peaks, highest



- Attract user to certain value ranges or individual values
  - Colormap uses particularly salient colors
  - Colormap can be influenced by:
    - Application
    - Domain-specific convention &Traditions



### Designing effective colormaps

- Some application, emphasize the variation of the data
  - Colormap containing two or more alternating colors
- Many other colormap designs
  - Geographical application
  - Classical medical imaging

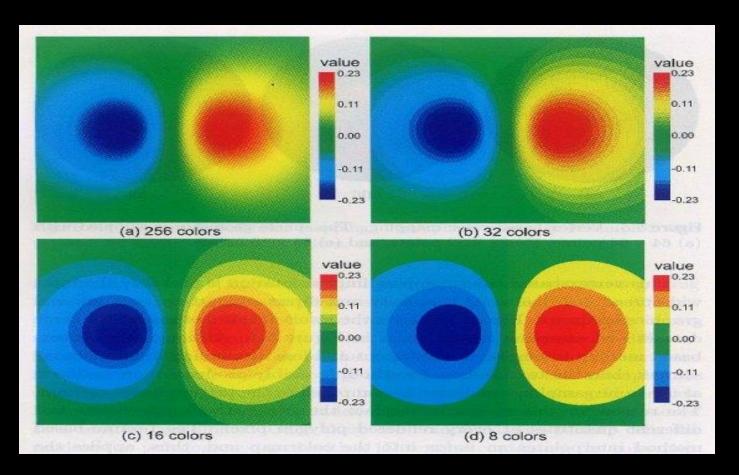


### Designing effective colormaps

- The choice of the number of Color N
  - A small N: color banding effect, artifact
  - Typical scalar visualization applications use 64 to 256 different colors
- Other factors for Colormap
  - Geometric factors
  - User group
  - The medium used to present the visualization

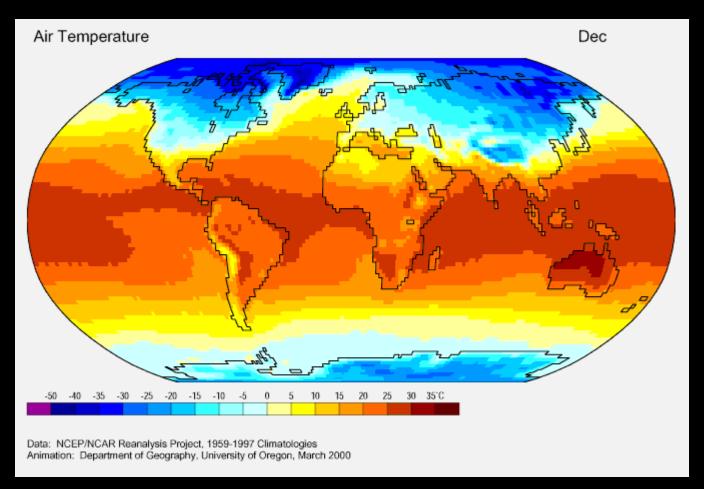


### Designing effective colormaps



Color banding caused by a small number of colors in a look-up table.

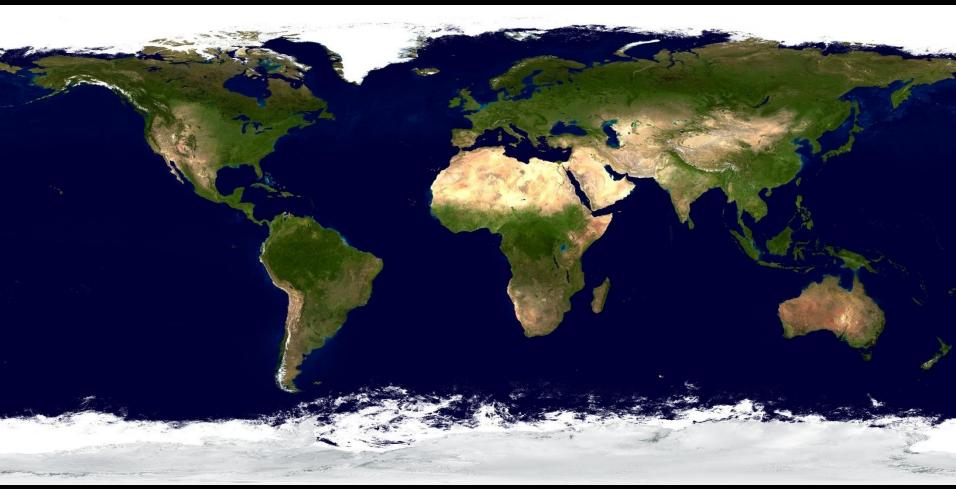




Global air temperature by month



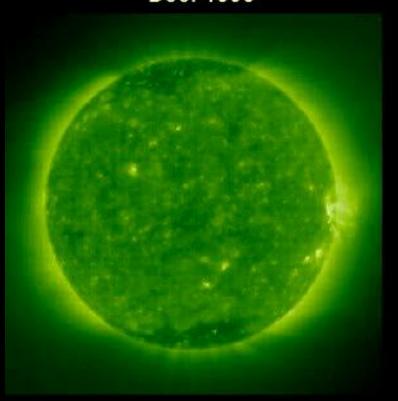
# Exp: Earth map



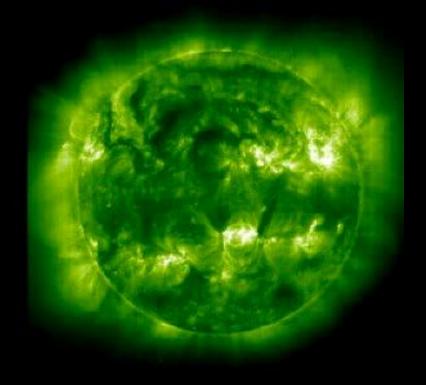


#### Exp: Sun in green-white colormap

EIT 195 Å Dec. 1996



EIT 195 Å June 1999





# **Exp:** Coronal loop



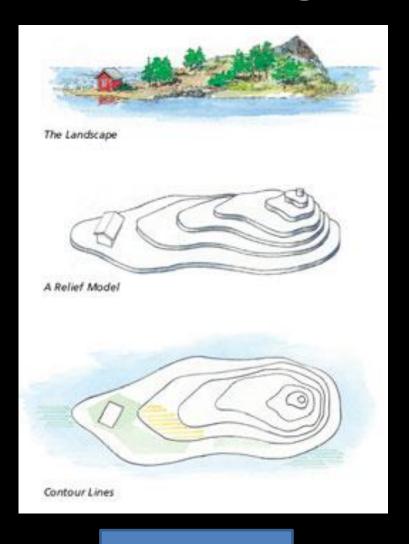
#### Summary

- Color mapping: generate color values from scalar values by
  - Colormap
  - Color transfer function
- Design issues for effective colormaps:
  - Knowledge of the application domain conventions
  - Typical data distribution
  - Visualization goals
  - General perception theory
  - Intended output devices
  - User preference

## Visualizing scalar data Popular scalar visualization techniques

- Color mapping
- Contouring
- Height plots





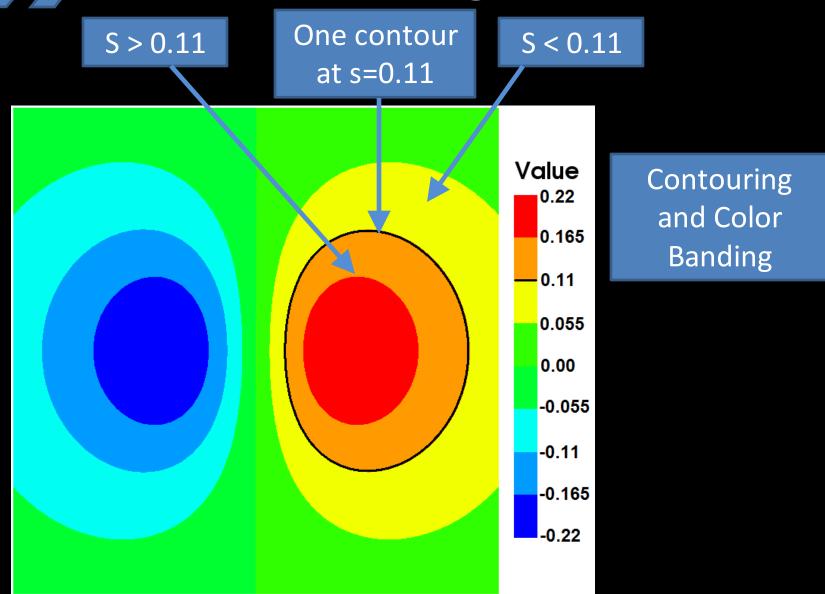
Cartograph

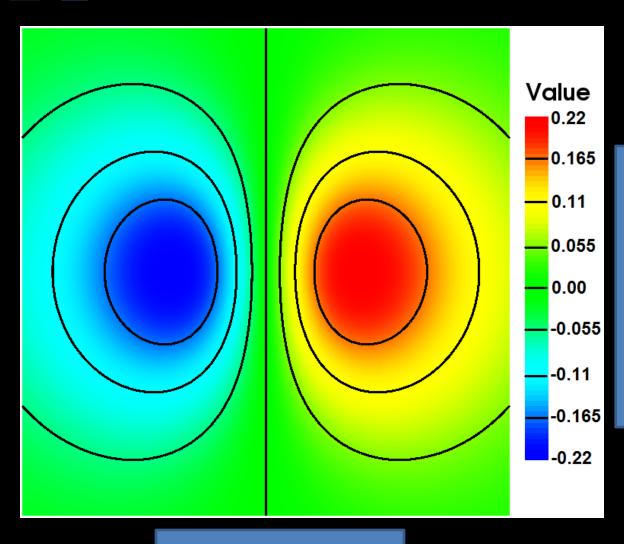


•A contour line C is defined as all points p in a dataset D that have the same scalar value, or isovalue s(p)=x

$$C(x) = \{ p \in D \mid s(p) = x \}$$

- For 2D dataset, a contour line is called an isoline
- For 3-D dataset, a contour is a 2-D surface, called isosurface





Contouring and Colormapping:

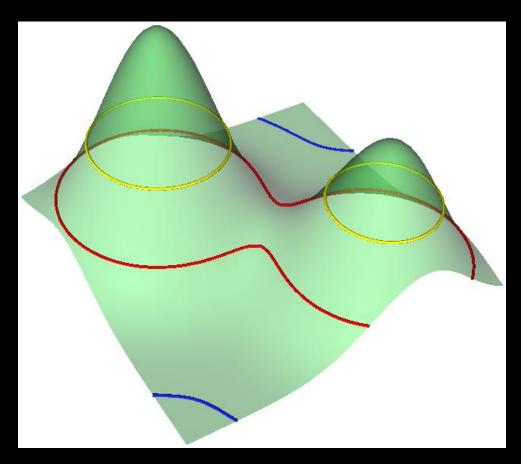
Show (1) the smooth variation and (2) the specific values

7 contour lines



## **Properties of Contours**

- Indicating specific values of interest
- •In the height-plot, a contour line corresponds with the interaction of the graph with a horizontal plane of s value

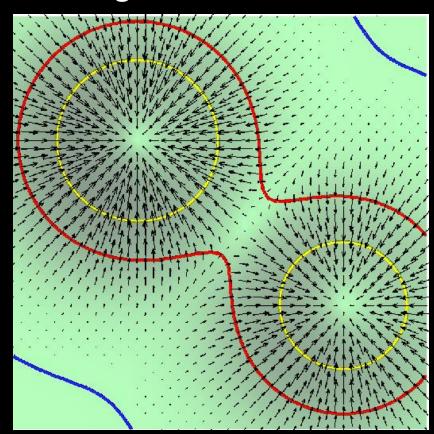




### **Properties of Contours**

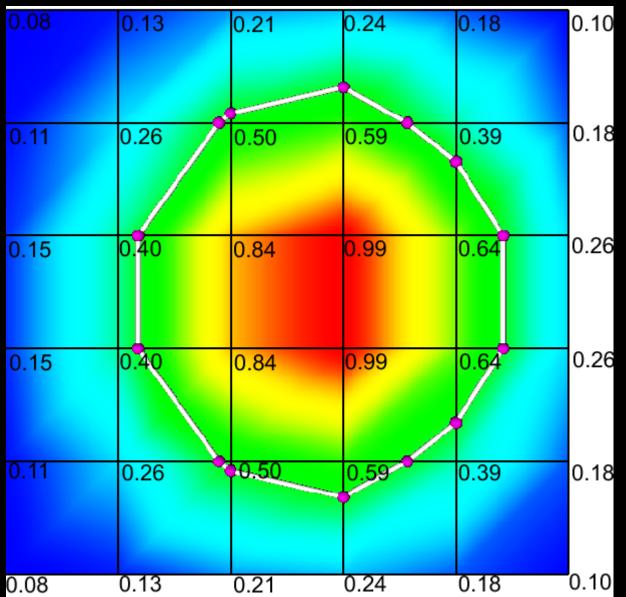
- •The tangent to a contour line is the direction of the function's minimal (zero) variation
- •The perpendicular to a contour line is the direction of the function's maximum variation: the gradient

Contour lines and **Gradient vector** 





#### **Constructing Contours**



V=0.48

Finding line segments within cells

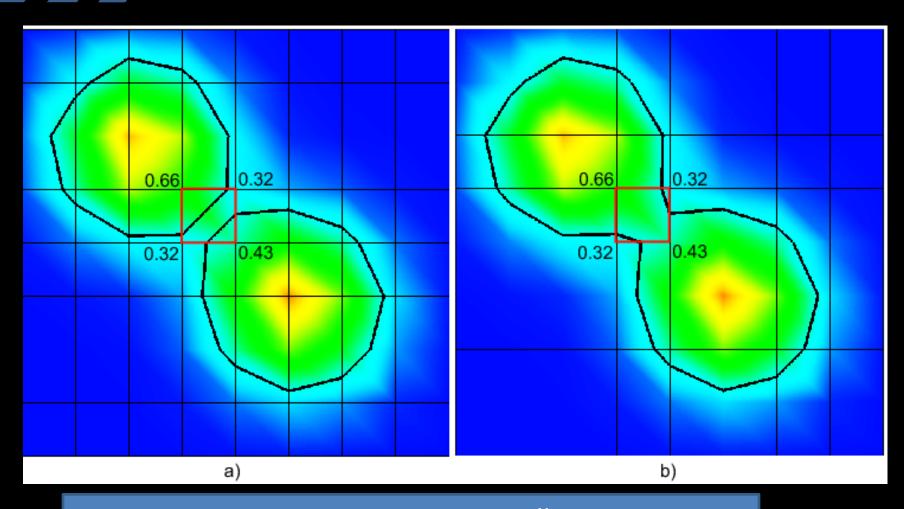
#### **Constructing Contours**

- For each cell, and then for each edge, test whether the isoline value v is between the attribute values of the two edge end points  $(v_i, v_i)$
- If yes, the isoline intersects the edge at a point q, which uses linear interpolation

$$q = \frac{p_i(v_j - v) + p_j(v - v_i)}{v_j - v_i}$$

- For each cell, at least two points, and at most as many points as cell edges
- •Use line segments to connect these edge-intersection points within a cell
- A contour line is a polyline.

# Constructing Contours



V=0.37: 4 intersection points in a cell

-> Contour ambiguity

Contouring need

- At least piecewise linear, C<sup>1</sup> dataset
- The complexity of computing contours
- The most popular method
  - 2D: Marching Squares
  - 3D: Marching Cubes

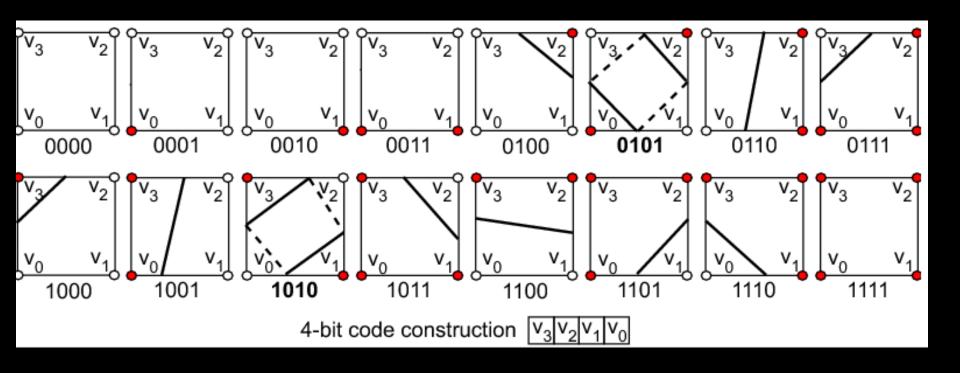


# Implementation: Marching Squares

- Determining the topological state of the current cell with respect to the isovalue v
  - •Inside state (1): vertex attribute value is less than isovalue
  - •Outside state (0): vertex attribute value is larger than isovalue
  - •A quad cell:  $(S_3S_2S_1S_0)$ ,  $2^4$ =16 possible states
    - •(0001): first vertex inside, other vertices outside
- •Use optimized code for the topological state to construct independent line segments for each cell
- Merge the coincident end points of line segments originating from neighboring grid cells that share an edge



# Implementation: Marching Squares



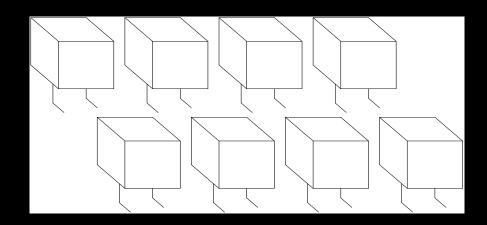
Topological State of a Quad Cell

#### **Marching Cubes**

- Similar to Marching Squares but 3D versus 2D
- 2<sup>8</sup>= 256 different topological cases; reduced to only
   15 by symmetry considerations
  - 16 topological states

- Marching Cubes: A High Resolution 3D Surface Construction Algorithm
  - William E. Lorensen & Harvey E. Cline
  - ACM SIGGRAPH 1987





Marching Cubes is an algorithm which "creates triangle models of constant density surfaces from 3D scalar data."

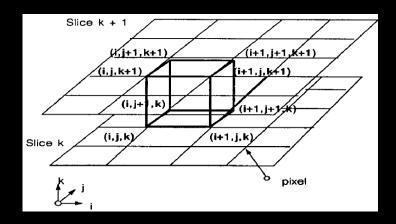


- High resolution surface construction algorithm.
- Extracts surfaces from adjacent pairs of data slices using cubes.
- Cubes "march" through the pair of slices until the entire surface of both slices has been examined.

# Marching Cubes Overview

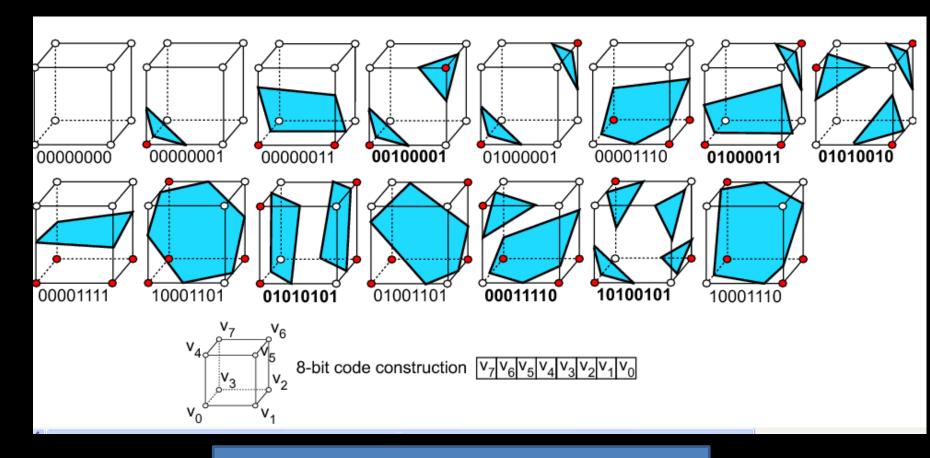
- Load slices.
- Create a cube from pixels on adjacent slices.
- Find vertices on the surfaces.
- Determine the intersection edges.
- Interpolate the edge intersections.
- Calculate vertex normals.
- Output triangles and normals.

#### How Are Cubes Constructed



- Uses identical squares of four pixels connected between adjacent slices.
- Each cube vertex is examined to see if it lies on or off of the surface.

### Implementation: Marching Cube

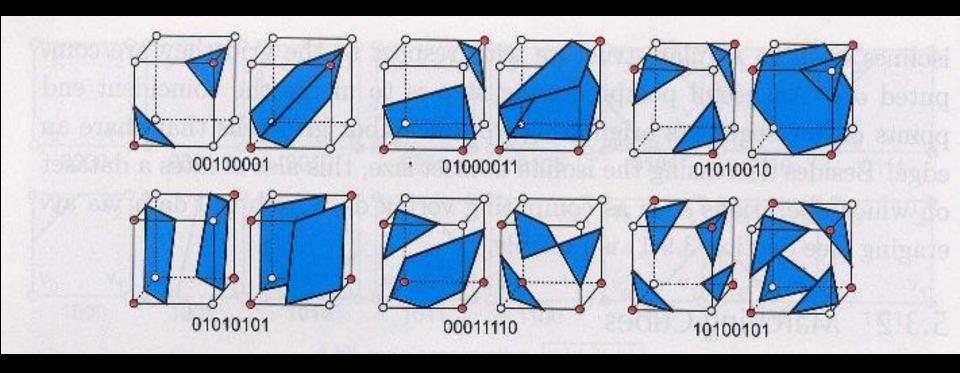


Topological State of a hex Cell

Marching cube generates a set of polygons for each contoured cell: triangle, quad, pentagon, and hexagon



## Marching Cubes -- Ambiguity

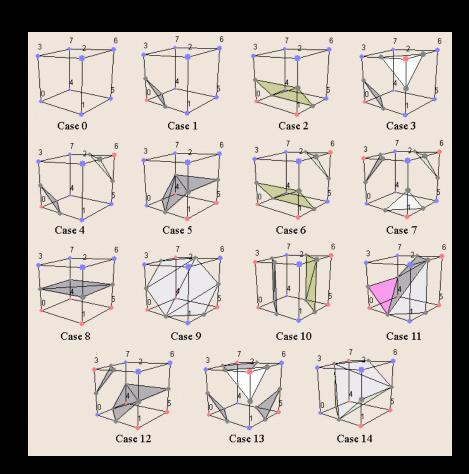


Ambiguous cases for marching cubes. Each case has two contouring variants.



### How Are The Cubes Used

- Pixels on the slice surfaces determine 3D surfaces.
- 256 surface permutations, but only 14 unique patterns.
- A normal is calculated for each triangle vertex for rendering.



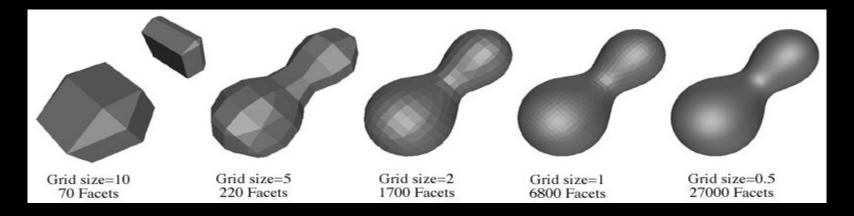


# Triangle Creation

- Determine triangles contained by a cube.
- Determine which cube edges are intersected.
- Interpolate intersection point using pixel density.
- Calculate unit normals for each triangle vertex using the gradient vector.



#### **Grid Resolution**



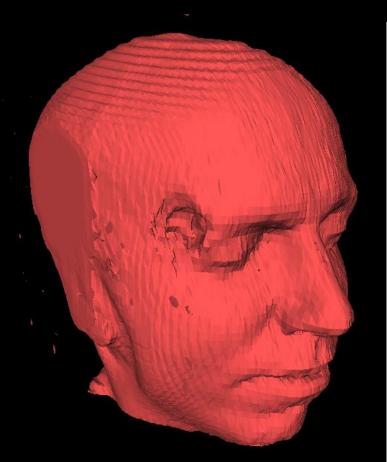
Variations can increase/decrease surface density.

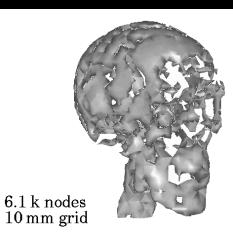


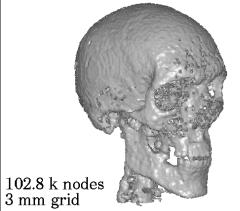
#### Improvements over Other Methods

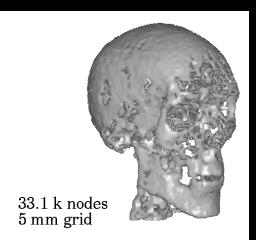
- Utilizes pixel, line and slice coherency to minimize the number of calculations.
- Can provide solid modeling.
- Can use conventional rendering techniques and hardware.
- No user interaction is necessary.
- Enables selective displays.
- Can be used with other density values.

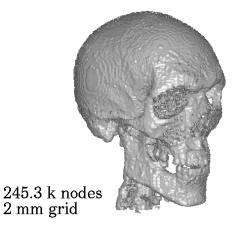














- General rule: most isosurface details that are under or around the size of the resolution of the iso-surfaced dataset can be
  - either actual data or artifact
  - should be interpreted with great care
- Can draw more than a single iso-surface of the same dataset in one visualization



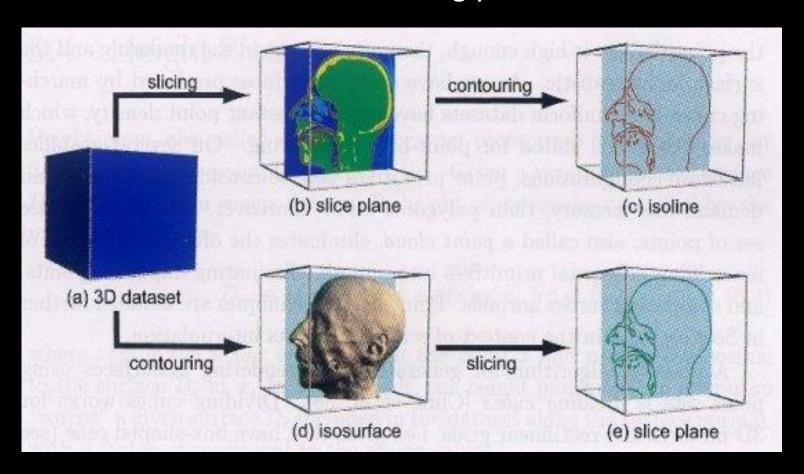
# Marching Cubes



Nested isosurfaces of a tooth scan dataset

#### **Marching Cubes**

Isosurfaces and isolines are strongly related



Isosurfaces, isolines, and slicing

#### Summary

- Marching Cubes provides a simple algorithm to translate a series of 2D scans into 3D objects
- Marching Squares and Marching Cubes have many variations to address:
  - Generalcity in terms of input dataset type
  - Speed of execution
  - Quality of obtained contours
- Isosurface can also be generated and rendered using pointbased techniques
  - 3D surface can be rendered using large numbers of (shaded) point primitives
  - Point primitive can be considerably faster and demand less memory than polygonal ones on some graphics hardware
  - Point cloud

# Visualizing scalar data Popular scalar visualization techniques

- Color mapping
- Contouring
- Height plots



 The height plot operation is to "warp" the data domain surface along the surface normal, with a factor proportional to the scalar value

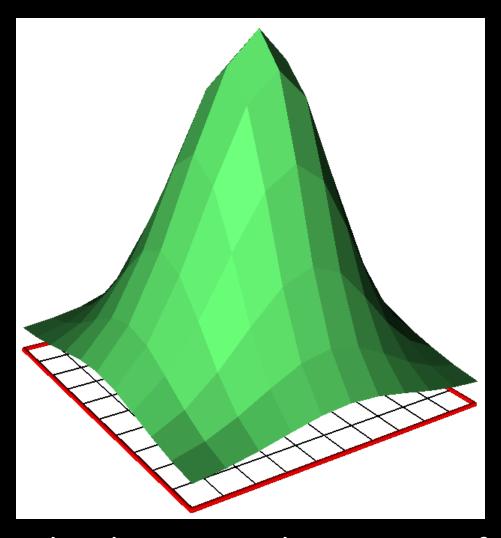
$$m: D_s \to D_h$$
,  
 $m(x) = x + s(x)\vec{n}(x)$ ,  
 $\forall x \in D_s$ 

Height plots (elevation or carpet plots)

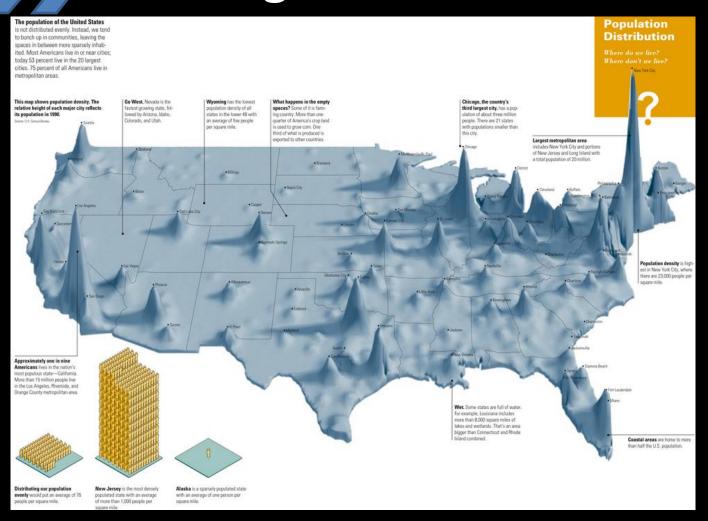
$$m: D_s \rightarrow D, m(x) = x + s(x)n(x), \forall x \in D_s$$

- S(x) is the scalar value of D at the point x
- n(x) is the normal to the surface Ds at x
- The height plot mapping operation "warp" a given surface Ds included in the dataset along the surface normal, with a factor proportional to the scalar values.
- Height plots are a particular case of displacement, or warped plots



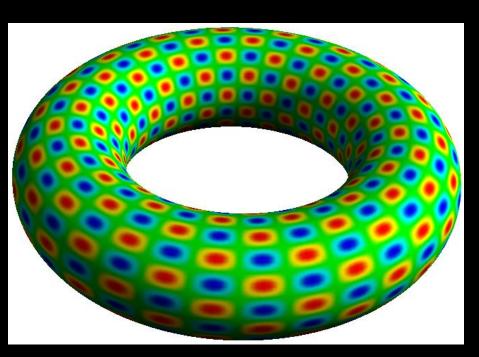


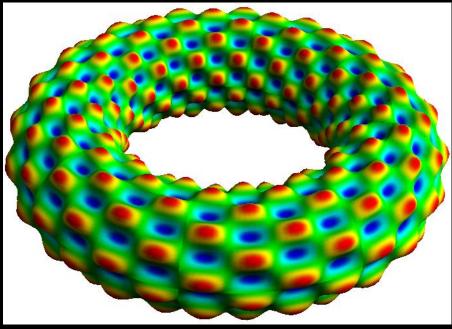
Height plot over a planar 2-D surface



Population density of America

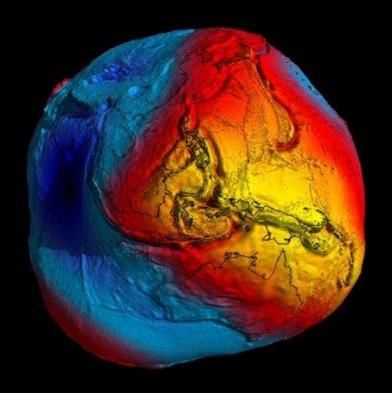






Height plot over a nonplanar 2-D surface





"Potato Earth" shows variations in planet's gravity

# 

#### Summary

- Visualizing scalar data
  - Color mapping

Assign a color as a function of the scalar value at each point of a given domain

- Contouring
  - Displaying all points with a given 2D or 3D domain that have a given scalar value
- Height plots
  - Deform the scalar dataset domain in a given direction as a function of the scalar data
- Advantage
  - Produce intuitive results
  - Easily understood by the vast majority of users
  - Simple to implement
- Disadvantage
  - A number of restrictions
  - One or two dimensional scalar dataset
  - We want to visualize the scalar values of ALL, not just a few of the data points of a 3D dataset