

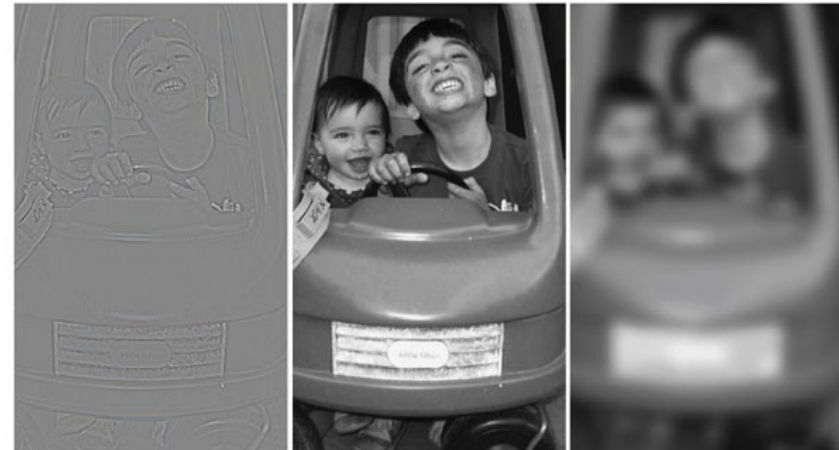
Content

- **Smoothing Images**

- spatial frequency
- box masks
- Gaussian masks

Computer Vision / Image Formation (Artificial and Biological)

Spatial Frequency: example

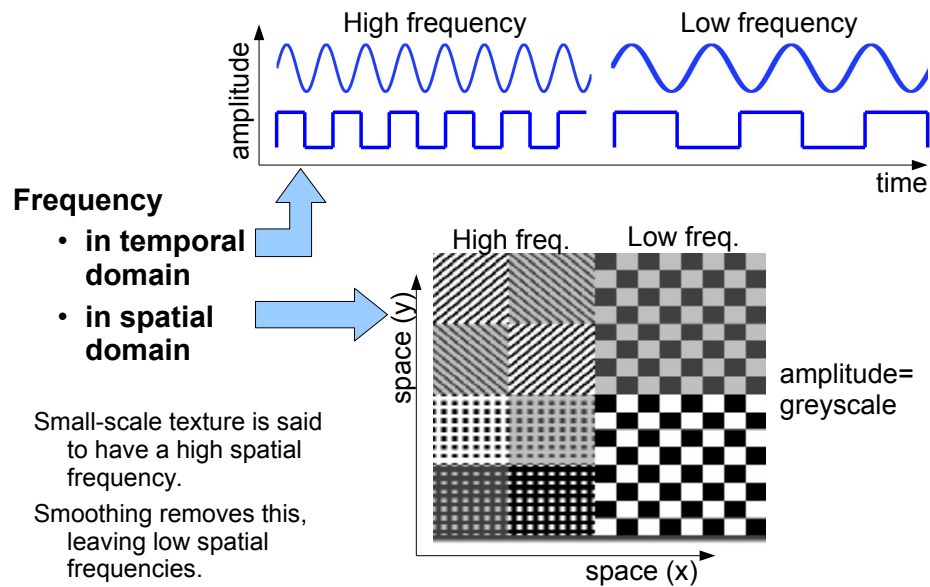


High

Low

Computer Vision / Low-Level Vision (Artificial)

Spatial Frequency



Computer Vision / Low-Level Vision (Artificial)

Box mask

1/9	1/9	1/9
1/9	1/9	1/9
1/9	1/9	1/9

Each pixel replaced by average of itself and its eight neighbours.

Generates a smoothed (blurred) image.

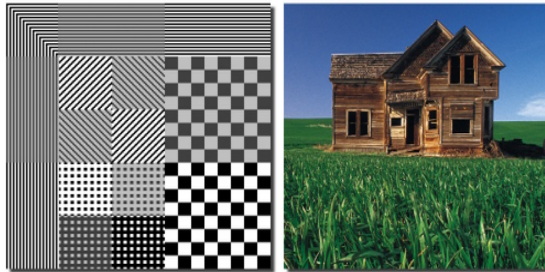
Useful.

Called “mean filter” or “box mask”.

Computer Vision / Low-Level Vision (Artificial)

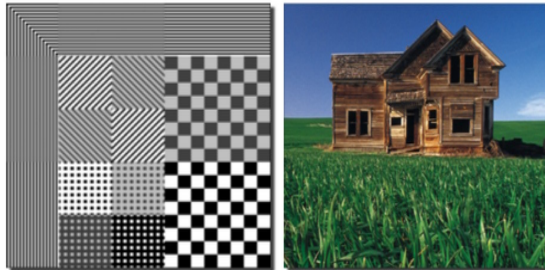
Smoothing mask example

Original Images



Images convolved with 3x3 box mask

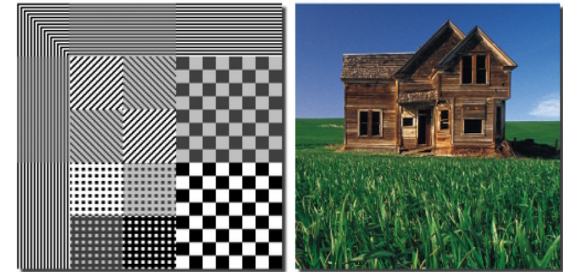
1/9	1/9	1/9
1/9	1/9	1/9
1/9	1/9	1/9



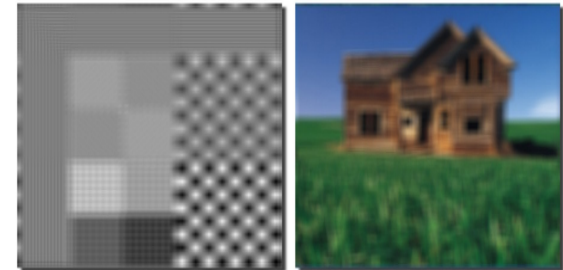
Computer Vision / Low-Level Vision (Artificial)

Smoothing mask example

Original Images



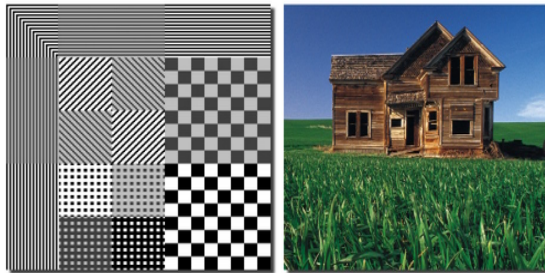
Images convolved with 17x17 box mask



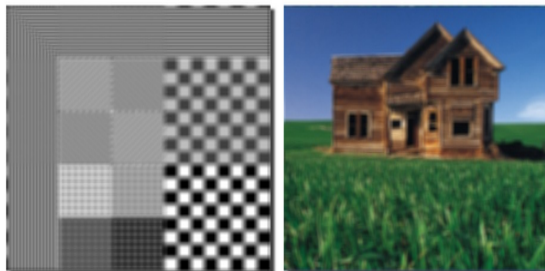
Computer Vision / Low-Level Vision (Artificial)

Smoothing mask example

Original Images



Images convolved with 9x9 box mask



Computer Vision / Low-Level Vision (Artificial)

Gaussian mask

The box mask is not very good at smoothing as it has sharp edges. The Gaussian mask is more effective as it falls off gently at the edges. It gives more weight to nearby pixels.



$$G(x, y) = \frac{1}{2\pi\sigma^2} \exp\left(\frac{-(x^2 + y^2)}{2\sigma^2}\right)$$

The Gaussian mask effectively removes any spatial frequencies with a period or wavelength smaller than the mask dimensions (defined by σ = standard deviation, or “scale”).

Computer Vision / Low-Level Vision (Artificial)

Smoothing with Gaussian mask

Original image



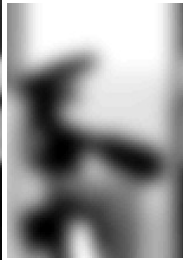
$\sigma=1$



$\sigma=2$



$\sigma=4$



“Scale” = the standard deviation of the Gaussian (i.e. σ)

as this parameter goes up:

- the size of the mask needs to increase (mask width should be $\geq 6\sigma$)
- more pixels are involved in the average
- the image gets more blurred (more high frequencies suppressed)
- noise is more effectively suppressed

Computer Vision / Low-Level Vision (Artificial)

Separability of the Gaussian mask

$$\begin{aligned} G(x, y) &= \frac{1}{2\pi\sigma^2} \exp\left(-\frac{(x^2 + y^2)}{2\sigma^2}\right) \\ &= \left\{ \frac{1}{\sqrt{2\pi}\sigma} \exp\left(-\frac{x^2}{2\sigma^2}\right) \right\} \left\{ \frac{1}{\sqrt{2\pi}\sigma} \exp\left(-\frac{y^2}{2\sigma^2}\right) \right\} \end{aligned}$$

i.e. 2D Gaussian is the product of two 1D Gaussians.

Each 1D Gaussian is a function of one variable only (either x or y)