HW #4 (Polygon & Polynomial)

Part A

- A *Polygon* is characterized by *m* points (or sides). Each
 of the points is *n*-dimensional. For example, for point *i*,
 its coordinates is given by (x_{i, 0}, x_{i, 1}, ..., x_{i, n-1}).
- You are to implement, using C++, or Java if you prefer, a class for *Polygon* using an internal 2D array *point*. *point*[i] is the ith point of the polygon $(0 \le i \le m)$, which stores all the n coordinates. In other words, $_point[i][j]$ is the jth coordinate of the ith point, where $0 \le i \le m$ -1 and $0 \le j \le n$ -1.
- You are given the polygon class defined as below:

HW #4 (2)

```
class Polygon {
public:
  // default constructor
  // m is the number of points
  // n is the dimension of the points
  Polygon (unsigned int m = 0, unsigned int n = 0) {
       cout << "default constructor" << endl;
       // ...
```

HW #4 (3)

```
Polygon (const Polygon& mt); // copy constructor ~Polygon (); // destructor double* FindCentroid() const; // return the centroid of the // polygon
```

```
const int getNumOfPoints() const { return _m; }
const int getDimension() const { return _n; }
```

HW #4 (4)

```
// Accessor: Get the value stored at the m-th point and n-th
// dimension
const double getValue (unsigned int m, unsigned int n)
  const {
  if (m<0 || m>=_m || n<0 || n>=_n) {
       cerr << "ERROR: Index our of range" << endl;
      exit(-1);
  else return _point[m][n];
```

HW #4 (5)

```
// Mutator: Set the value at the m-th point and n-th
// coordinate
bool setValue (double & value, unsigned int m, unsiged int
  n) {
  if (m>=0 && m<_m && n>=0 && n<_n) {
       _point[m][n] = value;
       return true;
  else
       return false;
```

HW #4 (6)

HW #4 (7)

A1:

```
    Implement the copy constructor. Note that the input parameter mt may be a polygon which has no points (i.e., its _point is NULL and _m = _n = 0.)
    // copy constructor
    Polygon::Polygon (const Polygon& mt) {
        cout << "copy constructor" << endl;
        // implement your code below</li>
```

HW #4 (8)

A2:

Implement the destructor.
 // destructor
 Polygon::~Polygon() {
 cout << "destructor" << endl;
 // implement your code below

HW #4 (9)

A3:

• Implement the member function FindCentroid(), which returns the centroid of the polygon. Given a polygon of m points labeled as $x_0, x_1, x_2, ..., x_{m-1}$ and the coordinates of point i given by $(x_{i, 0}, x_{i, 1}, ..., x_{i, n-1})$, then the coordinate of the centroid is given by $(c_0, c_1, ..., c_{n-1})$ where

for
$$0 \le j \le n-1$$
. $c_j = \frac{1}{m} \sum_{i=0}^{m-1} x_{i,j}$,

 FindCentroid returns a pointer to an array which holds the centroid of the polygon.

```
// Returns the centroid of the polygon as an array double* Polygon::FindCentroid() const {
    // implement your code below
```

HW #4 (10)

A4:

HW #4 (11)

```
int main() {
  Polygon p(3, 4);
  double k = 0;
  for (int i=0; i<p.getNumOfPoints(); i++)
       for (int j=0; j<p.getDimension(); j++) {
              k += 1:
              p.setValue(k, i, j);
PrintPoints(p);
double* centroid = p.FindCentroid();
```

HW #4 (12)

```
for (int n=0; n<p.getDimension(); n++)
     cout << "centroid[n] << " ";
cout << endl;
return 0;</pre>
```

HW #4 (13)

Part B

- A polynomial f(x) of degree n is written as $f(x) = c_n x^n + c_{n-1} x^{n-1} + \dots + c_i x^i + \dots + c_1 x^1 + c_0 x^0$, (1) where i is called the exponent of x^i , c_i is the coefficient of x^i , and $c_i x^i$ is called the ith term, $0 \le i \le n$.
- In this problem, you will implement a polynomial ADT using a linked list with a dummy header (for sentinel) node. For example, we represent the polynomial $f(x) = 5x^7 + 2x^4 + 1x^3 + 4x^0$ by the following linked list, where the first node is a dummy whose term field has no meaning:

 Dummy Node

2

3

NULL

0

next

head

0

HW #4 (14)

 In the implementation, each term is stored as a Term object consisting of the coefficient and exponent. Each node in the linked list consists of a Term object and a next pointer pointing to the next node. The definition of all the classes are shown below:

```
#define NodePointer Node*
typedef int CoefType;
// term in a polynomial
class Term {
public:
    CoeffType coef;
    int expo;
\.
```

HW #4 (15)

```
// node in a linked list
class Node {
private:
  Term data;
  NodePointer next;
public:
// node constructor
  Node (CoefType co = 0, int ex = 0, Node * ptr = NULL) {
       data.coef = co;
       data.expo = ex;
       next = ptr; }
  friend class Polynomial; };
```

HW #4 (16)

 The polynomial ADT with some of its supporting functions is given below:

```
// polynomial ADT
class Polynomial {
  private:
    NodePointer head; // pointing to the first dummy node
  public:
    // constructor
    Polynomial (CoefType* c = NULL, int* e = NULL, int num
    = 0);
```

HW #4 (17)

```
// destructor
~Polynomial();
// add a term into the polynomial
void add (CoefType c, int e);
// differentiation
void differentiate();
};
```

HW #4 (18)

B1:

 Implement the add member function in the polynomial class, which adds a term with coefficient c and exponent e to a polynomial object. Note that the term should be added into the polynomial object in such as way that the exponents are in decreasing order. If the exponent has already existed, their coefficients will be added.

```
// adding a term to the polynomial with decreasing
// exponents
// c: the coefficient
// e: the exponent
void Polynomial::add(CoefType c, int e) {
```

HW #4 (19)

B2:

 Given the above, implement the constructor, which takes in an array of coefficients and their corresponding exponents to form a polynomial with decreasing exponents. Note that the exponents that e points to may not be sorted and may be repeated. If the exponents are repeated, their coefficients should be added together.

```
// constructor
// c: pointer to an array of coefficients
// e: pointer to the corresponding exponents
// num: the number of elements in c (or e); num >= 0
Polynomial::Polynomial (CoefType* c, int* e, int num) {
```

HW #4 (20)

B3:

Implement the destructor:

// destructor

Polynomial::~Polynomial() {

B4:

Implement the differentiation (or derivative) function which self-differentiates the polynomial. The derivative of f(x) given by Equation (1) is defined as f'(x) = nc_nxⁿ⁻¹ + (n-1)c_{n-1}xⁿ⁻² + ... + 2c₂x + c₁x⁰. void Polynomial::differentiate() {