



Fabio Bergonti



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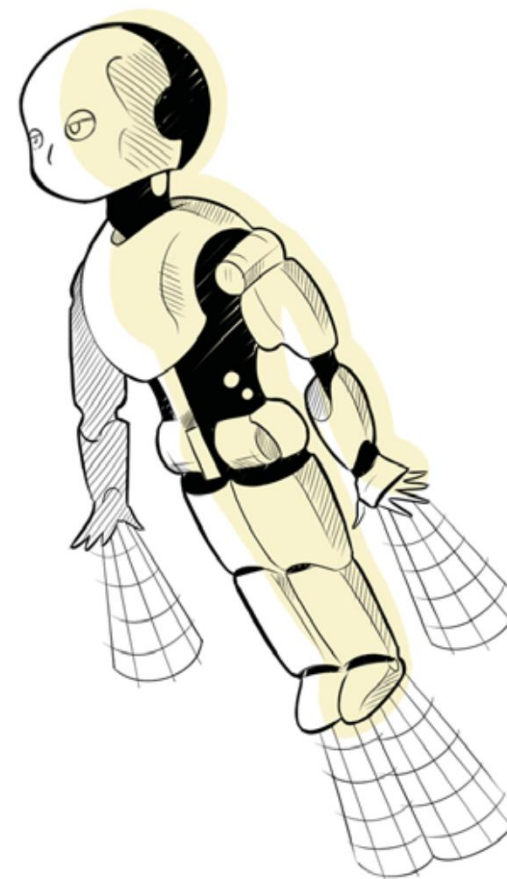
PhD Student (1y) @ Italian Institute of Technology
«Design and control of morphing covers in robot applications»

Team member of **iRonCub**

MSc in Mechanical Engineering @ Polytechnic of Milan
«Wholebody control for jumping humanoid robot»

Research interests

- Compliant mechanisms
- 3D printing
- Mechanical system dynamics



ISTITUTO ITALIANO
DI TECNOLOGIA
DYNAMIC INTERACTION
CONTROL