

view_frames Result
Recorded at time: 1611896567.629

base_footprint

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1611896567.629 sec old)
Buffer length: 0.000 sec

Base_Frame

base_link

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1611896567.629 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1611896567.629 sec old)
Buffer length: 0.000 sec

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Most recent transform: 0.000 (1611896567.629 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot_state_publisher
Average rate: 10.204 Hz
Most recent transform: 1611896567.612 (0.016 sec old)
Buffer length: 4.900 sec

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Average rate: 10.204 Hz
Most recent transform: 1611896567.612 (0.016 sec old)
Buffer length: 4.900 sec

zed_camera_center

laser_base_link

maximum_lighthouse_x

maximum_lighthouse_xy

minimum_lighthouse_x

minimum_lighthouse_xy

laser_data_link

lighthouse_mount

wheel_back_left

wheel_back_right

wheel_front_left

wheel_front_right

zed_right_camera_frame

zed_left_camera_frame

laser_spinny_link

lighthouse_rotate

Lighthouse BeFrame

Lighthouse Frame

zed_right_camera_optical_frame

zed_left_camera_optical_frame

zed_right_camera_optical_frame

zed_left_camera_optical_frame

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