

# Demonstration of Paraview



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# Contents

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- **Abstract**
- **Introduction**
- **Examples**
- **Concluding Remarks**
- **Reference**

# Abstract

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## Paraview:

- ❖ Brief tutorial for visualization

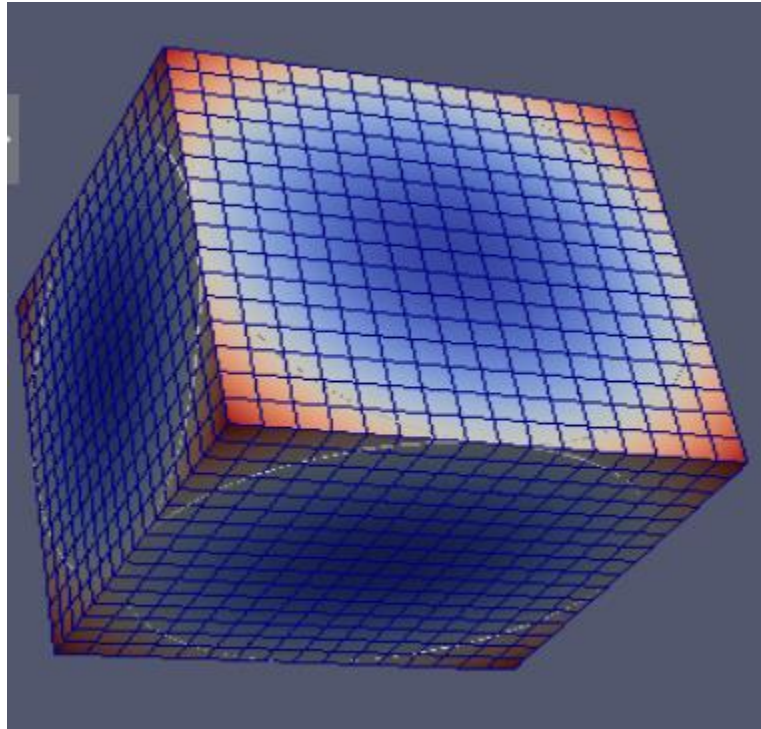
2D

3D

# Introduction

## Paraview:

- ❖ Demonstration of 2D and 3D file
- ❖ Explain step 57



# Step-57

Navier Stokes equation:

$$\begin{aligned} -\nu \Delta \mathbf{u} + (\mathbf{u} \cdot \nabla) \mathbf{u} + \nabla p &= \mathbf{f} \\ -\nabla \cdot \mathbf{u} &= 0. \end{aligned}$$

Linearization:

$$F(\mathbf{u}, p) = \begin{pmatrix} -\nu \Delta \mathbf{u} + (\mathbf{u} \cdot \nabla) \mathbf{u} + \nabla p - \mathbf{f} \\ -\nabla \cdot \mathbf{u} \end{pmatrix}.$$

Newton's iteration on a vector function can be defined as

$$\mathbf{x}^{k+1} = \mathbf{x}^k - (\nabla F(\mathbf{x}^k))^{-1} F(\mathbf{x}^k),$$

Final Linearization system

$$\begin{aligned} -\nu \Delta \delta \mathbf{u}^k + \mathbf{u}^k \cdot \nabla \delta \mathbf{u}^k + \delta \mathbf{u}^k \cdot \nabla \mathbf{u}^k + \nabla \delta p^k &= -F(\mathbf{x}^k), \\ -\nabla \cdot \delta \mathbf{u}^k &= \nabla \cdot \mathbf{u}^k, \end{aligned}$$

Initial Guess

Preconditioner

$$\begin{aligned} -\nu_1 \Delta \mathbf{u} + (\mathbf{u} \cdot \nabla) \mathbf{u} + \nabla p &= \mathbf{f}, \\ -\nabla \cdot \mathbf{u} &= 0, \end{aligned}$$

$$\begin{pmatrix} A & B^T \\ B & 0 \end{pmatrix} \begin{pmatrix} U \\ P \end{pmatrix} = \begin{pmatrix} F \\ 0 \end{pmatrix}.$$

Test case

$$\begin{aligned} (u(x, y), v(x, y)) &= (1, 0) && \text{if } y = 1 \\ (u(x, y), v(x, y)) &= (0, 0) && \text{otherwise.} \end{aligned}$$

**Thank You**