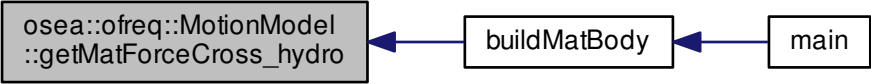


osea::ofreq::MotionModel
::getMatForceCross_hydro



```
graph RL; main --> buildMatBody; buildMatBody --> osea::ofreq::MotionModel::getMatForceCross_hydro;
```

buildMatBody

main