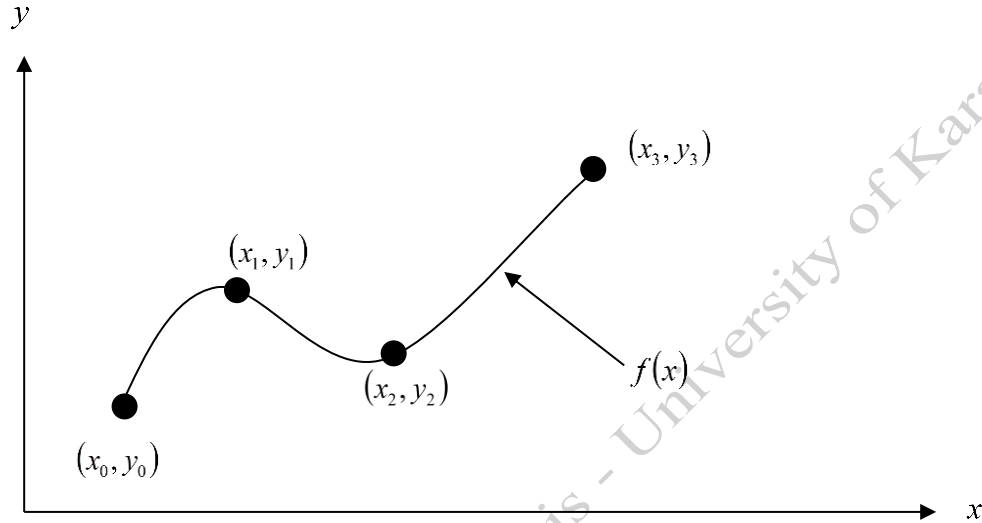


INTERPOLATION:

NEWTON DIVIDED DIFFERENCE (POLYNOMIAL METHOD)

**Derivation:**



**Figure 1 Interpolation of discrete data.**

### Linear Interpolation

**Given**  $(x_0, y_0)$  and  $(x_1, y_1)$ , **fit a linear interpolant through the data.** Noting  $y = f(x)$  and  $y_1 = f(x_1)$ , **assume the linear interpolant**  $f_1(x)$  **is given by (Figure 2)**

$$f_1(x) = b_0 + b_1(x - x_0)$$

**Since at**  $x = x_0$ ,

$$f_1(x_0) = f(x_0) = b_0 + b_1(x_0 - x_0) = b_0$$

**and at**  $x = x_1$ ,

$$\begin{aligned} f_1(x_1) &= f(x_1) = b_0 + b_1(x_1 - x_0) \\ &= f(x_0) + b_1(x_1 - x_0) \end{aligned}$$

**giving**

$$b_1 = \frac{f(x_1) - f(x_0)}{x_1 - x_0}$$

**So**

$$b_0 = f(x_0)$$

$$b_1 = \frac{f(x_1) - f(x_0)}{x_1 - x_0}$$

**giving the linear interpolant as**

$$f_1(x) = b_0 + b_1(x - x_0)$$

$$f_1(x) = f(x_0) + \frac{f(x_1) - f(x_0)}{x_1 - x_0}(x - x_0)$$

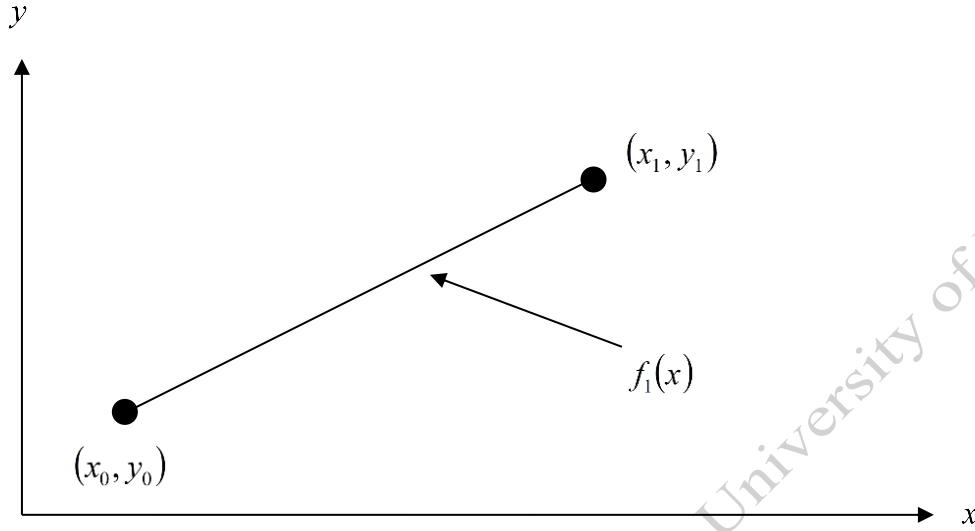


Figure 2 Linear interpolation.

### Quadratic Interpolation

**Given**  $(x_0, y_0)$ ,  $(x_1, y_1)$ , and  $(x_2, y_2)$ , **fit a quadratic interpolant through the data.** Noting  $y = f(x)$ ,  $y_0 = f(x_0)$ ,  $y_1 = f(x_1)$ , and  $y_2 = f(x_2)$ , **assume the quadratic interpolant  $f_2(x)$  is given by**

$$f_2(x) = b_0 + b_1(x - x_0) + b_2(x - x_0)(x - x_1)$$

**At**  $x = x_0$ ,

$$= b_0$$

$$b_0 = f(x_0)$$

**At**  $x = x_1$

$$f_2(x_1) = f(x_1) = b_0 + b_1(x_1 - x_0) + b_2(x_1 - x_0)(x_1 - x_1)$$

$$f(x_1) = f(x_0) + b_1(x_1 - x_0)$$

**giving**

$$b_1 = \frac{f(x_1) - f(x_0)}{x_1 - x_0}$$

**At**  $x = x_2$

$$f_2(x_2) = f(x_2) = b_0 + b_1(x_2 - x_0) + b_2(x_2 - x_0)(x_2 - x_1)$$

$$f(x_2) = f(x_0) + \frac{f(x_1) - f(x_0)}{x_1 - x_0}(x_2 - x_0) + b_2(x_2 - x_0)(x_2 - x_1)$$

**Giving**

$$b_2 = \frac{\frac{f(x_2) - f(x_1)}{x_2 - x_1} - \frac{f(x_1) - f(x_0)}{x_1 - x_0}}{x_2 - x_0}$$

**Hence the quadratic interpolant is given by**

$$\begin{aligned} f_2(x) &= b_0 + b_1(x - x_0) + b_2(x - x_0)(x - x_1) \\ &= f(x_0) + \frac{f(x_1) - f(x_0)}{x_1 - x_0}(x - x_0) + \frac{\frac{f(x_2) - f(x_1)}{x_2 - x_1} - \frac{f(x_1) - f(x_0)}{x_1 - x_0}}{x_2 - x_0}(x - x_0)(x - x_1) \end{aligned}$$

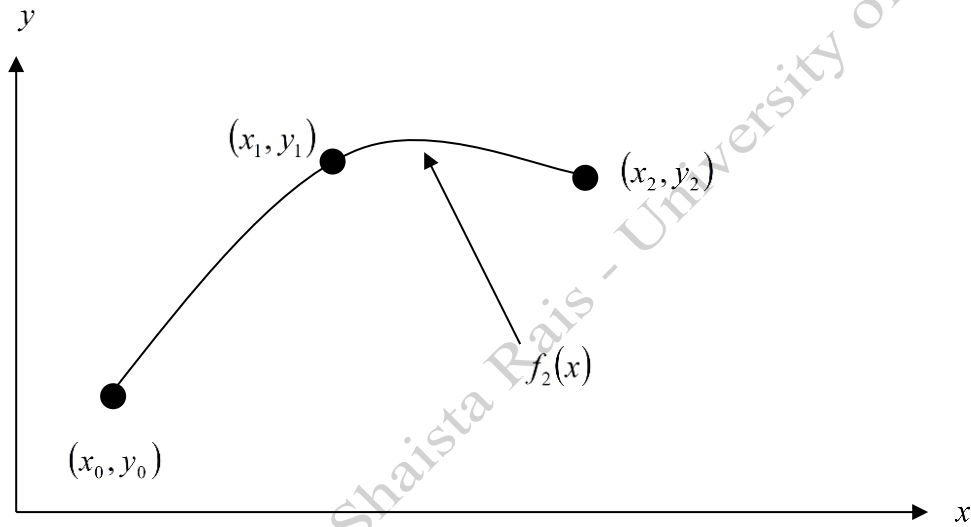


Figure 3: Quadratic interpolation.

General Form of Newton's Divided Difference Polynomial

**In the two previous cases, we found linear and quadratic interpolants for Newton's divided difference method. Let us revisit the quadratic polynomial interpolant formula**

$$f_2(x) = b_0 + b_1(x - x_0) + b_2(x - x_0)(x - x_1)$$

**where**

$$\begin{aligned} b_0 &= f(x_0) \\ b_1 &= \frac{f(x_1) - f(x_0)}{x_1 - x_0} \\ b_2 &= \frac{\frac{f(x_2) - f(x_1)}{x_2 - x_1} - \frac{f(x_1) - f(x_0)}{x_1 - x_0}}{x_2 - x_0} \end{aligned}$$

**Note that  $b_0$ ,  $b_1$ , and  $b_2$  are finite divided differences.  $b_0$ ,  $b_1$ , and  $b_2$  are the first, second, and third finite divided differences, respectively. We denote the first divided difference by**

$$f[x_0] = f(x_0)$$

the second divided difference by

$$f[x_1, x_0] = \frac{f(x_1) - f(x_0)}{x_1 - x_0}$$

and the third divided difference by

$$\begin{aligned} f[x_2, x_1, x_0] &= \frac{f[x_2, x_1] - f[x_1, x_0]}{x_2 - x_0} \\ &= \frac{\frac{f(x_2) - f(x_1)}{x_2 - x_1} - \frac{f(x_1) - f(x_0)}{x_1 - x_0}}{x_2 - x_0} \end{aligned}$$

where  $f[x_0]$ ,  $f[x_1, x_0]$ , and  $f[x_2, x_1, x_0]$  are called bracketed functions of their variables enclosed in square brackets.

Rewriting,

$$f_2(x) = f[x_0] + f[x_1, x_0](x - x_0) + f[x_2, x_1, x_0](x - x_0)(x - x_1)$$

This leads us to writing the general form of the Newton's divided difference polynomial for  $n+1$  data points,  $(x_0, y_0), (x_1, y_1), \dots, (x_{n-1}, y_{n-1}), (x_n, y_n)$ , as

$$f_n(x) = b_0 + b_1(x - x_0) + \dots + b_n(x - x_0)(x - x_1) \dots (x - x_{n-1})$$

where

$$b_0 = f[x_0]$$

$$b_1 = f[x_1, x_0]$$

$$b_2 = f[x_2, x_1, x_0]$$

$$\vdots$$

$$b_{n-1} = f[x_{n-1}, x_{n-2}, \dots, x_0]$$

$$b_n = f[x_n, x_{n-1}, \dots, x_0]$$

where the definition of the  $m^{\text{th}}$  divided difference is

$$\begin{aligned} b_m &= f[x_m, \dots, x_0] \\ &= \frac{f[x_m, \dots, x_1] - f[x_{m-1}, \dots, x_0]}{x_m - x_0} \end{aligned}$$

From the above definition, it can be seen that the divided differences are calculated recursively.