

# Learnability Is a Compact Property

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# Warm-up: binary classification

## Known

Domain  $\mathcal{X}$

Label set  $\mathcal{Y} = \{0, 1\}$

Class  $\mathcal{H} \subseteq \{0, 1\}^{\mathcal{X}}$

## Unknown

Distribution  $\mathcal{D}$  on  $\mathcal{X}$

(Realizable learning:  $\mathcal{D}$  arbitrary)

Ground truth  $h^* \in \mathcal{H}$

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Given iid draws from  $\mathcal{D}$  (labeled by  $h^*$ ),  
guess  $h^*$ !

Judged by error,

$$\mathbb{P}_{x \sim \mathcal{D}}(f(x) \neq h^*(x))$$

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Can  $\mathcal{H}$  be learned with error  $\rightarrow 0$  as  
 $\# \text{ samples} \rightarrow \infty$ ?

# VC dimension is all you need

## VC dimension

$\mathcal{H}$  shatters  $S = (x_1, \dots, x_n)$  when  
 $\mathcal{H}|_S = \{0, 1\}^n$

$\text{VC}(\mathcal{H})$  = size of largest shattered set

Fundamental theorem:

$\mathcal{H}$  is learnable  $\Leftrightarrow \text{VC}(\mathcal{H}) < \infty$ .

Attaining error  $\leq \varepsilon$  w.h.p. requires  $\tilde{\Theta}\left(\frac{\text{VC}(\mathcal{H})}{\varepsilon}\right)$  points.

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Binary classification solved 😊

An observation: VC dimension only “knows” about finite projections of  $\mathcal{H}$ ...

## Why is that enough?

### Fundamental theorem:

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# Binary classification is “compact”

VC theory reveals compactness:

- If  $\mathcal{H}$ ’s finite projections look good, then  $\mathcal{H}$  is learnable
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**Why does this work?**

When learning  $\mathcal{H}$ , distribution  $\mathcal{D}$  can have infinite support, even be continuous!

Considering finite projections  $\mathcal{H}|_S$  doesn’t pick up on hardness of learning these distributions...

# Beyond binary classification

Much of learning theory follows the skeleton of VC dimension

1. Say  $\mathcal{H}$  shatters  $S = (x_1, \dots, x_n)$  if  $\mathcal{H}|_S$  has a finite subset such that...
2. Let  $d = d(\mathcal{H})$  be the size of the largest shattered set
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## Examples

- Fat shattering dimension
- Graph dimension
- Natarajan dimension
- DS dimension
- Littlestone dimension

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Why is this happening? Will we eventually describe all kinds of learning in this way?

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**No.**

# EMX learning: noncompact

## EMX Learning

$$\mathcal{X} = \mathbb{R}, \mathcal{Y} = \{0,1\}$$

$$\mathcal{H} = \{h : |h^{-1}(1)| < \infty\}$$

Given  $h^*$ ,  $\mathcal{D}$  must be supported  
on  $(h^*)^{-1}(1)$ . I.e., only see the  
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Learner must be *proper*, emit  
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## In English:

- Ground set  $\mathcal{X}$
- Distribution  $\mathcal{D}$  over  $\mathcal{X}$  (finite support)
- Given iid samples from  $\mathcal{D}$ , pick finite  $S \subseteq \mathcal{X}$  with maximum  $\mathcal{D}$ -measure

When  $\mathcal{X}$  is finite, trivial.

Pick  $S = \mathcal{X}$ !

What about  $\mathcal{X} = \mathbb{R}$ ?

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For infinite  $\mathcal{X}$ , learnability depends on  $|\mathcal{X}|$

(Such that  $\mathcal{H}$  is learnable  $\Leftrightarrow |\mathcal{X}| < \aleph_\omega$ . Thus, undecidable when  $\mathcal{X} = \mathbb{R}$ .)

If  $\mathcal{X}$  too large,  $\mathcal{H}$  is not learnable. Even though all its finite restrictions are easy!

Failure of compactness!  
(When learners are required to be proper)

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*Where and why does compactness appear in improper supervised learning?*

*In light of EMX learning, why do standard learning paradigms happen to be compact?*

# Our Results

Let:

- $\mathcal{X}$  = arbitrary set
- $\mathcal{Y}$  = *proper* metric space
- $\mathcal{H}$  = hypothesis class
- “Finite projection” of  $\mathcal{H}$  = finite subset of  $\mathcal{H}|_S$  for finite  $S \subseteq \mathcal{X}$

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**Compact  $\Leftrightarrow$  closed & bounded**

- $\mathbb{R}^n$  and its closed subsets (any norm)
- Any finite space
- Any compact space

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**Theorem:** For realizable learning, the following are equivalent,

1.  $\mathcal{H}$  can be learned with transductive sample complexity  $m$
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Very general and **exact** form of compactness!

What if  $\mathcal{Y}$  isn't proper?

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**Theorem:** For realizable learning, there exists an (improper)  $\mathcal{Y}$  s.t.

1. Any finite projection of  $\mathcal{H}$  can be learned with complexity  $m$
2. Learning  $\mathcal{H}$  requires  $m_{\mathcal{H}} > m$  samples, with  $m_{\mathcal{H}}(\varepsilon) \geq m(\varepsilon/2)$  for some  $\varepsilon$

Improper  $\mathcal{Y}$ : compactness can fail by at least a factor of 2

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**Theorem:** Suppose any finite projection of  $\mathcal{H}$  can be learned with realizable complexity  $m$ . Then  $\mathcal{H}$  is learnable with at most  $m(\varepsilon/2)$  samples.

Improper  $\mathcal{Y}$ : compactness can fail by at least **most** a factor of 2.

Complete characterization of compactness for realizable learning with metric losses!

# Beyond the realizable case

## Agnostic learning

$\mathcal{D}$  can be any distribution on  $\mathcal{X} \times \mathcal{Y}$

Proper  $\mathcal{Y}$ : **exact** compactness of sample complexity!  $\mathcal{H}$  learnable with  $m$  samples  
 $\Leftrightarrow$  finite projections learnable with  $m$  samples

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## Distribution-family learning

$\mathcal{D}$  constrained to certain distributions on  $\mathcal{X} \times \mathcal{Y}$ , i.e.,  $\mathcal{D} \in \mathbb{D}$

Call  $\mathbb{D}$  **well-behaved** if it is closed under empirical distributions  
( $\forall \mathcal{D} \in \mathbb{D}$  and  $S \sim \mathcal{D}^n$ ,  $\text{Unif}(S) \in \mathbb{D}$ . E.g., partial, EMX, etc.)

Proper  $\mathcal{Y}$ , well-behaved  $\mathbb{D}$ : **exact** compactness of sample complexity

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EMX pathology relies on constraining to proper learners!

# Transductive learning

## Transductive learning model

1. Adversary selects  $n$  datapoints
2. One label removed uniformly at random
3. Fill in the blank

Cat



Dog



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Error = average loss over uniformly  
random “?”

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Looks more fine grained than iid model,  
i.e., sample by sample

However, essentially equivalent to PAC  
(Sample complexities equivalent up to log factors)



Key point: one-inclusion graphs (OIGs)  
perfect to study transductive model

Error = average loss over uniformly  
random “?”

# One-inclusion graphs

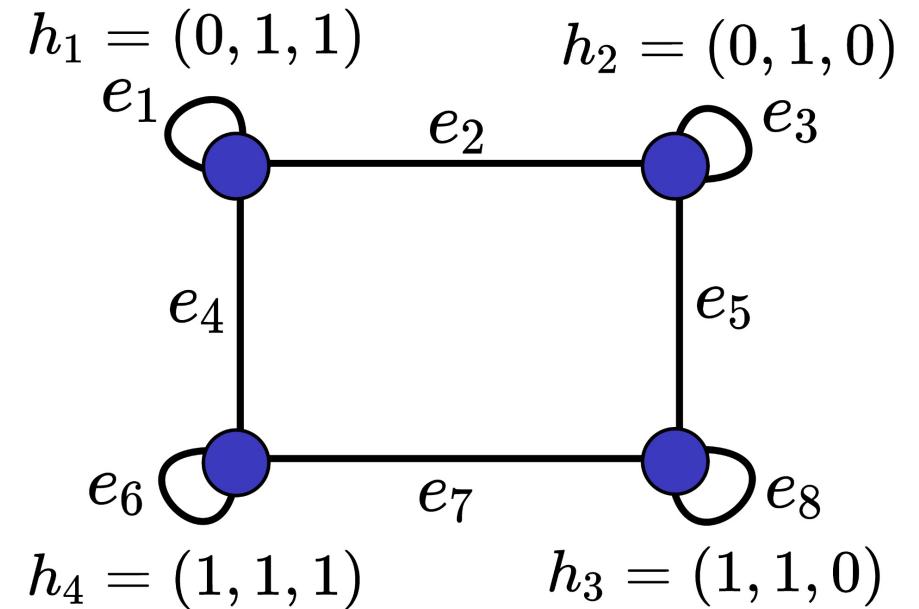
Realizable **one-inclusion graph** of  $\mathcal{H}$  on  $S \in \mathcal{X}^n$ :

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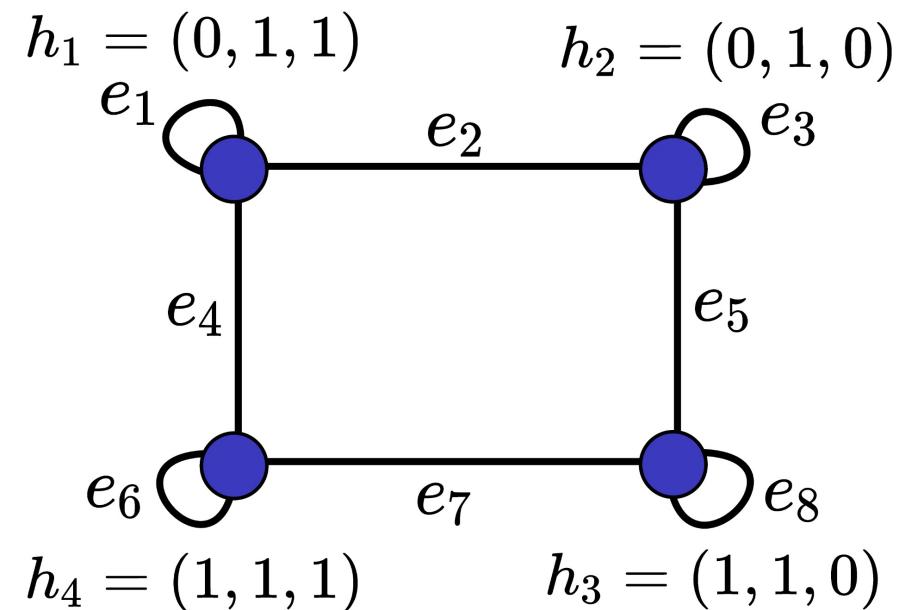
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Learner for  $\mathcal{H}$  = orientation of OIGs

- edge = training set + unlabeled test point
  - e.g.,  $e_2 = (0, 1, ?)$
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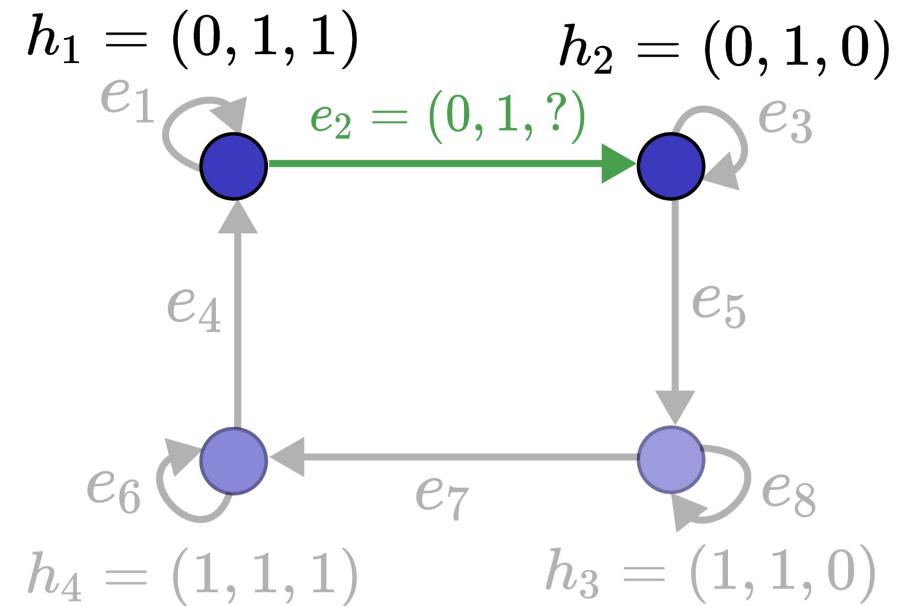
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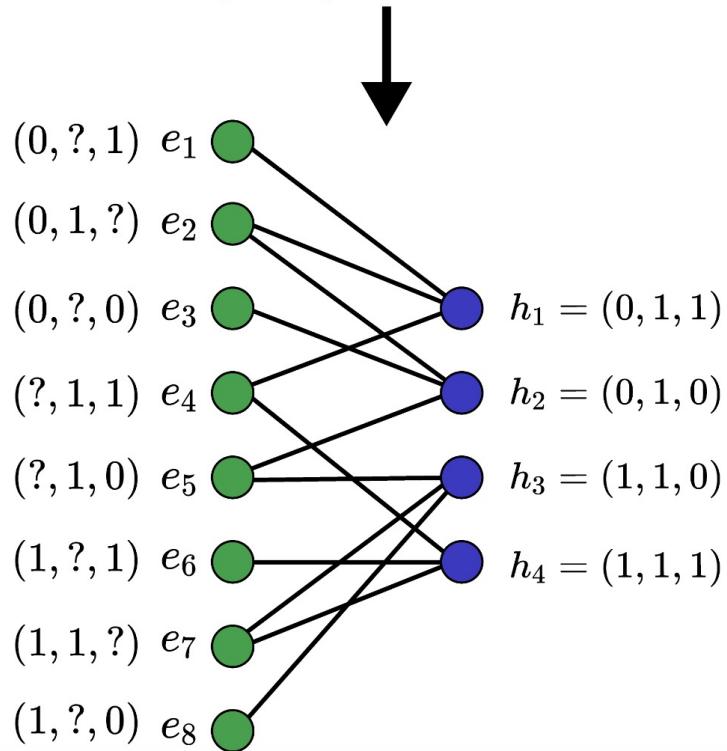
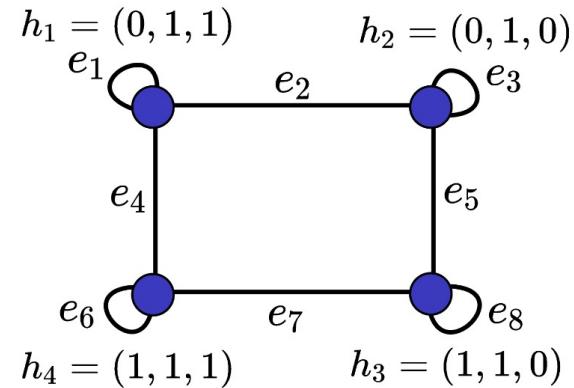
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# One-inclusion graphs

## Bipartite view:

- LHS = *variables* valued in  $\mathcal{Y}$
- RHS = *functions* tracking error of ground truth
  - E.g.,  $h_4(e_4, e_6, e_7) = \ell(1, e_4) + \ell(1, e_6) + \ell(1, e_7)$



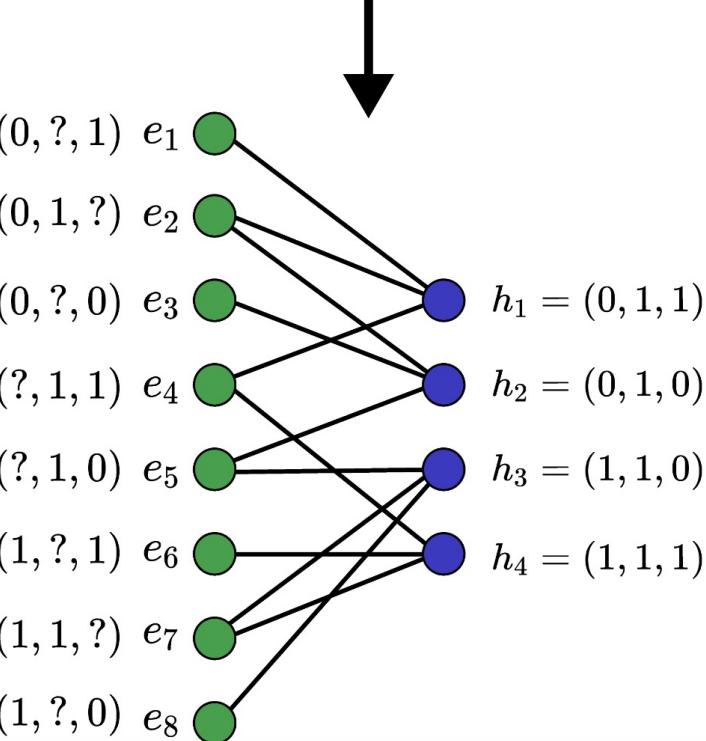
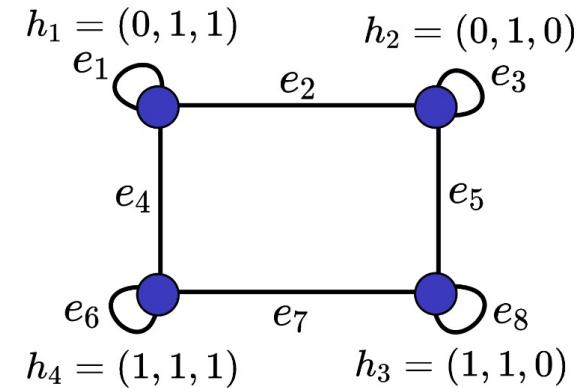
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Now, learner = assignment of variables

**Goal:** assign variables to keep all functions below  $\epsilon$



# Realizable compactness

**Theorem:** Let

- $L$  = set of variables, valued in metric space
- $R$  = set of *proper* functions, each of form  
 $\prod_{i=1}^n \ell_i \rightarrow \mathbb{R}_{\geq 0}$

Pre-image of compact is compact

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- $\mathcal{P}$  = partial assignments of variables that can be completed to satisfy any finite  $S \subseteq R$
- Any  $P \in \mathcal{P}$  can have one free variable assigned  
(Use finite intersection property of compact sets)
- Chains in  $\mathcal{P}$  have upper bounds  
(Use fact that each  $r \in R$  depends upon finitely many variables)
- Thus maximal element = total assignment

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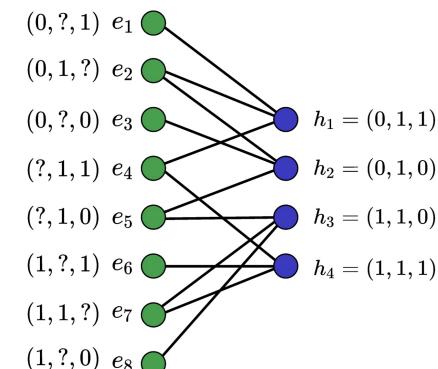
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**For learning:**

- $L$  = LHS nodes, thought of as variables in  $\mathcal{Y}$
- $R$  = RHS nodes, tracking transductive error
  - E.g.,  $h_4(e_4, e_6, e_7) = \ell(1, e_4) + \ell(1, e_6) + \ell(1, e_7)$
  - When  $\mathcal{Y}$  is proper, these functions are proper, b/c continuous & reflect bounded sets

1. = learning  $\mathcal{H}$

2. = learning  $\mathcal{H}$ 's finite projections



# Realizable noncompactness

Build a pathological  $\mathcal{Y}$ :

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e.g.,  $b_A$  for  $A \subseteq \mathcal{A}$ .
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Let  $\mathcal{H}$  be very complex class (e.g.,  $\mathcal{Y}^{\mathcal{X}}$ )

- Learning  $\mathcal{H}$ : pay distance 2 in worst case
- Learning finite projection: promised to only see labels from  $Y \subseteq \mathcal{Y}$ 
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Hence failure of compactness by factor 2

- *But* this is tight: similar(ish) use of Zorn’s lemma
- Factor 2 arises from triangle inequality

# Beyond realizable

**Agnostic and distribution-family:** use abstract compactness result, black-box

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- $L$  = transductive learning instances, with “?”
  - E.g.,  $(y_1, y_2, ?, y_4)$
  - Thought of as variable valued in  $\mathcal{Y}$
- $R$  = excess transductive error of ground truths
  - Subtract error of best  $h \in \mathcal{H}$

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1. Can assign variables to keep all functions  $\leq \epsilon$
2. For each finite  $S \subseteq R$ , can assign variables to keep those functions  $\leq \epsilon$

# Beyond realizable

**Agnostic and distribution-family:** use abstract compactness result, black-box

- $L$  = transductive learning instances, with “?”
  - E.g.,  $(y_1, y_2, ?, y_4)$
  - Thought of as variable valued in  $\mathcal{Y}$
- $R$  = excess transductive error of ground truths
  - Subtract error of best  $h \in \mathcal{H}$

Exact compactness for proper  $\mathcal{Y}$

By same counterexample, fails by factor of 2 for improper  $\mathcal{Y}$ . Maybe more?

**Theorem:** Let

- $L$  = set of variables, valued in metric space
- $R$  = set of *proper* functions, each of form
$$\prod_{i=1}^n \ell_i : \mathbb{R}_{\geq 0}$$

Then the following are equivalent:

1. Can assign variables to keep all functions
$$\leq \epsilon$$
2. For each finite  $S \subseteq R$ , can assign variables to keep those functions
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# Bonus result: Hall's theorem

Proper  $\mathcal{Y}$ : covers almost everything

- $\mathbb{R}^n$  and its closed subsets (any norm)
- Finite metric spaces
- Compact metric spaces

But doesn't cover multiclass classification  
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**Theorem:** Classification enjoys *exact* compactness, in both the realizable and agnostic cases.

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Proper  $\mathcal{Y}$ : covers almost everything

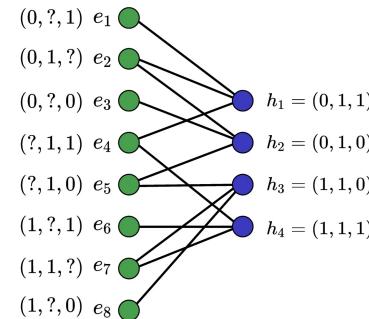
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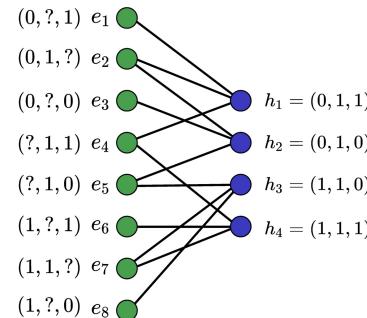
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- Learning becomes a matching problem
- Key step: our compactness result implies M. Hall's theorem for infinite graphs
  - Uses fact that RHS degrees are all finite
- Thus matchability  $\equiv$  Hall's criterion. Done!

# Thank you

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