

Searching

L.EIC

Algoritmos e Estruturas de Dados

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The Search problem

Problem: given an array v storing n elements, and a target element el , locate the position in v (if it exists) where $v[i] = el$

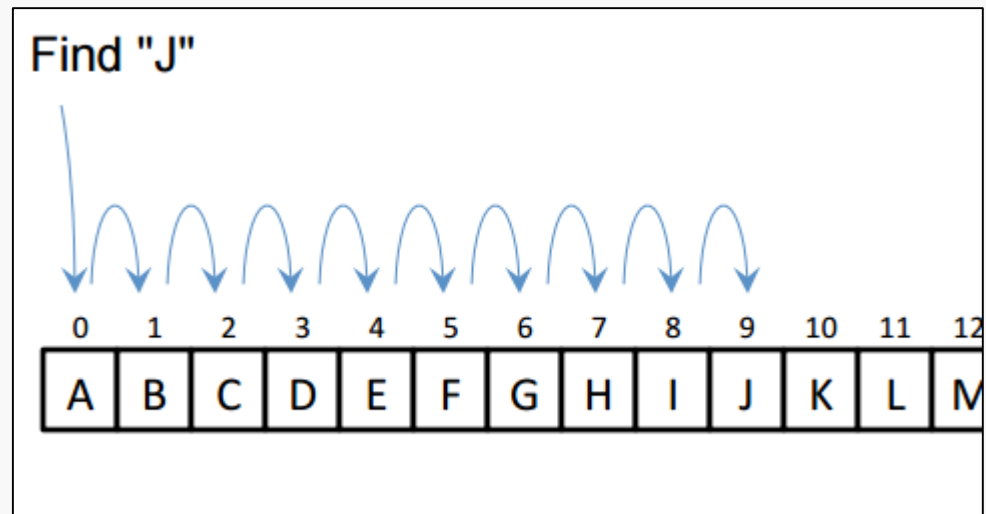
- variants for the case of arrays with repeated values:
 - a) indicate the position of the first occurrence
 - b) indicate the position of the last occurrence
 - c) indicate the position of any occurrence
- when the target el does not exist, return an undefined position, such as -1

Sequential Search

- Algorithm (*sequential search*)

sequentially checks each element of the array, from the first to the last ^(a) or from the last to the first ^(b), until a match is found or the end of the array is reached

- ^(a) if you want to know the position of the first occurrence
- ^(b) if you want to know the position of the last occurrence



suitable for unordered or small arrays

Sequential Search

variant a)

```
/* Search for an element el in a vector v of comparable elements
with the comparison operators. Returns the index of the first
occurrence of el in v, if found; otherwise, returns -1 */

template <class T>
int SequentialSearch(const vector<T> &v, T el)
{
    for (unsigned i = 0; i < v.size(); i++)
        if (v[i] == el)
            return i; // found

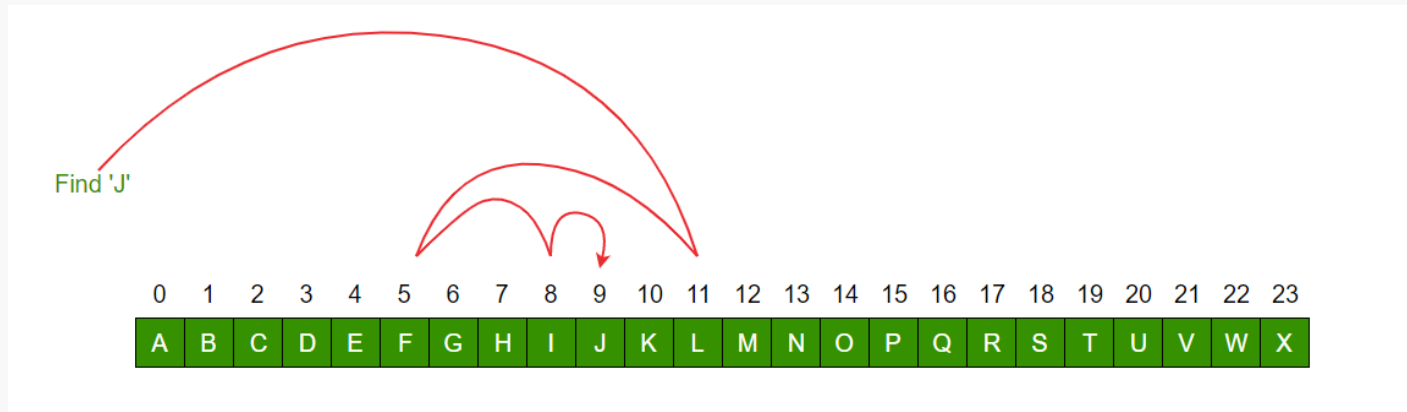
    return -1; // not found
}
```

Sequential Search complexity

- Sequential Search **time complexity**
 - the operation performed most often is the test “`if (v[i] == el)`”, at most **$n+1$** times (in case it doesn't find the target element).
 - if the target element exists in the vector, the test is performed approximately **$n/2$** times on average (1 time in the best case)
 - **$T(n) = O(n)$** in worst case and average case
- Sequential Search **space complexity**
 - space on local variables (including arguments)
 - since vectors are passed "by reference“, the space taken up by the local variables is constant and independent of the vector size.
 - **$S(n) = O(1)$**

Searching in sorted arrays

- Suppose the array **is ordered** (arranged in increasing or non-decreasing order)
 - Sequential search on a sorted array still yields the same analysis $T(n) = O(n)$
 - Can exploit sorted structure by performing **binary search**
 - *Strategy*: inspect middle of the structure so that half of the structure is discarded at every step



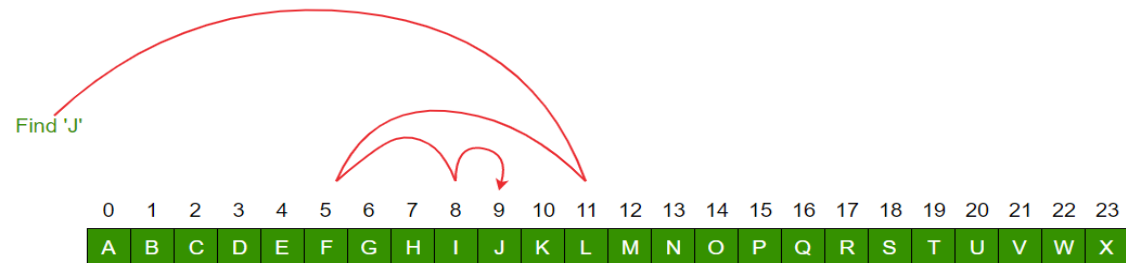
Binary Search

- Algorithm (*binary search*)

compares the element in the middle of the array with the target element:

- is equal to the target element → found
- is greater than the target element → continue searching (in the same way) in the sub-array to the left of the inspected position
- is less than the target element → continue searching (in the same way) in the sub-array to the right of the inspected position

if the sub-array to be inspected reduces to an empty vector, it is concluded that the target element does not exist



Binary Search

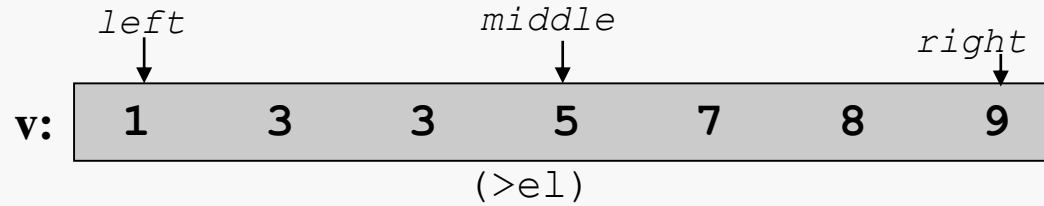
```
/* Search for an element el in an ordered vector v of comparable elements
with the comparison operators. Returns the index of one occurrence of el
in v, if found; otherwise returns -1. */

template <class T>
int BinarySearch(const vector<T> &v, T el)
{
    int left = 0, right = v.size() - 1;
    while (left <= right)
    {
        int middle = (left + right) / 2;
        if (v[middle] < el)
            left = middle + 1;
        else if (el < v[middle])
            right = middle - 1;
        else
            return middle; // found
    }
    return -1; // not found
}
```

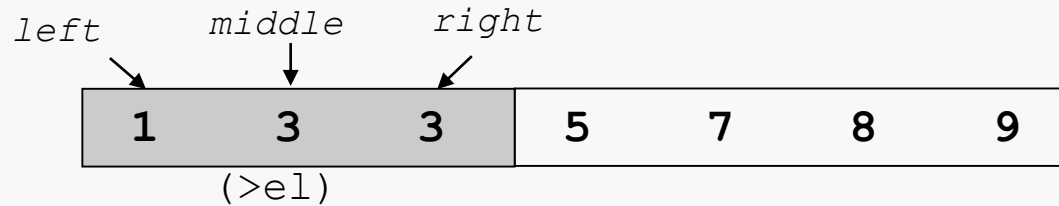

Binary Search

el: 2

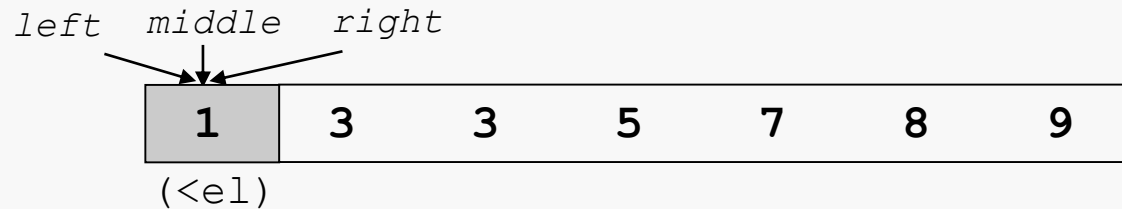
iteration 1



iteration 2



iteration 3



iteration 4



sub-array is empty → element 2 does not exist!

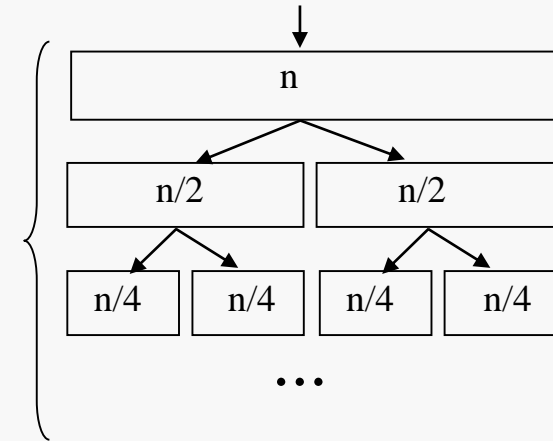
Binary Search complexity

- Binary Search **time complexity**

- in each iteration, the size of the sub-vector to be analyzed is divided by ≈ 2
- after k iterations, the size of the sub-vector to analyze is approximately $n/2^k$
- if the target element does not exist in the vector, the cycle only ends when

$$n/2^k \approx 1 \rightarrow n \approx 2^k \rightarrow k \approx \log_2 n$$

- so, in the worst case, the number of iterations is $k \approx \log_2 n$, **$T(n) = O(\log n)$**



- Binary Search **space complexity**

$$S(n) = O(1)$$

The Painter's Partition Problem: using binary search

Problem

- there are paint n boards of length $\{l_1, l_2 \dots l_n\}$ and there are k painters available
- each painter takes 1 unit of time to paint 1 unit of the board
- any painter will only paint continuous sections of boards
- the problem is to find the **minimum time** to get this job done

example: $k = 2$, $board = [10, 20, 30, 40]$

algorithm:

- apply binary search on the **search space** and
- according to the problem reduce the search space which will finally give the final result

The Painter's Partition Problem: using binary search

example: $k = 2$, $board = [10, 20, 30, 40]$

- Search space is the maximum range where the answer contains:
 - the maximum time will be $(10+20+30+40) = 100$
 - the minimum time will be 40
- the search space will be $[40 - 100]$

40	41	42	98	99	100
----	----	----	-------	----	----	-----

- divide the search space, $middle = 40 + (100 - 40) / 2 = 70$

40	41	42	...	55	...	68	69	70
----	----	----	-----	----	-----	----	----	----

- assume that no painter will paint more than 70 units of the board
- how many painters will be required? $k=2$ is enough? yes, so the search space will be reduced and will change to $[40, 70]$
- ...

The Painter's Partition Problem: using binary search

```
int partition(vector<int> &board, int k)
{
    int n = board.size(), s = 0, m = 0;
    for(int i = 0; i < n; i++)
    {
        m = max(m, board[i]);
        s += board[i];
    }

    int low = m, high = s;
    while (low < high)
    {
        int mid = low + (high - low) / 2;
        int painters = findkp(board, mid);

        if (painters <= k) high = mid;
        else low = mid + 1;
    }
    return low;
}
```

The Painter's Partition Problem: using binary search

```
int findkp(vector<int> &board, int atmost)
{
    int n = board.size();
    int s = 0, painters = 1;

    for (int i = 0; i < n; i++)
    {
        s += board[i];
        if (s > atmost)
        {
            s = board[i];
            painters++;
        }
    }
    return painters;
}
```

STL algorithms

- **Sequential Search** in vectors

iterator find(iterator start, iterator end, const T& val);

- looks for first occurrence of an element identical to *val* in $[start, end[$ (comparison performed by operator `==`)
 - success, returns iterator for the found element
 - no success, returns iterator to “the end” of the vector (*v.end()*)

iterator find_if(iterator start, iterator end, Predicate pred);

- looks for first occurrence for which unary predicate *pred* is true in $[start, end[$

STL algorithms

- **Binary Search** in vectors

bool binary_search(iterator start, iterator end, const T& val);

- looks for one occurrence of an element identical to *val* in $[start, end[$
- uses operator $<$

bool binary_search(iterator start, iterator end, const T& val, Compare comp);

- looks for one occurrence of an element identical to *val* in $[start, end[$
- uses predicate *comp* (*comp* compares two elements)

Example

```
class Person {  
    string cc;  
    string name;  
    int age;  
public:  
    Person (string c, string nm="", int a=0);  
    bool operator < (const Person & p2) const;  
    bool operator == (const Person & p2) const;  
    // ...  
};
```

```
bool Person::operator < (const Person & p2) const {  
    return name < p2.name;  
}  
  
bool Person::operator == (const Person & p2) const {  
    return cc == p2.cc;  
}
```

Example

```
bool isTeenager(const Person &p1)  {
    return p1.getAge() <= 20;
}

bool younger(const Person &p1, const Person &p2)  {
    if (p1.getAge() < p2.getAge()) return true;
    else return false;
}

template <class T> void writeVector(vector<T> &v)  {
    for (val:v)
        cout << val << endl;
    cout << endl;
}
```

Example

```
int main()
{
    vector<Person> vp;
    vp.push_back(Person("6666666", "Rui Silva", 34));
    vp.push_back(Person("7777777", "Antonio Matos", 24));
    vp.push_back(Person("1234567", "Maria Barros", 20));
    vp.push_back(Person("7654321", "Carlos Sousa", 18));
    vp.push_back(Person("3333333", "Fernando Cardoso", 33));

    cout << "initial vector:" << endl;
    writeVector(vp);
}
```

initial vector:

cc: 6666666, name: Rui Silva, age: 34

cc: 7777777, name: Antonio Matos, age: 24

cc: 1234567, name: Maria Barros, age: 20

cc: 7654321, name: Carlos Sousa, age: 18

cc: 3333333, name: Fernando Cardoso, age: 33

Example

```
Pessoa px("7654321");  
vector<Person>::iterator it = find(vp.begin(), vp.end(), px);  
if (it == vp.end())  
    cout << px << " does not exist in vector" << endl;  
else  
    cout << px << " exists in vector as:" << *it << endl;
```

cc: 7654321, name: , age: 0 exists in vector as
cc: 7654321, name: Carlos Sousa, age: 18

```
it = find_if(vp.begin(), vp.end(), isTeenager);  
if (it == vp.end())  
    cout << "there is no teenager in the vector" << endl;  
else  
    cout << "teenager found " << *it << endl;
```

teenager found cc: 1234567, name: Maria Barros, age: 20

Example

```
// note that vector vp2 is sorted by age
vector<Person> vp2;
vp2.push_back(Person("7654321", "Carlos Sousa", 18));
vp2.push_back(Person("1234567", "Maria Barros", 20));
vp2.push_back(Person("7777777", "Antonio Matos", 24));
vp2.push_back(Person("3333333", "Fernando Cardoso", 33));
vp2.push_back(Person("6666666", "Rui Silva", 34));

Person py("xx", "xx", 24);
bool exist = binary_search(vp2.begin(), vp2.end(), py, younger);
if (exist == true)
    cout << "there is a person aged " << py.getIdade() << endl;
else
    cout << "there is no person aged " << py.getIdade() << endl;
```

there is a person aged 24

Sorting

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The Sorting problem

Problem: given an array v storing n elements, rearrange these elements in ascending **order** (or rather, in non-descending order, because there may be repeated elements)

- there are several sorting algorithms with complexity $O(n^2)$ that are very simple (Insertion Sorting, BubbleSort, ...)
- there are sorting algorithms that are more difficult to code with complexity $O(n \times \log n)$

(some) Algorithms

Comparative algorithms

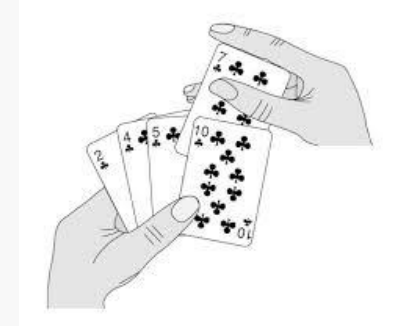
- InsertionSort - $O(n^2)$
- SelectionSort - $O(n^2)$
- BubbleSort - $O(n^2)$
- MergeSort - $O(n \times \log n)$
- QuickSort - $O(n \times \log n)$
- HeapSort - $O(n \times \log n)$, to study later

Non-comparative algorithms

- CountingSort
- RadixSort

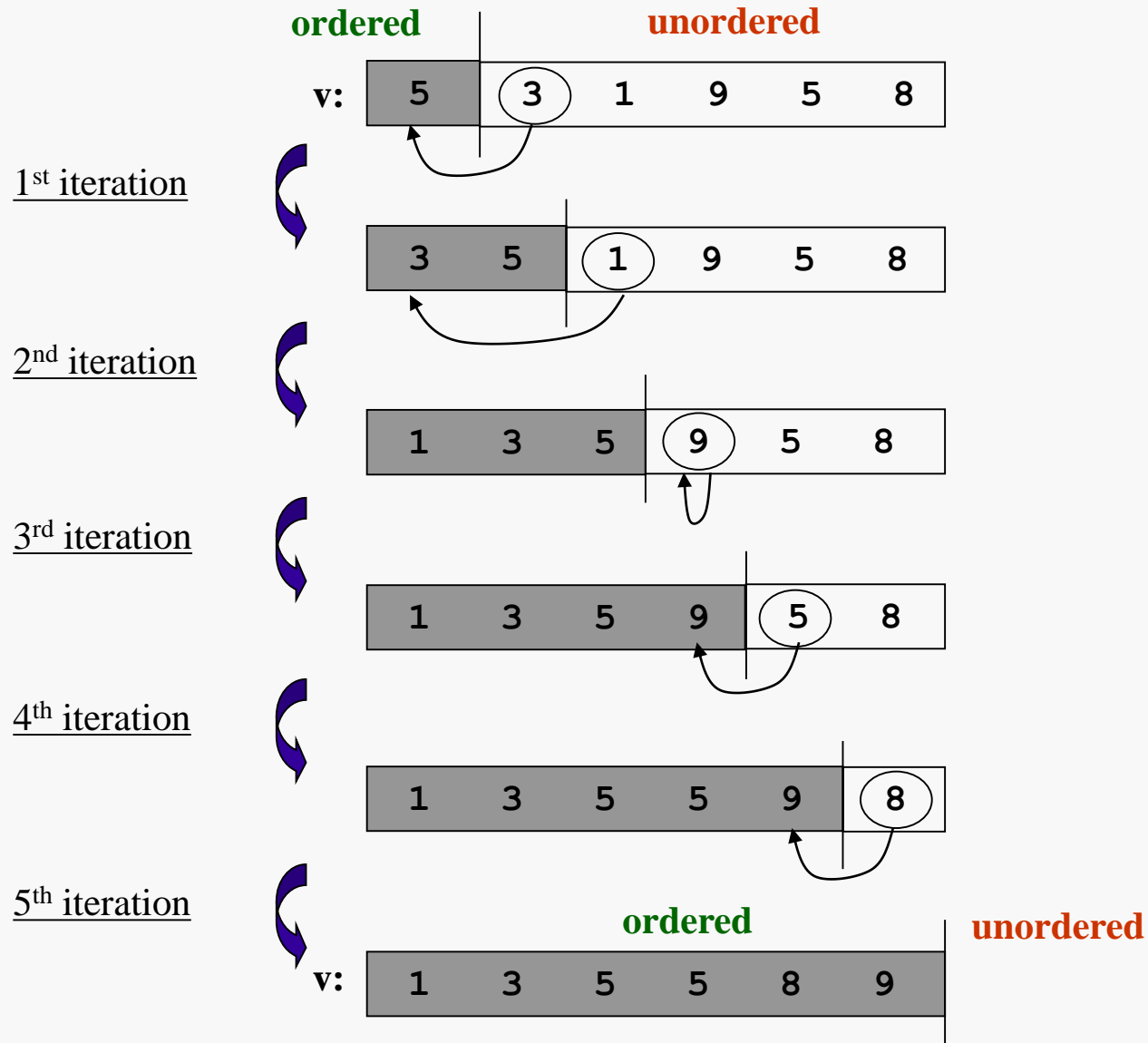
InsertionSort

Idea: insert each element in the correct position



- **Algorithm** (sort by insertion):
 - considers the vector divided into two sub-vectors (left and right)
 - the left sub-vector is ordered and
 - the right sub-vector is unordered
 - starts with just an element in the left sub-vector
 - moves one element at a time from the right sub-vector to the left sub-vector, placing it in the correct position to keep the left sub-vector sorted
 - ends when the right sub-vector is empty

InsertionSort



InsertionSort

```
// Sorts vector v
// Comparable: must have copy constructor,
//             assignment operator (=) and comparison operator (<)

template <class Comparable>
void insertionSort(vector<Comparable> &v) {
    for (unsigned p = 1; p < v.size(); p++) {
        Comparable tmp = v[p];
        unsigned j;
        for (j = p; j > 0 && tmp < v[j-1]; j--)
            v[j] = v[j-1];
        v[j] = tmp;
    }
}
```

see animation in [VisuAlgo](#)

InsertionSort complexity

- InsertionSort **time complexity**

- the number of iterations of the for interior cycle is:
 - 1 , best case
 - n , worst case
 - $n/2$, average case
- the total number of iterations of the for exterior cycle is:
 - best case, $1 + 1 + \dots + 1 = n - 1 \approx n$
 - worst case, $1 + 2 + \dots + n - 1 = (n - 1) \times (1 + n - 1)/2 = n \times (n - 1)/2 \approx n^2/2$
 - average case, $\approx n^2/4$

$$T(n) = O(n^2)$$

- InsertionSort **space complexity**

- space taken up by the local variables is constant and independent of the vector size

$$S(n) = O(1)$$

SelectionSort

Idea: select minimum

look for the minimum and put in his position

- **Algorithm** (probably the most intuitive)
 - find the minimum of the vector
 - swap with the first element
 - continue for the rest of the vector (excluding the first one)

SelectionSort

```
template <class Comparable>
void selectionSort(vector<Comparable> &v) {
    for (unsigned i = 0; i < v.size()-1; i++) {
        unsigned imin = i;
        for (j = i+1; j < v.size(); j++)
            if (v[j] < v[imin])
                imin = j;
        swap(v[i], v[imin]);
    }
}
```

- SelectionSort **time complexity**
 - two nested cycles, each can have n iterations $T(n) = O(n^2)$

BubbleSort

Idea: swap adjacent elements that are out of order

- **Algorithm**

- compare adjacent elements; if the second is smaller than the first, swap them
- repeat for all elements except the last one (which is already correct)
- repeat the two previous steps, using one less pair in each iteration until there are no more pairs (or no swaps)

BubbleSort

```
template <class Comparable>
void bubbleSort(vector<Comparable> &v) {
    for(unsigned int j = v.size()-1; j > 0; j--) {
        bool troca=false;
        for(unsigned int i = 0; i < j; i++)
            if(v[i+1] < v[i]) {
                swap(v[i],v[i+1]);
                troca = true;
            }
        if (!troca) return;
    }
}
```

- BubbleSort **time complexity**
 - two nested cycles, each can have n iterations $T(n) = O(n^2)$

MergeSort

Idea: divide in two (easy to order), order and merge

- **Algorithm** (recursive approach)
 - divide the vector in half
 - sort each half, using MergeSort recursively
 - merge the two halves already ordered
- MergeSort **time complexity**
 - 2 recursive calls of size $n/2$
 - vector merge operation: $O(n)$
$$T(n) = O(n \times \log n)$$
- MergeSort **space complexity**
 - vector merge requires extra space $S(n) = O(n)$

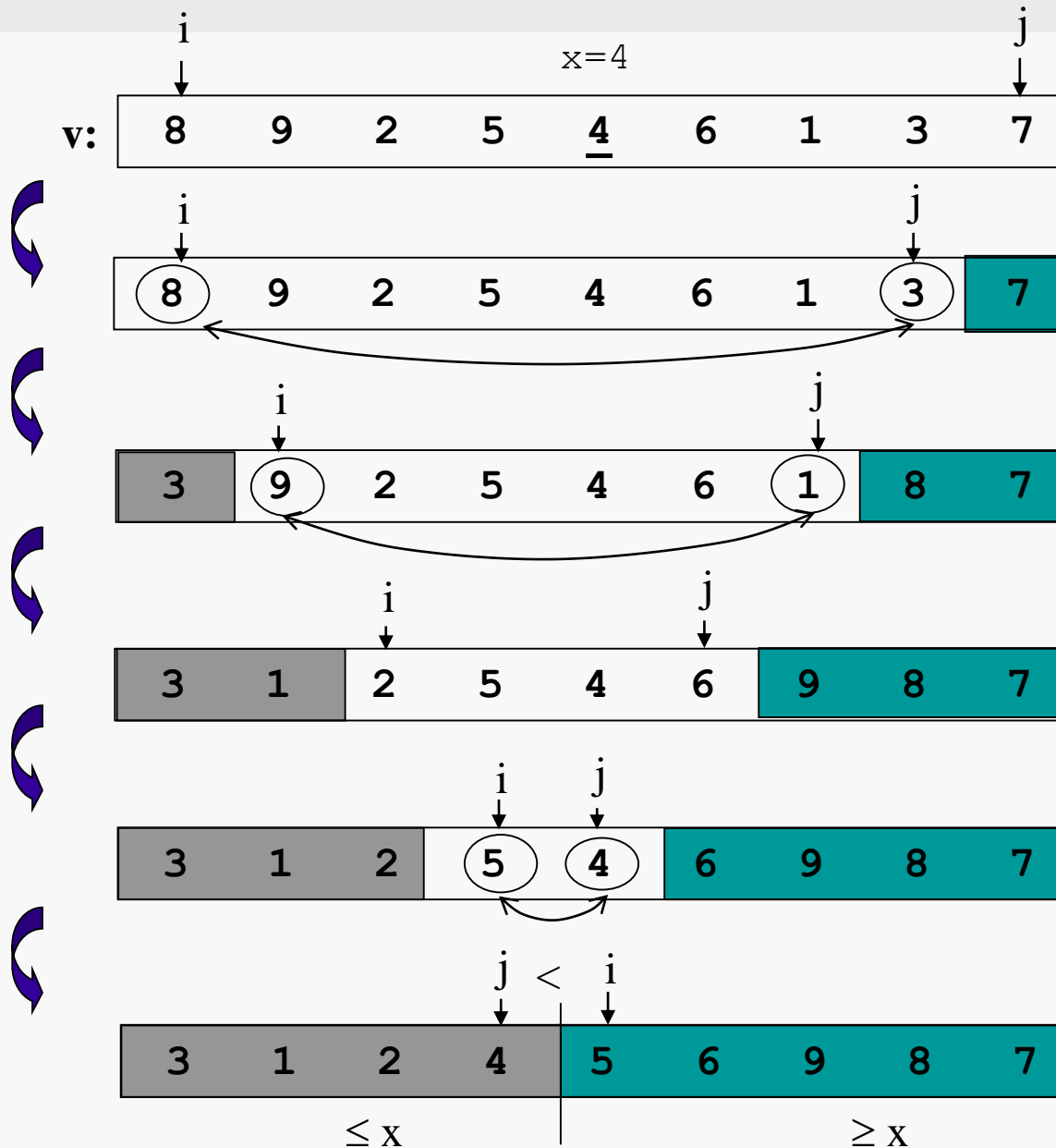
Idea: partition according to a pivot

invented by Tony Hoare in 1959

- **Algorithm** (recursive approach)
 - choose an "arbitrary" element (x) of the vector (called pivot)
 - break the initial vector into two sub-vectors (left and right), with
 - $\leq x$ values in the left sub-vector and
 - $\geq x$ values in the right sub-vector
 - sort the left and right sub-vectors using the same method recursively

if the number (n) of elements to sort is too small, use another algorithm (*insertionSort*)

QuickSort



QuickSort

```
template <class Comparable>
void quickSort(vector<Comparable> &v, int left, int right){
    if (right-left <= 10)        // if small vector
        insertionSort(v, left, right);
    else {
        Comparable x = median3(v, left, right);    // x is the pivot
        int i = left; int j = right-1;
        for(;; ) {
            while (v[++i] < x) ;
            while (x < v[--j]) ;
            if (i < j)
                swap(v[i], v[j]);
            else break;
        }
        swap(v[i], v[right-1]);    //reset pivot
        quickSort(v, left, i-1);
        quickSort(v, i+1, right);
    }
}
```

QuickSort

```
template <class Comparable>
void quickSort(vector<Comparable> &v){
    quickSort(v, 0, v.size()-1);
}
```

```
template <class Comparable>
const Comparable &median3(vector<Comparable> &v, int left, int right){
    int center = (left+right) /2;
    if (v[center] < v[left])
        swap(v[left], v[center]); //swap elements if order incorrect
    if (v[right] < v[left])
        swap(v[left], v[right]); //swap elements if order incorrect
    if (v[right] < v[center])
        swap(v[center], v[right]); //swap elements if order incorrect

    swap(v[center], v[right-1]); //puts pivot in position right-1
    return v[right-1];
}
```

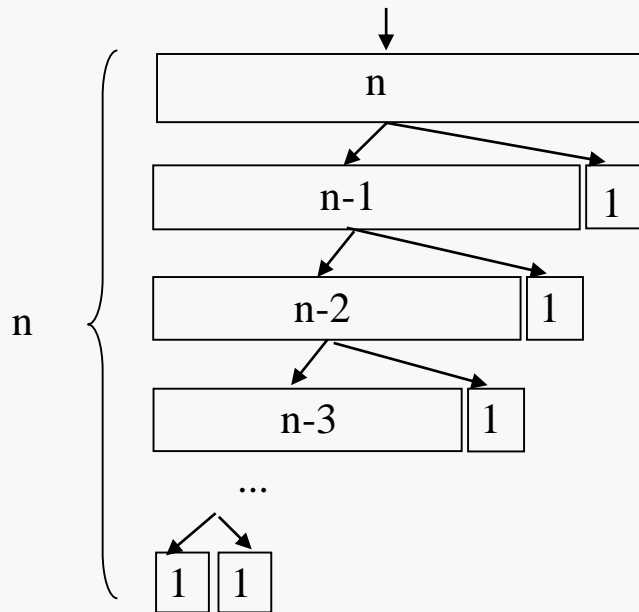
QuickSort

- Choice of **pivot** determines efficiency
 - *worst case*: pivot is the smallest element
 - $T(n) = O(n^2)$
 - *best case*: pivot is the middle element
 - $T(n) = O(n \times \log n)$
 - *average case*: pivot cuts vector arbitrarily
 - $T(n) = O(n \times \log n)$
- Choice of pivot
 - one of the extreme elements of the vector
 - bad choice: $O(n^2)$ if ordered vector
 - random element
 - one more heavy function
 - median of three elements (extremes and middle of vector)
 - recommended

QuickSort

- QuickSort **time complexity**

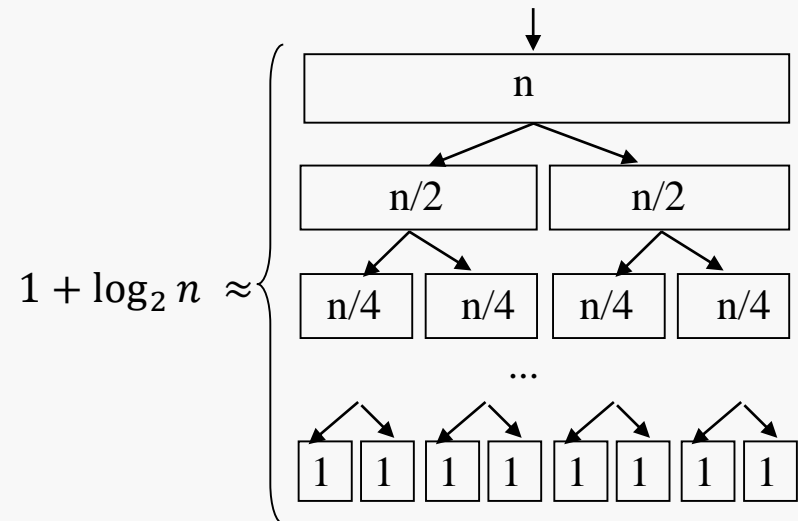
worst case



- recursion depth: n
- execution time

$$\begin{aligned} T(n) &= n + n + (n - 1) + \dots + 2 \\ &= O(n^2) \end{aligned}$$

best case



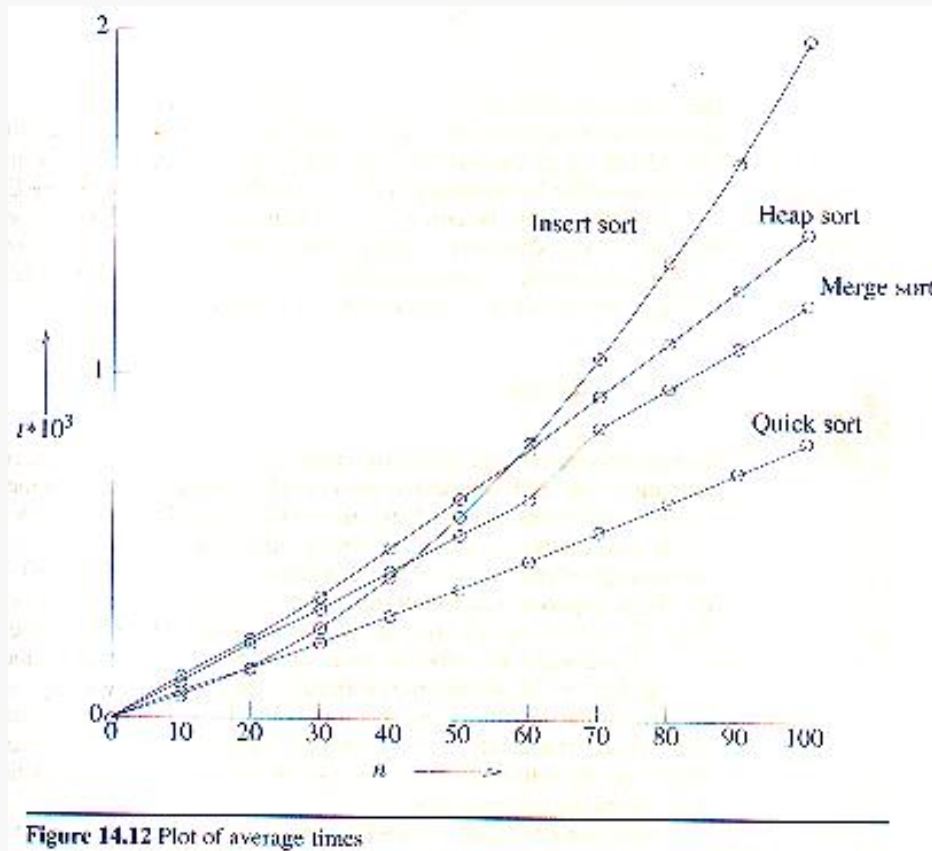
- recursion depth: $\approx 1 + \log_2 n$
- execution time (each line is n)

$$\begin{aligned} T(n) &= (1 + \log_2 n) \times n \\ &= O(n \times \log n) \end{aligned}$$

QuickSort

- QuickSort **space complexity**
 - the memory space required by each QuickSort call, not counting recursive calls, is independent of the size (n) of the vector.
 - the total memory space required by the QuickSort call, including recursive calls, is therefore proportional to the recursion depth
 - QuickSort **space complexity** is:
 - *worst case:* $S(n) = O(n)$
 - *best case, average case:* $S(n) = O(\log n)$

Comparative sorting algorithms (some comparison)



Sahni, "Data Structures, Algorithms and Applications in C++"

- **QuickSort** is in practice the most efficient
- except for small vectors where the insertion sort method (**insertionSort**) is better

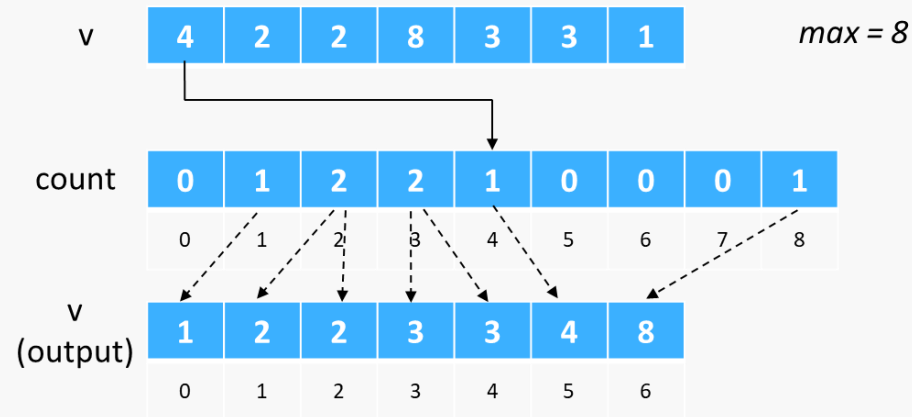
Sorting (comparative/non-comparative)

- Comparative based sorting algorithms:
 - Several sorting algorithms have been discussed and the best ones, so far:
 $T(n) = O(n \times \log n)$
 - It can be proven that any deterministic comparison based sorting algorithm will need to carry out at least $O(n \times \log n)$ steps
- Non-comparative based sorting algorithms:
 - we can avoid comparing elements and still sort
 - this is fast if the range of data is small
 - for simplicity we will assume that elements are numbers, but
 - idea can be generalized to other types of data

CountingSort

Idea: count the number of occurrences of an element

- Algorithm:
 - count the number of occurrences of each element
 - count is stored in an auxiliary array
 - mapping the count as an index of the auxiliary array



$T(n) = O(n + k)$, k is the maximum element

Counting Sort

```
void countingSort(vector<int> &v){
    if (v.empty())
        return;
    auto min_max = std::minmax_element(v.begin(), v.end());
    int min = *min_max.first;
    int max = *min_max.second;
    std::vector<unsigned> count((max - min) + 1, 0);
    for (auto v1:v)
        ++count[v1-min];
    unsigned i=0;
    for (auto c = 0; c < count.size(); c++)
        for (auto j = 0; j < count[c]; j++) {
            v[i]= c+min;
            i++;
        }
}
```

see animation in [VisuAlgo](https://visu.algo)

RadixSort

Idea: repeatedly sort by digit

- **Algorithm:**

we have to go through all the significant places of all elements

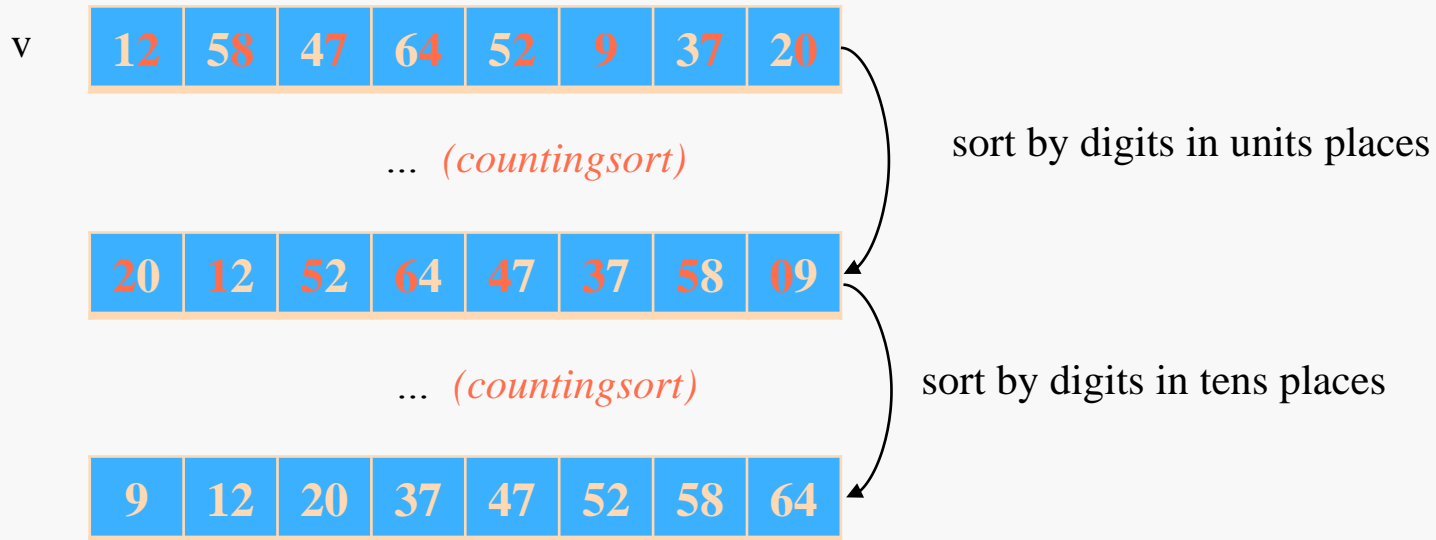
- go through each significant place one by one
- use any stable* sorting technique to sort the digits at each significant place (counting sort)

```
for each digit i=0 to d-1    (0 is the least significant digit)
    countingSort by digit i    (or other stable sorting algorithm)
```

$T(n) = O(d * (n + k))$, d is the maximum number of digits of an element

* a sorting algorithm is stable if it always leaves elements with equal keys in their original order

Radix Sort



see animation in [VisuAlgo](#)

Sorting

- There are many sorting algorithms (many other exist)
- The "best" algorithm depends on the specific case
- It is possible to combine several sorting algorithms. In practice, in real implementations, this is what is done.
 - when size or portion of unordered array is small use insertion sort
 - C++ STL uses *IntroSort*: (QuickSort + HeapSort) + InsertionSort

STL algorithms

- **Sorting**

LegacyRandomAccessIterator !

void sort(iterator start, iterator end);

- sorts the elements between $[start, end[$ in ascending order, using the **operator <**

void sort(iterator start, iterator end, StrictWeakOrdering cmp);

- sorts the elements between $[start, end[$ in ascending order, using the ***StrictWeakOrdering* function**

Algoritmo de ordenação implementado em *sort()* é o algoritmo ***IntroSort***:

- (QuickSort + HeapSort) + InsertionSort

Example

```
class Person {  
    string cc, name;  
    int age;  
public:  
    Person (string c, string nm="", int a=0);  
    bool operator < (const Person & p2) const;  
};
```

```
bool Person::operator < (const Person & p2) const {  
    return name < p2.name;  
}  
  
bool compPerson(const Person &p1, const Person &p2) {  
    return p1.getAge() < p2.getAge();  
}
```

Example

```
int main()
{
    vector<Person> vp;
    vp.push_back(Person("6666666", "Rui Silva", 34));
    vp.push_back(Person("7777777", "Antonio Matos", 24));
    vp.push_back(Person("1234567", "Maria Barros", 20));
    vp.push_back(Person("7654321", "Carlos Sousa", 18));
    vp.push_back(Person("3333333", "Fernando Cardoso", 33));
    vector<Person> vp1=vp;
    vector<Person> vp2=vp;

    cout << "initial vector:" << endl;
    write_vector(vp);
}
```

initial vector:

v[0] = (cc: 6666666, name: Rui Silva, age: 34)

v[1] = (cc: 7777777, name: Antonio Matos, age: 24)

v[2] = (cc: 1234567, name: Maria Barros, age: 20)

v[3] = (cc: 7654321, name: Carlos Sousa, age: 18)

v[4] = (cc: 3333333, name: Fernando Cardoso, age: 33)

Example

```
sort(vp1.begin(), vp1.end());  
cout << "sort using 'operator <':" << endl;  
write_vector(vp1);
```

sort using 'operator <':

v[0] = (cc: 7777777, name: Antonio Matos, age: 24)
v[1] = (cc: 7654321, name: Carlos Sousa, age : 18)
v[2] = (cc: 3333333, name: Fernando Cardoso, age : 33)
v[3] = (cc: 1234567, name: Maria Barros, age : 20)
v[4] = (cc: 6666666, name: Rui Silva, age : 34)

```
sort(vp2.begin(), vp2.end(), compPerson);  
cout << "sort using comparison function:" << endl;  
write_vector(vp2);  
}
```

sort using comparison function:

v[0] = (cc: 7654321, name: Carlos Sousa, age : 18)
v[1] = (cc: 1234567, name: Maria Barros, age : 20)
v[2] = (cc: 7777777, name: Antonio Matos, age : 24)
v[3] = (cc: 3333333, name: Fernando Cardoso, age : 33)
v[4] = (cc: 6666666, name: Rui Silva, age : 34)